

TREE STATION SIERRA LEONE TRIANGULATION

TEXT BOOK

OF

TOPOGRAPHICAL AND GEOGRAPHICAL SURVEYING

BY

MAJOR C F CLOSE, C M G , R E.

FELLOW OF THE ROYAL ASTRONOMICAL SOCIETY MEMBER OF COUNCIL OF THE ROYAL GEOGRAPHICAL SOCIETY HEAD OF THE TOPOGRAPHICAL SECTION OF THE GENERAL STAFF LATE INSTRUCTOR IN SURVEYING AT THE SCHOOL OF MILITARY ENGINEERING LATE BRITISH COMMISSIONER NYASA TANGANYIKA BOUNDARY COMMISSION FORMERLY OF THE ORDNANCE SURVEY AND OF THE SURVEY OF INDIA



LONDON
PRINTED FOR HIS MAJESTY'S STATIONERY OFFICE,
BY HARRISON AND SONS, ST MARTIN'S LANE,
PRINTERS IN ORDINARY TO HIS MAJESTY

1905

Price Three Shillings and Sixpence

(Wt 11975 5000 3/05—H & S 3455)

PREFACE.

The methods described in this book are chiefly based on the actual experience of Royal Engineer Officers who are, or have been, engaged in carrying out geographical and topographical surveys.

Chapter IV, on Traverses, is mainly written by Captain W. J. Johnston, Captain H. D. Pearson and Captain C. J. Heath.

Chapter VII, 'Survey under Active Service Conditions,' is from the writings of Colonel Sir Thomas Holdich, K.C.M.G., K.C.I.E., Colonel Gore, C.S.I., late Surveyor General of India, Colonel the Hon. M. G. Talbot, Director of Surveys in the Sudan, and Colonel Walsh, C.I.E.

Chapter VIII, 'Levelling,' is due to Captain H. L. Crosthwait and Captain C. Russell Brown.

A portion of Chapter X, the use of the theodolite for contouring, is taken from a report by Major P. H. du P. Cregan.

Chapter XII, 'The Reproduction of Maps in the Field,' has been written by Captain B. A. G. Shelley, with some additions by Lieutenant F. V. Thompson.

Chapter XIV, 'Field Astronomy,' is based on the 'Notes on Astronomy,' written for the School of Military Engineering by Colonel A. C. MacDonnell, rearranged by Captain C. J. Heath.

In Chapter XVI the description of 'Photo-longitudes' is taken from the account published by Major J. H. Hills, C.M.G., in the 'Memoirs of the Royal Astronomical Society' Vol. LIII., 1897.

The section on 'Occultations' has been written by Captain C. H. Poulkes.

The 'Graphic Method of predicting the circumstances of an Occultation' is due to Colonel S. C. N. Grant, C.M.G., and permission to use the diagrams explanatory of this method has been kindly granted by the Royal Geographical Society. Appendix VIII. is also due to Colonel Grant.

The extension of the 'Graphic Method' is from a paper by Mr. A. C. D. Crommelin.

Tables I., II., IX., XI. and XII. were computed by Major C. H. Inthoven.

Tables XVII. and XVIII. were computed by Lieutenant G. P. Evans.

The diagrams for rapidly determining the Time and Altitude of a star on the Prime Vertical were devised by Captain C. J. Heath.

The Star Charts were drawn by Captain H. P. Winsloe.

Mr. A. R. Hinks, M.A., of Cambridge Observatory, has very kindly read and criticised the chapters which deal with field astronomical methods, these chapters have benefited greatly in consequence.

The reproductions of British and Foreign Topographical Maps were executed under the direction of Colonel D. A. Johnston, C.B., Director General of the Ordnance Survey. Most of

the other plates were drawn in the Topographical Section of the War Office under the direction of Major L. H. Hills, C.M.G., a few, however, have been produced by H.M. Stationery Office.

Plate V is from a plane table sheet of Kroonstad by Lieut.-Colonel H. M. Jackson, Surveyor General of the Transvaal.

Plate VI is from a plane table survey executed in Somaliland under Captain G. A. Beazeley.

Plate VII is from an original field sheet lent by Lieut.-Colonel F. B. Longe, Surveyor General of India.

The field methods described are, for the most part, those in use by the Survey of India, but advantage has been taken of recent experience in mapping and exploring various territories in Africa and elsewhere to include useful methods which are not commonly employed in India.

CONTENTS.

		Page
Chapter I	Introduction. General Principles	1
II	Plane	5
III	Triangulation	10
IV	Traverses	34
V	Stadia Methods and Tachometry	51
VI	Plane Tabling	57
VII	Surveys by Active Service Contingents	63
VIII	Levelling	74
IX	Heights (Barometrical and Hypsometrical)	86
X	Contouring and Hill Sketching	89
XI	Map Projections and Graticules	92
XII	Explanation of Maps in the Field	112
XIII	Portions of Foreign Government Maps and Surveys	118
XIV	Index Notation	123
XV	Latitudes and Azimuths	182
XVI	Longitude	184
XVII	Theory of Errors applied to Topographical Work	204
Table I	Values of P Q P′ S T (True Lat. Long. and Reverse Azimuths)	209
II	(a) A (f) Proportional parts	222
III	Heights. Value of k. Coefficient of refraction 07	223
IV	Computation of value of k	223
V	A VI Barometer Heights	224
VII	A VIII Hypsometer Heights	226
IX	Graticules for Maps scale 1 = 1 m (Scales and diagonals for 15′ Lat. and Long.)	227
X	Length in miles of 15′ Lat. and Long.	232
XI	Linear value in feet of 1″ arc and Natural parts along Meridian	234
XII	Parallel	246
XIII	Spherical Excess	258
XIV	Astronomical Refraction	259
XV	Parallax of the Sun	261
XVI	Reduction to Meridian (for Latitude)	262
XVII	Correction of Moon's Equatorial Parallax (for Occultation)	264
XVIII	Reduction of Latitude (for Occultation)	265
Appendix I	Explanation of Table I	267
II	Computation of Distances and Azimuths	268
III	Alternative Formulæ for Lat. Long. and Reverse Azimuth	270
IV	Explanation of Table IV	271
V	Formulæ for correction for Sag in steel tapes	272
VI	List of Instruments, Tools and Camp Equipment	273
VII	Sketching in Dense Forest	275
VIII	Photographic Surveying	279
IX	Useful Trigonometrical Formulæ	280
X	Length of the Metre	282

LIST OF PLATES.

		To face page
Frontispiece	Tree Station, Sierra Leone Triangulation	
I	Port Elizabeth Base Extension	8
II	Trigonometrical Signals for Short Distances	10
III	Five inch Micrometer Transit Theodolite	12
IV	Service Plane Table	57
V	Example of Small Scale Plane Table Work in Undulating Country (Kroonstad)	58
V (*b*)	Example of Two inch Plane Table Work (Jersey)	60
VI	Specimen of Small Scale Plane Table Work (A portion of a survey in Somaliland during the operations 1903–4)	62
VII	Form Lines for Plane Table Work Plane Table Field Sheet (Baluchistan)	62
VIII	Diagram of Afghan Boundary Triangulation	71
IX	Cooke's Reversible Level	75
X	'Y' Level	78
XI	Dumpy Level	79
XII	Water Level Ordnance Survey Pattern	90
XIII	Ordnance Survey 1 inch, black with brown hills	91
XIV	Gnomonic Projection	104
XV	Clarke's Perspective Projection	105
XVI	Conical Projection with Rectified Meridians	109
XVII	Field Lithographic Press	112
XVIII	Ordnance Survey 1 inch to 1 mile (coloured)	118
XVIII (*b*)	2 miles to 1 inch	118
XIX	½ to	120
XX	French $\frac{1}{1\,000}$ (Bizerta)	122
XXI	United States $\frac{1}{62\,500}$	122
XXII	Germany $\frac{1}{10\,000}$	122
XXIII	France $\frac{1}{10\,000}$ Engraved black	122
XXIV	Switzerland $\frac{1}{50\,000}$ Coloured	122
XXV	Italy — $\frac{1}{100\,000}$ Engraved black	122
XXVI	St Helena 2½ inches to 1 mile	123
XXVII	Occultation Diagram No 1	192
XXVIII	" 2	192
XXIX	Star Chart	End of Book
XXX	"	" "
XXXI		" "
XXXII		" "
XXXIII	Diagram for Determining the Hour Angle of a Heavenly Body when on Prime Vertical	" "
XXXIV	Diagram for Determining the Altitude of ditto	" "

TEXT BOOK OF TOPOGRAPHICAL SURVEYING.

CHAPTER I

INTRODUCTION GENERAL PRINCIPLES

Surveying is the process of accurately determining the relative positions of the features of a portion of the Earth's surface

Topography (τόπος a place, γράφειν to describe) is the delineation of the natural and artificial features of a locality

Topographical Surveying is thus the process of accurately determining the relative position of the surface features of the earth and of delineating them on a map The surface features are of two kinds artificial that is to say those produced by the agency of man, such as towns, roads or railways and natural features such as rivers, lakes forests, hill features and the undulations of the ground

A Topographical Map should depict all the surface features which can be legibly drawn, all the accidents of the surface should be shown which distinguish it from a level, featureless plain The amount of information presented on a topographical map is thus conditioned by two principal factors, the complexity of the surface features, and the scale of the map

Since it is not customary to construct maps in the field on scales smaller than about $\frac{1}{100000}$ this scale will be taken as the lower limit for topographical maps Maps on scales smaller than this are compilations or atlas maps

It is not the primary intention of a topographical map to show property boundaries, this is the function of a large scale *Cadastral Plan* Nor on the other hand, has a topographical survey for its object the investigation of any scientific questions connected with the shape and dimensions of the earth this is the domain of a *Geodetic Survey*

The production of a map, in the ordinary sense of the word, is, in fact, the aim of a topographical survey

The scales of topographical maps may vary from 6 inches to 1 mile to $\frac{1}{8}$ inch to 1 mile, or from about $\frac{1}{10^{1}}$ to $\frac{1}{500^{1}}$, but for military and administrative purposes, the most useful scales are 2 inches 1 inch, $\frac{1}{2}$ inch, and $\frac{1}{4}$ inch to 1 mile, or say from $\frac{1}{31680}$ to $\frac{1}{253440}$ and this book is to be considered as dealing mainly with maps on such scales

Topographical maps naturally vary in accuracy, according to the conditions *under which* they have been produced Thus a plane table survey made rapidly on active service will be wanting in that refinement of accuracy which is to be expected of a map deliberately executed in peace time In a broad sense, even a military sketch may be considered a rough

topographical map, but military sketches will not be considered in this book, which will deal with —

(1) Deliberate topographical surveys,
(2) Topographical surveys executed on service,
(3) Geographical surveys, such as are required for the delimitation of an international boundary
(4) Exploratory surveys

Topographical geographical and exploratory surveys merge into one another, and there is no very definite dividing line between them Generally speaking, there should be no detectable error in a topographical map, whilst geographical surveys are somewhat rough and ready The value of a survey on active service depends on the extent to which it assists the operations in progress and minute accuracy must often, in such a case, be sacrificed

The extent of the field before the topographer may be realised from the fact that, excluding Canada Australia New Zealand and India, the total unmapped area of the British Empire amounts to about 3,700 000 square miles

Main Principle to Observe in Carrying Out a Topographical Survey

The main principle to observe in a map making is to work from the whole to the part, and not from the part to the whole It would be entirely wrong for instance, to map a block of four English counties by making independent surveys of each county and then joining the surveys together It is still more incorrect to attempt to compile a map of a large country by piecing together farm surveys Such a proceeding, which has several times been attempted, results in a thoroughly untrustworthy map The technical reasons for this will be better understood later on meanwhile it must be accepted as an axiom that however large or however small may be the area to be surveyed, it must be treated as a whole, and that all over the area a number of carefully determined points must be fixed, forming, as it were, an accurate framework or skeleton on which the detail is to depend It is clear that such a method prevents the accumulation of any system of errors except that of the accurate framework

The accuracy of a map will thus ultimately depend on the accuracy of the framework, which will consist of points fixed by one of the following methods —

(1) Triangulation,
(2) Traverses,
(3) Astronomical determinations, or
(4) Combinations of the above

Of these triangulation is always to be preferred, and should be adopted whenever possible

Triangulation —It is an elementary proposition in trigonometry that, given the angles of a triangle and the length of one side, the lengths of the other sides can be calculated

If then, we have a chain of triangles as below, and know all the angles and the length of one side we can compute the lengths of all the other sides

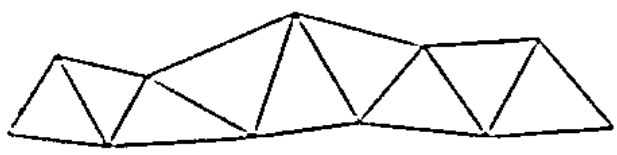


Fig 1

The same check applies to a network or to any figure built up of triangles

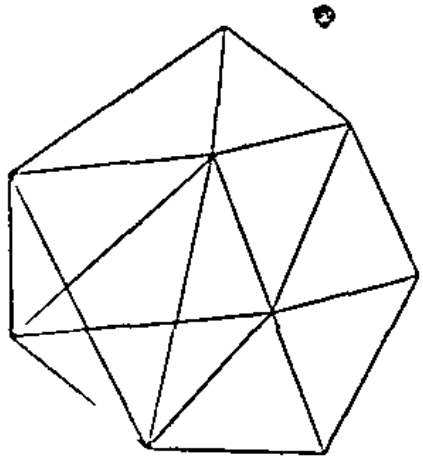


Fig. 2

Now imagine that these points are objects on the earth's surface and that at each object horizontal angles have been observed to those surrounding it and suppose that the horizontal distance between any two of these points has been measured it is clear that the distance between any two unmeasured points is easily computed and plotted on paper

The measured side is called the *base*

Classes of Triangulation

(1) **Principal Triangulation** or **Geodetic Triangulation** is the main triangulation of a country carried out with every refinement of care of which the sides vary in length from about 10 to 50 miles (though rays well over 100 miles have been used) in which no precaution is neglected and of which the computations are most exact and laborious The triangular error of a principal triangle *i.e.* the algebraic sum of the errors of the three angles of the triangle would not be expected to exceed 1 second

(2) **Secondary Triangulation**—In a regularly surveyed country this would break up the principal triangles into sides of 5 to 10 miles in length, or else be carried out in the form of secondary chains connecting the principal chains Triangular error say, 2 to 5 seconds

The observations are not usually reduced so rigorously as in principal work

(3) **Tertiary Triangulation** The minor triangulation of a regularly surveyed country covering the whole surface of the land with triangles the sides of which are from 1 to 5 miles in length Triangular error say 5 to 15 seconds

In the Ordnance Survey of the United Kingdom—

The sides of the Principal Triangles average	35½	miles
Secondary	5	,
Tertiary ,	1¼	

In the Survey of India the average length of the sides of the principal triangles is 52 miles

(4) **Topographical Triangulation**—Though it may be considered certain that in course of time the whole land surface of the world will be systematically surveyed and covered with principal, secondary, and tertiary triangles still for some time to come there will be, in many cases, the need for topographical maps produced rapidly and with a minimum of expense without the aid of rigorous triangulation As an example of a geographical survey carried out rapidly without waiting for a rigid framework, the survey of Burma may be

mentioned This country, which was annexed at the end of 1887 was rapidly surveyed on the scale of 4 miles to 1 inch The triangulation for this survey was carried out during the execution of the topography the sides were of very varying lengths the points observed were mainly pegolas or well defined hill tops, the sole object was to provide points for the plane tablers to work on, and provided there was no plotable error on the particular scale used, no further accuracy was demanded This sort of triangulation, of which the sole intention is to provide a framework sufficiently accurate for the scale in use, and which will never be used for geodetic or cadastral work or for larger scale topographical maps, may be called a *topographical triangulation*

(5) **Rapid Triangulation**—A topographical triangulation carried out during an expedition, or when marching with a column on active service, in this many devices, which would be objectionable in more deliberate triangulation are used to expedite the work

Other Methods of Forming the Framework

As has been mentioned on p 2 the other methods of forming a framework of accurately fixed points on which the detail of the map is to depend are *Traverses Astronomical Determinations* or combinations of these methods with each other or with triangulation

Traverses are described in Chapter IV

Astronomical Determinations are dealt with in Chapters XIV, XV, and XVI

Note

The framework should always be trigonometrical where the circumstances permit The two chief hindrances to triangulation are the absence of hills or the existence of forest, and the most difficult country to triangulate is a flat forest clad region In such a region the expense of triangulation may render it necessary to execute a framework of traverses

Generally speaking, astronomical determinations are to be avoided a map of which the framework is entirely astronomical falls far short of the standard of a good topographical map In exploratory and geographical surveys however it may be necessary to make a free use of astronomical methods

CHAPTER II

BASES

If the angles of a triangulation are correctly observed any error in the measurement of the base will be reproduced in the triangulation Thus if the measurement makes the base 1 longer than it really is and the furthest point of a triangulation is really 500 miles distant from the base the triangulation will place that point at a distance of 501 miles or 1 mile too far

Bases are of various degrees of accuracy according to the class of triangulation which it is desired to fix them viz

(1) Base lines of Geodetic Triangulation with a probable error of — to
(2) Base lines for accurate Secondary work with a probable error of to —
(3) Base lines for Topographical work with a probable error of to
(4) Rough base lines

The measurement of a Geodetic Base line is a very special operation which occupies some weeks and costs much money There is a large literature on the subject which will not be further referred to in this book

Topographical Bases —The *length* of a topographical base will depend on the stretch of level or evenly sloping ground available Such bases have varied in length from ½ mile to 3 or 4 miles *It is important that the base should be connected directly with the triangles by a side or diagonal*

The base at Mandalay measured in 1886 for the Topographical Survey of Upper Burma was 1 mile long

The base for the Uganda Triangulation Survey in 1900 was 5300 feet

Base for Bermuda was 2890 feet

Base for Guernsey was 3163 feet

Base for the Sierra Leone Liberia Boundary was 3073 feet

Site for a Base The ideal site is a level even ground from which good views of the surrounding country can be obtained

Measurement of Base A topographical base should always be measured with a steel tape It should be carefully compared with a standard steel tape before and after using The error of the standard at a given temperature should be known It can be ascertained at home at the Ordnance Survey Office Southampton in India at the offices of the Survey of India in South Africa at the Cape Observatory

The standard tape itself should not be used

Steel tapes can be bought of the following lengths 100 300 or 400 feet or 50 or 100 metres

The line of the base should first be cleared of trees bushes or high grass, ant heaps and such small mounds should be removed

Each terminal point of the base should if time allows be marked by burying a marl stone 2 feet under ground, accurately centred over this should be built a small masonry pillar, surface flush with the ground A fine mark should be made in a metal plug sunk into the surface of the pillar

Having marked the terminal points of the base set a theodolite over one of them and direct it on the other end over which a pole should have been fixed with the aid of the theodolite align 4 or 5 poles at intervals of about 300 yards By means of this alignment

hammer into the ground square headed pickets accurately in the line of the base, and at tape lengths from each other, starting from one end of the base The tops of the pickets should be just flush with the ground, on these pickets nail strips of wood or zinc

In measuring the base, stretch the tape from terminal point to first picket, and from picket to picket, the tension should be taken on a spring balance and should be about 15 lb The end of the tape should be marked by a fine pencil line on the wood strip, or by a cut with a knife Take the temperature of the tape at frequent intervals by letting the bulb of the thermometer come in contact with the under side of the tape

At the other terminal the small space between the last graduation and the end of the base should be measured with a pair of dividers

Now measure the inclinations to horizontal from peg to peg with level or theodolite

If the section consists of one or two fairly uniform slopes it is sufficient to take the inclinations of these only noting where the changes of slope occur

Minor undulations crossed by the tape are to be disregarded

The base should be thus measured *at least once in each direction* on a dull day, if possible, or in early morning or late afternoon

Base Computations —The measured length of the base is subject to five corrections* —

i For *tape land*
ii , *temperature*,
iii , *inclination*,
iv , *sag*,
v , *height above sea*

The following case may be taken as an example —

One tape was kept as a reference tape and not used for measuring This when tested at Southampton, had been found to be 0 05 feet short at 62° F

The base tape (supposed to be 100 feet long) used was 0 02 feet long on reference tape at 71° F

The temperature of base tape during measurement was 82 1

Length as measured 5301 24 feet

Height of base line above sea 1,520 feet

For 2 300 feet, base had a slope of 1 15, rem under level

i *Standard* —

Reference tape was 0 05 short at 62 F

Now steel expands 0000625 of its length for 1 F

Therefore, at 71 it was $\frac{9 \times 100 \times 62\cdot5}{10\,000\,000}$ longer, or 0056 feet longer

Reference tape was therefore 0 0444 short at 71 F

Base , , 0 0200 long on reference tape at 71

, 0 0244 short at 71 (*a*)

ii *Temperature* —

Temperature of base tape during measurement was 82, when computed was 71

Incre e of length $\frac{11 \times 100 \times 62\cdot5}{10\,000,000}$, or 0 0069 (*b*)

Subtracting (*b*) from (*a*) we find that the base tape during measurement was 0 0175 short, correction for standard and temperature is therefore

$$-\ 0175 \times \frac{5301}{100} = -\ 0\cdot928 \text{ feet}$$

* There is a sag correction for relative extension which may be disregarded if the tape is always tested at the same tension

m *Inclination* —

For 2 300 feet the base had a slope of 1 in
Correction = − 2 300 (1 − cos 1 15) = − 0 550

n *Sag* —

In the measurement of a base it is desirable that the whole length of the tape should as far as possible be supported by the ground, so that no correction is necessary for the sag of the tape. Where the ground is uneven, it is customary to support the tape at intervals by pickets, but it may happen in the measurement of a base that a millrace or ravine has to be crossed. In such a case the sag, the difference between the length when suspended and the length when laid on a plane surface, must be determined and corrected for.

If s = the correction for sag
l = the length of the tape suspended between two supports (in feet)
w = the weight of the tape in lbs.
t = the tension applied in lbs.

$$s = l \frac{w}{24t} \text{ approximately}$$

See Appendix V.

Height above sea —

All measurements are supposed to be made at sea level. If the base is measured at a mean height h above sea level it will require a correction of $\frac{h}{R} \times$ length of base, where R the radius of the earth may be taken as 20 900 000 feet.

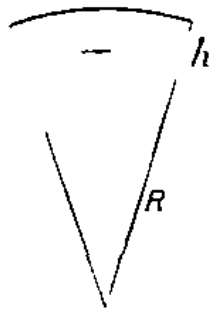


Fig. 3

In this case l = 1 520

Then correction $\frac{1,520 \times 5\ 301}{20\ 900\ 000}$ = 1 146

Collecting these corrections

	Feet
l and n Standard and temperature	0 928
m Inclination	0 550
n Sag	− 0 000
v Height above sea	− 1 146
Total correction	2 624
Measured length	5301 240
Reduced length of base	5298 62

It is clear that corrections m and n must always be negative, l and n may be either positive or negative.

hammer into the ground square headed pickets accurately in the line of the base and at tape lengths from each other, starting from one end of the base The tops of the pickets should be just flush with the ground, on these pickets nail strips of wood or zinc

In measuring the base stretch the tape from terminal point to first picket and from picket to picket, the tension should be taken on a spring balance and should be about 15 lb The end of the tape should be marked by a fine pencil line on the wood strip, or by a cut with a knife Take the temperature of the tape at frequent intervals by letting the bulb of the thermometer come in contact with the under side of the tape

At the other terminal, the small space between the last graduation and the end of the base should be measured with a pair of dividers

Now measure the inclinations to horizontal from peg to peg with level or theodolite

If the section consists of one or two fairly uniform slopes it is sufficient to take the inclinations of these only noting where the changes of slope occur

Minor undulations crossed by the tape are to be disregarded

The base should be thus measured *at least one and a half times* on a dull day, if possible or in early morning or late afternoon

Base Computations — The measured length of the base is subject to five corrections* —

i For *standard*
ii ,, *temperature*
iii ,, *inclination*
iv ,, *sag*,
v ,, *height above sea*

The following case may be taken as an example —

One tape was kept as a reference tape and not used for measuring This when tested at Southampton had been found to be 0 05 feet short at 62 F

The base tape (supposed to be 100 feet long) used was 0 02 feet long on reference tape at 71 F

The temperature of the tape during measurement was 82 F

Length as measured 5 301 24 feet

Height of base line above sea 4 520 feet

For 2 300 feet base had a slope of 1 15 rem under level

i *Standard* —

Reference tape was 0 05 short at 62 F

Now steel expands 0000006 25 of its length for 1 F

Therefore at 71 it was $\frac{9 \times 100 \times 6{\cdot}5}{10\,000\,000}$ longer or 0 06 feet longer

Reference tape was therefore 0 0444 short at 71 F

Base 0 0200 long on reference tape at 71

0 0244 short at 71 (*a*)

ii *Temperature* —

Temperature of base tape during measurement was 82 when compared was 71

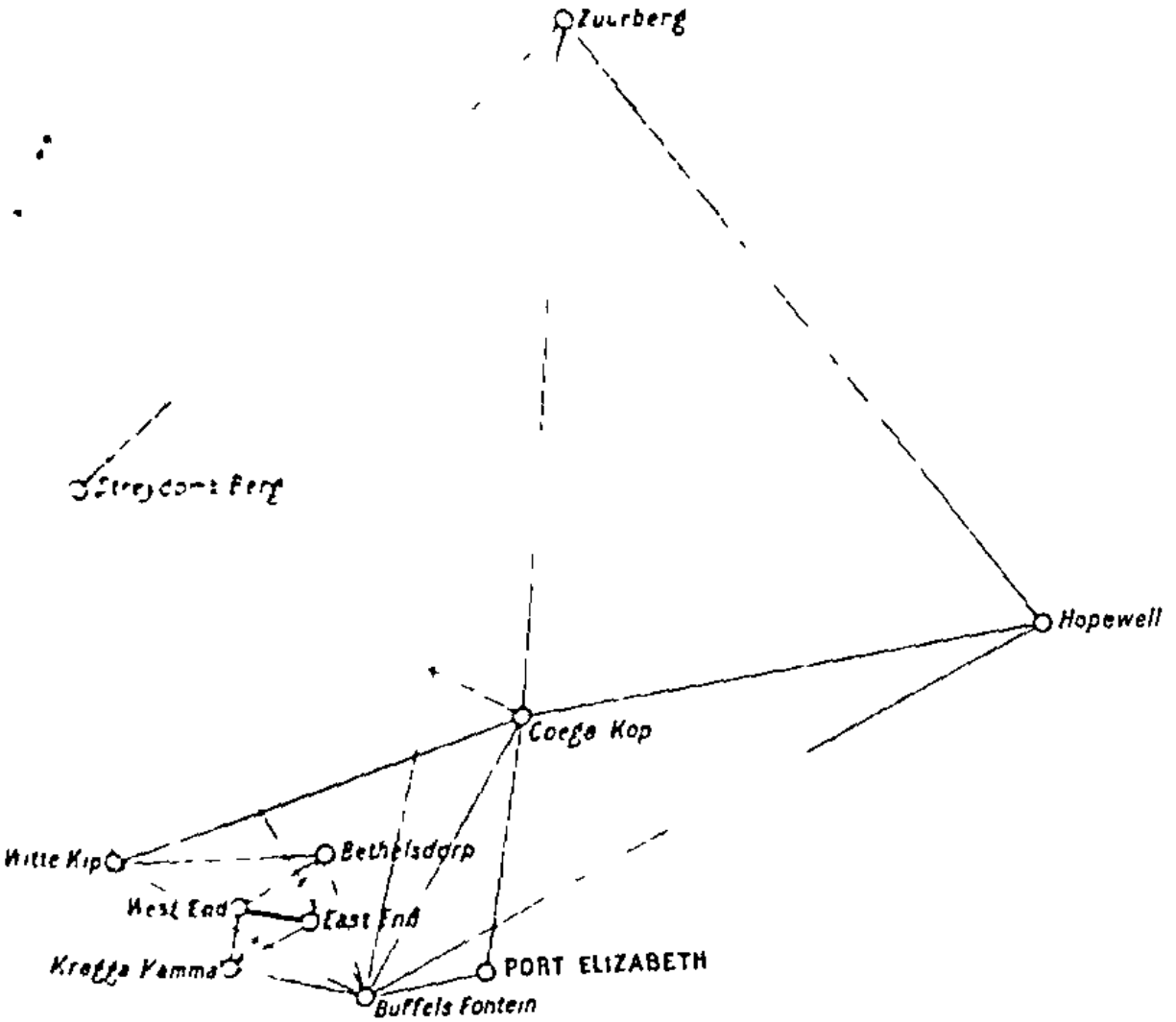
Increase of length $\frac{11 \times 100 \times 62{\cdot}5}{10\,000\,000}$ or 0 0069 (*b*)

Subtracting (*b*) from (*a*) we find that the base tape during measurement was 0 0175 short, correction for standard and temperature is therefore

$$-\ 017{\cdot}5 \times \frac{5301}{100} = -\ 0{\cdot}9\,28 \text{ feet}$$

* There is a small correction for *elastic extension* which may be disregarded if the tape is always stretched to the same tension

PORT ELIZABETH BASE EXTENSION



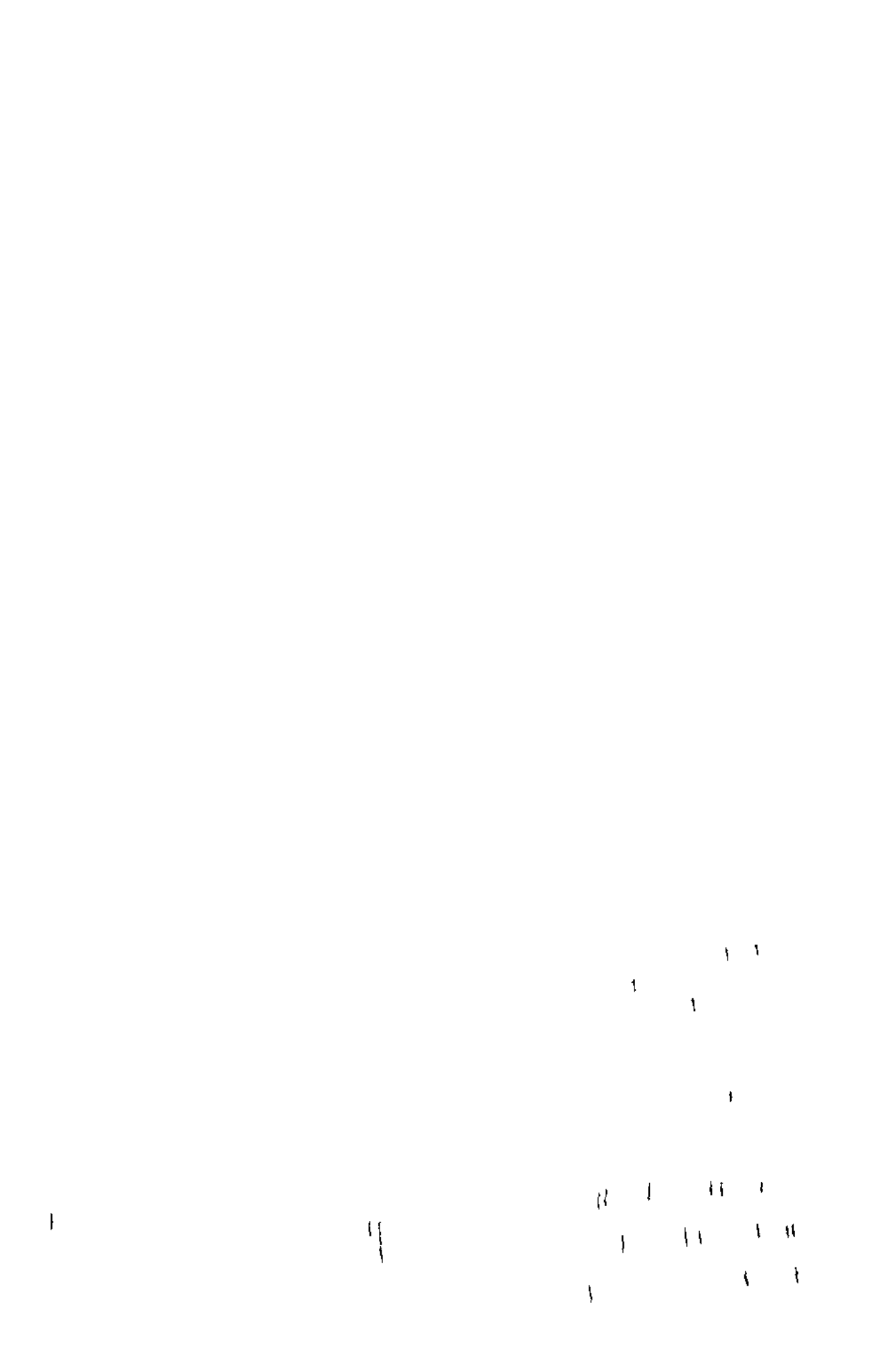
Scale 11 7 Miles – 1 Inch

expansion of any metal or alloy, *i.e.* $\frac{1}{11}$ that of platinum or $\frac{1}{2}$ that of brass (Less than $\frac{1}{1,000,000}$ for 1° Centigrade)

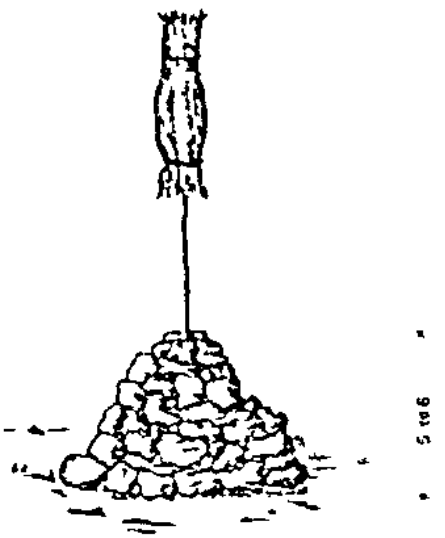
Tapes of this metal are now available, 25 metres long, or of special lengths if required

The agent for the sale of Invar in England is Mr T H A Baugh, 92, Hatton Garden, London The metal requires special treatment in manufacture and is liable to slow residual variations of length, it is therefore necessary that tapes used for the measurement of accurate bases should be tested by exact standards before and after measurement

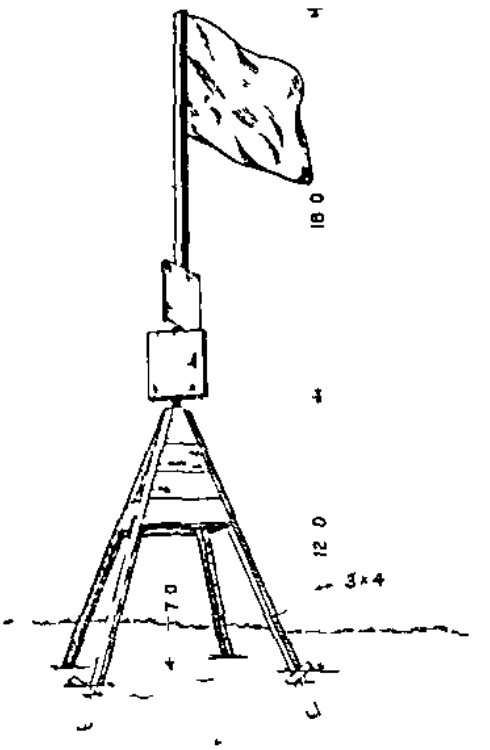
The use of Invar for the measurement of good topographical bases renders negligible the errors caused by uncertainty of tape temperatures



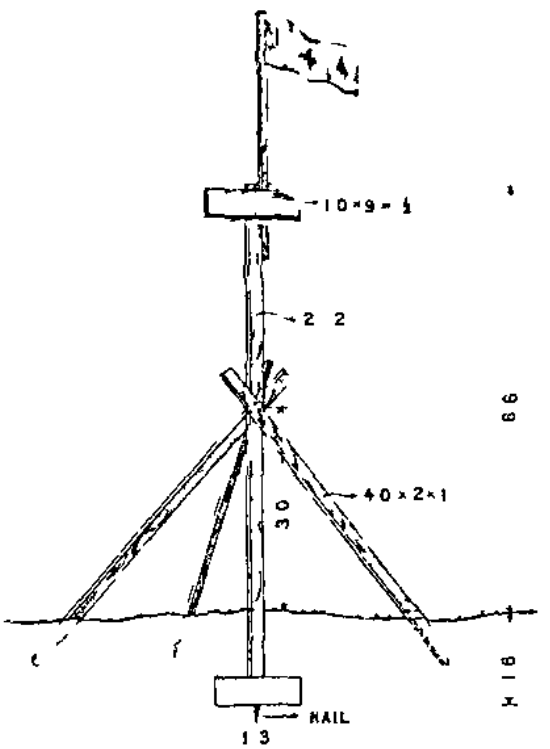
TRIGONOMETRICAL SIGNALS FOR SHORT DISTANCES



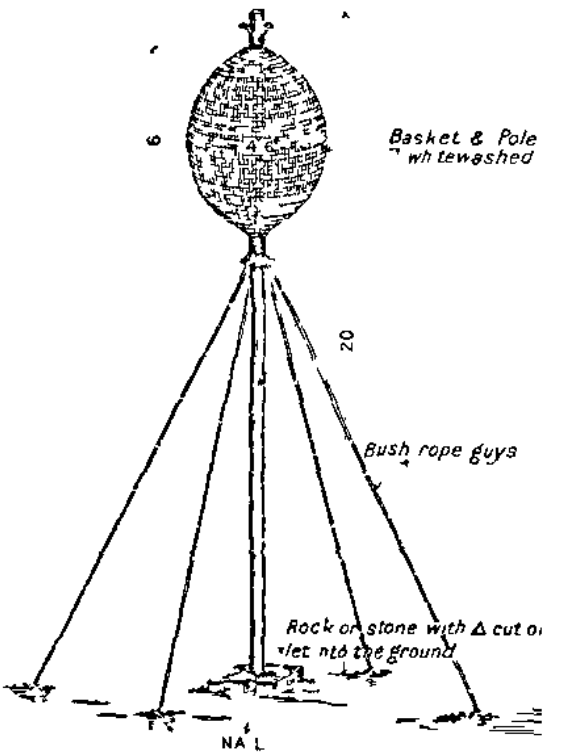
INDIAN POLE AND BRUSH SIGNAL



QUADRIPOD SIGNAL



TRIGONOMETRICAL POLE



W T AFRICAN BASKET SIGNAL

should be some 4 or 5 inches apart on paper Thus for triangulation for a 1 inch map the sides would be 4 or 5 miles long for a ½ inch map some 16 to 20 miles long But so much will depend on the nature of the country that this rule must only be treated as a rough guide

Chain or Net—When the extension of the base is completed in a large country, such as India or South Africa, the geodetic triangulation is carried out in the form of chains of triangles running for preference N and S, and E and W thus —

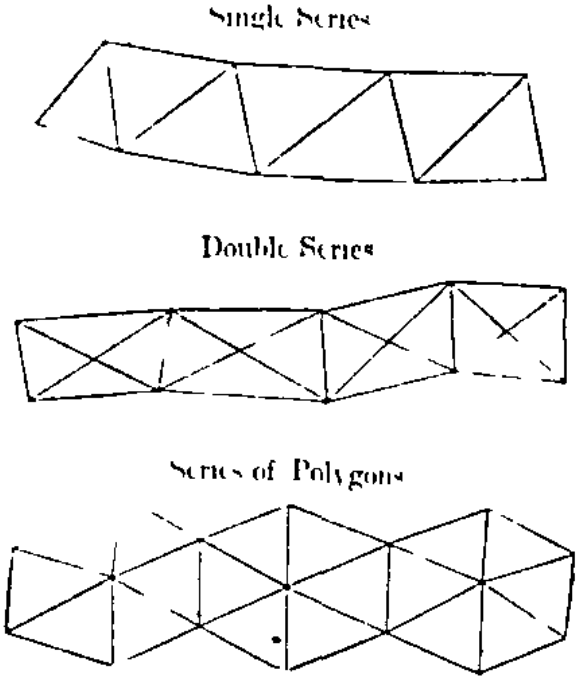


Fig 4

Secondary chains are run to fill up the spaces between the principal chains

In small countries such as the United Kingdom, the country is covered with a network of principal triangles

Triangulation executed rapidly during a march or along a frontier during a boundary survey will usually take the form of a chain, but of course less symmetrical and less well conditioned than a principal or secondary chain

A topographical triangulation which is essentially required to provide points for the detail surveyors will necessarily cover with a net the whole country to be surveyed

Intersected Points—In tertiary, topographical and rapid triangulation, angles are often observed to objects which are not visited, such objects are called intersected points, and should always be fixed by at least three rays the extension of the triangulation should not except in the case of rapid triangulation, depend on these points, which are, however, very often most useful to the detail surveyors such objects will be spires tall chimneys isolated or inaccessible rocks or trees

The Theodolite—The angles of a triangulation are invariably observed with a theodolite, which is an instrument devised for the measurement of horizontal and vertical angles

Theodolites are designated by the diameter in inches of their engraved horizontal circles In times past in geodetic triangulation theodolites have been used with circles as much as 36 inches in diameter, but improvements in graduation of the circles have made it possible to obtain even better results with far smaller instruments In Burma, for instance, the geodetic triangulation was executed with a 12 inch, and in South Africa with a 10 inch theodolite

For ordinary topographical work it may be assumed that the triangulation will be carried out with one of the following instruments —

(1) 5 inch micrometer transit theodolite
(2) 6 inch vernier " "
(3) 5 inch " " "

A transit theodolite is one in which the telescope can be rotated vertically end for end and in which the vertical circle is graduated throughout its circumference

Verniers and micrometers are different means of reading graduated circles

Verniers —

Principle of the Vernier —If the length of six, three divisions of a primary scale be taken and divided into four (fig 5) it is evident that the length of each of the latter is $\frac{1}{4}$ that of a primary division and that the difference between the length of one of the four divisions and

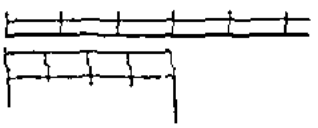


Fig 5

the length of a primary division is $\frac{1}{4}$ of a primary division and generally if $(n-1)$ primary divisions be divided into n divisions to form a vernier, then the difference in length between a primary and a vernier division is $\frac{1}{n}$th of a primary division

The same result obtains if we take six, five divisions of a primary scale and divide it into four for a vernier (fig 6) each of the vernier divisions is then $\frac{1}{4}$ of a primary division,

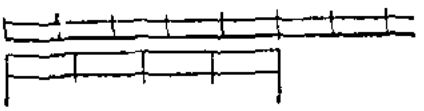


Fig 6

and the difference between their lengths is as before, $\frac{1}{4}$ of a primary division and generally if $n+1$ primary divisions be divided into n vernier divisions the difference between the length of a primary and a vernier division is $\frac{1}{n}$th of a primary division

For the application of this principle see fig 7 below which represents a portion of the graduated arc of a theodolite

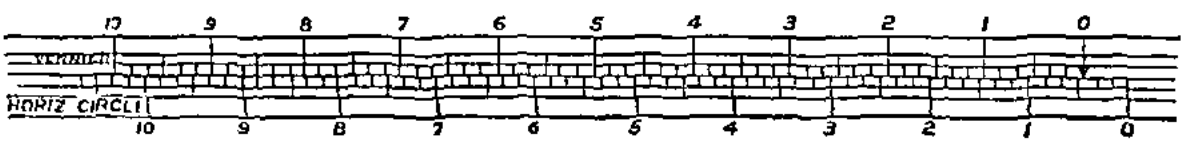
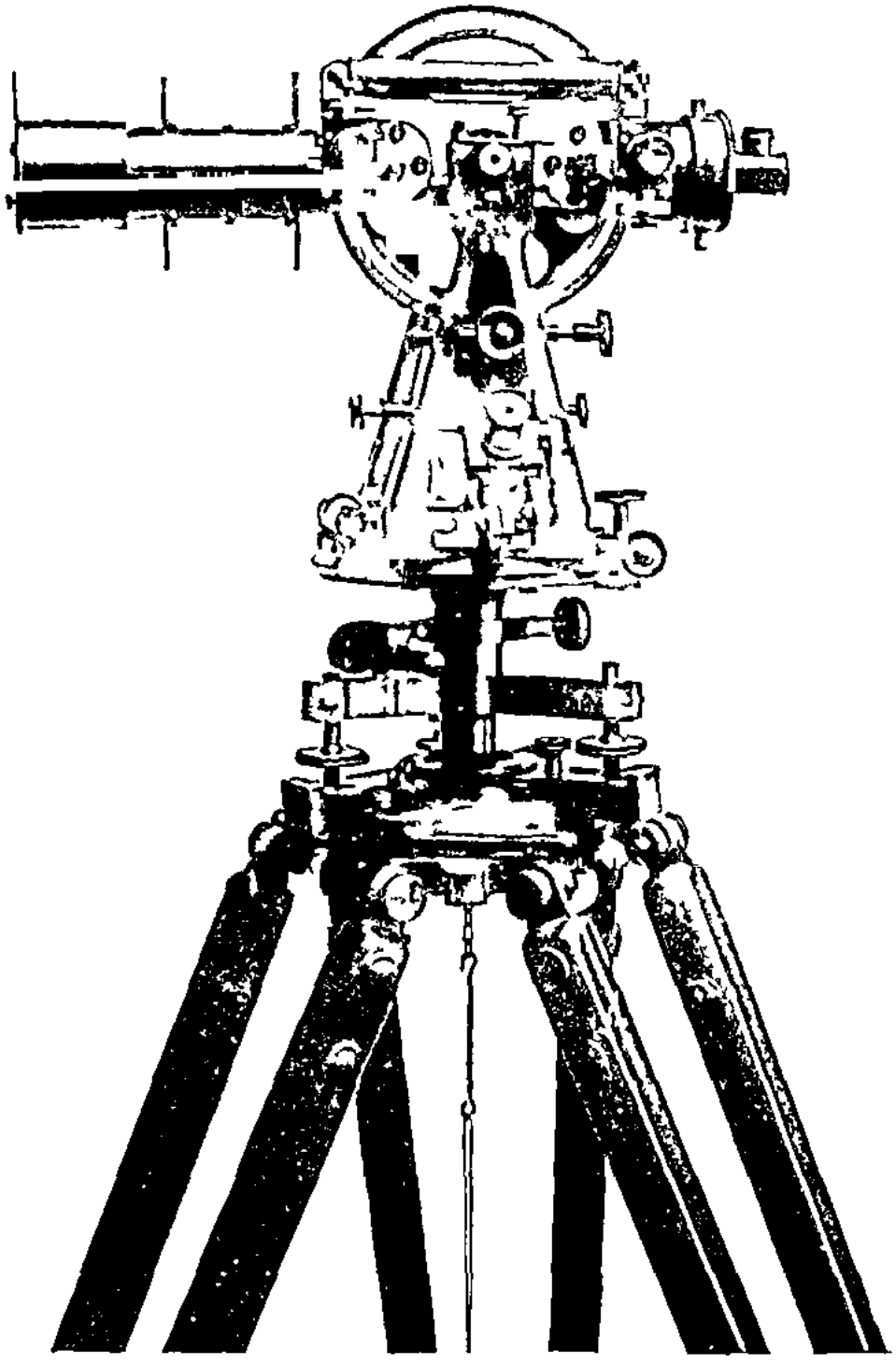


Fig 7

In this example the lower set of numbers represents degrees, these in turn are divided into six divisions each representing 10 minutes

The upper set of figures represents minutes, these are also divided into six divisions each being equal to 10 seconds To read the present example it will *be seen that the arrow of the* vernier plate comes between the second and third divisions of the lower plate, which indicates the reading to be between 20 and 30

PLATE III



3 Micrometer Transit Theodolite

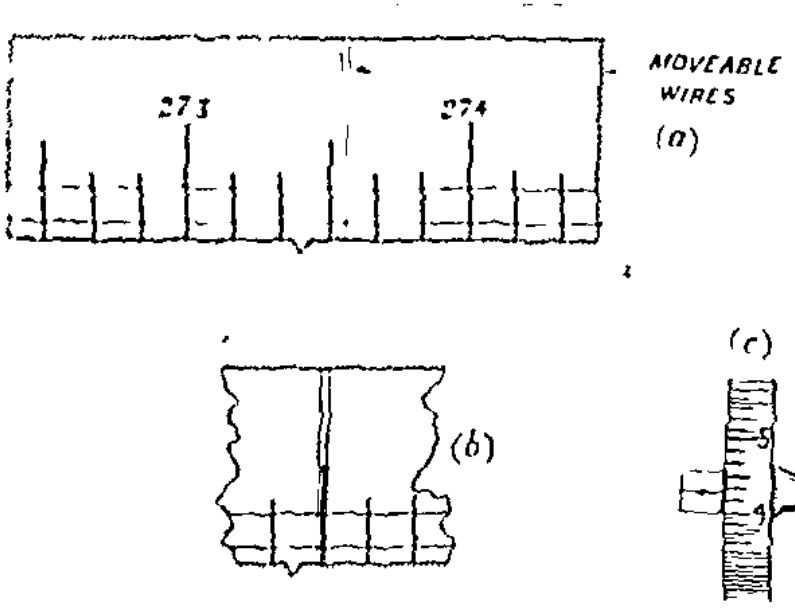


Fig. 8

lines are the divisions of the limb, the numbers are degrees, and the limb in this example is divided into 10 minute spaces. At the *bottom* of the field will be seen a V shaped notch in the frame of the diaphragm. *It is the position* of this notch which it is required to measure.

It will be at once seen that the notch is somewhere between 273° 20′ and 273° 30′. Two fine vertical lines will be noticed; these can be moved laterally by turning the graduated micrometer head, of which a separate sketch is shown in fig. 8 (c). These should be moved laterally until they occupy a position one on each side of a graduation on the limb, as in (b), and the graduation selected should be that which is nearest to the notch, it is *unimportant* which side. The minutes and seconds can now be read off the graduated head of *the micrometer* (c); in this example the graduated head reads 4 + between 10 and 20, by estimation 4′ 17″. The complete reading is therefore 273° 24′ 17″.

Taking Runs —It is part of the principle of this apparatus that a lateral movement of the parallel wires from one division of the limb to the next should be accomplished in a complete revolution of the micrometer head This should be tested occasionally before beginning work, the test is called "taking runs If the mean of two or three runs does not differ from the proper amount by more than 2 or 3 seconds, the error for topographical work may be neglected Should there be a large error, it means that the microscope is not properly adjusted

Adjustment for "Run"—The adjustment will be described as applied to a 5 Micro microscope theodolite by Messrs Troughton & Simms (See Plate III)

Take runs four times each on each microscope Determine the error of the mean of the two microscopes, and correct this by altering one microscope twice the amount Thus supposing that the mean of two microscopes, instead of reading 10 in traversing the wires from one division of the limb to the next, reads 10 5 , correct one of the microscopes so that it shall read 10 less than it did in a run *i e* the image of the limb in the field of the micro cope must be diminished in size

Now if it is wished to increase or diminish the power of the microscope it will be necessary to increase or decrease the distance between the object glass and the wires

The microscope has at the end a screw in the body, *b*, a clamping ring embracing the

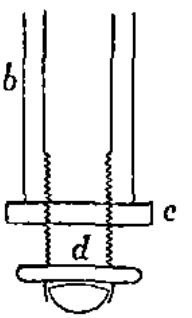


Fig 9

object glass cell *c* and a cell *d* carrying the object-glass the cell having a long screw cut on it for the purpose of adjustment

First release the ring *c* then move *d* towards the limb if it is desired to increase the readings then take care to make fast again

A little adjustment for focus will be necessary after every alteration, this is done by releasing the screw in the aluminium socket and sliding the whole microscope towards or from the graduations as may be necessary

In practice it is found that the microscopes very rarely need adjustment Instruments of this class have recently been much used on boundary commissions and even on active service Their advantages over vernier instruments are, that they are more accurate and more quickly read no one accustomed to micrometers would willingly go back to verniers

Examination of Theodolite—On receiving a theodolite examine it to see if it is in good order

Inspect the stand and see that there is no shrinkage in any part of it When the feet are all shod with metal it sometimes happens that shrinkage of the wood allows a little play in one of the feet which is quite enough to vitiate the observations

The theodolite box should be opened, the positions of the object and eye ends of the telescope marked on the box, and the places of the tangent screws of the upper and lower plates carefully noted

Setting up at a Station—Supposing now, that the observer has reached the station of observation with his instrument* The first thing to do is to place the stand with its legs wide apart, so as to give a firm base, and with its centre exactly over the station dot its head being as nearly level as the eye can judge Dust the grooves of the tribrach, and having taken out the lower portion of the theodolite remembering always to hold it by the strongest parts—place it gently on the stand and clamp it to the tribrach

It is well at this stage to level the upper plate approximately, as it is quite possible that it may be necessary to alter the position of the legs in order to avoid bringing undue strain on the foot screws If the legs are moved care must be taken to keep the instrument centred over the station dot

Having centred and approximately levelled the lower portion of the theodolite, open the clamps and dust the V supports of the transit axis of the telescope Take out the telescope wipe the transit axis and lower it gently into the Vs close the clamps and screw them down Take the cap off the object glass and focus the telescope Dust with a soft camels hair brush the horizontal and vertical circles Set the vernier or microscope lenses Make quite sure that there is no shake in any part of the theodolite or stand and that the feet of the latter rest upon firm ground into which there is no fear of their sinking during the observations In loose or marshy soil hammer in pickets on which the feet of the theodolite may rest

See that the tangent screws are in about the centre of their run

The Adjustments of the Theodolite

Adjustments of the Telescope, Focus and Parallax To focus the telescope first remove the cap from the object glass If this moves on a hinge no remark is necessary, but if it pulls off care must be taken to draw it with a screwing up motion to avoid any change of the object glass being partially unscrewed

The telescope should now be pointed to the sky and the eye piece pushed in or pulled out also with a screwing up motion until the wires are seen with perfect distinctness

The telescope is now directed on to some distant and well defined object and the object glass moved in or out until distinct vision is obtained When this has been done the foci of the object glass and the eye piece should coincide on the plane of the wires

To test the focus, move the eye slightly to one side and note if the object appears to move relatively to the wires If it does not move the focus is perfect but if there is movement, it is due to imperfect focus on *parallax*, which must be eliminated before observing is commenced To effect this note whether the object moves with the eye or against it—*i.e.* if when the eye is moved to the left the object moves to the left or to the right of the wires If the former, it shows that the focus of the object glass is beyond the wires and the object glass must therefore be brought nearer to the observer If the latter the focus is too near, and the object glass must be moved further out

From what has been said above, it will be seen that the proper position of the eye piece varies with the eyesight of the individual observer, but not with the distance of the object while the position of the object glass is unaffected by the eyesight of the observer but varies with the distance of the object

The object glass, however will be set at the same position called *the focus*, for all objects so far distant that the rays falling on it from them may be taken as practically parallel to one another

In the case of a theodolite of the class described this applies to all objects not less than half a mile from the observer but for nearer objects at any distance over 250 yards the change required is very slight

* For very accurate work with large instruments isolated pillars are built In this case it is assumed that the legs of the stand rest upon the natural soil or rock

Taking Runs —It is part of the principle of this apparatus that a lateral movement of the parallel wires from one division of the limb to the next should be accomplished in a complete revolution of the micrometer head This should be tested occasionally before beginning work, the test is called taking runs If the mean of two or three runs does not differ from the proper amount by more than 2 or 3 seconds, the error, for topographical work may be neglected Should there be a large error it means that the microscope is not properly adjusted

Adjustment for "Run"—The adjustment will be described as applied to a 5 Micro microscope theodolite by Messrs Troughton & Simms (See Plate III)

Take runs four times each on each microscope Determine the error of the mean of the two microscopes, and correct this by altering one microscope twice the amount Thus supposing that the mean of two microscopes, instead of reading 10 in traversing the wires from one division of the limb to the next reads 10 5 , correct one of the microscopes so that it shall read 10 less than it did in a run ie the image of the limb in the field of the microscope must be diminished in size

Now if it is wished to increase or diminish the power of the microscope, it will be necessary to increase or decrease the distance between the object glass and the wires

The microscope has at the end a screw in the body, *b* a clamping ring embracing the

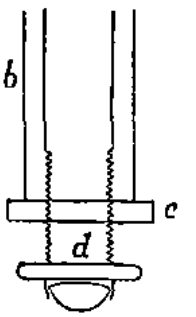


Fig 9

object glass cell and a cell *d* carrying the object glass the cell having a long screw cut on it for the purpose of adjustment

First release the ring *c* then move *d* towards the limb if it is desired to increase the reading then take care to make fast again

A little adjustment for focus will be necessary after every alteration, this is done by releasing the screw in the aluminium socket and sliding the whole microscope towards or from the graduations as may be necessary

In practice it is found that the microscopes very rarely need adjustment Instruments of this class have recently been much used on boundary commissions and even on active service Their advantages over vernier instruments are, that they are more accurate and more quickly read no one accustomed to micrometers would willingly go back to verniers

Examination of Theodolite—On receiving a theodolite, examine it to see if it is in good order

Inspect the stand and see that there is no shakiness in any part of it When the feet are shod with metal it sometimes happens that shrinkage of the wood allows a little play in one of the feet which is quite enough to vitiate the observations

The theodolite box should be opened the positions of the object and eye ends of the telescope marked on the box, and the places of the tangent screws of the upper and lower plates carefully noted

Setting up at a Station—Supposing now that the observer has reached the station of observation with his instrument* The first thing to do is to place the stand with its legs wide apart, more to give a firm base and with its centre exactly over the station dot its head being as nearly level as the eye can judge Dust the grooves of the tribrach, and having taken out the lower portion of the theodolite remembering always to hold it by the strongest parts—place it gently on the stand and clamp it to the tribrach

It is well at this stage to level the upper plate approximately, as it is quite possible that it may be necessary to alter the position of the legs in order to avoid bringing undue strain on the foot screws If the legs are moved care must be taken to keep the instrument centred over the station dot

Having centred and approximately levelled the lower portion of the theodolite, open the clamps and dust the V supports of the transit axis of the telescope Take out the telescope wipe the transit axis and lower it gently into the Vs close the clamps and screw them down Take the cap off the object glass and focus the telescope Dust with a soft camel's hair brush the horizontal and vertical circles Set the vernier or microscope lenses Make quite sure that there is no shake in any part of the theodolite or stand and that the feet of the latter rest upon firm ground but which there is no fear of their sinking during the observations In loose or marshy soil hammer in pickets on which the feet of the theodolite may rest

See that the tangent screws work about the centre of their runs

THE ADJUSTMENTS OF THE THEODOLITE

Adjustments of the Telescope, Focus and Parallax To focus the telescope first remove the cap from the object glass If this moves on a hinge no remark is necessary, but if it pulls off care must be taken to draw it with a screwing up motion to avoid any chance of the object glass being partially unscrewed

The telescope should now be pointed to the sky and the eye piece pushed in or pulled out also with a screwing up motion until the wires are seen with perfect distinctness

The telescope is now directed on to some distant and well defined object and the object glass moved in or out until distinct vision is obtained When this has been done the foci of the object glass and the eye piece should coincide on the plane of the wires

To test the focus move the eye slightly to one side and note if the object appears to move relatively to the wires If it does not move the focus is perfect but if there is movement it is due to imperfect focus or *parallax* which must be eliminated before observing is commenced To effect this note whether the object moves with the eye or against it—*i.e.* if when the eye is moved to the left the object moves to the left or to the right of the wires If the former, it shows that the focus of the object glass is beyond the wires and the object glass must therefore be brought nearer to the observer If the latter the focus is too near, and the object glass must be moved further out

From what has been said above, it will be seen that the proper position of the eye piece varies with the eyesight of the individual observer but not with the distance of the object, while the position of the object glass is unaffected by the eyesight of the observer, but varies with the distance of the object

The object glass, however will be set at the same position, called *telluric or solar focus*, for all objects so far distant that the rays falling on it from them may be taken as practically parallel to one another

In the case of a theodolite of the class described, this applies to all objects not less than half a mile from the observer, but for nearer objects at any distance over 250 yards the change required is very slight

* For very accurate work with large instruments isolated pillars are built In this case it is assumed that the legs of the stand rest upon the natural soil or rock

When the proper adjustment of the eye-piece and of the object glass for the solar focus have been found it is convenient to mark the tubes, so that on subsequent occasions focus may be found at once

Adjustment for Collimation in Azimuth—A theodolite is said to be collimated in azimuth when the *line of collimation*, *cc*, the imaginary straight line joining the intersection of the wires and the optical centre of the object glass cuts the transit axis or axis of *vertical* motion at right angles

In fig 10 let tt_1 denote the transit axis, then when the line of collimation, which for shortness call *c* coincides with the perpendicular to tt_1, or the line pp_1, the instrument is in collimation and if the telescope be made to describe a semicircle in its Y's, its line of collimation produced will pass through the zenith, describing a great circle But if *c* be represented by *cz*, then the semicircle traced out will be represented by cz_1 the false zenith being z_1 while the arc described will be that of a small circle In other words, by changing face, the object end of *c*, will arrive at c_1, while the wires, *z*, will describe a similar small circle and reach z_1 Whence if any object on the horizon give a horizontal reading at face left of *z* and then the pivots of the instrument be changed and the telescope be turned sufficiently in azimuth to intersect the object the two readings thus obtained will instead of exactly coinciding, disagree by cc_1

The error in collimation will, therefore, be $\frac{cc_1}{2} = cz$ *

Description of the Diaphragm—Before entering into the methods of collimating, a short description of the diaphragm is necessary

The wires the arrangement of which varies in different theodolites, are attached to a metal ring or diaphragm, whose position in the tube of the telescope can be regulated by

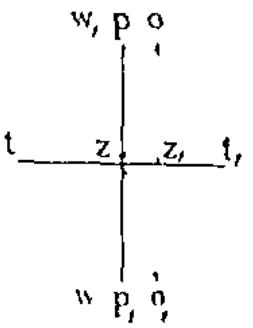


Fig 10

means of four capstan headed screws, *a*, *b*, *c*, *d* (see fig 11), which pass loosely through slots, S, in the tube so as to allow the diaphragm to be moved as required Each of these slots is covered by a small plate to exclude dirt

If it is necessary to move the diaphragm towards *b*, loosen the screw *a* and slacken the screws *c* and *d* then by screwing *b* into the tube, the diaphragm is drawn in its direction When it has been moved sufficiently, tighten up the three screws *a*, *c*, *d*

If an ordinary eye piece is used with the usual inverting telescope with the result that the image is seen upside down, it must be remembered that, if the object that has to be intersected appears to the left of the wire the wire must be shifted to the left and the diaphragm moved accordingly

* The object is said to be face left or face right when the vertical circle is on the observer's left or right face is changed by turning the telescope through 180 degrees vertically so as to bring the object glass where the eye piece was before If now the instrument is turned in azimuth so as to bring the eye piece to the observer's eye the vertical circle will be found to be on the opposite side to that occupied previously with reference to the observer

Methods of Collimating in Azimuth — There are three methods of collimating in azimuth

(1) By changing pivots This process would be used for all small theodolites the telescope of which cannot revolve through a complete vertical circle

(2) By changing face This is applicable to those theodolites only whose telescope can revolve through a complete vertical circle (*i.e.* transit theodolites)

(3) By Gauss's method This is applicable to all theodolites but as it requires two other telescopes fitted with cross wires it is comparatively seldom available and will, therefore not be treated of further

(a) By changing pivots Throw open the clasps and see that the clip screws of the index arm are barely biting their shoulder and no more Intersect the object azimuthally, and note the reading, taking care that the clamps are holding firmly Next, release the clip screws raise the telescope gently and revolve the transit axis through 180 degrees, so that the level comes underneath, leaving the index arm and clip screws upwards Replace the telescope gently with the pivots changed and with the object glass still pointing towards the object If the wires in this second position of the telescope still intersect the object, the instrument is in collimation if not complete the intersection by the tangent screw of the upper plate and note the second reading Set the instrument to the mean of the two readings, and then, looking into the telescope move the diaphragm by its collimating screws *a b c d*, fig 11, until the

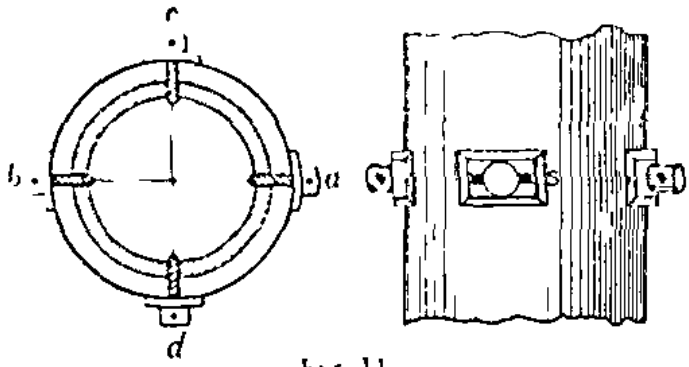


Fig 11

wires again intersect the object Repeat the process until the intersection remains constant on changing pivots remembering that half the apparent is the real error *

(b) By changing face —Intersect and note the reading of any fixed object change face intersect and read again The two readings should differ by exactly 180 degrees If they do not the error is corrected as above

In collimating by changing face any errors that may exist in the graduation of the limb are involved in the process

In collimating an instrument it is desirable that the object selected for intersection should be at such a distance that the object glass be set to the focus which will be employed during the subsequent observations, as the line of collimation is liable to be distorted when the focus is altered

To make the Vertical and Horizontal Wires respectively Vertical and Horizontal — As the correct positions for these wires are cut on the diaphragm by the maker so that the lines cut each other at right angles it follows that to adjust one wire is to adjust both, and this may be done by the following method —

Level the instrument with care, intersect any small well defined object with the vertical wire, and see if it continues bisected along the wire when the telescope is moved in a vertical plane If this is not the case, the collimating screws must be slackened sufficiently to allow the diaphragm to be revolved until this condition is secured when they must be again

* The same result can be obtained by estimating half the error as it appears in the telescope and dispensing with the readings

tightened It will now be found that the horizontal wire, if properly placed by the maker, will continue to bisect an object on which it has been placed when the instrument is turned in azimuth

Levelling the Theodolite—This consists in making the vertical axis truly perpendicular to the horizon

Place the longer of the levels a, of the horizontal plate parallel to any two foot screws, c, c and by suitably turning these latter bring the bubble into the centre of its tube In doing this the observer must remember always to turn the foot screws in opposite directions, that is to say to work both hands either towards or away from himself Then turn the upper plate 180 degrees in azimuth Supposing the bubble to occupy a different place from what it did before, move it by means of the same two foot screws into the mean of these two places, and it is evident that if the upper plate be turned another 180 degrees until it occupies its original position, the bubble will continue to occupy that mean place, called the *zero of the level* Now turn the upper plate 90 degrees in azimuth, and by means only of the third and hitherto unused foot screws bring the bubble into its mean place

The instrument is now approximately level, and the above described process must be continued until the level remains steady in whatever direction the telescope may be pointed The mean place is not necessarily in the centre of the tube, but if the deviation is considerable the bubble can be brought into the centre by means of the two drawing screws which secure the level to the horizontal plate The length of the bubble varies inversely as the temperature and consequently the positions of the ends of the bubble alter with a change of temperature It is convenient to have one end of the level marked and to watch that end only while levelling

The levelling is now as perfect as it can be made by the body level As the level attached to the microscope arms is usually more delicate the final levelling can be completed with this by bringing the bubble approximately into the centre of its run by the clip screws, and then proceeding exactly as above described

Level on Microscope Arms—If the level is on the vernier or microscope arms, it is necessary to have it well adjusted

To do this level the instrument bring the bubble into the centre by means of the clip screws // intersect the object and note the reading change face and set the bubble by the clips as before and intersect again The mean of the two readings will be the true elevation Set the vertical circle to this reading and intersect the object by the clip screws and, keeping the instrument clamped bring the bubble of the level into the centre by means of its drawing screws It is clear that where the error is small the discrepancy between the two faces may be eliminated in a similar way to that used for collimation in azimuth But the method just described is better

When a level is carried on the vernier arms of the vertical limb it is desirable to know the value of the level scale for the purpose of correcting the observed vertical angles See p 19

To Level the Transit Axis Level the upper plate Place the striding level on the pivots and by tapping it gently sideways bring the bubble of the cross level into the centre of its run

When the bubble of the striding level is steady, read and register the number of the level scale at which one end of it stands say the end nearer to the cross level

Now reverse the level end for end, cross level read and register the same end of the bubble as before If the transit axis is level the same end of the bubble will read the same on both occasions If it does not read the same, half the apparent is the real error, which can be corrected by the capstan headed screw, k, which raises or lowers the Y above it

Unless the error of collimation and the dislevelment of the transit axis are very large, it is better not to try to correct them, as their effect can be eliminated by a suitable method of observation

Determination of Value of One Division of Level Scale

The level is usually graduated, but, if not, make a paper scale of equal parts, reading outwards from the centre towards both ends, and paste it on to the side of the level, so that the centre of the scale corresponds with the centre of the run of the bubble, assuming that the level is on the vernier arms (as it is only in that position that it affords a means of correcting the vertical angles), by means of the clip screws move the bubble up to one end of its run, say towards the object end, so that the object end of the bubble corresponds approximately with the extreme reading of the scale. Intersect with the horizontal wire some convenient object for observing. Read and record one end of the bubble, say the object end, and the vertical angle. Now by means of the clip screws bring the bubble back towards the eye as far as you can, taking care that it is really floating and within the graduations of the scale. Intersect the same object as before, and record the vertical angle and the reading of the object end of the bubble in its new position. The difference between the two readings of the object end of the bubble gives the displacement in terms of divisions of the scale, and the difference between the two vertical angles gives the same displacement in minutes and seconds of arc. Dividing this angular measurement by the number of divisions of displacement you obtain the value in arc of one division of the scale.

Thus —

	Elevation			Object end of bubble
	°	′	″	
1st observation	7	3	28	18
2nd „	7	0	0	5
Difference	0	3	28	13

Value of one division $= \frac{208}{13} = 16$

This operation must be repeated several times in order to get a good mean value. The bubble of a level is very susceptible to changes of temperature so care must be taken that it is not exposed to such changes while this operation is being performed. Should there be any chance of the bubble altering its length while you are determining the value of the divisions of the scale, it will be necessary to read and record both ends of the bubble. In observing, as described previously for each vertical angle taken, the readings of both ends of the bubble must be recorded. *To apply the correction* the rule is as follows —

Divide the difference between the sums of the readings of the object end and eye end by the total number of readings and the result will be the displacement in terms of divisions of the scale. Multiply this result by the angular value of one division of the scale and you obtain the angular correction for displacement to be applied to the mean vertical angle. Supposing two observations are taken to a point one face left and one face right and the readings are as follows —

	O	I
1 L	5	8
F R	7	6
	12	14

tightened It will now be found that the horizontal wire if properly placed by the maker, will continue to bisect an object on which it has been placed when the instrument is turned in azimuth

Levelling the Theodolite—This consists in making the vertical axis truly perpendicular to the horizon

Place the longer of the levels, *a*, of the horizontal plate parallel to any two foot screws, *c*, *c*, and by suitably turning these latter bring the bubble into the centre of its tube In doing this the observer must remember always to turn the foot screws in opposite directions, that is to say, to work both hands either towards or away from himself Then turn the upper plate 180 degrees in azimuth Supposing the bubble to occupy a different place from what it did before, move it by means of the same two foot screws into the mean of these two places, and it is evident that if the upper plate be turned another 180 degrees until it occupies its original position, the bubble will continue to occupy that mean place, called the *zero of the level* Now turn the upper plate 90 degrees in azimuth, and by means only of the third and hitherto unused foot screws bring the bubble into its mean place

The instrument is now approximately level, and the above described process must be continued until the level remains steady in whatever direction the telescope may be pointed The mean place is not necessarily in the centre of the tube, but if the deviation is considerable the bubble can be brought into the centre by means of the two drawing screws which secure the level to the horizontal plate The length of the bubble varies inversely as the temperature and consequently the positions of the ends of the bubble alter with a change of temperature It is convenient to have one end of the level marked, and to watch that end only while levelling

The levelling is now as perfect as it can be made by the body level As the level attached to the microscope arms is usually more delicate, the final levelling can be completed with this by bringing the bubble approximately into the centre of its run by the clip screws, and then proceeding exactly as above described

Level on Microscope Arms—If the level is on the vernier or microscope arms, it is necessary to have it well adjusted

To do this level the instrument bring the bubble into the centre by means of the clip screws // intersect the object and note the reading change face and set the bubble by the clips as before and intersect again The mean of the two readings will be the true elevation Set the vertical circle to this reading and intersect the object by the clip screws and, keeping the instrument clamped bring the bubble of the level into the centre by means of its drawing screws It is clear that where the error is small the discrepancy between the two faces may be eliminated in a similar way to that used for collimation in azimuth But the method just described is better

When a level is carried on the vernier arms of the vertical limb it is desirable to know the value of the level scale, for the purpose of correcting the observed vertical angles See p 19

To Level the Transit Axis Level the upper plate Place the striding level on the pivots, and by tipping it gently sideways bring the bubble of the cross level into the centre of its run

When the bubble of the striding level is steady, read and register the number of the level scale at which one end of it stands say the end nearer to the cross level

Now reverse the level end for end, cross level read and register the same end of the bubble as before If the transit axis is level, the same end of the bubble will read the same on both occasions If it does not read the same, half the apparent is the real error, which can be corrected by the capstan headed screw, *k*, which raises or lowers the Y above it

Unless the error of collimation and the dislevelment of the transit axis are very large, it is better not to try to correct them as their effect can be eliminated by a suitable method of observation

Determination of Value of One Division of Level Scale

The level is usually graduated, but, if not, make a paper scale of [illegible] outwards from the centre towards both ends, and paste it on to the [illegible] the centre of the scale corresponds with the centre of the run of the bubble [illegible] level is on the vernier arms (as it is only in that position that it [illegible] the vertical angles), by means of the clip screws move the bubble [illegible] say towards the object end, so that the object end of the bubble [illegible] with the extreme reading of the scale. Intersect with the horizontal wire [illegible] object for observing. Read and record one end of the bubble, say the [illegible] vertical angle. Now by means of the clip screws, bring the bubble back towards [illegible] far as you can, taking care that it is really floating and within the graduated [illegible] Re-intersect the same object as before, and record the vertical angle and [illegible] object end of the bubble in its new position. The difference between the two [illegible] object end of the bubble gives the displacement in terms of divisions of the [illegible] difference between the two vertical angles gives the same displacement in minutes [illegible] of arc. Dividing this angular measurement by the number of divisions of [illegible] obtain the value in arc of one division of the scale.

Thus —

	Elevation			Object end of bubble
1st observation	7	3	28	18
2nd "	7	0	0	5
Difference	0	3	28	13

$$\text{Value of one division} = \frac{208}{13} = 16$$

This operation must be repeated several times in order to get a good mean value. The bubble of a level is very susceptible to changes of temperature, so care must be taken that it is not exposed to such changes while this operation is being performed. Should there be any chance of the bubble altering its length while you are determining the value of the divisions of the scale, it will be necessary to read and record both ends of the bubble. In observing, as described previously for each vertical angle taken, the readings of both ends of the bubble must be recorded. *To apply the correction* the rule is as follows —

Divide the difference between the sums of the readings of the object end and eye end by the total number of readings and the result will be the displacement in terms of divisions of the scale. Multiply this result by the angular value of one division of the scale, and you obtain the angular correction for displacement to be applied to the mean vertical angle. Supposing two observations are taken to a point one face left and one face right, and the readings are as follows —

	O	E
F L	5	8
F R	7	6
	12	14

In this case the sum of the readings of the eye ends exceeds that of the object end by 2 The number of readings of ends of the bubble is 4 So to get the dislevelment in terms of division of the scale we must divide 2 by $4 = \frac{1}{2}$ Suppose the value of one division of the level scale is 16 seconds, then to get the correction we must multiply $\frac{1}{2}$ by 16 seconds $= 8$ seconds The 8 seconds of arc must be applied to the mean of the two observed angles With regard to its sign, the eye end being in excess, the correction must be subtracted from an elevation and added to a depression If the object end were in excess, the process would of course, be reversed

Generally correction to altitude $= + \frac{O - E}{\text{number of readings}} \times$ value of 1 division

If the level graduations read from one end and not outwards from the centre, book the readings of the zero end as negative, and then apply the above rule

Method of Observing Horizontal Angles —Observations taken to elevated objects are subject to two great sources of error, viz , dislevelment of the transit axis and want of adjustment of the line of collimation These causes of error are generally large in small instruments, and although capable of rectification, adjustments do not long remain perfect, hence the system of observation should be such as to cancel these errors This is attained by changing face, i e , by observing the same angle with the vertical circle or face alternately to the left and to the right This system should be adopted in all theodolite observations, for it is as effectual as it is simple

The angles at a station are taken thus supposing the observer to be at B, and that it is required to observe the angles to the signals at C, D, E

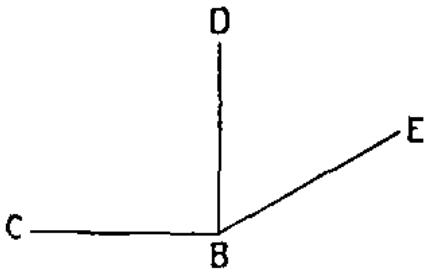


Fig 12

Clamp the upper plate to the lower having set A vernier or microscope to about 0° on the horizontal limb Loosen the lower clamp and turn the whole instrument till station C comes into the field of the telescope, now tighten the lower clamp, and intersect C with the lower tangent screw , see that the vernier still reads about 0 Now loosen the upper clamp and turn the upper plate and telescope completely round till C comes into the field of view, taking care not to overshoot it, clamp the upper plate and intersect

Read off both verniers or microscopes and enter in angle book The reading of A vernier should be identical with the setting If the difference is greater than can be accounted for by a slight difference in the intersection, there must be a defect in the instrument, which should be examined

Now loose the upper clamp, and turn the telescope on to D, clamp intersect with the upper tangent screw without overshooting Read the verniers or microscopes, and book the readings Repeat the same process with E, and so on, with a continuous movement from left to right this is termed "**swinging right**"

It is generally desirable to intersect the zero station again at the end of the swing, so as to detect any movement of the instrument which may have occurred If such has occurred, the observations must be taken again In some surveys the starting point is called the R O , or Referring Object , there is no necessity to use this term in topographical work

Suppose that during these observations the vertical circle had been to the right of the telescope, this set would be described as one round of angles, **face right** swing right, on zero 0° The **zero** or **arc** is the setting of the first station or signal read during a round of angles In the geodetic triangulation of Burma, for instance, the successive rounds of angles were taken on the following zeros 0° 0, 20° 1, 40° 2, 60 3, and so on, 9 zeros in all The object of changing zero is to minimize the effects of errors of graduation and to prevent any bias due to reading the same angle constantly on the same portion of the arc

The number of changes of face, of swings, and the number of zeros will depend on the class of the work

In geodetic triangulation the number of zeros will probably be at least 6, with 2 faces on each zero, 2 swings on each face

In secondary work probably 2 or 3 zeros each of 2 faces and 2 swings

In tertiary, 2 zeros, 2 faces, 1 swing on each face

In topographical work the numbers will naturally vary with the time available The following system is generally suitable —

Zero 0°, F R, swing R,
„ 0°, F L, „ L,
„ 35°, F L, „ L,
„ 35°, F R „ R

or 4 rounds of angles at each station

But if time does not allow of so many then

Zero 0°, F R, swing R,
„ 35°, F L „ L

The reason for taking 35 as the second zero is that, whether there are 2 or 3 microscopes or verniers, they will not fall on changing zero over the same part of the arc But any arbitrary change—not 60 nor 180 —will do

Method of Observing Vertical Angles —To observe vertical angles see that the instrument is perfectly *levelled* Direct the telescope on the object leaving the horizontal clamp free, clamp the vertical circle when the object comes into the field and intersect with the tangent screw It is generally convenient to intersect with a portion of the horizontal wire at one side of the intersection of the cross wires If this is done care must be taken to intersect with exactly the same spot on the wire when the telescope is reversed on changing face, remembering that if the spot appeared to be on the left of the centre F L it will be on the right when the object is observed F R

Read and record both the verniers, noting if the angle is in elevation or depression If there is a level on the vernier arms, enter the readings of both ends of the bubble under the headings of O or object end, and I or eye end

If the object was intersected from *above* the first time it should be intersected from *below* when a second observation is taken

Now change face and observe the object F R in exactly the same manner The mean of the F L and F R observations should give the true elevation or depression If however, there is a level on the vernier arms and the sum of the readings of the two ends do not exactly agree, a correction will have to be applied See p 20

The height above their station dots of the instrument and of the objects observed should be entered

A vertical angle is of very small value if it has not been observed on both faces

Generally, when taking *horizontal* angles leave the vertical arc unclamped, and when taking vertical angles leave the horizontal arc unclamped This implies that the horizontal and vertical angles should not be taken simultaneously, and that the object should not be

observed on intersection of the cross wires but separately on vertical and horizontal wires If time presses, however, this restriction may be ignored, and vertical and horizontal angles may be taken together

General Remarks on Observations—It is a general rule of all regular surveys that all the observations should be entered in ink before the observer leaves his station A description of each station should also be entered in the angle book, in order to enable any other observer or the detail surveyor to recognise it without difficulty

This description should contain not only such information as would enable anyone to identify both the general locality and the exact spot used as a station but should also state the most convenient camping ground in the neighbourhood, and the best direction from which to ascend the hill in the case of a hill station The nature of the mark left should also be given and its height above the station dot

Satellite Stations—It sometimes happens that angles are required from some point such as a tree steeple temple, or pagoda where it is impossible to erect the theodolite This case never occurs in geodetic or good secondary triangulation, but it is not very uncommon in rapid work where the stations have not been laid out beforehand, and the observer is dependent on natural objects for his marks In such cases the theodolite is set up at the nearest convenient point called a *dellite tation*, at a short distance from the object, and

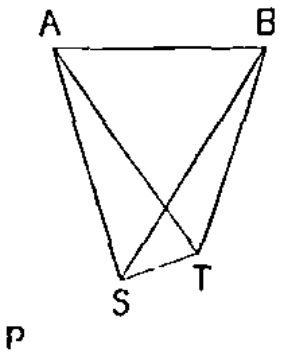


Fig 13

the angles taken from this station can afterwards be reduced to the true values at the object itself

Supposing now that the triangulator has observed the trunk of a tree on the summit of a hill and that on his arrival he finds that it is impossible for him to observe with his theodolite nearer to the tree than several feet, he would put up his theodolite in the most convenient place as near to the tree as possible and observe his round of angles as usual, taking care to include the centre of the trunk of the tree He must also measure accurately the distance from his station to the trunk of the tree He can now correct his angles in either of two ways —

(1) If a number of angles have been taken from the station and only two or three have been taken to the tree, and if it is possible to raise upon the station a mark sufficiently conspicuous to be visible from future stations, it is preferable to correct the two or three angles already taken to the tree

(2) If on the other hand only a few angles have been taken at the station, and if it is impossible to erect on it as useful a mark as the tree, then it is advisable to reduce the angles taken at the station to what they would have been had they been taken on the spot occupied by the tree This is called reduction to the centre

Let AB be two stations from which the tree, T, has been observed, and let S be the station or spot where the theodolite was put up

(1) In the first case the angles SAB and ABS are required, the angles TAB and A being known Evidently SAB = TAB + SAT and sin SAT = sin TSA $\frac{ST}{AT}$ AT can computed approximately or measured with sufficient accuracy from the working chart of triangulation

(2) In the second case, which is the usual one, ATB is required Produce TS to P

Then $$BSP = BTS + SBT$$

$$ASP = ATS + SAT$$

Subtracting (2) from (1)

$$ASB - ATB + SBT - SAT, \text{ whence } ATB = ASB + SAT - SBT$$

Now sin SAT = sin TSA $\frac{ST}{AT}$, AT being found in any approximate way, such as measurement from the chart of triangulation, and sin SBT = sin TSB $\frac{ST}{BT}$, BT being found in a approximate way

Computations

Lengths of the Sides Suppose AB to be the measured base C a point in triangulation the angles A B C having been observed

Now since the surface of the earth is a curved surface the horizontal angles at A, B, and have been observed in planes which are very slightly inclined to each other and, if perfec observed, the sum of A, B, and C will exceed 180 by a small quantity known as the **spheri excess** In geodetic and secondary triangulation this quantity is always computed subtracted from the sum of the three angles and any remaining excess or defect on 180° is error to be adjusted by an elaborate process which will not here be described

But in tertiary and topographical triangulation the procedure is very simple viz divide the excess or defect on 180 equally between the three angles The angles th corrected are the *correct angles*

By elementary plane trigonometry, we have

$$l = \times \frac{\sin B}{\sin C} \text{ and } a \quad \times \frac{\sin A}{\sin C}$$

c being the known base

The most convenient arrangement for logarithmic computation is shown on p 24, t ends of the known side being written first and the stations entered in order in the direction motion of the hands of a watch

The other triangles are solved in succession in the same way

It is sometimes, though not often necessary to compute the third side of a triangle which two sides a, b, and the included angle C are known The following formula is used

$$\tan \frac{A}{2} \frac{B}{} = \frac{a - b}{+ b} \cot \frac{C}{2},$$

whence $\frac{A}{2} \frac{B}{}$ is found and

$$\frac{A}{2} + \frac{B}{} = 90 - \frac{C}{2}$$

From these A and B are found and the triangle can be solved in the ordinary way

It is desirable, whenever possible to obtain more than one value for the length of a sid the mean being taken in subsequent computations

Form A.—(S.M.L. Topographical Survey, Form I.)

Computation of Sides of Triangles

Formula $\frac{\sin A}{a} = \frac{\sin B}{b} = \frac{\sin C}{c}$

Triangle	Letter of station	Name of station	Mean of observed angles —or satellite angles reduced to centre	Correction	Corrected angles	Logarithmic computation	Sides (log feet)
14	A	Dirnet Fort	96 50 20	+ 3	96 50 23	$\log_{10}$ AB 4.3937724	
	B	Callun Hill	29 38 26	+ 3	29 38 29	I sin 9.9068307	4.1853038 (BC)
	C	Stoke Ch	53 30 53	+ 3	53 31 2	I sin = 9.6912276	4.1827247 (AC)
			179 59 51	+ 9	180 0 0	L cosec −10.0917247	
15	D	Naval Hospital	56 28 6	−10	56 23 26	$\log_{10}$ DB = 4.5323728	
	B	Callun Hill	55 16 26	− 9	55 16 17	L sin = 9.9207741	4.4854049 (BC)
	C	Stoke Ch	68 15 26	− 9	68 15 17	I sin = 9.9147976	4.4792277 (CD)
			180 0 28	−28	180 0 0	L cosec = 10.0320080	

Co-ordinates or Latitudes and Longitudes—The next step in the computations is to put the results in a form which permits of accurate plotting, and which enables a record to be kept of the position of each trigonometrical point

This can be done in two ways —

I By rectangular co-ordinates,

II By latitudes and longitudes

I Rectangular Co ordinates—If the distance east or west of the starting point is not likely to exceed 100 miles and there is no probability of geographical positions being required accurately, nor of there being any further extension of the triangulation and if the azimuths of the sides are not likely to be wanted, proceed as follows —

(*a*) Calculate by plane trigonometry the lengths of all the sides of the triangles

(*b*) Select one station as the initial station and the meridian through that station as the initial meridian, then, treating the earth's surface as a plane calculate the *co-ordinates* of all the stations, the co-ordinates being measured along and at right angles to the initial meridian thus—

If α is the azimuth, or true bearing of the first side AB A the initial point, then x_1 (the co-ordinate at right angles of the meridian) = AB sin α

$$y_1 = \text{AB} \cos \alpha$$

$$\left.\begin{aligned} x &= \text{BC} \sin \beta \\ y &= \text{BC} \cos \beta \end{aligned}\right\} \text{where } \beta = \text{ABC} - \alpha$$

Then co-ordinates of A are O, O

" " B " x_1, y_1

" " C " $x_1 + x$ $y_1 - y$, &c

All these points can now be plotted with reference to the initial point, A and its meridian

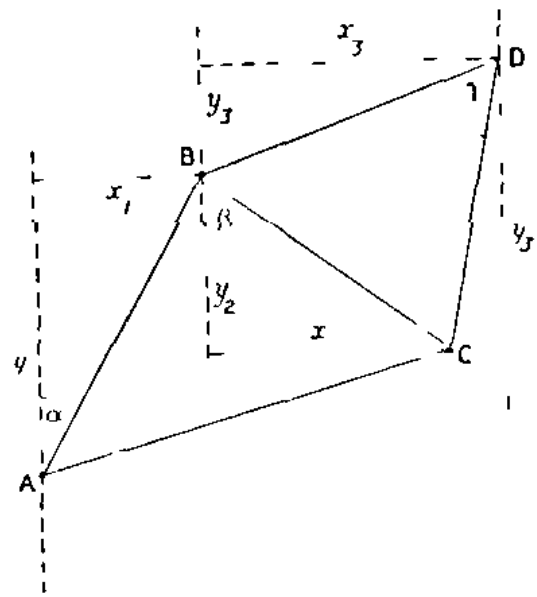


Fig 14

It is important to note that once the initial meridian has been left the angles β, γ, &c, formed by the sides with lines parallel to the meridian, are no longer the true bearings of these lines, and should never be used as such

It is clear that if a chain of triangles runs in an oblique direction it may be convenient to

plot along, and at right angles to, a line of known bearing, running generally in the same direction

II Latitudes and Longitudes*—If the distance east or west of the starting point is likely to exceed 100 miles, or if the geographical positions of the stations are of importance, or if the azimuths of the sides are likely to be wanted, or if the triangulation is likely to be extended in the future then calculate the latitude and longitude of each trigonometrical station having regard to the true shape of the earth, as follows —

It is first necessary to know the latitude and longitude of some trigonometrical station and the azimuth (*i e*, true bearing) of some ray from that station The latitude, longitude and azimuth are either determined astronomically (see Chapter XIV) or have been brought up by former triangulation In the case of astronomical determination there is no difficulty in obtaining the required latitude and azimuth, but the longitude may present some difficulty, and an approximate value may have to be assumed This will not, in any way, affect the accuracy of the work in itself

Suppose now that A and B are two stations and that we know —

λ – latitude of A,
L – longitude of A,
A – azimuth of B from A,
s – distance in feet at mean sea level between A and B,

then we require λ_b – latitude of B,
L_b – longitude of B,
B – azimuth of A from B

If we put $\lambda_b = \lambda + \Delta\lambda$
$L_b = L + \Delta L$
$B = - + A + \Delta A$,

and if $\Delta\lambda = \delta_1\lambda + \delta\lambda$,
$\Delta L = \delta_1 L + \delta L$
$\Delta A = \delta_1 A + \delta A$,

then it can be shown that

$$\delta_1\lambda = P \cos A \; s, \qquad \delta\lambda = \delta_1 A \; R \sin A \; s,$$
$$\delta_1 L = \delta_1\lambda \; Q \sec\lambda \tan A, \qquad \delta L = \delta\lambda \; S \cot A,$$
$$\delta_1 A = \delta_1 L \sin\lambda, \qquad \delta A = \delta L \; T,$$

which are the expressions used in the form for computation

It will be noticed that each term is found consecutively from the preceding one

The quantities P, Q, R, S, T will be found by interpolation from Table I The proper signs to be given to $\delta_1\lambda$, $\delta_1 L$, &c, will be found in Tables II (*a*) and (*b*)

Examples of the Computation of Latitude, Longitude, and Reverse Azimuth — This is shown on Form B In this example Sugar Loaf is the station of which the latitude and longitude are known Blorenge that of which they are required The distance Sugar Loaf—Blorenge is known and also the azimuth of the ray Sugar Loaf—Blorenge *Azimuth for these purposes is always to be reckoned from south by west*

In the example given, the longitude of the known station was *west* of Greenwich, and was therefore booked as a negative quantity, east longitude is booked as a positive quantity The signs of the quantities $\delta_1\lambda$, $\delta\lambda$, $\delta_1 L$, δL, $\delta_1 A$, δA are to be booked exactly as found in Tables II (*a*) and (*b*)

Suppose that we start with a triangle ABC, of which the latitude and longitude of A are known, the azimuth of AB, and the lengths of all the sides —

First compute the latitude and longitude of B and reverse azimuth BA Then, by adding

* See also Appendix III

Form B—(S M E. Topographical Survey Form III)

Latitudes, Longitudes, and Reverse Azimuths

Station A	Sugar Loaf	
Lat of A (λ)	51° 51′ 44·00″	° ′
Long of A (l)	W 3 3 23 00	
Station B	Blorenge	
Az B from A (A)	1° 23′ 58″	° ′ ″
log AB (e) in feet	4 356240	
P	3 993983	
log cos λ	1 999870	
log e	4 356240	
log δ₁ λ	2 349427	
Q	1 998867	
log sec λ	0 299240	
log tan λ	2 387994	
log δ₁ L	0 045 38	
log sin λ	1 893742	
log δ₁ λ	0 811280	
R	6 37848	
log sin λ	2 38779	
log e	4 35662	
log δ λ	″ 06317	
S	0 29922	
log cot λ	1 01208	
log δ I	2 08447	
T	0 01267	
log δ₂ λ	2 09714	
λ	51° 51′ 44·00″	°
δ₁ λ	− 0 3 43·68	
δ² λ	− 0 0 0·00	
Lat of B	51 48 0·42	°
* L	W − 3° 3 23·00	°
δ₁ I	− 0 0 8·82	
δ² I	+ 0 0 0·01	
Long of B	− 3 3 31·81	°
π + A	181° 23 58	°
δ₁ A	− 0 0 6·9	
δ² A	+ 0 0 0·01	
Az of A from B	181° 23 51	° ′

* When A is W of Greenwich give L the negative sign

the angle at B to this last obtain the azimuth of BC, and, knowing now the latitude and longitude of B and azimuth BC, calculate the latitude and longitude of C

Now, as a check, calculate the latitude and longitude of C direct from A

And generally, to avoid arithmetical errors, compute the latitude and longitude of each point from at least two rays

Latitudes and longitudes should be worked out to two places of decimals of a second

The latitudes and longitudes of all the stations of a triangulation are thus computed successively from those of previously computed stations These latitudes and longitudes are definite and sufficient records of the positions of the stations, and the positions can be plotted on any scale required

Trigonometrical Heights—Having computed the lengths of the sides and the co-ordinates or latitudes and longitudes, the next step is to calculate the heights of the stations above mean sea level For this purpose some initial height is necessary, which may have been determined by former triangulation or may be determined by direct observation of the mean sea level or by careful barometer readings at sea level and at the point in question (see p 87)

We will assume that the height above mean sea level of one station of the triangulation is known, and that vertical angles have been taken at each station to all stations visible therefrom and that these vertical angles have been observed with a theodolite on both faces, and that the means have been corrected for level error

All vertical angles require a correction for refraction The ray of light from a distant object lies, as a rule, in such a curve as to make the object appear higher than it really is The amount of this deflection varies with the place, season and time of day Sometimes, but rarely it makes an object appear lower than it really is

In fig 15 A and B are the summits of two hills, AR, BR the apparent directions of the distant stations (due to refraction) As AR BR are portions of an arc of small curvature, BAR and ABR are sensibly equal Make OC = OA Then it is required to find BC the difference of height of A and B

Let the observed depressions at A and B be D_a and D_b,

BAC = OCA − ABO and

BAC = BAO − CAO, and since OCA = CAO,

$BAC = \frac{1}{2}(BAO - ABO) = \frac{1}{2}(RAO - RBO)$ (since BAR = ABR) $= \frac{1}{2}(D_b - D_a)$

Now as AC is a very small part of the earth's surface,

BC = AC tan BAC (sensibly), or

$$h = C \tan \frac{D_b - D_a}{2}, \text{ or if one angle is an elevation}$$

$$h = C \tan \frac{E_a + D_b}{2}, \text{ or } C \tan \frac{E_b + D_a}{2},*$$

where

h is the required difference in height

C the distance between the stations

D_a D_b the angles of depression at A and B

It has been assumed above that the reciprocal observations were taken simultaneously This is usually impracticable, so in order to attain the same result as far as possible, vertical angles should be taken (when time allows) about the same time of day, that time being between noon and 3 p.m., when refraction is fairly constant

* See Form C p 31

Where reciprocal angles have not been observed, it is necessary to adopt some approximate value for the refraction (BAR)

From fig 15 it is clear that, calling the refraction r,

$$r = \frac{c - D_a - D_b}{2},$$

where c is the arc of the earth's surface between A and B

So that whenever reciprocal angles have been observed the amount of the refraction can be found

The result of a very large number of observations all over the world is to show that the

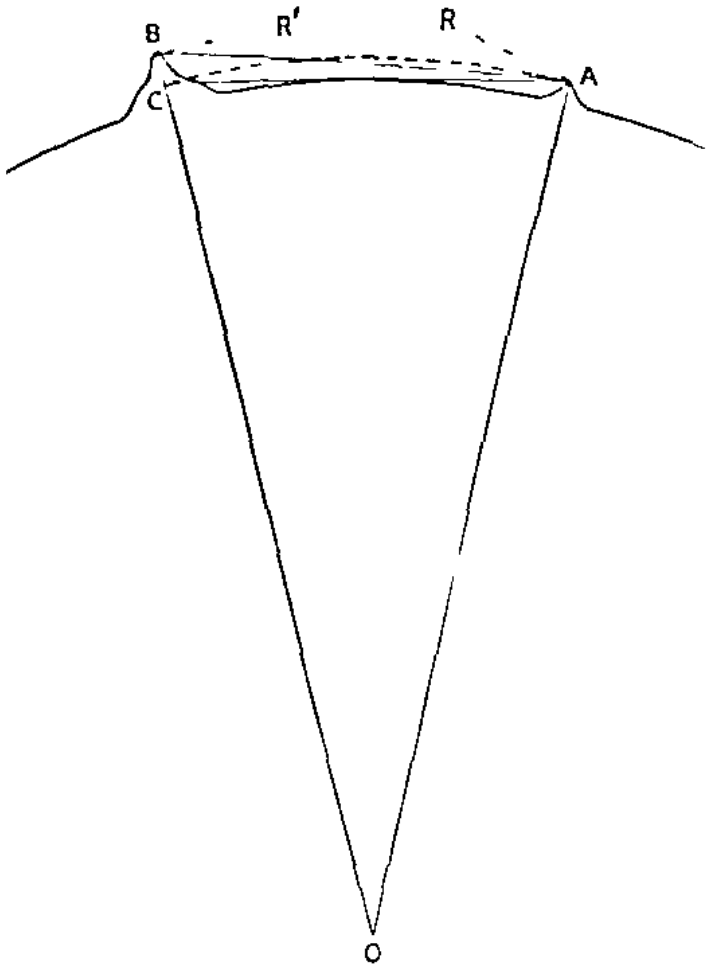


Fig 15

quantity $\frac{r}{c}$, called the **coefficient of refraction** is fairly constant for a given country and climate

The mean coefficient of refraction for South Africa is	064
" " " " Burma	067
" " " " the United Kingdom (for rays not crossing the sea)	075
" " " " the United Kingdom (for rays crossing the sea)	081

Generally the coefficient of refraction may be taken as 070

Having adopted a suitable coefficient of refraction, it is clearly easy to compute the effect

produced by curvature and refraction combined The labour saving table on p 31 has been computed for a coefficient of 070 Its use is as follows —

If a vertical angle has been observed at only one of the stations, if this is a depression call it D, if an elevation I

Then look out the value of K in the Table, corresponding to the distance between the stations

Let

$$S = K - D \quad \text{or} \quad K + E,$$

then the difference in height between the stations

$$= \tan S \times \text{distance between the stations}$$

To get the exact height, a correction must be applied for the heights in feet above their station dots of the instruments at A and B t_a and t_b and of the signals at A and B g_a and g_b

This correction, to be applied to the already obtained difference of height,

$$= + \frac{g_a - g_b}{2} + \frac{t_a - t_b}{2}$$

Two examples of the computation of heights are given on Form C, one where reciprocal angles have been observed and the other where only one angle has been observed

Datum Level—All heights on a map should be referred to mean sea level The mean sea level for the Ordnance Survey of the United Kingdom was determined at Liverpool The datum level of the Survey of India is the mean sea level at Karachi

Mean Sea Level—This is the mean height of the surface of the sea during an indefinitely long period As determined by the Survey of India the mean sea level is the mean of the hourly heights extending over a period of 5 years Five years is chosen so as to cover the cycle of recurrence of astronomical phenomena producing tidal effect This is the mean sea level which should be used in all civilized countries having an organized survey

It will often however, be impossible on a topographical survey to determine mean sea level so accurately In such a case, if there are any tidal records at the port chosen, the mean of high and low water heights throughout a year will give a good value

If there are no tidal records fix a graduated pole in the sea and observe the heights of high and low water during the progress of the survey, the period to extend over a definite number of lunations

Under any circumstances the period must extend over at least one lunation

This latter method will give only a rough value for mean sea level

Trigonometrical Interpolation

In rapid triangulation during military operations or on an expedition or with a boundary commission many artifices have to be employed which it would be improper to use on a regular topographical survey in the execution of which rapidity is not a governing condition A very valuable expedient in such cases is **interpolation**, or the determination of the observer's position by means of observations taken to previously fixed points

There are three methods of interpolation —

(a) By observing the horizontal angles from 1 unfixed point to 3 known points

(b) " " " 2 points to 2 "

(c) " 1 " point to 2 "
with the help of an azimuth

Form C—(S M I Topographical Survey Form II)

Computation of Trigonometrical Heights

Data

A is the Station of which the height is known
B " " required
c = Distance in feet between A and B
D_a = Vertical angle of depression at A
D_b = " " " B
E_a = " elevation " A
E_b = " " B
i_a = Height of instrument above ground at A
i_b = " " " B
s_a = Height of signal A
s_b = " B
K = Correction for curvature and refraction (see Table below)

General Formulæ

Height of B = Height of A + $c \tan S + \frac{s_a - s_b + i_a - i_b}{2}$

(I) Where S or Subtended Angle = $\frac{D_b - D_a}{2}$

If either angle is an elevation it is to be treated as a

required

(II) If one angle only is observed—
$S = K - D$ or $K + D$

Data		Data	
Station (A)	Patwa	Station (A)	Chiltan
Known height of A	= 642 2	Known height of A	= 453
Station (B)	Sung	Station (B)	Murdah
Length c (in feet)	= 50 540	Length c (in feet)	= 53 420
I $+E_a$ or $-D_a$	= − 1 17 20	I $+E_a$ or $-D_a$	=
$+D_b$ or $-E_b$	= + 0 57 30	$+D_b$ or $-E_b$	=
2	0 19 50	2	
½ Algebraic sum (± S)	= − 0 9 55	½ Algebraic sum (± S)	=
II $+E_a$ or $-D_b$	=	II $+E_a$ or $-D_b$	= 0 5 10
K (from Table)	=	K (from Table)	= 0 3 48
Algebraic sum (± S)	=	Algebraic sum (± S)	= + 0 8 58
Log tan S	= 3 4600930	Log tan S	= 3 4163581
Log c	= 4 7036352	Log c	= 4 7277039
Log h	= 2 1637282	Log h	= 2 1440620
h (±)	= −145 09	h (±)	= +139 93
$\frac{s_a - s_b + i_a - i_b}{2}$ *	= + 8 3	$\frac{s_a - s_b + i_a - i_b}{2}$ *	= + 4 25
Known height of A	= 642 2	Known height of A	= 453 0
Deduced height of B	= 504 71	Deduced height of B	= 596 61

Table—Value of K

These values are obtained by using a coefficient of refraction of 07

Distance (c) in feet	K	Distance (c) in feet	K	Distance (c) in feet	K
1 000	0 1	8 000	0 34	60 000	4 10
2 000	0 9	9 000	0 38	70 000	4 58
3 000	0 13	10 000	0 43	80 000	5 49
4 000	0 17	20 000	1 25	90 000	6 23
5 000	0 21	30 000	2 8	100 000	7 5
6 000	0 26	40 000	2 50		
7,000	0 30	50 000	3 33		

* Where only one angle is observed at A to the *ground line* at B the correction will be $+ i_a$

produced by curvature and refraction combined The labour saving table on p 31 has been computed for a coefficient of 070 Its use is as follows —

If a vertical angle has been observed at only one of the stations if this is a depression call it D if an elevation E

Then look out the value of K in the Table, corresponding to the distance between the stations

Let

$$S = K - D \quad \text{or} \quad K + E$$

then the difference in height between the stations

$$= \tan S \times \text{distance between the stations}$$

To get the exact height a correction must be applied for the heights in feet above their station dots of the instruments at A and B i_a and i_b and of the signals at A and B g_a and g_b

This correction to be applied to the already obtained difference of height

$$= + \frac{g_a - g_b + i_a - i_b}{}$$

Two examples of the computation of heights are given on Form C, one where reciprocal angles have been observed and the other where only one angle has been observed

Datum Level—All heights on a map should be referred to mean sea level The mean sea level for the Ordnance Survey of the United Kingdom was determined at Liverpool The datum level of the Survey of India is the mean sea level at Karachi

Mean Sea Level—This is the mean height of the surface of the sea during an indefinitely long period As determined by the Survey of India the mean sea level is the mean of the hourly heights extending over a period of 5 years Five years is chosen so as to cover the cycle of recurrence of astronomical phenomena producing tidal effect This is the mean sea level which should be used in all civilized countries having an organized survey

It will often however be impossible on a topographical survey to determine mean sea level so accurately In such a case if there are any tidal records at the port chosen, the mean of high and low water heights throughout a year will give a good value

If there are no tidal records fix a graduated pole in the sea and observe the heights of high and low water during the progress of the survey the period to extend over a definite number of lunations

Under any circumstances the period must extend over at least one lunation

This latter method will give only a rough value for mean sea level

Trigonometrical Interpolation

In rapid triangulation during military operations or on an expedition or with a boundary commission many artifices have to be employed which it would be improper to use on a regular topographical survey in the execution of which rapidity is not a governing condition A very valuable expedient in such cases is **interpolation** or the determination of the observer's position by means of observations taken to *previously fixed points*

There are three methods of interpolation —

(*a*) By observing the horizontal angles from 1 unfixed point to 3 known points

(*b*) " 2 points to 2

(*c*) " 1 point to 2 with the help of an azimuth

Form C—(S M E. Topographical Survey Form II)

Computation of Trigonometrical Heights

Data

A is the Station of which the height is known
B " " required
c = Distance in feet between A and B
D_a = Vertical angle of depression at A
D = " " B
I_a = " " elevation A
I_b = " " B
i_a = Height of instrument above ground at A
i_b = " " B
r_a = Height of signal " A
r_b = " " B
k = Correction for curvature and refraction (see Table below)

General Formulæ

Height of B = Height of A + c tan S + $\frac{r_a - r_b + i_a - i_b}{2}$

(I) Where S or Subtended Angle = $\frac{D_b - D_a}{2}$

(II) If one angle only is observed—
$D_b = k - D$ or $k + D$

required

Data			Data		
Station (A)	Pahun		Station (A)	Chiltan	
Known height of A	=	612 2	Known height of A		403
Station (B)	Sung		Station (B)	Murdah	
Length c (in feet)	=	20740	Length c (in feet)	=	53490
I $+S_a$ or $-D_a$	= − 1 17 20		I $+I_a$ or $-D_a$	=	° ′
$+D$ or $-S_b$	= + 0 57 30		$+D$ or $-E_b$	=	
	0 13 50			2	
Half Vert. sum (± S)	= − 0 9 55		Half Vert. sum (± S)	=	
II $+I_a$ or $-D$	=		II $+I_a$ or $-D_b$	=	° 0 5 10
k (from Table)	=		k (from Table)	=	0 3 48
Alg. true sum (± S)	=		Alg. true sum (± S)	=	+ 0 8 58
Log tan S	=	3 4609039	Log tan S	=	3 4163581
Log c	=	4 7036 52	Log c	=	4 7277039
Log h	=	2 1037 89	Log h	=	2 1440 0
h (±)	=	−140 70	h (±)	=	+139 93
$\frac{r_a - r_b + i_a - i_b}{2}$ *	=	+ 8 3	$\frac{r_a - r_b + i_a - i_b}{2}$ *	=	+ 4 2
Known height of A	=	612 2	Known height of A		403 0
Deduced height of B	=	611 71	Deduced height of B	=	596 61

Table—Value of k

These values are obtained by using a coefficient of refraction of 07

Distance (c) in feet	k	Distance (c) in feet	k	Distance (c) in feet	k
1 000	0 1	8 00	0 34	60 000	4 15
2 000	0 3	9 000	0 38	70 000	4 58
3 000	0 13	10 000	0 43	80 000	5 43
4 000	0 17	20 000	1 25	90 000	6 33
5 000	0 21	30 000	2 8	100 000	7 5
6 000	0 26	40 000	2 50		
7 000	0 30	50 000	3 33		

* Where only one angle is observed at A to the ground flat at B the correction will be + r

(*a*) **Fixing the position of a point by angles taken from it to 3 previously fixed points**, in this there are three cases as below.

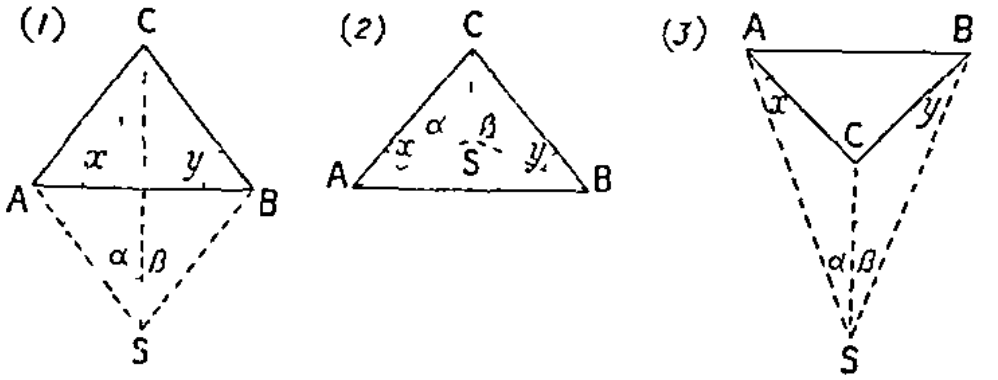


Fig 16

Let S be the observer's position, α and β observed angles, then

$$x + y = 360 - (\alpha + \beta + C) \text{ in (1) and (2)},$$

$$x + y = C - (\alpha + \beta) \text{ in (3)}$$

Let

$$\tan \phi = \frac{\sin \alpha}{\sin \beta} \times \frac{a}{b},$$

then

$$\tan \frac{x - y}{2} \quad \tan (\phi - 45^\circ) \tan \frac{x + y}{2}$$

NOTE —In case (1) if S, A, B, C, are on the circumference of the same circle the problem is insoluble

(*b*) **Fixing the position of 2 points by angles taken from them to 2 previously fixed points**

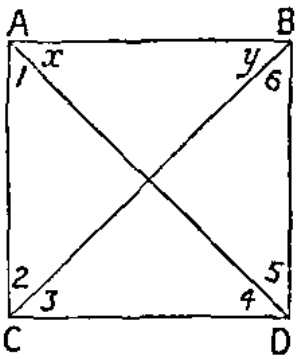


Fig 17

A and B are known points The angles 2, 3, 4, 5 are observed 1 6 are deduced Then if

$$P = \frac{\sin 1 \sin 3 \sin 5}{\sin 2 \sin 4 \sin 6},$$

$$\tan \tfrac{1}{2} (y - x) = \tan \tfrac{1}{2} (3 + 4) \frac{1 - P}{1 + P}$$

(c) Fixing the position of a point by angles taken from it to 2 known points and an azimuth

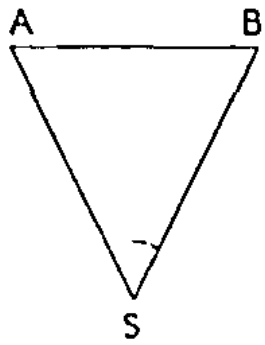


Fig 18

Let A and B be 2 known points At S observe the angle ASB and the azimuth of SA or SB (by the sun will do See p 148)

Get some approximate value for the position of S from the plane table, or by traverse

Then compute reverse azimuths of AS and BS, as below

$$d\mathrm{A} = d\mathrm{L} \sin \lambda,$$

where $d\mathrm{A}$ = increment of azimuth in seconds,

$d\mathrm{L}$ = difference of longitude in seconds of arc,

λ = mean latitude

The way to apply the quantity $d\mathrm{A}$ can easily be seen by considering in which direction the meridians converge Then knowing the azimuths of AS, BS, and that of AB (which is a known line) the differences give the angles A and B, and in the triangle ASB we know the three angles and one side (AB)

NOTE.—Method (*a*) and method (*b*) are much strengthened if an azimuth is observed The use of an azimuth enables two solutions to be found in each case and a check is thus obtained It is a general maxim in interpolation that azimuths should be observed when possible

CHAPTER IV

TRAVERSES

Definition —A traverse consists of a connected series of straight lines (on the earth's surface) of which the lengths and bearings have been determined

Different Forms of Traverse —Traverses may be carried out in different ways, according to the accuracy required

Where great precision is aimed at, the linear measurements are made with a chain or steel tape and the included angles are measured with a theodolite

Where rapid work is desired and where accuracy is not so important, the angles may be measured with a prismatic compass, and the distance either chained, paced, or taken by means of a perambulator, or by time

These two classes of traverses are known as —

(1) Theodolite traverses,
(2) Compass traverses

The latter are dealt with in Appendix VII

Theodolite Traverses —The principal varieties of theodolite traverses are —

A Traverses between points already fixed trigonometrically
B " used on the line of march during an expedition
C " as a substitute for triangulation in a country unsuited to the latter

A Traverses between Trigonometrical Points *

This class of traverse is used —

(*a*) On the Ordnance Survey of the United Kingdom, for large scale town surveys
(*b*) In India for cadastral surveys
(*c*) For certain large scale engineering surveys
(*d*) For forest surveys
(*e*) For the detailed survey of special routes, roads, railways, river banks, &c, &c
(*f*) To fix points for detail survey which cannot be provided by triangulation

The starting and finishing points of these traverses are trigonometrical points already fixed

Errors —Traverses are liable to errors of two kinds —

(1) Errors of direction These are due partly to inaccurate observations of the angles, and partly to bad centering of the theodolite, and also of the signals over the points marking the traverse stations
(2) Linear errors, due to faulty chaining

Traverse Stations —These stations should be as far apart as possible consistent with the ultimate object of the traverse, that is to say, in the case of traverses along winding roads the positions of the stations are governed to a great extent by the fact that offsets from the traverse line to detail along the road should not exceed a certain length

All stations should be carefully marked, and where possible a picket of about 2 × 2 section should be driven in flush with the ground A tintack should then be driven into the picket to show the exact centre point The further the stations are apart, the less will be the effect produced by bad centering of the theodolite, or signal over these points

* Including the case where there are no trigonometrical points but the traverse closes on the starting point

Signals—The sight vane commonly in use consists of a staff about 6 feet long and about 3 × 1 section, having a cross vane (a black cross on a white ground) which can be clamped at any height The difficulty is to hold this staff vertically over the centre point It is best therefore in order to minimise the errors in direction when taking horizontal readings, to make the cross wires of the theodolite bisect the bottom of the staff at the ground level In this case the horizontal reading should first be taken and recorded, after which the vertical angle to the cross vane clamped to the height of the instrument may be read Where the distance between the traverse points is small, it increases the accuracy of the work, if the horizontal readings are taken on the tintack itself, if visible, or else on an arrow or nail held over the same

There is an excellent sight vane in use on the Ordnance Survey, consisting of a tripod and staff with cross vane attached This last can be adjusted so as to be vertical over the centre points

Observations—We will assume that we have to run a traverse along a certain defined route, starting at A and finishing at B where A and B are stations mutually visible (fig 19)

Proceeding to A the theodolite is carefully centred over the station mark in the ground, and then levelled The horizontal plates are now clamped together so that the reading on the A vernier is anything between 0 0 0 and 0 10 0 (it is best not to try to set it to an exact reading) and with the plates so clamped the theodolite is directed on point B (the I O) and the signal bisected by the cross hairs The bottom plate is clamped and the horizontal verniers are read and recorded

Now release the top plate and direct the theodolite on to traverse station No I whither a man has been sent on with a sight vane clamped to the height of the theodolite The intersection of the cross hairs must then be carefully directed on the sight vane The horizontal verniers are now read and the verniers of the vertical are also the vertical level

A complete observation has now been taken on one face of the instrument

Now reverse the instrument and setting the A vernier at about 35 0 proceed in precisely the same manner as just described

This completes the observations at point A The theodolite is then taken to traverse point I where after careful centering and levelling a similar set of observations is made Here the trigonometrical point A becomes the R O Each traverse station is then visited in turn the station the observer has just left becoming the R O in each case On arriving at the point B the R O will be the last traverse station and forward readings taken on point A (*vide* fig 19)

Form D shows how the readings at traverse point VI would be recorded in the field book It is unnecessary to observe the vertical angles to the back station The details at VI correspond with those on Form I

Linear Measurements—The linear measurements are made with a chain or steel tape, preferably the latter The distance between traverse stations should be taped twice, to ensure accuracy A pull of 12 lbs is to be applied when taping this is done by means of a spring balance

Where the slope between stations are practically continuous, surface chaining should be employed The reduction to the horizontal is made afterwards by means of the vertical angles observed

Where the ground is broken horizontal chaining must be resorted to In this case the observation of vertical angles is unnecessary

Computations of Co ordinates—In order to plot a traverse correctly it is necessary to work out the co-ordinates of the station points referred to some origin For the class of traverse under consideration rectangular co ordinates are always used It is found convenient to calculate the ordinates (y) for north and south, and the abscissæ (x) for east and west

FORM D

Traverse Book.

		(Horizontal) A	B		(Vertical) C	D	E	O
F R	V	0° 3′ 20″	3′ 30′		— — —	— —	—	—
	VII	122° 15′ 20′	15′ 20′	VI	4° 30′ 0″	30′ 10	7	5
F.L	V	35° 5′ 10″	5′ 10″		— — —	— —	—	—
	VII	157° 17′ 5″	16 55′		175° 29′ 40′	29′ 50′	4	8

320

194

163

150

FENCE

32

15

30

16

0

V

Theodolite No 101
Bubble Value 1 Div 20′

Form I is the form used for the computation of these co-ordinates The traverse is that shown in fig 19, the starting and finishing points A and B, being mutually visible The observations taken at point VI are shown on Form D

Now A and B being points of a triangulation, the horizontal distance AB and also the true bearing of AB will be known

The legs of the traverse together with the line AB form an enclosed figure, and the sum of all the interior angles should be equal to twice as many right angles as the figure has sides less four right angles We thus have a check on the observed horizontal angles

It should be carefully noted that the included angles at the stations are always measured, either all to the right or all to the left of the back station

This is an invariable rule In the case of fig 19 they are all measured to the left of the back station Take point VI for instance Form D shows that the mean of the differences of the readings on V and VII is 122 11 52 5 The horizontal plate of a theodolite however, is always graduated in the same direction as a watch Hence we must deduct our result from

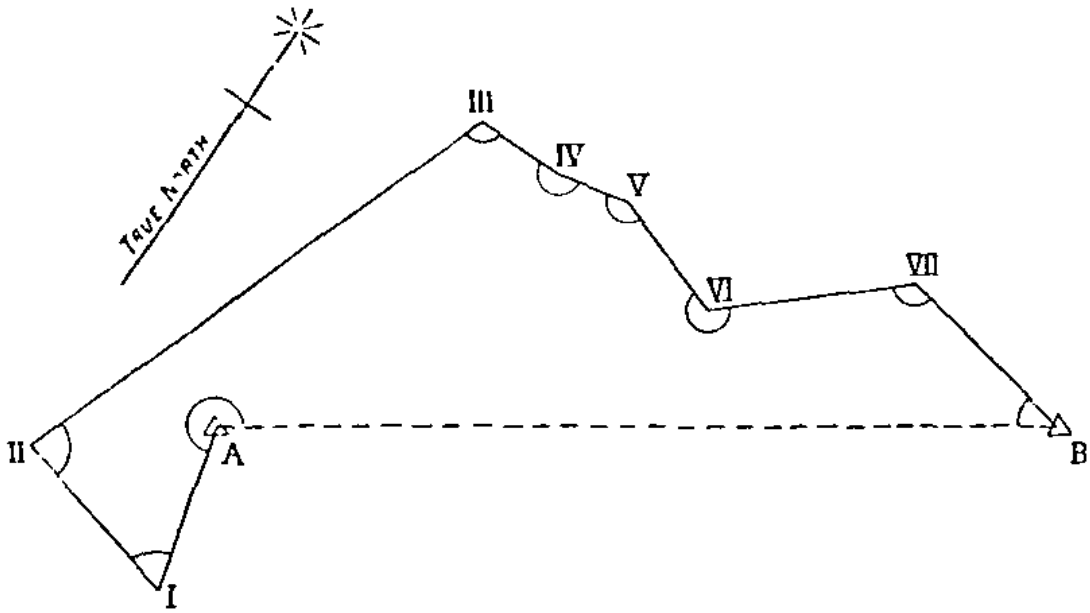


Fig 19

360°, which gives 237 48 7 5 The same must be done with all the angles before entering them in column 2 Form I It is obvious that this last operation is unnecessary where the required angles are all measured to the right of the back station

Angular Error—The sum of all these interior angles then should be equal to $(2n \times 90 - 360)$ degrees where n is the number of sides to the figure Any discrepancy between these two is called the 'total angular error' This error must then be distributed equally among the observed angles For example, if there are 6 sides to the figure and the sum of the observed angles comes out to 719 59 0 , then the error to be distributed is 1 Hence 10 must be added to each observed angle

Columns 2, 3, and 4, Form I , are self-explanatory

In this class of traverse it is quite unnecessary to take into account the convergence of the meridians, owing to the distance AB being short Hence the bearing of each leg is a "false bearing," as computed in column 5

It may here be stated that, before making any computations at all, it is best to draw a rough diagram of the traverse, such as in fig 19

Column 5 is computed thus —the bearing A to I is 360° − (249° 17 14 2) + (59° 4 33″)

FORM I —(S M I Form N)

Traverse

COMPUTATION OF CO ORDINATES

Date —Hor Dist AB – 1995 78 ft

True Bearing of AB – 59° 4 33

arting Point △ (A) } Mutually visible
losing Point △ (B) }

1		3	4		6	7	8	10	11	1	13	14	1	16	1
ns	Angles of Stations	Angle Error	Corrd Angles	Tal Lengths of Lines	Values Angles	Distances in Feet	Hypothetical stations	Deduced Co-ordinates			Errors of Co rdinates Closing	Corrected Co-ord nates from Origin			
T								North Lings	South Lings	East ings	West Lings	Correction	North	Correction	South	East	East	Correction	West
B	0 0 0		°	° 9 4 33			100 8	10 5·64		1 1 ·08			10 64				171° 09		
												−		+		+		−	
I	°19 16	+1 6	°19 17 14 °	109 47 19	E 3 16 11	4 9 3	479		4°° 4	6 09			"	1	4 ·3·	36	6 4		
II	60 °1 0	+1 6 7	60 0 7	99 1	E 0 10 0	476 0	4 6	1 7 87			449·06			31	01 84			°	3 ° 2
III	88 5	+1 6 7	86 3 9	8 13	E 0 41 40	176 1	1361 9	1 1 0		31 °		46	89 00			1 09	1 9 3		
IV	111 49 7 5	+1 6 7	111 50 14 °	91 7 9	E 0 0 0	°10 1	10		4 1	°09 °°		0	981 7			1 44	°69 91		
V	191 1 7 5	+1 6 7	191 5 14 °	9 42 41	E 0 3 0	164 0	164	9 9		1 1 6		7	1013 89			1 8	31 03		
VI	144 6 4	+1 6 7	144 7 1 7	11 34 03	D 1 31	3 0 0	°10 8		138 17	88 63			8 E			°15	8 0 61		
VII	°37 43 7 5	+1 6 6	°37 43 11 1	4 9	D 4 30 0	101	100	66 3		4 °° 01		1 0	114° 04			°3	1°41 8		
R	133 47 0	+1 6 6	133 48 6 6	103	E 4 18 35	483 9	48° °		116 3	4 7 85		1 1	100 61			86	1 1 09		
A	41 1 5	+1 6 6	41 52 9 1																
								1 07 89	681 01	°1 8 8	449 06								
al	1 9 0 0		1 60 0 0					691 01		449 06									
r t	1 60 0 0																		
						B (ledu ed)		10 6 88		1 09 °									
0	0 10 0																		
	0 1 6 6	to be added					Error	+ 1·°1		− °·86									

Closing errors are + 1·°1 N and − 86 E
corrections S + and W −

NOTE —There are 9 sides to the figure sum of included angles = × 0 × 9 − 60 1 60

or 10 47 18 S The next bearing is got by adding 180 to this last, and then subtracting the corrected angle at II, and similarly for all the rest An examination of the figure will always reveal the correct method of computing the bearing

Column 6 gives the vertical angles of elevation or depression column 7 the distance observed along the surface The horizontal distances in column 8 are obtained thus —

$$\text{Horizontal dist} = \text{surface dist} \times \cos \text{vert (or D)}$$

The co-ordinates Formulæ are computed with A taken as the origin From the triangulation data we know the length AB to be 1995 78 feet and the bearing of AB 59 4 33 The co-ordinates of B will then be 1995 78 × cos 59 4 33, or a north co-ordinate of 1025 64 and 1995 78 × sin 59 4 33 or an east co-ordinate of 1712 08

The next step is to compute in this manner by using the bearings in column 5 and the distances in column 8, the co-ordinates of each point of the traverse referred to the last point as origin

We have now a set of deduced co-ordinates referred to parallel axes throughout in columns 9 10 11 and 12 Thus the co-ordinates of III are 1251 0 N and 531 52 E referred to II as origin Also the co-ordinates of II are 157 87 N and 449 06 W, referred to I as origin

It is easily seen that where the bearing of the line lies between certain values, the deduced co-ordinates must be measured from the axes in certain directions thus —

Bearings		Deduced co-ordinates
°	°	
0 to	90	North and East
90	180	South and East
180	270	South and West
270	360	North and West

Now we see from the form that the co-ordinates of I referred to A are 422 4 S and 76 09 E, and the co-ordinates of II referred to I are 157 87 N and 449 06 W Hence the co-ordinates of II referred to A are—

422 4		449 06
157 87	and	76 09
264 53 S		372 57 W

Thus it is evident that the co-ordinates of any point referred to the primary origin (in this case A) are obtained by taking the algebraic sum of the deduced northings and southings and of the eastings and westings up to the point in question

These co-ordinates from the origin are entered in columns 14, 15 16 and 17 with certain corrections to be now described

On computing the co-ordinates of B by the algebraic sum of the deduced co-ordinates of the points throughout the traverse we find that they come to 1026 88 N and 1709 22 E Now, from the data the co-ordinates of B are 1025 64 N and 1712 08 E, hence the total northing at B is too large by 1 24 and the total easting too small by 2 86

In this class of traverse a rigorous adjustment of such errors is unnecessary The simplest way to distribute the errors of the co-ordinates is as follows —

If

n = number of legs of traverse,
y = error to be adjusted N and S,
x = error to be adjusted E and W,

then the several corrections to be applied to the points of the traverse in order will be

$$\frac{y}{n}, \frac{2y}{n}, \frac{3y}{n} \quad \frac{ny}{n},$$

$$\frac{x}{n}, \frac{2x}{n}, \frac{3x}{n} \quad \frac{nx}{n}$$

In the example on Form E the corrections to northings are all negative, and therefore, to southings all positive Similarly the corrections to all eastings are positive, and to westings negative

For example the corrections to be applied to the computed co-ordinates of VI are

$$\tfrac{3}{4} \times 1\,24 = 93 \text{ on northing,}$$

and

$$\tfrac{3}{4} \times 2\,86 - 2\,15 \text{ on easting}$$

The algebraic sum of the deduced co ordinates up to this point gives 876 44 N and 818 46 F The corrections are entered in the columns provided on the left of columns 14 and 16, and applied to above results The corrected co-ordinates are then entered in columns 14 and 16

Thus the computed traverse co-ordinates of B have been made to agree with the trigonometrical values, and those of the other points have been adjusted in proportion

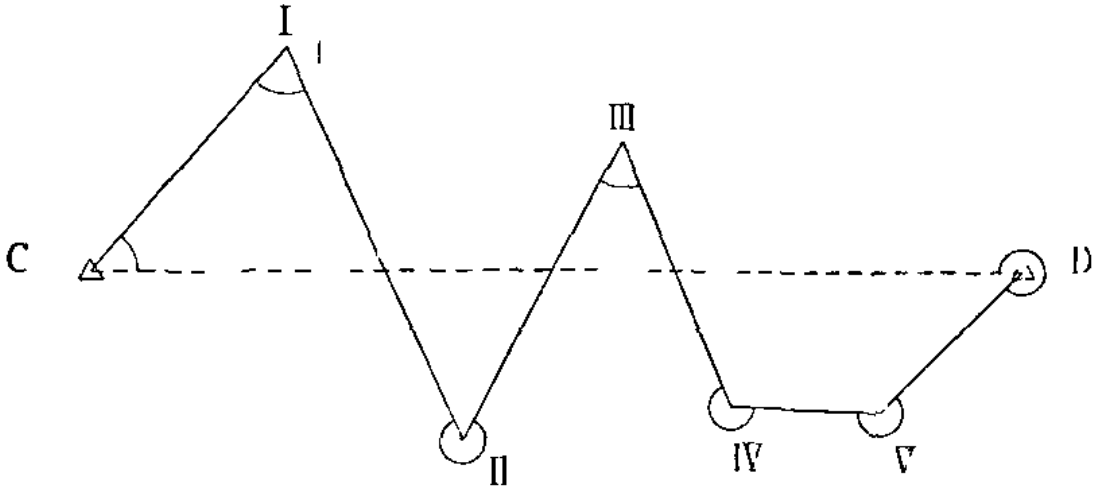


Fig 20

It often happen that the traverse crosses and re crosses the line joining the two terminal points as in fig 20

In such a case, where the traverse is started at C, the angle required at C must be under 180° In fig 20 this angle is measured to the left of the back station D As stated before all the other angles must be so measured

Then, as before

$$\Sigma\theta - 2n \times 90° - 360°$$

if the traverse crosses CD an *even* number of times

Where, however, the traverse crosses CD an *uneven* number of times

$$\Sigma\theta = 2n \times 90°$$

The co-ordinates are computed in the manner already explained

Where it is desired to start and finish a traverse on the same point, the method is identical with that described, care being taken that only the interior angles of the figure are used in the computation, and that at the starting point the angle between the first and last legs of the

traverse is observed If the starting point be taken as origin whose co-ordinates are 0, 0, then the co-ordinates carried throughout the traverse round to this point again must be 0, 0 If they do not come out to this value, the final co-ordinates must be made to have this value, and the remaining points adjusted as shown in Form I

Chainage Errors—In reducing the surface measurements to the horizontal, the computer should bear in mind the errors involved in chaining The larger the scale to which the traverse is plotted the smaller must be the chainage error

Thus for the Ordnance Survey maps of scales $\frac{1}{2500}$ and $\frac{1}{10560}$ the error in ordinary chaining allowed is 1 in 1,000 For the $\frac{1}{2500}$ map an error of 1 in 500 is permitted

In traverses measured with steel tapes much greater accuracy is to be expected

B Traverses on the Line of March (Subtense Traverses)

(See also p 53)

Often during an expedition in a tropical country, the nature of the ground and the time available render it impossible to execute a chain traverse Under these circumstances, subtense methods may be employed

Even without proper subtense instruments and subtense bars fitted with discs to be observed to very fair accuracy can be obtained with the ordinary 5 inch micrometer theodolite and improvised signals placed at right angles to the forward ray

With ordinary care work the subtended angle should be from 8 to 12 minutes, the base would therefore be some 700 feet for a ray of 10 000 feet It is very important that the exact intersection of the signal posts with the ground should be measured and it is consequently necessary that the ground round the signal posts should be systematically cleared of all grass, if the background is dark a white sheet or piece of cloth will be found very useful to show up the darkened signal post Where it is impossible to observe the actual ground line, great care should be exercised in selecting signal posts as straight as possible and carefully plumbing them before measurement is made

It is immaterial what the exact distance between the posts is so long as the subtended angle is somewhere within the limits specified above and any suitable high ground or mounds should be selected in the vicinity of the traverse station care of course, being taken that the base is truly at right angles to the required ray

This method of traverse was almost exclusively used in the Anglo-Liberian Boundary Commission of 1902 03 its advantages being that the computations were of the simplest and could be readily worked out in the field enabling the necessary reductions to be put up at once

The procedure is as follows —

An assistant with a small clearing party and a compass is sent on ahead to a suitable hill as near the line of march as possible and proceeds to clear the hill and fix his subtense posts at right angles to the direction of the post he has just left this is done by any elementary method A little practice will enable him to judge the distance apart the signals should be and to select a suitable place with a good background He may or may not put up a separate signal at the traverse station proper but it is preferable perhaps, as on the appended sketch, to have a third signal traverse (theodolite) station

As soon as his signals are fixed he goes on to the next hill selecting a hill by his compass as near the line as he can judge He should be kept constantly informed how much he is distant from the required direction so that he may select suitable hills

The observer behind will take, say, three sets of 10 readings to the subtense base, see p 42, and if they accord, having taken the angle between forward and back stations, and altered the subtense signals at his own station so as to be at right angles to the new ray, and carefully measured the distance in between them, will proceed to the forward station Here he will at once, before there is any chance of the signals being disturbed, measure the length of base he has observed to He will then set up the instrument over the new traverse station

and take the subtense angle on the traverse station he has just left so that he will have two values for the length of each ray, and if the two readings have been taken under equal conditions of light and clearness the mean of the two should be his accepted length for the ray

Owing to the difficulty of measuring the exact distance between the signals without the help of another white man and to the shimmer caused by the sun and heat except at certain times of the day great accuracy with small instruments cannot be expected To measure the distance in between the posts it was found that the best method was to drive a nail into the middle of one of the posts and fix the ring at the end of the steel tape on it pulling the tape tight to the middle of a pencil mark on the other signal post This was more satisfactory than trusting the other end of the tape to a native

The posts should be invariably guyed with rope or wire to make them as firm as possible

As regards the accuracy of the work it may be noted that during the Anglo Liberian Boundary Delimitation above quoted a difference of 20 feet in a ray of 10 000 feet was thought good *i e* a discrepancy of 1 in 500 At the end of the march when rays as long as 10 miles had to be taken the discrepancy in a length of 21 miles between the amplitudes of the latitudes deduced respectively from the traverse and from astronomical observations was 1

With these long rays as many as 60 or even 100 readings were taken of the subtended angle

As regards rate of working from 2 to 3 legs can be measured in a day each leg being 2 o 3 miles long

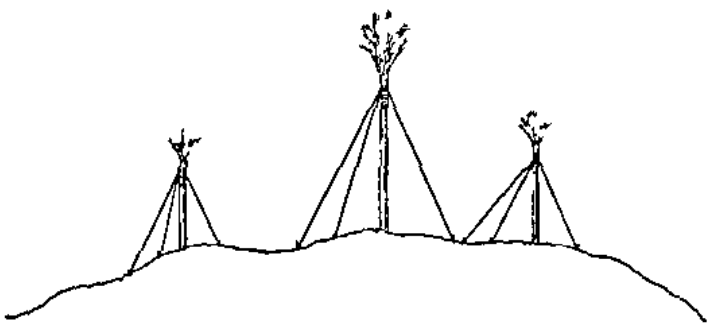


Fig 21 Subtense Station

Computations—In the instance quoted the latitude and longitude of each station of traverse was computed from the known length and azimuth of the ray by means of Form B, p 27

C Traverses as a Substitute for Triangulation in Countries Unsuited to the Latter and where Subtense Traverses are not Sufficiently Accurate

It is not suggested that traverses should ever be substituted for triangulation where the latter is possible but there are localities such as a dense forest or a flat grass covered country where the difficulties and expense of triangulation are such as to render it practically impossible In these circumstances **long traverses** will be found extremely useful in obtaining a framework of a high degree of accuracy on which topographical work can be based

In considering the relative accuracy of these two forms of survey, it must be remembered that after the triangles have been subjected to a rigorous treatment for the elimination of errors no side of a geodetic triangulation is likely to have an error of $\frac{1}{100\,000}$

The unsurmountable difficulty with regard to traverses in countries unfurnished with a Geodetic Survey is the impossibility of arriving at an accurate conclusion as to what errors have actually occurred In the absence of fixed geodetic points we are obliged to fall back on astronomical latitudes and telegraphic longitudes as a possible means of checking our measurements

Local Attraction.—Unfortunately, all astronomical observations are affected by "local attraction." The effect of this is that the plumb bob and the normal to the assumed geometrical surface of the earth do not coincide. The determination of the value of "local attraction" is one of the problems of a geodetic survey.

Those interested in the subject are referred to the "Account of the Principal Triangulation, Ordnance Survey," Vol. II. "Great Trigonometrical Survey of India," or "Geodesy," by Col. Clarke, C.B., F.R.S., R.E. Chapter X. of the Account of the Principal Triangulation, Ordnance Survey, gives an account of the deflections produced by masses of different density and form. It may be taken that "the probable error of an observed latitude is due to local disturbance of gravity is certainly not less than 1".5. Several instances, however, exist where "local attraction" far exceeds this amount. At a station in Elginshire, determinations show it to be something like 8", and at a station in the plains of Lombardy—a fact all the more remarkable owing to the absence of any large range of hills—it is over 20".

Despite the most careful observations we cannot, therefore, say with any certainty that an astronomical latitude is correct within about 2".

This represents 200 feet on the earth's surface, and, dealing with 2 latitude stations, the error of amplitude probably amounts to $2\sqrt{2}$, or say 300 feet.

We cannot therefore put confidence in latitudes as a check on accurate traverses.

We may, perhaps, lay down the rule, that the latitude stations shall be so far apart, that the errors of the traverse and latitude amplitudes shall be about equal.

Distance Apart of Astronomical Stations.—Suppose that a traversing error of $\frac{1}{1000}$ may be expected. We have seen above that 300 feet is the probable error of two latitude stations due to "local attraction." The distance at which latitude observations should be made should, therefore, not be closer than 300×1000 feet—say 60 miles (of latitude). The distances between longitude stations determined telegraphically in a traverse running east and west should be even greater.

Latitude Observations.—Latitude observations should be made with a zenith telescope*—the mean of two nights' work, 6 pairs on each night, being taken. This should give a probable error due to observing of about 0".2.

Clearings.—The principal aim of long traverses is to establish points within the area to be surveyed on which topographical surveys can be based. In most countries where traverses will be used this involves clearing the bush or forest in order to obtain as long legs as possible and the preparation of the surface of the ground for the chain measurement.

It is probable that native labour only will be available for this class of work, but it is desirable, if possible, to put a European in charge of the "clearing party." The traverse direction having been decided on, it is best to keep as much as possible in the same straight line, and it is advisable to let the traverse touch the villages falling near the proposed line. These form good closing points for further topographical work.

Rate of Clearing.—The rate of clearing depends on the nature of the bush and the number of men employed. On the Anglo-German Boundary Commission on the Gold Coast of 1901, 16 men, under a native clerk, cleared on the average about 2 miles a day. The country was, however, not very difficult for clearing and differed totally from that in the Ashanti forest, where the Gold Coast Survey experienced the greatest difficulty in getting long straight clearings.

The tools required for a party of, say, 20 natives for six months would be—

50 matchets or billhooks,
5 shovels,
3 cross cut saws,
2 tapes,
1 magnetic compass.

* Or a theodolite suitably fitted.

It is best, where possible, to make the clearing fairly wide This permits of a fair scope for the selection of the theodolite stations About 10 to 12 feet is a useful width

The "clearing party" should always be a mile ahead of the survey party which follows it

Detail of Traverse—The detail in carrying out these traverses is generally similar to that already described for traverses between fixed points Owing however, to the impossibility of obtaining any check on the results, it is important to use the greatest care in the measurement of the distance between stations The angular measurements, too, must be made with every possible care although they are to a certain extent checked by means of azimuth observations taken at every 30 or 35 stations apart

Causes of Error—The chief causes of errors in traverses are given in the account on Trigonometrical Traverses, but may be repeated here They are due to—

(1) Inaccurate centering of the instrument over the station mark,
(2) Inaccuracy in reading the verniers or micrometers and in the bisection of the station marks,
(3) Chaining errors,
(4) Insufficient length of traverse legs

Of these (1) has been dealt with and requires no further explanation beyond emphasizing the fact that, having no fixed points to work between it is of even greater importance in these long traverses to see that the centering is accurate

(2) This can best be minimized by taking a sufficient number of ares. The probable error of a mean varies inversely as the square root of the number of observations if all are equally good As regards the bisection of the station marks it must be borne in mind that the shorter the leg the more refined must be the method of bisection

When the leg is over 1000 feet it is sufficient to bisect a flag (at its junction with the ground)

When the leg is short say under 200 feet a nail or even a fine needle driven into a wooden picket forms the best station mark Between these distances an arrow stuck in the ground can be observed to

(3) Chaining should be done by steel tapes either of 100-feet or 300-feet lengths All steel tapes should be carefully standardized before they leave England and it is advisable to have them tested at the same pull say 12 lbs. with which it is intended to use them in the field The mean coefficient of expansion of steel* may be used and temperatures should be taken about every hour

If available Invar tapes should be used on account of their low coefficient of expansion and of their smaller liability to rust See p 8 The distance between stations should be measured twice once in each direction One tape should be kept solely for comparison purposes

The measured lengths must be corrected for expansion of the tape as explained in Trigonometrical Traverses

(4) The length of a traverse leg should not be less than 300 yards, but it is not always an easy matter to arrange this—depending as it does on the nature of the country and character of the bush On the Anglo-German Gold Coast Boundary Commission the average length was considerably over 2000 feet whereas in the Gold Coast Survey an average of 500 feet was extremely difficult to get

Azimuth Stations—Mention has been made of azimuth observations and these must be taken frequently in order to check any errors of angular measurement They should be taken, with short legs at every 30th or 35th station Much however depends on local circumstances In the Gold Coast Survey it is found almost impossible to adhere to this owing to the amount of clearing it would involve in order to see the sun or stars in a convenient

* 0000062 of its length for 1° Fahrenheit

position near the prime vertical. Under these circumstances one has to be contented with taking observations for azimuth as native clearings in the vicinity of villages present themselves.

As a rule it is sufficient to take the mean of three sets of observations to the sun. The probable error should not exceed ±0″. When, however, it is found impossible, for reasons above stated, to get azimuth stations as close together as 30 legs, precautions should be taken to ensure a higher degree of accuracy and east and west stars, or better still, circumpolar stars at elongation should be observed.

The difference found to exist between an observed azimuth and the azimuth deduced through the traverse should be proportionally divided amongst the angles. This difference is composed partly of the angular errors of the traverse and partly of the convergency of the meridians. The proportional adjustment is sufficiently exact for practical purposes.

Example. An example is given on p. 48 of a portion of a traverse carried out by the British Party of the Togo-Gold Coast Boundary Commission. The headings at the top of each column explain sufficiently what is required in adjusting the various errors in order to obtain the final true bearing of each leg.

Computations. The computations of the co-ordinates are similar to those already explained in the Trigonometrical Traverse, but in this case the sine and cosine of the *true bearing* are used to compute the co-ordinates.

Latitude Deduced through Traverse.—Having now obtained the value of the co-ordinates of each point it is an easy matter to deduce the latitude corresponding to the value of the co-ordinates in the north and south direction.

In doing so it is better to calculate this for each azimuth station and to add the amplitudes in order to obtain the final difference of latitude.

To determine the latitudes and longitudes of the azimuth stations of a long traverse.—

If the legs are short—

Let n be the total northings or southings between two adjacent azimuth stations in feet, let M be the value in feet of 1″ of arc at the mean latitude, then the difference of the latitudes of the two stations is $\frac{n}{M}$ seconds of arc.

The sum of all the amplitudes of the arcs between the azimuth stations will give the amplitude of the arc between the terminal stations of the traverse.

Similarly if e is the total westings or eastings between two adjacent traverse stations in feet, P the value in feet of 1″ of arc of longitude at the mean latitude, the difference of the longitudes of the two stations is $\frac{e}{P}$ seconds of arc.

If the legs are long (over 1 mile) the latitudes and longitudes should be determined by the method described on p. 6.

When the final latitude has been calculated it can be compared with that obtained astronomically, but, as previously remarked, owing to our ignorance of the value of "local attraction" this is but an indifferent test of the accuracy of the traverse.

To give a comparison between two latitude stations, and to show the method of deducing latitude through traverses, the following table is taken from the results of the British Party of the Togo-Gold Coast Boundary Commission (see p. 47) —

Column 1 gives the names of the azimuth stations.

Column 2 the distance in feet between the stations measured along the meridian. These are the summation of the co-ordinates in the north and south direction.

Column 3 gives the amplitudes of arc corresponding to these distances.

Column 4 gives the values of the latitudes obtained astronomically at the two stations.

Column 5 gives the latitudes deduced through the traverse.

It will be observed that the difference between the final observed and deduced latitudes is 0″.84.

The mean of the deduced and observed values is taken as the true latitude

Form H, p 49, gives a further illustration of work of this nature It is taken from the same Boundary Commission and shows the total differences between all the latitude stations observed and deduced in the two independent traverses carried out by both divisions of the Commission

Errors to be expected —To recapitulate, we see that the errors to which a traverse is subject are —

Errors of chainage and angular measurement, called traverse errors

Errors of observed latitude, longitude, and azimuth

Of these, traverse errors vary considerably (from $\frac{1}{1000}$ to $\frac{1}{50\,000}$), depending chiefly on the character of the country

On the Boundary Commission already quoted the following results were obtained as the measurement between two co-incident points by two quite independent traverses

	Feet N	Feet W
British	279 335	24 698
German	279 347	24,679
Difference	12	19

If the first of these be taken as representing principally the chainage errors (the traverses running almost due north) the resulting discrepancy was $\frac{1}{23\,280}$

Astronomical observation errors (omitting "local attraction") should not exceed —

Latitude by zenith telescope	± 0'5
Longitude by telegraphic exchange of signals	± 3 0
Azimuth	±20'

Reduction to Mean Sea Level —When the length of each traverse line has been finally computed (but not adjusted), it remains to reduce it to mean sea level This is done by the same method as used in the reduction of measured bases —

$$\text{Correction to length of traverse} = \text{length} \times \frac{h}{R},$$

R is the mean radius of the earth,

h is the mean height of the line

General Scheme for carrying out a Traverse Survey.—The following is a general scheme —

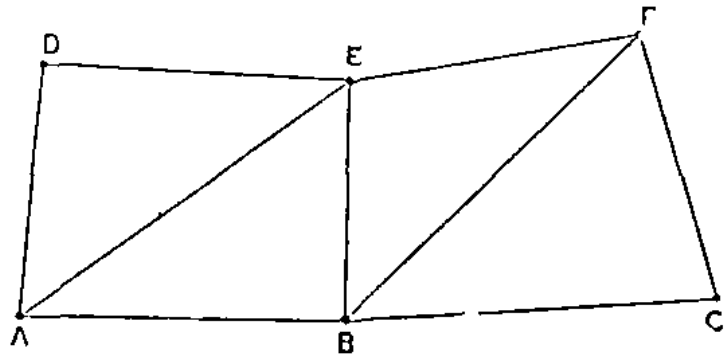


Fig 22

Each of the lines here represents a traverse of about 60 to 70 miles

FORM F

Name of Station	Distance in Feet of N Co-ordinate	Amplitude of Arc	Observed Latitude	Deduced Latitude
			°	° ′ ″
Baljas			8 10 30 19	
	32171 13	5 19 29		
Camp				8 15 49 30
	47199 74	7 41 41		
Kuruja				8 23 38 79
	16869 14	2 47 29		
Legon				8 26 26 08
	39723 85	6 31 13		
Salaga				8 33 1 21
	20183 60	3 20 23		
Kalandi				8 36 21 46
	38060 80	6 17 6		
Daka				8 42 39 06
	39899 61	6 35 88		
Kaleng				8 49 14 94
	28361 93	4 41 39		
Gwogi				8 53 06 33
	21666 44	3 34 85		
Djonayire				8 57 31 18
	1 372 88	2 32 —		
Lillar (near 9th Ierree)			9 0 2 88	9 0 3 72

FORM G

Road Traverse 9th Degree N L Pabiyá

Stations	Included angle from angle book	Deduced bearing	Azimuth observed	Error divided proportionally	True bearing	Horizontal distance in feet	Co ordinates		Co ordinates from origin (Station 1)	
							x	y	x E + W −	y N + S −
	° ′ ″	° ′	° ″	″	° ′ ″					
1 2	223 40 6	342 18 44	342 18 44		342 18 44	1355 0	− 411 69	+1290 9	− 411 69	+ 1290 9
2 3	193 59 53	356 18 37		− 2	356 18 35	2020 4	− 130 04	+2016 2	− 541 73	+ 3307 1
3-4	179 58 18	356 16 55		− 4	356 16 51	930 8	− 60 37	+ 928 82	− 602 10	+ 1235 9
4-5	120 48 9	303 5 4		− 6	303 4 58	1347 9	−1129 4	+ 734 06	−1731 5	+ 1970 0
5-6	238 18 44	1 53 48		− 8	1 53 40	3260 4	+ 108 03	+3258 6	−1623 47	+ 8228 6
6-7	179 43 26	1 37 14		−10	1 37 4	2377 7	+ 67 13	+2376 7	−1556 34	+10605 3
7 8	180 7 1	1 44 15		−12	1 44 3	2905 6	+ 87 93	+2904 25	−1468 41	+13509 5
8 9	179 58 43	1 42 58		−14	1 42 44	3182 3	+ 104 05	+3180 7	−1364 36	+16690 2
9 10	252 20 55	74 3 53		−16	74 3 37	2320 4	+2231 2	+ 637 2	+ 866 84	+17627 4
10 11	170 9 7	64 12 0		−18	64 11 12	2699 1	+2430 0	+1175 0	+3296 84	+18802 4
11 12	179 58 29	64 10 29		−20	64 10 9	1757 5	+1581 9	+ 764 0	+4978 74	+19566 4
12-13	180 9 5	64 19 34		−22	64 19 12	2744 3	+2473 2	+1189 2	+7451 9	+20755 6
13 14	110 37 19	354 57 23		−24	354 56 59	1496 5	− 131 74	+1490 7	+7320 16	+22246 3
14-15	179 40 15	354 37 38		−26	354 37 12	3067 6	− 287 62	+3054 1	+7032 54	+25300 4
15-16	170 16 40	344 54 18		−28	344 53 50	2633 8	− 686 24	+2542 8	+6346 30	+27843 2
16 17	179 55 56	344 50 14		−30	344 49 44	3010 5	− 787 75	+2905 6	+5658 55	+30748 8
17-18	180 21 55	345 12 9		−32	345 11 37	2643 9	− 675 06	+2556 1	+4972 89	+33304 9
18-19	179 57 36	345 9 45		−34	345 9 11	1972 8	− 437 17	+1552 6	+4377 4	+34837 5
19 20	178 49 33	343 59 24		−36	343 58 48	1584 1	− 505 51	+1907 0	+3340 23	+36744 5
20 21	179 49 23	343 48 47		−38	343 48 9	3923 8	−1094 5	+3768 0	+2845 73	+40512 5
21-22	182 28 56	346 17 43	346 17 4	−39	346 17 4	4555 4	−1081 1	+4177 3	+1765 6	+44689 8

Part II

Comparison of Traverse and Astronomical Amplitudes

Latitude station		Traverse amplitude	Observed latitude	Astronomical amplitude	Remarks
		° ′ ″	° ′ ″	° ′ ″	
British	Padjai	0 49 37 54	8 10 51 19	0 41 13 65	Latitude mean of 3 pairs N. at 18 stars per = ± 0″37
	Pillar	0 46 11 46	9 0 2 88	0 41 8 33	1 = ± 0 114
	Patenju	0 45 27 15	9 46 11 21	0 45 31 83	2 = ± 0 73
	Gambaja		10 31 42 10		2 = ± 0 101
		2 21 11 14		2 21 11 80	Difference = 0″77
German	Dubamontu	° ′ ″	8 7 49 86	° ′ ″	Latitude mean of 5 pairs N. at 18 stars per = ± 0″73
	Pillar	0 52 9 24	8 59 59 11	0 52 9 26	7 = ± 0 31
	Yendi	0 26 42 52	9 26 39 49	0 26 40 20	1 ?
	Gushiokho	0 28 44 58	9 55 25 85	0 28 46 45	1 ?
	Pion	0 21 11 1	10 16 35 90	0 21 10 05	1 ?
		2 8 47 7		2 8 46 04	Difference = 1″66

Observations for latitude are made at each of the stations A, B, C, D, E, and F, and, wherever possible, telegraphic signals are used as a means of obtaining differences of longitude

Approximate Adjustment—For any two stations such as A and D, we have an amplitude in latitude from the traverse, and one from the observed latitudes at A and D Take the mean of the amplitudes as the true amplitude and take as the true values of the latitudes at A and D, values which differ by the same amount from the observed latitudes, in opposite directions Treat the longitudes (if any have been determined telegraphically) in a similar way For a more rigorous method of adjustment, see Chapter XVII

Recapitulation—To recapitulate, the principal points to be observed are —

(1) The clearings should be as straight as possible,

(2)*The longer the legs of the traverse the better the result and the more rapid the work,

(3) Great care must be taken in centering the instrument,

(4) The shorter the leg the greater must be the care in centering, observing and bisecting,

(5) An azimuth should be observed at every 30 stations, if possible,

(6) Chain or tape each distance twice,

(7) Read at least two arcs in taking the included angle,

(8) Compute as you go along, the clearing generally delays the observing and an opportunity then presents itself for computing

* This does not apply to *subtense* traverses

CHAPTER V

SUBTENSE METHODS AND TACHEOMETRY

THE general principle of subtense work and tacheometry is the measurement of the angle subtended at the observer by a short measured length at a distance In the simplest case suppose AB to be a bar placed horizontally, C the centre of the bar, O the position of the observer Let AB be at right angles to OC Let $AOB = \alpha$, $AB = l$



Fig 23

Then
$$OC = AC \cot AOC$$
$$= \frac{l}{2} \cot \frac{\alpha}{2}$$

Hence if the length of the bar AB is known the measurement of the horizontal angle AOB is sufficient to determine the horizontal distance of the bar from the observer

The angle AOB may be measured —

(*a*) On the arc of a theodolite
(*b*) By a movable micrometer wire in the diaphragm of a theodolite
(*c*) By fixed wires in the diaphragm of a theodolite in which case AB must be a graduated bar and the graduations intersected by the fixed wires must be read

The distance AB may be —

(*b*) A bar with 2 fixed discs on it at a known distance apart
(*e*) The length between 2 signals the distance between which must be measured each time they are set up,
(*f*) A graduated bar, such as a level staff,
(*b*) and (*f*) may be either vertical or horizontal

Eliminating the combinations (*c*) (*b*) and (*e*) (*e*) which are impossible and (*a*) (*f*) (*b*) (*f*) which are unsatisfactory it is seen that there are eight practicable and useful methods of determining distances by measuring the angle subtended at the observer by a known short length To this it may be added that as regards (*e*) there are two distinct types of instrument which involve different computations

Nomenclature

Tacheometry (called also in American books Tachymetry or Tachyometry) is a system of 'rapid measuring' as above described and includes all the eight variations just mentioned The system was first largely employed in Italy in 1820 but had been used in the eighteenth century in England These various methods are clearly divisible into two main classes —

A Those in which the angle at the instrument is a variable one and the distant base is constant or specially measured—these we shall call *subtense methods*,

B Those in which the angle at the instrument is constant and the base is variable i.e., measured on a graduated bar—these we shall call *tacheometer methods*

A Subtense Methods —(1) *With an ordinary Theodolite and a* 10 *or* 20 *foot Bar*

Let a bar over 10 feet long be supported horizontally on a tripod or on trestles, the bar being at right angles to the line joining its centre to the observer's theodolite Let there be two discs on the bar whose centres are exactly 10 feet apart Intersect the left disc with the vertical wire of the theodolite, record the horizontal readings Now move the upper plate with the slow motion screw and intersect the right disc

Leaving the upper plate clamped move both plates with the slow motion screw of the lower plate till the wire again intersects the left disc The right disc is then again intersected by means of the slow motion screw of the upper plate This process should be repeated say 10 times and the final reading of the right disc is recorded The observer then has the initial reading of the left disc and the final reading of the right disc, the difference between these two readings divided by 10 will give him a fair measure of the angle subtended by the bar

The two readings mentioned are the only ones really required, but as a precautionary

Fig 24

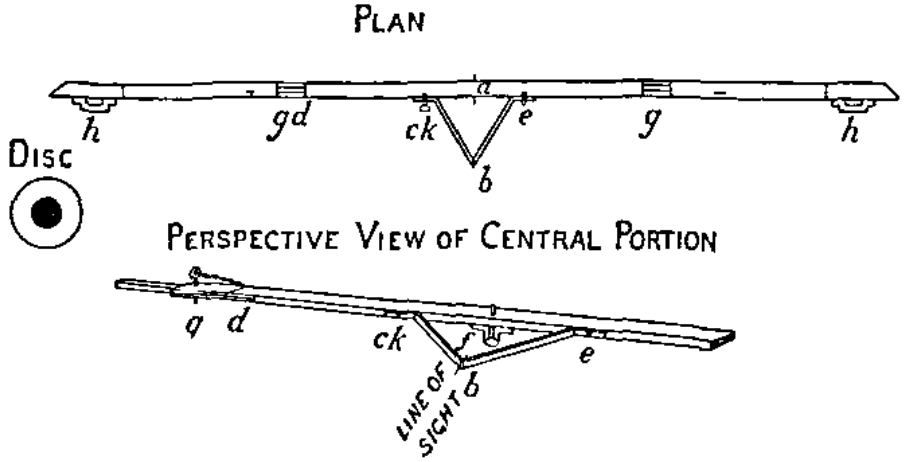


Fig 25* Subtense Bar used on the Survey of India

measure to give a check, it is a good plan to record also the reading of the right hand end of the bar the first time it is taken

The difference between the readings of the two ends of the bar will give a rough value for the subtended angle sufficiently near to expose any error in counting the number of times the process has been repeated

This method was introduced into the Indian Survey by Colonel Tanner, who used it largely in the Himalayas Colonel G Strahan also employed it exclusively for the traverses of the Nicobar Islands The mean linear error in the latter case which was very unfavourable, was about $\frac{1}{1}$

Bars have been used in India of 2 feet 10 feet and 20 feet In the Himalayas the 20 foot bar was in general use this had 12 inch circular discs, and under favourable conditions a ray 3 miles long could be measured with reasonable accuracy A 10 foot bar with 8 inch discs will give good results up to 1½ miles

Description of fig 24 —The bar is made of hard wood in three sections The central section is square in cross section $1_{\frac{1}{8}} \times 1_{\frac{1}{8}}$, with iron sockets 6 inches long $g\ g$ at each end into which the outer portions of the bar fit being pinned into place by the pins g' The outer ends of the bar carry iron sockets $h\ h$, which have the recesses in them accurately machined out Into these sockets the discs a fit by means of carefully fitted hooks on their backs The

* Extracted by permission from Hints to Travellers

discs are of wood 10 inches in diameter, painted white with a black centre Black cloth covers are also carried to fit tightly over the discs in case of working with a light back ground

In the centre of the bar is a brass socket plate, by means of which the bar can be attached to a tripod

The sighting arrangement consists of a light iron frame hinged at *e*, *f*, and *k* The pin of the hinge *f* carries a point on the top and a similar metal point is fixed at *a*, in the centre of the bar and the other end is fixed by a thumb-screw, *c*, in such a position that the line joining *ba* is at right angles to the line joining the discs For travelling the thumb screw *c* is unscrewed and the frame is closed up against the bar, in which position the thumb screw screws into the hole *d* in a metal plate affixed to the bar The bar is fixed in position by an assistant looking along the sights *a*, *b* and laying them on to the theodolite

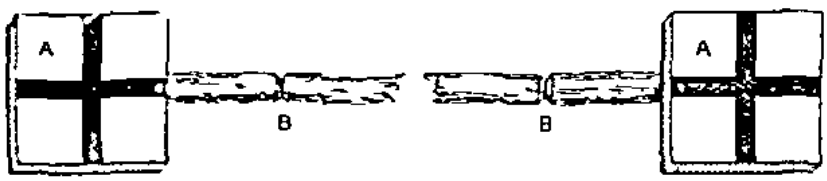


Fig 26 *

Fig 25 represents another form of rod and one more easily made, though not calculated to give such accurate results A A are two boards 1 foot square painted white with a black cross on each These are fastened on a bamboo B B in such a manner that the centres of the crosses shall be a known distance apart

When using the rod in a vertical position it will often be found convenient to fasten a stick to it, extending about 2 feet beyond one of the boards This when placed on the ground takes the weight off the rod and helps the assistant to keep it steady

(ii) *With an Ordinary Theodolite and Two Signals*

(See also p 41)

The line joining the signals must be at right angles to the line joining the observer and the central point between them The signals may be poles fixed vertically into the ground and stayed with rope or wire guys It is desirable that the ground line should be visible from the observer otherwise the poles must be very carefully plumbed In fixing the poles the right angle may be determined by compass or by tape, thus

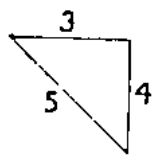


Fig 27

or, if available by a theodolite The space between the poles should subtend at the observer an angle of from 8 to 12 minutes The reason being that if we admit the possibility of an error of 1 this will in a total measurement of 8 be equivalent to an error of about $\frac{1}{800}$, which should not be exceeded The distance between the centres of the poles should be carefully measured with a tape this distance will vary from 10 feet to 100 feet, according to the length of the ray For long rays conspicuous marks must be fixed at the top of the poles to attract attention in India and W Africa wicker baskets about 3 feet in

* Extracted by permission from Hints to Travellers

diameter, have been found useful for the purpose The poles will be from 10 to 30 feet long One of the longest rays thus determined was one of 11½ miles, measured on the Sierra Leone Liberia Boundary Commission of 1903, the base (which on account of local conditions was somewhat small) subtended an angle of 5 47 and was 101 feet long, 5 sets of 10 repetitions of the angle were observed Experience shows that in such long rays it is desirable to use dark poles against a white back ground

The Observations —As a rule 3 sets of 10 repetitions should be taken for ordinary rays of 2 or 3 miles, for longer rays a larger number is necessary Each new set should begin on a different part of the arc, *i e*, if the left signal reads about 0° on the first set, it should read about 35° on the next set and so on Vertical angles should be taken also, 2 on F R, 2 on F L (Required for determination of heights)

The Computations —If α is the mean observed angle,
b the length of the base
d the required distance,

$$d = \frac{b}{2} \cot \frac{\alpha}{2}$$

(iii) *With a Theodolite fitted with an Eyepiece Micrometer, and a Bar of Fixed Length*

The eye piece micrometer screw moves a wire in the diaphragm The wire is made to intersect the discs or marks at each end of the bar, and the difference between the two readings of the micrometer head gives the subtended angle in terms of the divisions of the head This process can be repeated many times with great rapidity and the mean, say, of 10 readings, will give a good value of the angle

A table should have been previously prepared giving the distances corresponding to a series of intervals of the micrometer head This table should be determined by *actual experiment* The reason is that owing to optical principles, the angles measured cannot be taken as those subtended at the vertical axis of the instrument, but at a point in front of this (see also p 55) It is easy to show, if the focus has not been altered,* that if M is the micrometer reading of a staff of fixed length, A and B constants to be determined d the required distance *from the vertical axis of the instrument*, $d = \frac{A}{M} + B$ A few experiments at various distances will be sufficient to determine the constants A and B A table should then be prepared

This method is sometimes very valuable and was used in the traverse in Abyssinia, the horizontal angles being measured with the same theodolite, where the route followed was in many places so rough and blocked with troops and baggage animals, that any other system of measurement would have been impossible The rapidity with which such a traverse can be carried on depends upon many considerations but chiefly upon the length of the shots that can be taken In the Abyssinian expedition of 1868, a traverse was carried with one of these instruments from Adigerat to Magdala without any break of continuity, the daily rate of progress averaging 5 miles, and being occasionally as much as 8 miles After this run of some 300 miles nearly due north and south, the observed latitude differed from that given by the traverse by about ¼ of a mile

The bar may be similar to those described on p 52 For preference the bar should be horizontal Rays a mile or two long are convenient

The horizontal angles between the stations should be observed as in a chain or tape traverse

The subtense methods just described are more generally useful to the topographer than the tacheometer methods, which will be next dealt with

* The instrument must be used at solar focus

B Tacheometer Methods—(i) *An ordinary Theodolite, with Two Fixed Wires in the Diaphragm and a Graduated Bar*

The theodolite is provided with two horizontal wires fixed in the diaphragm at equal distances from the axis of the telescope The staff is held vertically, the divisions of the bar intersected by the fixed wires are read and these are sufficient to determine the distance of the bar from the observer

Now, an ordinary theodolite has a plane convex object glass and an eye piece and it is easy to show that the point at which the angle subtended by the fixed wires is constant is not on the vertical axis of the instrument, but at a distance $f+c$ in front of the vertical axis measured towards the bar, where

f is the focal length of the telescope (at solar focus),
c is the distance of the centre of the object glass from the vertical axis

f can be measured by focussing the telescope on a distant object and measuring the distance from the centre of the object glass to the diaphragm

Hence, if d is the required distance from vertical axis of theodolite to centre of bar, the bar being held vertically, the telescope being horizontal, if

a is the distance intercepted on the bar by the wires,
l a constant,

$$d = l\ a + (f + c)$$

l should be determined by experiment by taking several readings of the staff at 100, 200 and 300 feet distant, measuring from a point $f + c$ in front of the vertical axis

If the rod is held vertically, but on a different level from the telescope, so that the latter is inclined at an angle α to the horizon when pointing at the centre of the rod, using the same notation as before,

$$d = l\ a\ \cos\ \alpha + (f +)\cos\alpha$$

and the difference of height (h) between the axis of the theodolite and the mean reading of the staff is given by the expression

$$h = (f + c)\sin\alpha + a\ k\frac{\sin 2\alpha}{2}$$

The rapid and effective use of tacheometer methods thus clearly involves the employment of tables There are several such tables in existance * It will be seen that the method is not so straightforward as might at first sight appear

American experiments appear to show that the limiting length of the rays should be about 800 feet In English practice this limit is usually about 600 feet, but in exceptional cases rays of 1,200 feet may be measured On account of the shortness of the rays this method is more suitable for large scales than for small and generally it is more applicable to engineering than to topographical surveys Rods from 10 to 15 feet long should be used—they may be specially graduated or may be level staves

(ii)

By the introduction of a converging lens between the object glass and the diaphragm of a theodolite, measurements can be read directly from the vertical axis without the necessity of considering the quantity $f +$ The term tacheometer is best confined to instruments which have this optical arrangement If there are two fixed wires in the diaphragm of such an instrument and a graduated staff is observed the distance from the vertical axis

* See Theory and Practice of Surveying, by J B Johnson New York Wiley and Sons Messrs Troughton and Simms make an instrument of this type

to the staff varies directly as the number of graduations intercepted If the central l of vision makes an angle α with the horizon, if d is the required horizontal distance of the st from the vertical axis, if h is the height of the point at which the central line of vision strikes t staff, let m be the number of divisions between the wires,

$$d = k \ m \ \cos^2 \alpha, \text{ when } l \text{ is a constant,}$$

$$h = d \tan \alpha$$

It is desirable in this case also to use tables The instrument is more generally suitable for large scale surveys than for topographical work

There is considerable literature on the subject of subtense methods and tacheometry Amongst other books may be mentioned —

"The Tacheometer," N Kennedy, M I C E
"Hints to Travellers"
"Encyclopædia Britannica,' vol XXXIII
"Theory and Practice of Surveying S B Johnson New York Wiley and Sons
"A Treatise on Surveying,' Middleton and Chadwick, Spon, London

There are many special instruments depending on the same principles, but they are not generally of much value in topographical surveying

PLATE IV



SERVICE PLANE TABLE 18 × 24

CHAPTER VI

PLANE TABLING

The plane table is merely a portable table The table or board can be carried separately from the stand or legs the stand is usually a folding tripod For greater compactness, the stand is sometimes made of a collapsible pattern The adjuncts to the plane table are the sight vane, called also the sight rule or alidade and the box or trough compass, the plane table should also be provided with a waterproof cover

A convenient size is the Service pattern of which the board is 18 × 24 (see Plate IV)

The sight vane* should be about as long as the shortest side of the table, and the fittings should be of gunmetal or brass not iron or steel A common defect of sight vanes is that the slit in the rear vane is too small When working in hilly country the centres of the tops of the vanes should be joined by a string taut when the vanes are upright, to enable rays to be taken on steep slopes It is convenient as in the Service pattern for the sight vane to be graduated with useful scales notably 2 inches to 1 mile

The trough compass should not be combined with the sight vane The 6 inch trough compass in mahogany box with sliding lid which throws the compass off its pivot is the best Trough compasses should be stored horizontally They can be adjusted for dip' by tying string round the elevated end and dropping sealing wax on to the string

Mounting a Plane table—With an ordinary plane table which has a plain board (and all arrangements of clips should be eschewed) if time presses the only thing to do is to pin the paper on to the board with drawing pins and if the paper is linen backed so much the better

But if time allows, 'mount' the plane table as follows —

Get some fine linen about 8 inches larger in each direction than the board damp this slightly, and paste it on the underside of the board only The paste should be made of the finest flour available cornflour is the best Now take a piece of drawing paper the same size as the linen, damp it on the wrong side paste the linen all over and smooth the paper down on to the linen paste also the overlap of paper on the underside of the table Put in a few pins temporarily on the underside these can be removed in about 12 hours when the table will be ready to work on

When the work is finished and the field sheet is removed from the board its edges should be bound with tape

The reasons for mounting paper on linen are that it gives a good surface to work on and renders the paper less liable to be torn and somewhat less liable to be affected by expansion caused by wet and damp

SURVEYING AND SKETCHING WITH THE PLANE TABLE

The plane table is by far the most useful instrument employed in filling in detail

The following are **general maxims** which should always be observed —

(1) See that the leg screws and clamping screws are taut before beginning work

(2) Spread the legs widely especially with collapsible patterns the stiffness of the table largely depends on the spread of the legs In soft soil the legs should be well pressed into the ground The board should be horizontal

(3) Always keep the pencil sharp, there should be no error in essential features greater than the thickness of a pencil line With acute intersections which must sometimes be used, fineness of line is absolutely necessary Points required afterwards for

* The sights are not used in America and although they take away from the simplicity of the instrument they undoubtedly increase the accuracy of the work

interpolation should be fine dots surrounded by a circle No good results can be expected with a blunt pencil

(4) When it is required to draw a ray from a point, put the pencil upright on the table with the edge of the base just touching the point, and lay the sight-vane against the pencil Or instead of a pencil some expert plane tablers use the finger *Pins should never be used*

(5) When drawing a ray from a dot, set the point of the pencil into the dot first, so as to get the correct angle at which the pencil should be held when drawing it along the sight vane Without this precaution large errors creep in

(6) Whenever the plane table has to be set up or oriented by a previously drawn short ray it is important that the ray, when it is first drawn, should be extended by marking short lengths of it at or near the edges of the board These are called 'repere' marks and give a good line along which to lay the sight vane

(7) When drawing a ray to a distinct object mark its approximate position, as estimated, by a small circle on the ray Write the name of the object along the ray, to assist identification it is sometimes useful to draw a small sketch of the object at the end of the ray

The steps to be taken in making a plane table survey are the following —

1 **Plot the Graticule** —The method of doing this is fully described in Chapter XI Scales of latitude and longitude should be drawn on the board

2 **Plot the Trigonometrical Points** —The latitudes and longitudes of the trigonometrical points having been computed as described in Chapter III, the points are plotted with reference to the graticule lines and by means of the scales of latitude and longitude At the outset and before the graticule has had time to get distorted by expansion or contraction of the paper, it is perhaps somewhat more accurate to plot the points from the scale of inches used in constructing the graticule, by converting into inches the intervals in latitude and longitude from the graticule line

3 **Test the Plotting** by going to a trigonometrical station, lay the sight rule along the line joining this station and any distant visible station Move the board until the distant station is intersected by the vertical wire of the sight-rule, then clamp the table See if the other points are in their correct positions by aligning the sight rule on them Any point incorrectly plotted will easily be detected

Now place the box compass on the table (away from the area to be surveyed) move the compass until the needle points to the centre graduation, and draw a pencil line along each side of the compass box These lines will mark the magnetic north, and by their means the table can subsequently be set up approximately Remove the compass

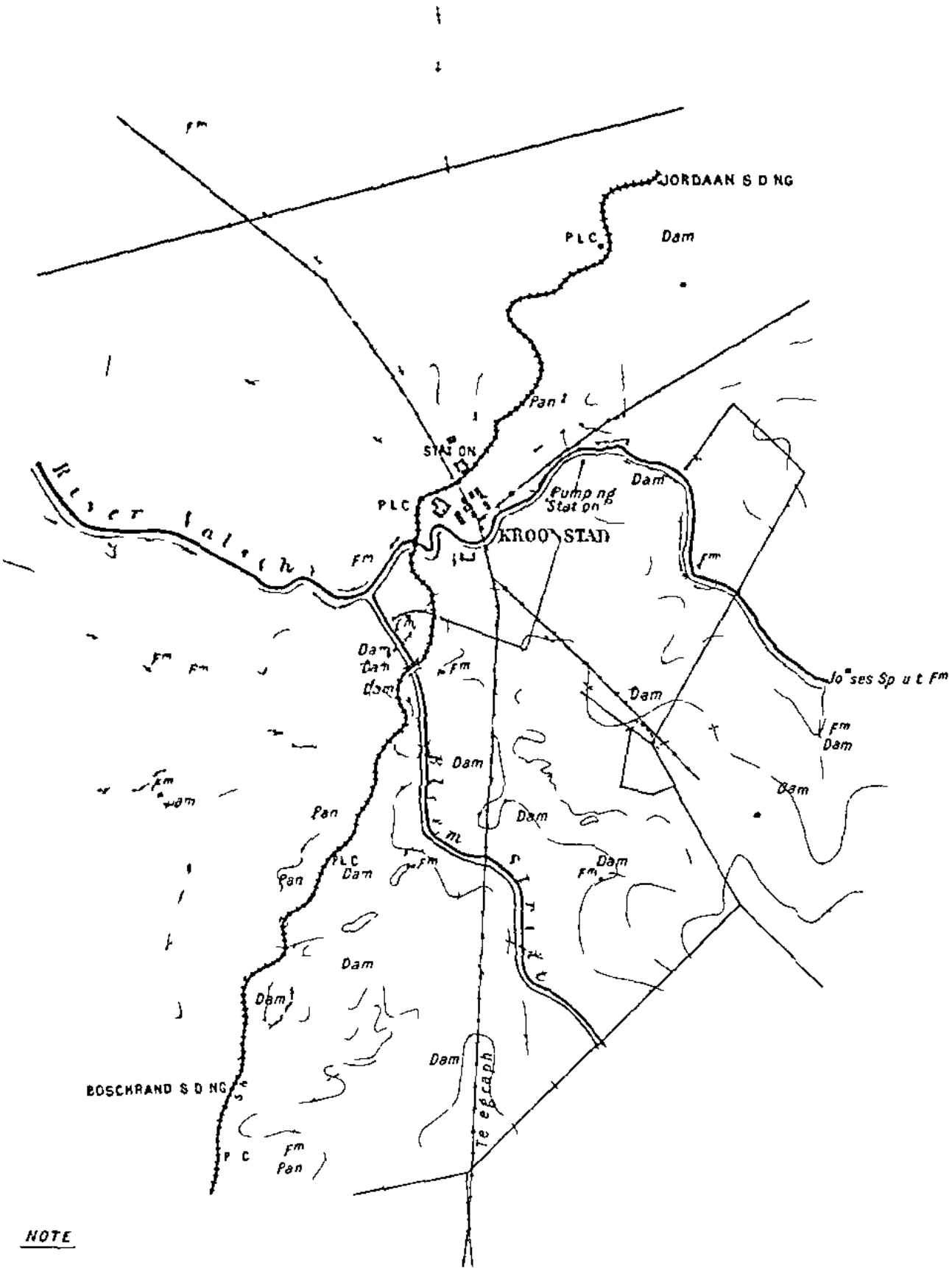
4 **Fix Points by Intersection** —At this station, and at every other point where the plane table is accurately set up rays should be drawn to all points which can be easily identified or are likely to assist in the execution of the work Along all such rays should be written a brief description occasionally it is useful to draw a small sketch of the object at the end of the ray and a small circle should be drawn on the ray in the supposed position of the object

A position fixed by intersection of 3 rays may be relied on If a point has been fixed by only 2 rays it should be considered doubtful, and should not be used afterwards for interpolation

5 **Fill in the Detail, mainly by Interpolation** —Interpolation, or fixing by resection from three known points, sounds a very formidable process, but is in reality very simple It is the principal means by which the bulk of the detail should be fixed The method is as follows —

Set up the plane table at any point from which three previously fixed points can be seen These should be trigonometrical points if possible Orient the table roughly by the trough

EXAMPLE of SMALL SCALE PLANE TABLE WORK
(IN UNDULATING COUNTRY)



compass, and from the three fixed points draw back rays If these three rays pass through a point, this point is the required position If they do not pass through a point, the rays will form a small triangle called the "triangle of error" The true position is now to be determined by the following rules —

I If the "triangle of error" is inside the triangle formed by the three fixed points, the position is inside the triangle of error, and if outside, outside

II* In the latter case the position will be such that it is either to the left of all the rays when facing the fixed points, or to the right of them all Of the six sectors formed by the rays, there are only two in which this condition can be fulfilled

III Finally the exact position is determined by the condition that its distances from the rays must be proportional to the lengths of the rays

In the attached example, for instance —

By condition I the point must be outside the triangle of error,
" " II " " " in sector 6 or in sector 3,
" " III " " " in sector 6, since the distances from it to the rays must be proportional to the lengths of the rays, and by estimation it will be where shown

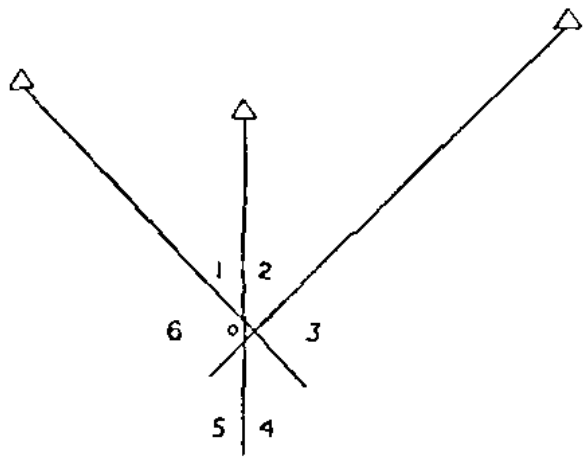


Fig 28

Having thus determined the position place the sight rule along the line joining this and the most distant of the points used, set the sight rule on the point by shifting the plane table, clamp and test on the two other points If there is still an error (which should, however be much smaller) go through the process again

The best position is inside the triangle formed by the three fixed points, of which two are near and one is distant Accuracy of *position* is ensured by two points being near, accuracy of *setting* is ensured by sighting on the distant point And in general, fix from near points, set by a distant point

It is very necessary to be able to interpolate by this method both rapidly and accurately It is the essential foundation of all good topographical plane tabling The plane tabler in open country need not pace or measure a yard after he has fixed his base In addition to the speed which results from a free use of interpolation there is also a gain in accuracy, since there is no piling up of errors and each fixing is dependent only on the main intersected or other well fixed points

There is one case in which the method fails, viz, that in which the observer's position and the three points lie on or near the circumference of a circle The plane tabler should be on the look out for this, and not interpolate from points so situated

* Rule II obviously includes Rule I

compass, and from the three fixed points draw back rays. If these three rays pass through a point, this point is the required position. If they do not pass through a point, the rays will form a small triangle called the 'triangle of error.' The true position is now to be determined by the following rules —

I. If the "triangle of error" is inside the triangle formed by the three fixed points, the position is inside the triangle of error, and if outside, outside.

II.* In the latter case the position will be such that it is either to the left of all the rays when facing the fixed points or to the right of them all. Of the six areas formed by the rays, there are only two in which this condition can be fulfilled.

III. Finally the exact position is determined by the condition that its distances from the rays must be proportional to the lengths of the rays.

In the attached example, for instance —

By condition I the point must be outside the triangle of error.

" " II " " " in sector 6 or in sector 3.

" " III " " " in sector 6, since the distances from it to the rays must be proportional to the lengths of the rays, and by estimation it will be where shown.

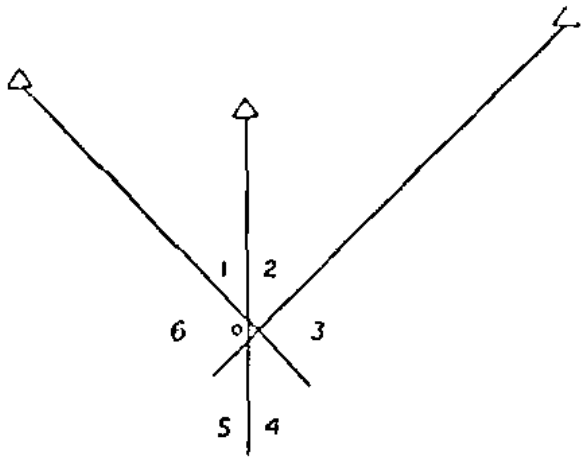


Fig. 28.

Having thus determined the position place the sight rule along the line joining this and the most distant of the points used, set the sight rule on the point by shifting the plane table, clamp and test on the two other points. If there is still an error (which should however, be much smaller) go through the process again.

The best position is inside the triangle formed by the three fixed points of which two are near and one is distant. Accuracy of *pointing* is ensured by two points being near, accuracy of *setting* is ensured by aligning on the distant point. And in general, fix from new points, set by a distant point.

It is very necessary to be able to interpolate by this method both rapidly and accurately. It is the essential foundation of all good topographical plane tabling. The plane tabler in open country need not pace or measure a yard after he has fixed his base. In addition to the speed which results from a free use of interpolation there is also a gain in accuracy, since there is no piling up of errors and each fixing is dependent only on the main intersected or other well fixed points.

There is one case in which the method fails, viz., that in which the observer's position and the three points lie on or near the circumference of a circle. The plane tabler should be on the look out for this, and not interpolate from points so situated.

* Rule II obviously includes Rule I.

It will have been noticed that the trough compass is only used to orient the plane-table roughly, the final fixing does not at all depend on the compass It is important that this should be remembered

Resection from Two Points—It will however, sometimes happen that only two fixed points or stations are visible, in this case the plane-table must be oriented by the compass, and rays must be drawn back from the two fixed stations intersecting in a point which must be taken as the required position It is clear that such a fixing depends entirely on the compass and may, therefore, be very inaccurate In parts of S Africa such a fixing would, on account of local magnetic attraction, be entirely worthless, and it is obvious that as a general rule compass fixings should be avoided

This method should, if possible, only be used for putting in detail, and not for throwing out points on which future work will depend

Whenever a fixing has been made the local detail should be drawn in, a combination of measurement and estimation should be used, the amount of estimation permissible will depend on the scale Thus on scales of 2 inches to 1 mile and smaller scales it is not necessary to pace the width of roads or size of houses, these are put in conventionally On a scale of 2 inches to 1 mile a distance of 8 yards is less than $\frac{1}{100}$ inch, so that any distance may be estimated which is not likely to be 8 yards in error, and so on When time presses, minute accuracy must be sacrificed

6 **Traverse Detail which cannot be Fixed by Interpolation**—It will sometimes happen even in open country that there are parts of the work, such as valleys and woods, in which plane table fixings cannot be made, it is then necessary to have recourse to plane table traversing Plane-table traversing has to be much used in flat country unprovided with prominent land marks and was so used in the mapping carried out during the operations in China in 1901

The method is as follows —Set up the plane table at some known point and orient it, draw a ray in the direction of some visible object (and the farther off this is the better), chain to this second point set up the plane-table there, place the sight rule along the ray previously drawn and turn the table until the sight-rule is on the first point, clamp, measure the chained distance along the ray and mark the second point on the plane table, draw a ray to some third point chain to it and go on as before Continue the traverse until it is possible to make an accurate fixing by interpolation, and then adjust the traverse between this fixing and the starting point Errors are inevitably generated in this sort of traversing which should therefore be penciled in quite lightly, as it will have to be rubbed out when adjusted

The adjustment is to be carried out as follows —

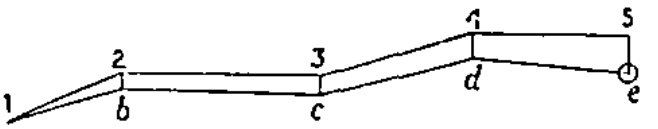


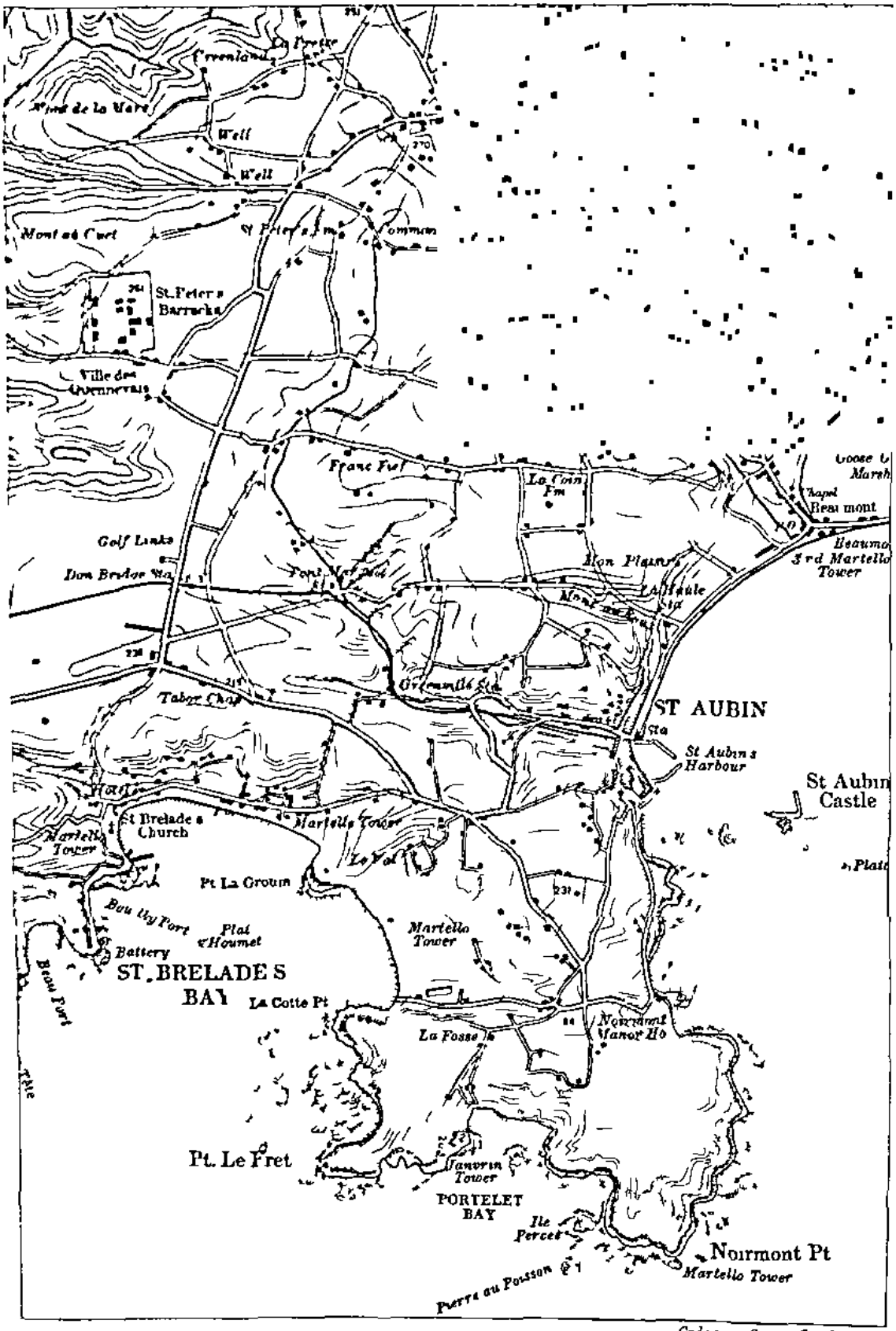
Fig 29

If 1 2 3 4 5 are the stations of a traverse, a fixing was made at 5, and the true position of this fixing was *e* draw lines through 2, 3, 4 parallel to 5*e*, and make 2*b*, 3*c*, 4*d* bear the same proportion to 1—2, 1—3 that 5*e* does to 15 Then the traverse as corrected will be 1, *b*, *c*, *d*, *e*

Or, instead of orienting by back rays as above described, the plane table may be oriented by compass alone But it is not advisable to use this method where it can be avoided as a little consideration will show, for a compass may easily be $\frac{1}{2}°$ out, which is equivalent to a lateral error of $\frac{1}{115}$, now, in aligning by a back ray, it is very unlikely that the sight rule in a ray 1200 yards long would be 10 yards off the object However, where the rays are very short, or the traverse is long or objects to line back on cannot be found, or where time is short it may be necessary to traverse with a compass

JERSEY

Scale – Two Inches to One Statute Mile 1/31680



Ordnance Survey Southampton

It is sometimes convenient to plot the traverse at the side of the board and subsequently to transfer it to its proper position when corrected

7 **Contouring**.—In the preceding description of plane tabling no mention has been made of contouring. As described in Chapter X, contours vary in accuracy according to the method adopted for the survey. They may be fixed by level, theodolite, water level, or clinometer or may be sketched in by eye. The method adopted depends on the scale of the map the time and instruments available, and the purpose of the map.

Speaking generally, so far as the scale is concerned, contours would be determined as follows:—

4 inches to 1 mile and larger		level, theodolite, or water level,
2	1 „	water level or clinometer,
1 inch to 1	„	„ „
1/2	1 „	clinometer or sketch contours,
1/4 „	1 „ and smaller	sketch contours

Where contours are determined by level or theodolite, the detail should be surveyed before the contouring is commenced. Where the contours are approximate contours put in by clinometer or sketch contours or form lines put in by eye, the contouring should be carried out during the survey of the detail.

To fix the ideas we will now suppose that it is intended to contour a 1 inch field sheet with the aid of the Indian pattern clinometer.

The Indian Clinometer is 9 inches long and has two vanes which are upright when in use, there is a sight hole in the rear vane and the front vane is graduated in degrees on the left side of its central slit and in natural tangents on the right. The sight hole is brought to a level with the zero of the front vane by a screw behind the rear vane, a level attached to the horizontal arm showing the position. The scale of natural tangents can be read by estimation to 3 places of decimals, the extreme range of elevation or depression is 23.

Suppose now that the plane tabler has fixed his position by means of resection from three known points of which the heights are known. He sets the clinometer on the table, levels it, and directs it on one of the known points, preferably the nearest. He looks through the sight hole and notes against which reading on the scale of natural tangents the point appears. He now measures the distance from his fixing to the point, multiplies the distance in feet by the natural tangent obtained, and the result is the approximate difference of height in feet between the plane table and the fixed point.

Thus, if the natural tangent is 043 depression, the distance 2000 yards, difference of level = 043 × 6000 feet = 258 feet, and if the height of the distant point was 401, and the plane table board was 3 feet above ground, the height of the ground at the plane table is clearly 258 + 401 − 3 = 656, and this height is marked against the fixing. It is not desirable to use this method for long rays on account of its comparative roughness, about 2 miles is a satisfactory limit. If values for the height can be got from more than one fixed point, it is advisable to take them and use the mean.

In place of actually computing the height a diagram may be used (such as Colonel Wahab's height indicator), from which the difference of height may be measured off.

Having now the height of the ground at the fixing, the next step is to determine the position of the nearest contour. Suppose that in the case quoted the fixing is on the top of a gentle rise, and that the ground slopes down uniformly in one direction at an angle of 1/2 as measured by the clinometer. Now a rule that all topographers should remember is that a slope of 1 is equivalent to a rise or fall of 1 in 57·3 for 1/2 this is 1 in 114·6, or 1 foot in 38·2 yards.

The height of the fixing is 656 feet, and if the contour intervals are 50 feet the nearest contour will be 650, 6 feet below the fixing, or a distance of 6 × 38·2 yards or 229 yards

away This point is marked on the table, and so are other surrounding points on the same contour

We must now define the terms vertical interval and horizontal equivalent

The **Vertical Interval** is the vertical distance between any two successive contours, and is usually given in feet

The **Horizontal Equivalent** is the distance on plan or on the map between any two successive contours, and is usually given in yards

The plane tabler should prepare a scale of horizontal equivalents for the particular interval in use Thus suppose the scale to be 1 inch, and the vertical interval to be 50 feet, the scale would be prepared as follows —

1 is equivalent to a rise of 1 foot in 19 1 yards,
1° „ „ „ 50 feet „ 955 „
2° „ „ „ 50 „ „ 478 „
&c, &c

We have therefore, this list of horizontal equivalents for a vertical interval of 50 feet

Degrees	Yards	Degrees	Yards	Degrees	Yards	Degrees	Yards
1	955	6	159	11	87	16	60
2	478	7	136	12	80	17	56
3	318	8	120	13	74	18	53
4	239	9	106	14	68	19	50
5	191	10	96	15	64	20	48

If the slope is uniform, the positions of the other contours will be found by stepping off the horizontal equivalent for the particular slope in question, from the first fixed contour, along the ray down which the slope was taken

But slopes, as a rule are not uniform throughout and this method should only be used for the distance up to which the slopes may be considered sensibly the same, the plane-table being then moved to the next change of slope and the same procedure carried out again there In mountainous country it is best to contour the top of a ridge or hill first, then when the valley is reached the lower contours can be put in

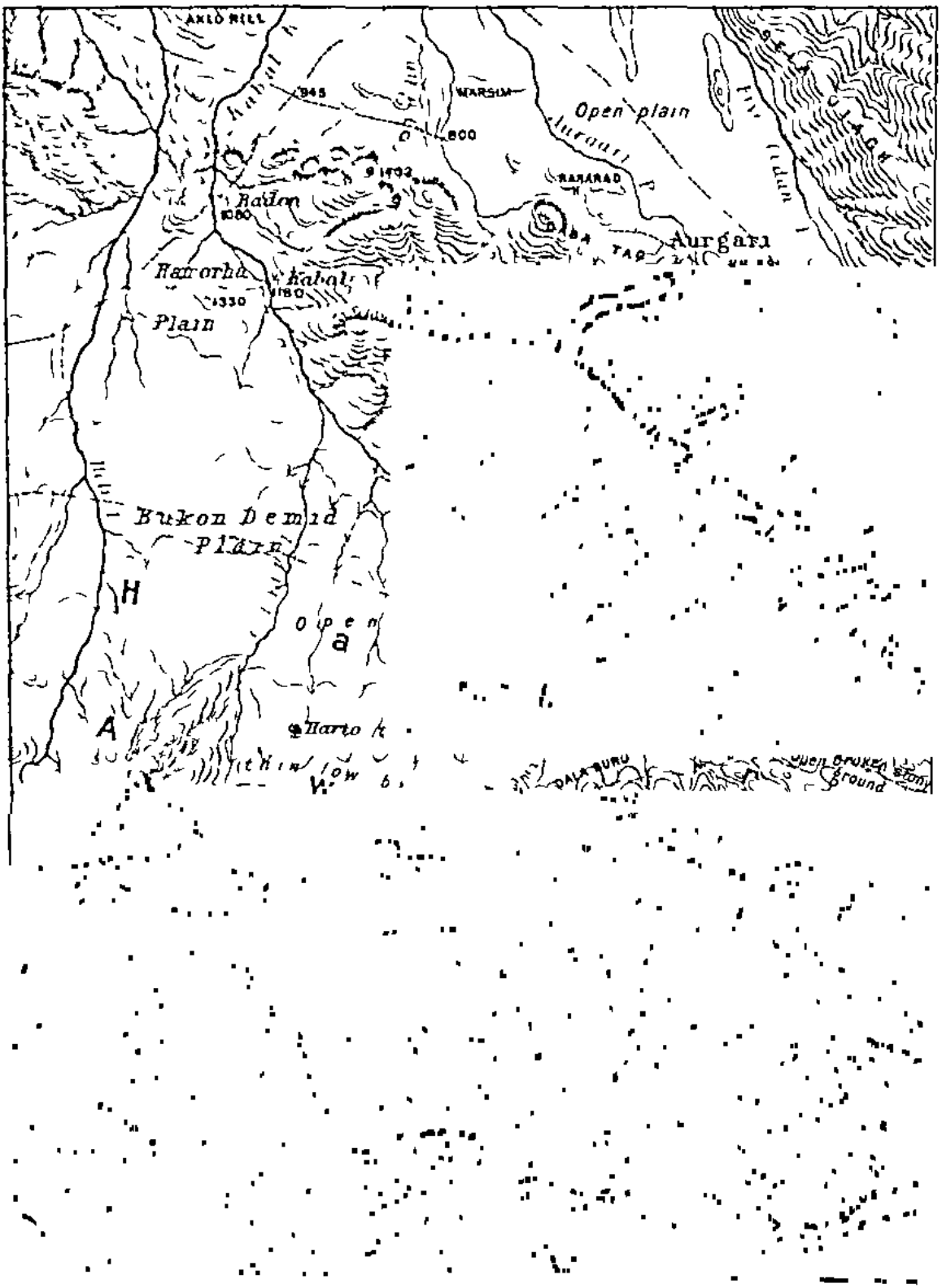
But if time presses, and the bottom of the valley is visible, the difference of level, and hence the number of contours, between the fixing and the bottom may be determined, and the contours spaced by eye, closer on the steep portions of the slope than elsewhere This is rapid approximate contouring

Generally in approximate contouring it is desirable to work in the first instance along ridges spurs and tops of hills putting in the valley contours subsequently

For a more elaborate method of contouring with the clinometer, see Chapter X

SPECIMEN or SMALL SCALE PLANE-TABLE WORK

(A portion of a survey in Somaliland during operations 1903 4)



Scale $\frac{1}{250\,000}$

FORM LINES
FOR SMALL SCALE WORK



Scale $\frac{1}{1.6\,720}$

Facsimile of a portion of a plane-table field sheet
Baluchistan Survey 1886

CHAPTER VII

SURVEYS UNDER ACTIVE SERVICE CONDITIONS

Rapid Triangulation – When officers are called on to undertake surveys, either on active service or [illegible] as explorers they map country with a view to [illegible] subsequent military operations the scene of their labours will generally be a more or less open one and extend over a considerable area. On such [illegible] there is every opportunity for more accurate work than is obtainable by mere sketching.

The object to be aimed at in such surveys is a rapidly executed map of an extended area by

(I) Triangulation with the chain from a measured base,
(II) Mere [illegible] of triangulation with astronomical observations,
(III) Mere [illegible] observations.

The last two methods are regarded as only suitable for rigorously accurate surveys of [illegible] importance. Each of them with liberation. It has however been proved on [illegible] that even under the limitations of active service it is possible, in a favourable [illegible] to execute work of a triangulation which though falling short of the accuracy to be attained in regular surveys can still be of immense use in eliminating errors and in facilitating the execution and the mapping and the subsequent compilation of different men's work by providing fixed points to which to hang the detail surveys.

The chief difficulties in this class of work are want of time, uncertainty as to when and in what direction a retreat may be made, the possibility that ground once passed may never be seen again, and [illegible] the risk of going far from camp without a strong escort.

To meet these difficulties the procedure to be followed though generally similar to that of regular triangulation requires certain modifications in practice of which the chief are —

(1) The use of smaller and more portable instruments.
(2) Less refinement in measuring the base.
(3) Less regard for symmetry in the triangles.
(4) Disregard of the rule of always observing all three angles of main triangles,
(5) The selection of natural marks to observe to, owing to the impossibility, as a rule, of making a preliminary reconnaissance and erecting artificial marks.

(1) It is obviously advisable to carry the lightest instrument that will give sufficiently accurate results.

Excellent small microscope theodolites are now made: – theodolites in which the divisions on the limbs are read by micrometers instead of verniers. Time is saved in reading and the readings are more accurate.

With such microscope theodolite the micrometer heads are graduated to 10 seconds and read to 1 second. These instruments are especially valuable when astronomical work has to be done. They will stand a good deal of rough usage. If this type of instrument is considered too heavy a Vernier theodolite must be taken. The smallest that has been used is a 3-inch theodolite reading to minutes in two small boxes with camel's stand. Weight with stand and boxes 19½ lbs.

(2) The base would be measured as described in Chapter II.

In selecting a site for a base it is necessary to consider the facilities afforded by the natural features of the surrounding ground for the extension of the triangulation. A stretch

of perfectly flat open ground, though admirably suited for the actual measurement, may be most unfavourably situated as regards extension, and, as a general rule, in surveys of the class now described, it is better to lay out the triangles symmetrically, and to run the risk of an error of a foot or so per mile in the measurement of the base, than to have a more accurately measured base and badly shaped triangles

In the first case the error will be carried through the work consistently, and may be eliminated later by measuring a check base on more favourable ground, in the second case, it is probable that still larger and discordant errors will be introduced, which will cause endless trouble to the computer and, perhaps throw out the detail surveyors

Bases of this description are seldom more than one or two miles in length, and time rarely allows of the measurement being made more than twice

As level ground is naturally selected for the base, and as high natural features are, if possible, chosen for the first stations fixed from it, it follows that the surveyor, when observing back from those stations to the ends of the base, will see them against a background of the surrounding plain or hills The result is that any artificial marks erected on the ends of the base will be very hard to see unless they are flashing instruments, such as heliographs Whenever therefore, it is likely that a base may have to be measured, it is desirable that the surveyor should have a couple of heliographers with their instruments at his disposal (N B—Camp looking glasses can be made very useful)

It may occasionally happen that there is no ground suitable for measuring a base at the starting point of a triangulation In such a case, if it is convenient to start from a long base, running nearly north and south, and if there are suitable hills some 10 or more miles apart and nearly on the same meridian an approximate value for the distance between their summits can be obtained by taking a careful series of latitude observations at each, and by observing the true bearing of one from the other See Chapter XV

Still, on account of instrumental errors and 'local attraction,' the resulting distance can be regarded as only approximate, and, although this method gets rid of the troublesome base measurement and extension of the triangulation from the base, the result obtained can never be regarded with confidence, and the earliest favourable opportunity should be taken of measuring a check base with a steel tape

(3) As mentioned previously, the ideal shape for a triangle is the equilateral Such triangles are unfortunately, seldom obtainable in rapid work, and though it is worth while expending some labour to avoid having any angle of the main triangulation less than 20°, still the work must not be regarded as valueless if angles of 15°, or even 10°, occur occasionally Distant intersected points can often be fixed within 200 or 300 feet by triangles whose apices do not exceed 4° or 5°

(4) The more rapid the work the less chance there is of the surveyor being able to observe all the angles of his principal triangles This need not, however, seriously impair the value of his work, if he makes a skilful use of his intersected points as described on p 69

The fact of all three angles not being invariably observed renders it far more necessary in rapid than in regular triangulation to fix each point by more than one triangle

(5) Whenever time and circumstances permit, a preliminary reconnaissance should certainly be made for the purpose of selecting and marking all the stations and intersected points. Unfortunately in rapid work it is seldom possible to do so, and consequently natural objects must in the main be relied on In these circumstances the measure of success with which rapid triangulation can be carried out must depend enormously upon the nature of the country The greater part of Afghanistan, Persia, and Baluchistan, abounding as it does with lofty, well marked peaks, which, owing to the clearness of the atmosphere, are visible from very great distances offers an ideal field for this class of work The forest clad hills of Upper Burma and the Shan States and of parts of tropical Africa, on the other hand, present very much greater, but not insuperable difficulties, and excellent work of this class has been

done in those regions, though with less rapidity than in the first mentioned countries When, however, the surveyor is called on to work in the forests of the Gold Coast, or on the rolling veldt of parts of South Africa, rapid triangulation becomes an impossibility Though at the first start, in a favourable country, it may be possible to make a small preliminary reconnaissance, and to erect marks on the first stations that are to be observed, still as a rule, the triangulator will be compelled to utilise for his observing stations and intersected points any natural marks that offer themselves such as tops of hills trees rocks, &c , and it is in the selection of these and in their identification from different points of view, that his skill and forethought will be most severely tried *Hints on triangulation from the highest point of a hill only*

General Sketch of the Method of carrying out a Rapid Triangulation — Assuming that the surveyor with a military expedition has arrived, with his instruments at the nearest point to the scene of operations to which he can proceed, and that he has a certain number of days in which to start his work before the force advances, he would probably proceed as follows —

Having taken a general look round from the nearest suitable elevation, he would proceed to select a site for his base and mark the two ends provisionally He would then measure its distance approximately by pacing, or by any other rough method and plot the two ends on a plane table on any suitable scale, 1 or 2 inches to the mile for choice From the two ends of his base he would intersect all the surrounding points that appear suitable for the first stations of his triangulation If time permitted he would extend his reconnaissance till he had embraced all the apparently suitable points in the required direction that he could fix approximately without moving his camp, and he would at the same time have cairns of stones or poles erected wherever the natural features were not sufficiently clearly marked for observing purposes As a general rule, these cairns should be of the smallest size compatible with their being clearly visible through the telescope at the required distance At very short distances a pole is better than a cairn, but if the latter is built, it need not be more than 2 feet high, and should have a sharp-pointed stone sticking up on its top

It is now possible to decide where to place the first stations and an inspection of the figures on the plane-table may show that an alteration is advisable in the length or position of the base, in order to make the triangles more symmetrical The ends of the base are now finally chosen, and marked with wooden pegs covered with small cairns of stones or mounds of earth, so as to be easily recognisable

The next step is to measure the base as accurately as possible under the circumstances, and to observe the angles from both ends of it If time permits, these observations should be *computed, and the lengths of the sides of the triangles fixing the first stations should be* obtained The true bearing of the base and the latitude of one end of it should also be determined astronomically

Next, the projection should be drawn on the plane table (p 93) The latitudes and longitudes of the points should be computed and plotted or if time does not allow this, the points must be plotted by bearing and distance *

On arriving at one of the near points that he has already observed the cairn must be taken down and the theodolite placed over the spot In order to make sure of finding this spot when the stones are removed, it is well to lay a couple of sticks or lines of stones so that their prolongations cut the highest point of the cairn at right angles When the cairn is removed, there will then be no difficulty in finding the exact point where the theodolite should stand When the observing is concluded, similar referring marks should be placed, to ensure that, when the cairn is rebuilt, its top is exactly over the spot where the theodolite stood

In addition to observing the ends of the base and the points observed from the base, fresh objects must be selected for observation in the direction in which the surveyor expects to move, with a view to their use as theodolite stations All natural features, too, which are

* The *triangulation chart* should not as a rule be on a larger scale than 4 miles — 1 inch (say $\frac{1}{250\,000}$) or the triangulator will run out of it much too soon The topography may be on any scale

likely to be of service as intersected points must be observed, in order that, when fixed, they may facilitate the delineation of the topography

In a regular survey, when the triangulator starts work he is provided with a plane table, on which all the points he has to observe are plotted with sufficient exactness to render it impossible for him to mistake or omit one of them In rapid work, on the other hand owing to the absence of a previous reconnaissance, the triangulator has to construct the diagram of his triangulation on his plane table as he goes along

Once the triangulation gets started clear of the base line and its surrounding stations—which, being necessarily rather close together are comparatively easy to recognise—the work of identification becomes more difficult, and to effect it with success the triangulator must trust to a skilful use of his plane table in the following manner —

Having oriented his plane table correctly, and having ascertained by calculation, intersection or resection the spot on it corresponding to the station from which he is observing the triangulator draws lines to each of the natural features that he has observed, and writes against each of them the name that he has given it in the angle book To this he adds an outline sketch of the hills as they appear to the naked eye and their estimated distances, together with any descriptive remarks that are likely to aid in their recognition from other points of view When the telescope discloses any peculiarities of shape that are invisible to the unaided eye, a sketch of the hill top as seen through the telescope should be made in the angle book

At the next observing station the same process would be repeated

From these two initial stations (the line joining them being as nearly at right angles to the line of probable route as possible), several hills that appear likely to serve as the next observing stations besides other objects to be used as intersected points will probably be fairly well fixed but others will remain still undetermined either on account of the acuteness of the two rays or because they have been observed from only one of the two stations

The force of circumstances, such as the direction of the next advance during military operations or the position of water the direction of the route, or the best site for a camp in other cases will generally decide which of the points observed to is to be made the next observing station When this point is a conspicuous hill there will be no difficulty in recognising it but the task is far from easy when, as often happens in mountainous country, on descending from the initial stations on to the low ground along which the line of march runs the observer finds that most if not all of the points to which the observations have been taken have disappeared from view

It is in such a case that the plane table becomes of the greatest value By its means the position of the observer on the line of march with reference to all points previously fixed, whether visible or invisible may always be ascertained by resection provided two of these are visible and sufficiently well situated to admit of their being used for this purpose From such resections rays should be drawn to other points and by this means a new series of points is obtained by the help of which the observer will be able to continue his advance without losing the means of finding his position

At the same time it will be necessary to ascend some sufficiently commanding hill near the line of march the position of which can be resected, in order to take second rays to such points as have not yet been sufficiently well fixed before the altered point of view changes their appearance beyond recognition

Supposing now that a hill has been reached which is believed to be a point previously observed to and from which it is now intended to observe the accuracy of the surmise can be tested as follows —

The plane table having been set up its position is resected from the fixed points that are most suitably situated If the fixing thus obtained falls upon the previous intersection or upon the single ray should only one have been taken there is little doubt that the hill has been rightly identified Once all doubt as to this has been removed all the other already intersected points can be easily recognised, if visible, by directing the ruler on them in turn

For the identification of the actual spot observed (the highest point of the hill for choice), with the theodolite the observer must trust to his recollection, aided by such notes and sketches as have been previously made

It will be seen from these observations how large a part of the difficulty in executing a rapid or reconnaissance triangulation consists in selecting suitable points, and in recognising them from different points of view, and how necessary practice with the plane table is, in order to make a proper use of its aid

This process will be much facilitated if circumstances allow of the surveyor visiting a hill some two to four miles on the right or left (with reference to direction of route) of his observing station, and of approximately the same height, from which he can get second plane table rays to his newly-observed points As the point of view will be so similar, he should have little difficulty in recognising them and though the intersections will be very acute if the points are distant still the approximate positions they will give will be most useful in aiding him to recognise his points

The same principle can be very advantageously applied to triangulation (see Fig 30)

Here the stations C and D have been fixed from A and B On visiting D, the triangulator selects F and G as his next forward stations, and observes to them There is

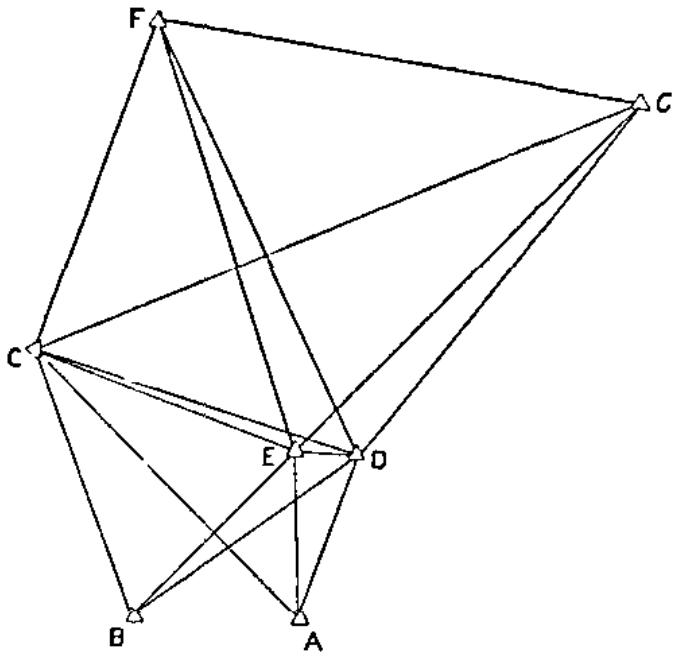


Fig 30

however, a considerable risk that when he visits C he may not be able to recognise these points with certainty He therefore makes a station on E, a hill near D, which he should have observed from A and B, and from it he observes with the theodolite to F and G If these hills are at all clearly marked, the triangles DEF and DEG, though very badly shaped, will suffice to enable him to fix the positions of E and G so nearly to the truth that, when they are plotted by their computed distances along the plane table rays from D, he cannot possibly have any difficulty in recognising them from C

In this way, too a second triangle is secured to fix each of the points F and G Should circumstances not allow of the theodolite being used at E, the intersection of plane table rays drawn thence with those drawn from D will probably fix the positions of F and G sufficiently accurately for subsequent identification from C

The length of sides permissible in the triangles depends upon the height of the stations and the extent of view from them, the nature of the objects observed, the clearness of the

atmosphere, and the maintenance of sufficient symmetry In some countries, as far as view is concerned triangles can be laid out of 30 and 40 mile sides, and intersected points as far distant as 100 miles may be fixed

The difficulties connected with this class of work, however, generally make it advisable to keep the sides of the triangles between 10 and 20 miles in length

Theodolite Observations—Unless the points to be observed are extremely well defined it is useless to multiply repetitions of the same angle When observing to natural objects under Service conditions, one observation on each face is as much as can generally be obtained, but the triangulator should satisfy himself, before taking down his theodolite, that the observations on the two faces agree within small limits If only one observation is taken to an object, no great reliance can be placed on it in view of the many possibilities of error in the observation, the reading of the verniers, and in the recording When, however, two accordant values have been obtained on different faces, it is extremely unlikely that there is anything wrong With regard to the selection of objects it is a good rule to observe everything that is observable (*i.e.*, every point that is sufficiently lofty to appear suitable for a station, and sharp enough to be intersected with accuracy), whether it lies in the probable direction of advance or not It constantly happens that observations to points far away from the direction in which the triangulator expected to move turn out not only useful but indispensable

In choosing intersected points, the great object is to fix such as will be useful for the topographers As they do not always require to be fixed with the same accuracy as the stations, it is not necessary that they should be so sharply defined, but they should be conspicuous points, about which, when seen with the naked eye there can be no mistake Many a hill appears to be an admirable point to observe to until it is examined through a telescope when it may turn out to have a flat, rounded top Such a hill, unless previously marked with a pillar or pole, would make a bad station, but an excellent intersected point for plane tabling purposes

Generally speaking, the highest point of a hill should always be observed, as a rule, there is little chance of making a mistake as to which of a group is the highest, but when there are several close together of apparently equal height, they should all be observed Occasionally it happens that the highest point, though suitable for the theodolite to stand on, and easily marked by a cairn when visited offers no point, when first seen, that can be intersected with any accuracy In such a case, if a little below the top there is a conspicuous rock or bush, it should be observed to and the angle can be corrected afterwards to the actual position of the theodolite

As each point is observed for the first time, its outline, as seen in the theodolite, is carefully sketched in the angle-book If possible it is entered under its real name but as this is seldom obtainable for a distant hill, it is usual to give it some descriptive name, such as Black rock, Jagged peak &c, or else to give it a distinguishing letter or number Whatever designation is given should be adhered to throughout the angle-book and computations If eventually a reliable name is obtained, all the entries can be changed together

Computations—The method of computing rapid triangulation is similar to that already described except that the computer must allow himself more latitude in dealing with any excess or defect on 180°, when the three angles of a triangle are observed, as it is seldom the case that all three are equally trustworthy, owing to the varying nature of the marks observed If the computer is familiar with the method of calculating the latitudes and longitudes of the triangulated points, he will probably find it best to make it his practice to compute them in spite of the additional labour involved Plotting by latitude and longitude is far more accurate than building up triangles by distances, and the advantage for computation of having all the topographical sketches properly located as regards latitude and longitude is alone sufficient to repay the labour of calculation The distance between points

not directly connected can be readily calculated, see Appendix III This is particularly useful for interpolations The advantage is perhaps most apparent when it is the triangulator's business to provide fixed points for several sketchers more particularly if they are working some distance apart

If his only means of communication with his assistants is by letter or heliograph, it is no easy matter to indicate to one of them how some newly fixed point should be plotted by distances supposing as may well happen that the stations from which it has been fixed lie off his board On the other hand if the latitude and longitude have been computed and sent to the plane tabler he can have no difficulty whatever in plotting them correctly on his projected plane table sheet.

It has been mentioned previously (p 64) that in rapid work it may be sometimes impossible to observe all three angles of the triangle and that by a skilful use of intersected

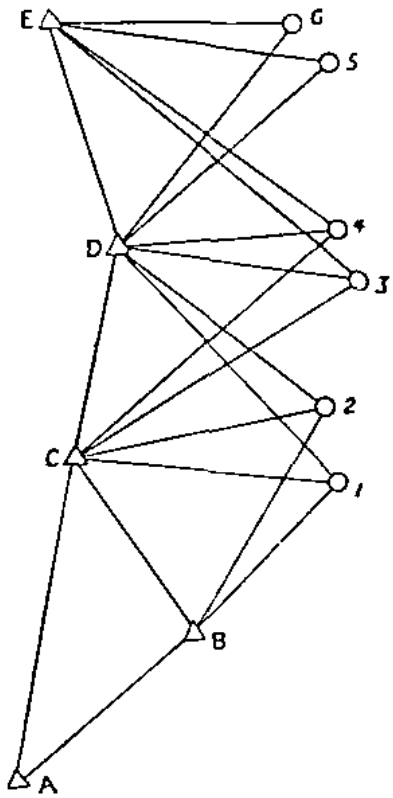


Fig 31

points triangulation may still be carried on without appreciable loss of accuracy Instances of this are given in figs 31 39

In these it is assumed that the observer finds it impossible from the nature of the country or for other reasons to visit any points better situated than ABCDE and that AB is the last side that he has been able to fix in the ordinary way by observing all three angles

A glance at the figures shows that BCDE are too nearly in a line for it to be possible to calculate with accuracy the triangles they form If there are no well marked points on either side rapid triangulation of a continuous nature becomes impossible But if there are well marked points on one flank such as 1 3 5 the difficulty can be surmounted If such points can be found in pairs as 1 2 3 4 5 6 the situation becomes much improved and the triangulation would be computed as follows —

Compute the side CB of the triangle ACB

Then with BC as base compute the triangles BC1 and BC2 the angles at 1 and 2 being the supplements of the angles at B and C

With the base 1C compute the value of the side CD Repeat the same operation with the base 2C

Take the mean value of CD as base, and compute D3 and D4 From these two bases obtain DE, and from DE calculate E5, E6, and so on

The most favourable case for this sort of triangulation is when points can be obtained on both sides of the line of stations as in Fig 32 Here the method of computing would be exactly similar, two values being obtained for each of the sides CD and DE

In spite of all the surveyor's foresight and energy cases may arise, even in a favourable country, where continuous triangulation becomes impossible For instance, after fixing one or more peaks on a range of hills, over which his route passes, he may be obliged to cross to the other side without having an opportunity of visiting any of these points In such a case, if circumstances allow, the best course is to start a fresh triangulation on the further side and

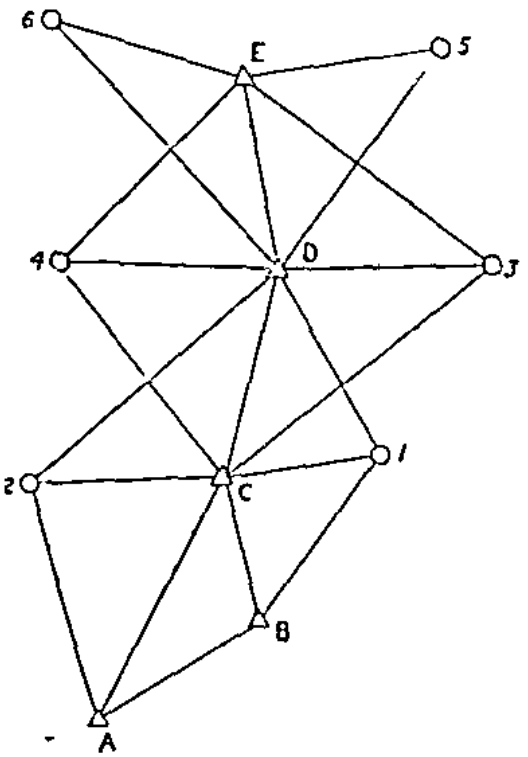


Fig 32

from it to intersect the peak or peaks already included in the previous triangulation If this is done the values of latitude and longitude of the new triangulation can be computed from the old one and all the points fixed by both can be plotted correctly relatively to one another

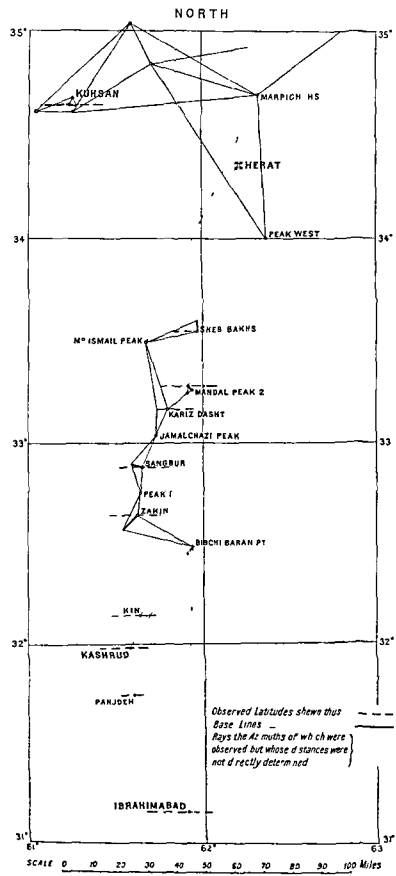
In this case also the methods of trigonometrical interpolation may be of great assistance (see p 3-)

If the march is very hurried indeed even this may be impossible, and if the route lies east and west the relative longitudes of the different points along the line can be ascertained only by astronomical observations, or by a traverse Which of these two methods was the more reliable would depend upon the circumstances under which they were carried out

If however, the route runs approximately north and south, a combination of observed latitudes with the azimuths of conspicuous points and the measurement of a few base lines will enable the surveyor to maintain a good value of longitude as long as the country is of a suitable character For, where the latitudes of two points and the azimuth of the line joining them are known, the difference between their longitudes can be computed (see Chapter XV)

CHART SHEWING THE TRIANGULATION AS EXECUTED ON THE MARCH OF THE AFGHAN BOUNDARY COMMISSION BETWEEN IBRAHIMABAD AND KUHSAN, FOR THE PURPOSE OF FIXING THE LONGITUDE OF KUHSAN

Th s portion of the March was 310 Miles long and took 19 days



For purely topographical purposes the same result could be obtained by plotting the initial point A and the azimuth from it to the second point, B Then the point B will be at the spot where the azimuth cuts the parallel drawn through the observed latitude of B A good instance of both this method and that above described, of starting a fresh triangulation when it is impossible to carry on the old one, is to be found in the march of the Afghan Boundary Commission to Herat in 1884 when it was considered of great importance to carry the true longitude from India up to the Afghan frontier (see Plate VIII)

By various methods the longitude had been carried with fair accuracy as far as Ibrahimabad At this point the route turned north and a lofty hill, Bibchi Baran, became visible on the horizon in the direction of the line of march

At Ibrahimabad a latitude was observed and an astronomical azimuth taken to the Bibchi Baran peak some 90 miles distant almost due north The column then marched through Panjdeh Karhrud and Kun at which places latitudes were observed and azimuths taken to the same Bibchi Baran hill these were afterwards used to fix the positions of these three places At Zakin a 7 mile base was measured with a perambulator along the line of march, and observations were taken to Bibchi Baran and other peaks from each end, the true azimuth of the base line and latitude of Zakin being also observed

From these data the distance from Zakin to Bibchi Baran peak, the difference of longitude between the two places, and the latitude of the latter, were computed Then from the latitudes of Ibrahimabad and Bibchi Baran peak, and the observed azimuth of the ray Ibrahimabad to Bibchi Baran the true longitude of Bibchi Baran peak, and thence that of Zakin were obtained From Zakin onwards to Sanghan Karez Dasht, and Mandal, short bases were daily measured on arrival in camp, and triangulation executed, by means of which each day points were fixed on ahead, which were observed back to from the next camp

At night azimuths and latitudes were observed, the latter serving merely as checks on the triangulation By these means the latitudes and longitudes were computed on from Zakin to Mandal At Mandal an azimuth was observed to 'Peak West,' a hill some 60 miles to the N N E. The march was then continued through various places to Kuhsan, bases being measured almost daily and triangulation executed as before It was found afterwards to be unnecessary to utilise these latter bases for the purpose of bringing up the longitude, but they served their purpose as aids to the topography at the time At Kuhsan a base was carefully measured, and a comprehensive system of triangulation commenced based on an observed latitude This triangulation which was afterwards extended to Mashhad in one direction and to Bamian in the other, included, among other points fixed, that called "Peak West which had been observed from Mandal The latitude of this "Peak West' and its difference of longitude from the Kuhsan base were then computed With the latitudes of 'Peak West" and Mandal and the observed azimuth of the line Mandal to "Peak West," the difference of longitude between these two points was now calculated, and the true longitude thus brought up from Mandal through 'Peak West' to Kuhsan

A check was also obtained by an azimuth taken from Marpich Hill Station—a station of observation of the Kuhsan main triangulation—to Mahomed Ismail Peak, a point that had been fixed from the Karez Dasht base The result on the whole was most satisfactory, the work standing rigorously any check applied to it by observations taken to various alternative points

While on the march it was impossible to compute all the observations, in fact only those that were of immediate use to the topographers, such as the latitudes of the camps and the distances of some of the prominent peaks, were computed daily Still, even with this limitation, the work could not have been carried through unless there had been a very strong party employed upon it, and it was found that the trigonometrical and astronomical observations, together with a plane table and perambulator traverse, on the scale of 1 inch to 4 miles, provided full employment for three officers and three native surveyors

As a measure of the rapidity with which this method can be conducted in a very favourable country, such as this was, it may be noticed that the whole distance from Ibrahimabad to Kuhsan, some 310 miles, was covered in 19 days including halts, during which the connection in longitude was kept unbroken In the diagram of the triangulation, Plate VIII, many of the daily local triangulations are omitted, as it was found unnecessary to use them when the triangulation was subsequently extended from Kuhsan As regards the accuracy, it was estimated that the error in the longitude of Kuhsan relatively to Ibrahimabad, computed as described above, probably did not exceed 5 seconds of arc, that is less than 200 yards If there had been no opportunity of starting an extensive triangulation from Kuhsan and working back, and the daily work of the march had been alone available, it is probable that the error in the longitude of Kuhsan would not have exceeded half a mile

Interpolations (See also p 30)—In rapid work interpolations play a more important part than they do in regular surveys By means of this method useful stations can sometimes be made in the middle of a valley where there is no marked spot to which it would be possible to observe

In interpolating a station it is always advisable and sometimes indispensable to observe the azimuth of one of the points from which the station is to be fixed

For instance, supposing that the surveyor finds, that, owing to the configuration of the country and the exigencies of the occasion, his triangulation ends in an intersected point A

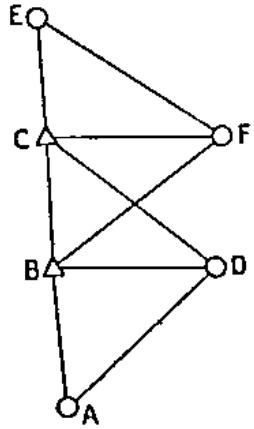


Fig 33

and a hill station B situated on a range of hills running parallel to the direction in which he proposes to travel, and that from B he has observed to C, another point on the same range The surveyor having crossed the range ABC is encamped at D on flat ground

Now, if a third fixed point were visible in a suitable position, it would be possible for him to interpolate the position of D as described on p 32, but as there are only two fixed points visible he must observe at D the azimuth of either A or B as well as the angle between them, as described on p 33

In the same way the position of the next camp, E, can be interpolated, and if the observer visits C and observes E from it the position of E can be fixed, and so on

In this way it would be possible to carry a triangulation along a single ridge of hills without ever observing from it to any points on a flank, and though the work would not be of very great accuracy, still, if the triangles were fairly well conditioned, the points on the hills were well marked, and the azimuth observed with accuracy, no great error could creep in

In all rapid triangulation, where it is always an object to observe from as few stations as possible, the important thing to remember is to keep a continuous series of azimuths This is attained by ensuring that from each station at least one back station is observed, from

which it has itself been observed When it is impossible to do this, as in the instance just described, the azimuth must be observed astronomically

Of course, the use of azimuths involves the calculation of the latitudes and longitudes of all the stations and intersected points of the triangulation, a procedure which has been advocated above on other grounds

Perhaps the most successful application of the method of interpolation ever utilized in a new country was made when triangulation was carried across the "snowy range" of the Himalayas into the Pamirs for the Boundary Commission of 1895 The interpolation was made from peaks of one of the secondary series of the Himalayan triangulation

When Triangulation is impossible, owing to the nature of the country or the extreme rapidity of the march if north to south or diagonal rays can be obtained the next best thing is to provide a framework of points by means of latitudes and azimuths (see Chapter XV)

If, on an expedition, even this is impossible, positions must be fixed by rough compass traverses controlled by astronomical observations This is the explorer's method of mapping, and is necessarily of a low standard of accuracy If the march is generally north to south, observed latitudes will serve to check the distances traversed, if east to west, they will check the bearings observed, if the march is in a diagonal direction, the observed latitudes will serve to check both bearings and distances For the methods of determining latitudes see Chapter XIV

CHAPTER VIII

LEVELLING

Levelling is the art of determining the relative heights of various points referred to a hypothetical surface which cuts the direction of gravity everywhere at right angles This surface is consequently slightly irregular where the direction of gravity is influenced by local and abnormal attractions

Mean sea level, at some selected station on a coast is the usual datum to which such heights are referred though other arbitrary levels may be assumed if necessary

There are three principal methods by which relative heights may be determined

(i) The first and most accurate method is by spirit levelling

(ii) The second in order of accuracy is by trigonometrical or angular measurement This method has the advantage that it enables the relative heights of inaccessible points to be determined

(iii) The third method is by the comparison of the barometric or atmospheric pressure at the required points

The last two are indirect methods of levelling, and are described elsewhere in this book The first is the only method which is technically speaking, included in the term "levelling'

By levelling is meant the direct determination of the differences of height of various points from the readings of the heights at which graduated staves held vertically over these points are cut by the horizontal plane which passes through the eye of the observer

Direct levelling may be subdivided into —

(*a*) Geodetic, or precise levelling
(*b*) Ordinary, or engineering levelling

These two classes of levelling are similar in general principles, but differ chiefly in the details of their execution particularly as regards the degree of accuracy to which personal and instrumental errors are eliminated

Geodetic or Precise Levelling has for its object the determination of the heights above mean sea level of a number of fixed points known as bench marks,' scattered over the country The main object is to afford reliable points of reference for mapping and engineering purposes consequently every precaution should be taken to make these heights as accurate as possible Geodetic lines of levels are run so as to cross and recross each other, forming a network over the country The crossing points, where there are bench marks common to two or more lines, afford a means of checking the accuracy of the work This class of levelling is of a special character and of a high order of accuracy

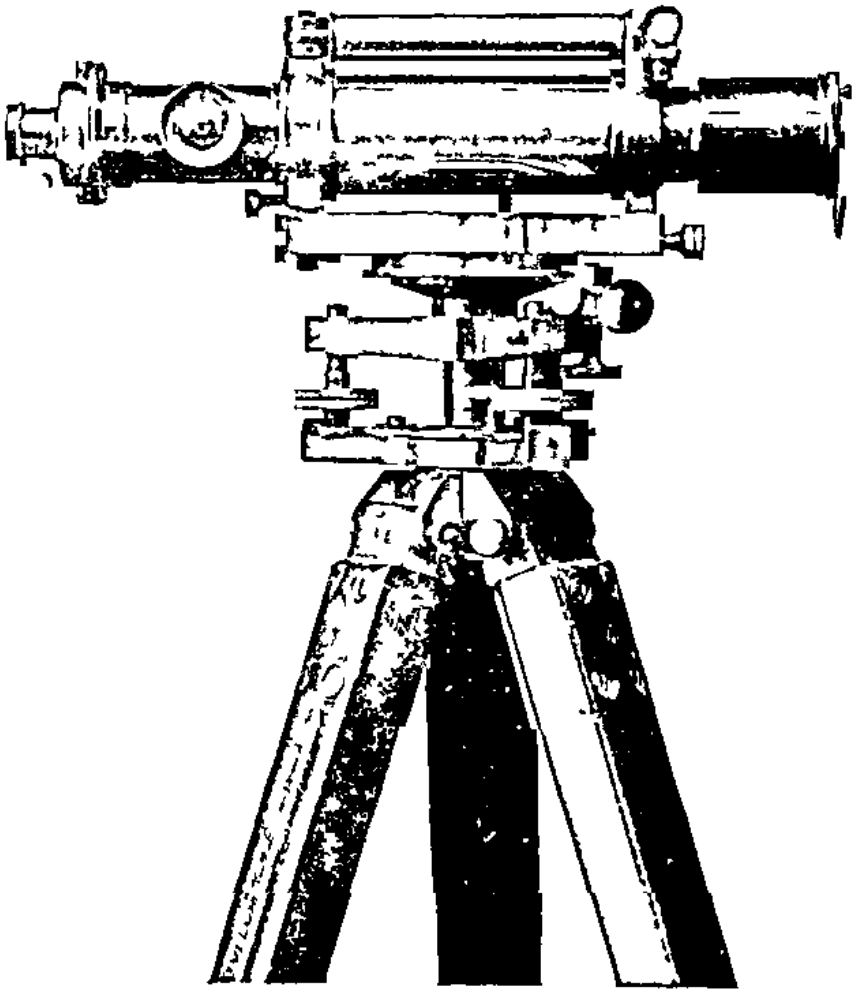
We are here only concerned with **Ordinary or Engineering levelling** such as is required for general engineering purposes, as the construction and laying out of irrigation works, roads railways, canals, buildings, &c , also for the accurate contouring of maps

Instruments

The instrument generally employed is known as a **level**, though any theodolite which carries a spirit level attached to its telescope may be used for this purpose, and is, at times, more expeditious though less accurate than the regular level

The essential part of all levels is a telescope provided with a long spirit level and containing a diaphragm carrying a horizontal and (usually) two vertical wires

PLATE IX



COOKE'S REVERSIBLE LEVEL.

The telescope is capable of being revolved in azimuth about a vertical axis, and is secured to the usual tripod stand It is supplied with three foot screws for the purpose of making the axis round which the telescope revolves truly vertical

Some old pattern levels are mounted on four instead of three foot screws, this is a mechanically unsound method of support

A level is described by the focal length* of its telescope and sometimes, in addition, by the aperture of the object glass

Fourteen inches focal length is the size in most common use Ten inch levels are used for rough surveys, and 16 to 26 inch levels for very exact work

Patterns of Levels—There are several kinds of levels, of which the Dumpy, Cookes Reversible and the "Y" pattern are the ones most frequently used The two latter are more readily adjusted than the Dumpy and are generally used for ordinary levelling operations

It will be sufficient here to describe Cooke's reversible level, which is the pattern most generally used in the Service and to explain the adjustments of all three above named patterns

Cooke's Reversible Level

An illustration of this instrument is given on Plate IX

Its construction is shown below, where fig 34 is the telescope (in longitudinal elevation) This telescope has two equal cylindrical flanges, F and F, turned on it concentrically with the tube

The cross wires, consisting of one horizontal and two subsidiary vertical wires, are lines ruled upon parallel glass, carried by a perforated block in the eye end which is adjustable vertically to correct for collimation by the two antagonising diaphragm screws *d* and *d*

The eye-piece is focussed by pushing it in or out The object-glass is focussed by turning the milled head M

The two flanges F and F fit closely inside two corresponding collars S and S, *vide* figs 35 and 36

When the cover of the object glass and the screw Sc are removed, the telescope can be introduced indifferently from either end of the socket SS (fig 35) and pushed home until the stop flange St (fig 34) comes in contact with the socket end S or S

Great care should be used in reversing the instrument, not to allow any grit to enter the sockets

One end S of the socket is furnished with a threaded bolt which passes through a hole in the base plate PP (fig 36), and is adjustable vertically by means of the two lock nuts N and N

1 Adjustment for Parallax—To make the focus of the eye piece and the image formed by the object glass coincide on the plane of the cross wires

First adjust the eye piece by carefully pushing it in or out in its tube, until the cross wires are seen as distinctly as possible, after which there should be no necessity to adjust the eye piece again, then focus the telescope on some well defined object at the average distance at which the levelling staff may be expected to be held (say 200 feet)

If, when the eye is moved gently up and down behind the eye-piece the image of the object does not move in the slightest degree with respect to the horizontal cross wire then the telescope is correctly focussed But if the image seems to follow the movements of the eye, that is, to tend to move above the cross wire when the eye is raised and to move below it when

* The focal length of a level is usually measured from the front shoulder of the object glass to the cross wires when the telescope is focussed for parallel rays It would be sufficiently accurate to focus on an object 2 miles distant It is near enough for most purposes though not theoretically correct the true focal length being measured from the cross wires to the optical centre of the object glass and the latter point is a varying distance (according to size) behind the front shoulder

the eye is lowered, then the image is not focussed exactly upon the cross wire, but lies on the side towards the object glass, which must consequently be made to approach the cross wires by means of the milled head M (*vide* fig 36) The reverse is the case when the image tends to move below the cross wire when the eye is raised and *vice versâ*, that is, the error of parallax must be corrected by moving the object glass further away from the cross wires

The above adjustment for parallax is the same for all levels and theodolites, and must be carried out before any correct observations can be taken This adjustment should precede all others, including even the levelling of an instrument for ordinary use

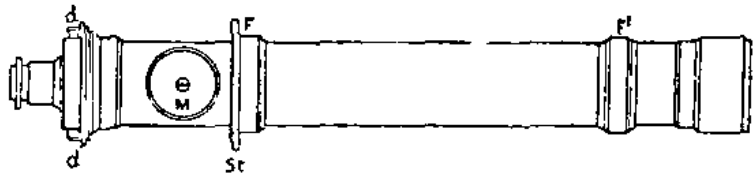


Fig 34

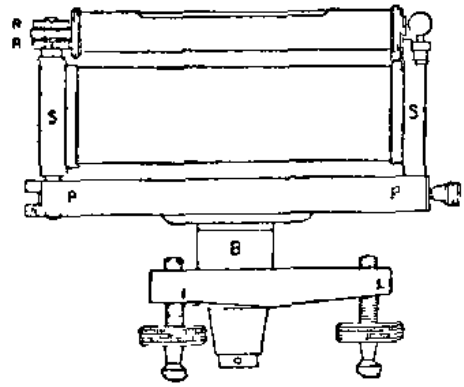


Fig 35

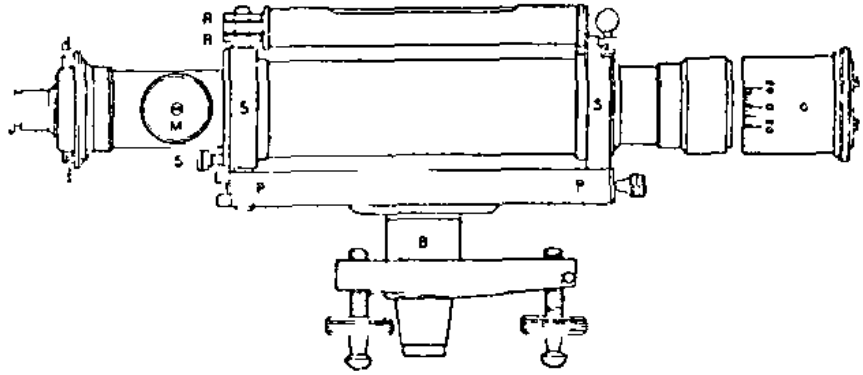


Fig 36

Generally, when once set for the day, there is no occasion for altering the focus of the eye piece But the focus of the object glass will obviously require alteration as the distance of the object varies

2 Adjustment for Collimation.—To make the line of collimation* coincident with the axis of rotation of the telescope in its sockets

* The *line of collimation* is the line joining the optical centre of the object glass and the intersection of the cross hairs

Having set the telescope over a foot screw, direct it on an object as in the last adjustment and bisect this object with the horizontal cross wire, then clamp the instrument, withdraw the fixing screw Sc (*vide* fig 36) and twist or rotate the telescope half way round in its socket, so that the screw hole, through which Sc passed, is brought to the top and the cross wire is again horizontal but reversed If the object is not still bisected, the error of collimation is corrected half by means of the foot screw lying under the telescope, and half by the antagonising diaphragm screws *d* and *d*

3 Adjustment for making the "Horizontal Axis of the Reversible Socket exactly at Right Angles to the "Vertical" Axis—The terms 'horizontal' and "vertical" are here used in an explanatory sense, as the two axes are not made truly horizontal and vertical until the final adjustment is carried out Referring to fig 36, this adjustment is to make the "axis of figure" of the reversible socket SS exactly at right angles to the 'vertical' axis B

First remove the cover of the object glass and the screw Sc (*vide* fig 36), then set the telescope over a foot screw, direct on and bisect an object, as in the last adjustment With draw the telescope carefully from its socket SS then turn the socket round end for end and carefully insert the telescope again keeping the screw hole in the stop flange St through which the screw Sc passes vertically below the centre of the tube when the telescope is pushed home The socket SS will now be reversed with reference to the telescope Again direct on the object, and if it be not now bisected by the horizontal cross wire correct half the error by the foot screw below the telescope and half by the lock nuts N N

This operation of reversing the socket on the telescope and the correction of the error half by the foot screw and half by the lock nuts, should be repeated until the bisection of the image remains undisturbed by the reversal of the socket When the adjustment is complete the telescope ought to be in its socket with its stop flange St against the end S of the collar so that it may be secured by the screw Sc

Care should be taken that no dust is allowed to settle on the flanges of the telescope during its insertion in the socket

4 Adjustment of Vertical Axis of Rotation—That is, to make the vertical axis of rotation truly vertical, and to make the telescope level at right angles to it

This is the same adjustment which is gone through for levelling a theodolite on first setting up

Place the telescope parallel to two foot screws and with them alone bring the bubble approximately to the centre of its run, noting the reading at one end of the bubble (say the end near the capstan headed screws)

Turn the telescope through 180 degrees until it is again parallel to the same two foot screws, and again note the reading of the same end of the bubble By means of the two foot screws, bring this end of the bubble to the mean of the two readings Now turn the telescope until it is over the third foot screw and by it alone bring the same end of the bubble to this mean reading

Repeat until one end of the bubble reads the same in any position, when the upright axis will be truly vertical The bubble can then be brought to the centre of its run by means of the two lock nuts R R at one end of the level (*vide* fig 36)

It is obvious that if the third adjustment is carried out and both axes of the instrument are thereby made exactly at right angles to each other then the last adjustment necessarily makes the horizontal axis of the reversible socket truly horizontal

All the above adjustments should be repeated until the required degree of accuracy is attained

Slight errors in adjustment may in many cases be eliminated as explained later in the procedure for levelling

The "Y" Pattern Level

An illustration of this instrument is given in Plate X
The following are the necessary adjustments —

1 Parallax,
2 Collimation,
3 Telescope level,
4 Vertical axis of rotation

The first and last adjustments are the same as those already described for the Cooke's pattern level

Adjustment for Collimation—Having set the telescope over a foot screw, turn the telescope by a rotary motion in the Y's until one pair of diaphragm screws is vertical and direct the intersection of the cross wires on some distant and well defined object Now turn the telescope half round in the Y's and if the horizontal wire has moved vertically from the object bring it back half by the foot screw and half by the vertical diaphragm screws

Adjustment of Telescope Level—To make the telescope level parallel to the axis of revolution of the telescope in the Y s and therefore parallel to the line of collimation bring the bubble of the telescope level to the centre of its run by means of two foot screws, reverse the telescope end for end in the Y s and if the bubble does not still remain in the centre, adjust by means of the screws giving vertical motion at the other end of the telescope level Repeat until perfect

The Dumpy Level

This is the usual pattern of non reversible level An illustration is given in Plate XI
The adjustments of the Dumpy level are for —

1 Parallax,
2 Vertical axis of rotation
3 Collimation

The first two adjustments are the same as the first and last adjustments of the Cooke s reversible level already described But, owing to the Dumpy level not being reversible it is impossible to correct for collimation in the same way

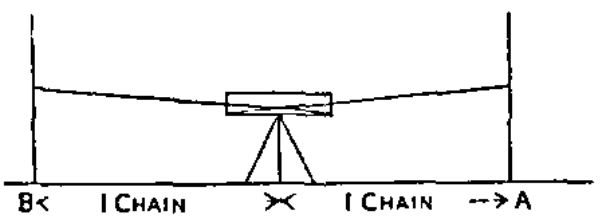


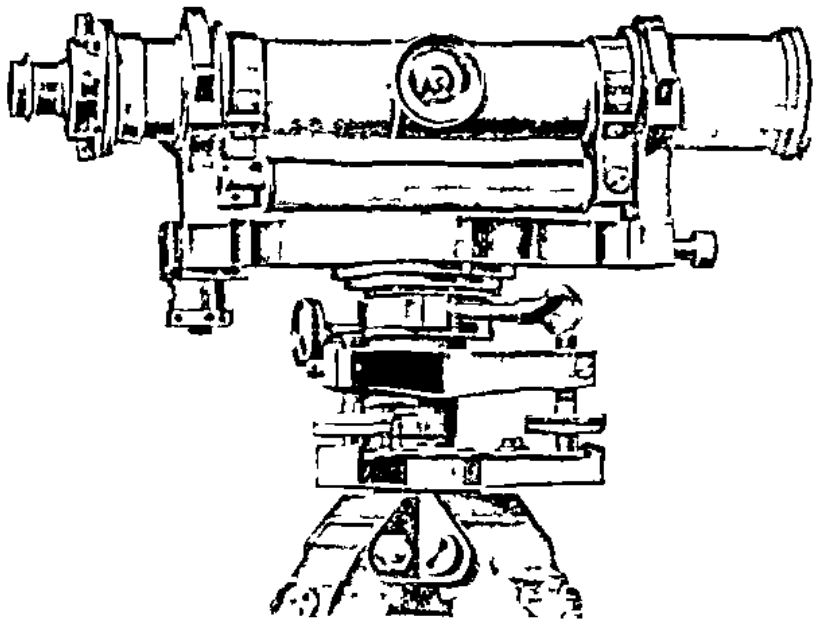
Fig 37

Therefore instead of this the line of collimation (*i e*, the line joining the optical centre of the object glass and the intersection of the cross wires) is made at right angles to the vertical axis of rotation

The method of carrying out this **adjustment for collimation** of a Dumpy level is as follows —

Select a level piece of ground set up the instrument in the centre, and carry out the first

PLATE X



Y Level

is so adjusted that the staff is perpendicular in all directions when the pendulum point hangs in the centre of the ring

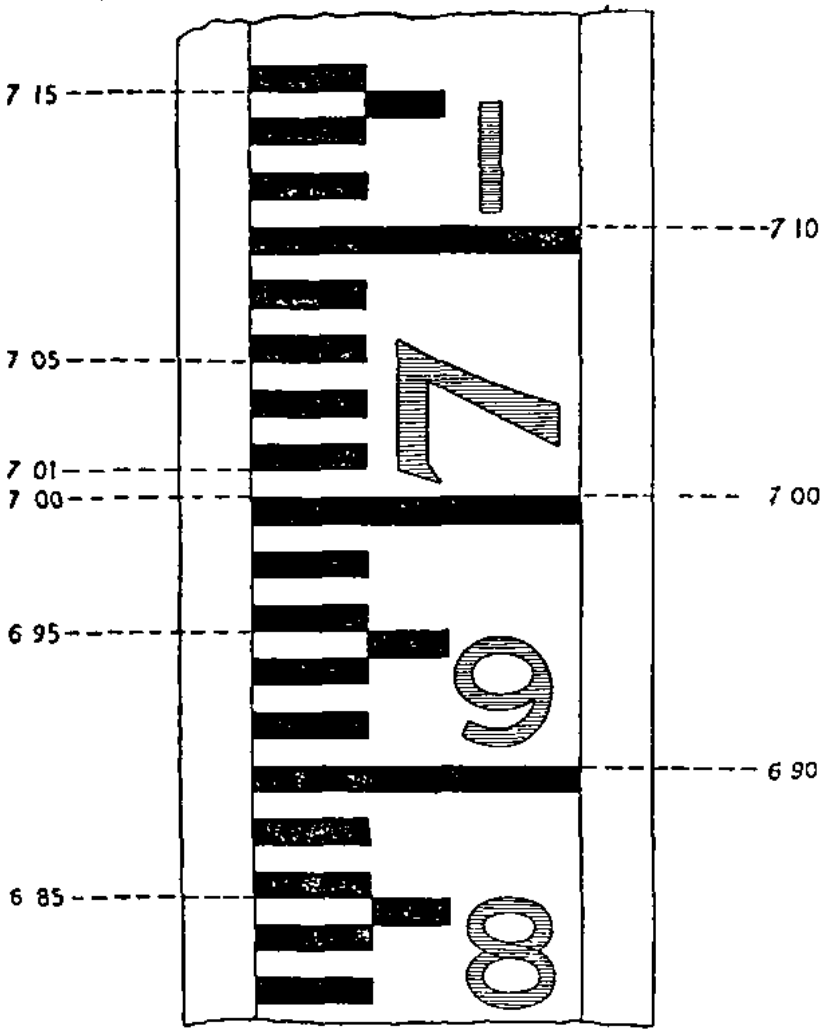


Fig 39

Curvature

By means of the level a line can be traced tangential to the surface of the earth at the point where the instrument is set up Owing to the sphericity of the earth it is evident

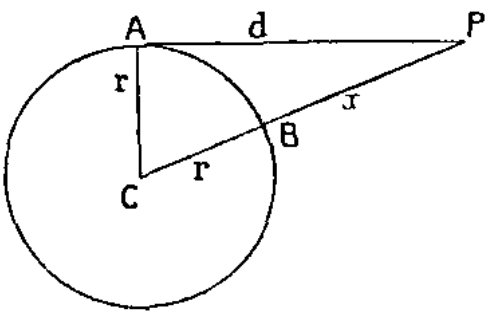


Fig 40

that the further this tangential line is produced the further it moves from the centre of the earth

In fig 40 representing a vertical section through the centre of the earth, let A be the

observer's position, P that of the distant object, situated in the plane tangential to the surface of the earth at A. Let C be the centre of the earth. Join CP, cutting the circumference at B. Call BP, x, and AP, d, and AC and BC, each representing the radius of the earth r.

Then

$$(r + x)^2 = r^2 + d^2 \quad \text{or} \quad (2r + x)\, x = d^2$$

But the diameter of the earth $2r$ being so great in comparison with the quantity x at all distances to which a levelling operation usually extends $2r$ may be taken for $2r + x$ without sensible error.

Then

$$2rx = d^2 \quad \text{and} \quad x = \frac{d^2}{2r}$$

The mean diameter of the earth may be taken as 7 916 miles; therefore if $d = 1$ mile the excess x of the apparent over the true level = $\frac{1}{7916}$ of a mile, or a little over 8 inches; at 2 miles it is four times that quantity, or 32 inches, and so on increasing in proportion to the square of the distance. Hence the simple formula is deduced that the correction *for curvature in feet is 8 tenths of the square of the distance in miles*. That is to say, if a man were swimming in a perfectly smooth sea with his eyes on a level with the surface of the water, he would be just able, as regards curvature, to see the top of an object floating in the sea a mile off, if it protruded 8 inches above the surface.

Curvature and Refraction

The distance at which objects are visible is however, augmented by the effects of refraction, which makes objects as a rule appear higher than they really are.

Taking the normal amount of refraction in the middle of the day, it would increase the distance at which an object of a certain height could be seen taking curvature only into consideration by about $\frac{1}{13}$.

This gives the approximate formula for both curvature and refraction that the height in feet of the distant object equals $\frac{6}{7}$ of the square of the number of miles that it is distant from the observer, or $h = \frac{6}{7} d^2$.

The effect of refraction however varies so much with the place, season and time of day that it is necessary to adopt some method of observing that will eliminate it. This is attained by placing the instrument at an equal distance from any two points to which observations are taken. If this is done the errors in the readings of both staves will be equal in amount even if the telescope is not perfectly collimated, and consequently the differential reading will be correct.

This method also obviates the necessity of changing the focus of the telescope, and so avoids the possibility of introducing an instrumental error caused by the focussing tube not moving truly parallel to the visual axis of the instrument on a change of focus.

Procedure when Levelling

Suppose the spirit level to be set up and adjusted at A (fig. 41), directed on the levelling staff at 1, and the figure noted which is cut by the horizontal wire. This figure would be the difference of level between 1 and A, minus the height of the horizontal cross wire of the instrument above the ground at A (which might be measured and deducted). Suppose the staff was now held at 5, and the telescope directed on it, the difference between the readings at 1 and 5 would evidently be the difference of level between these two points, and is independent of the height of the instrument above the ground which is common to both, assuming that

points 1 and 5 are equidistant from the instrument at A, they would be equally affected by curvature,* refraction, and instrumental errors, which might therefore be ignored

The levelling staff might also be held at intermediate points 2, 3, 4, &c , and the readings noted It would then only be necessary to measure the horizontal distance between these points in order to obtain the data for drawing a section of the ground between them, as shown in fig 41

It is evident that, unless the intermediate points 2, 3, and 4 are the same distance from the instrument at A as 1 and 5, the accuracy of the determination of their heights will be slightly affected by curvature, refraction, and instrumental errors

These errors will not be cumulative if entries of level readings are made as shown in the form of field book described on the next page, in which the levels of successive sets of readings depend only on the heights of the forward and back stations

If it were required to continue the levelling beyond 5, the spirit level would be carried forward and set up in such a position B and at such a height that it might intersect some part

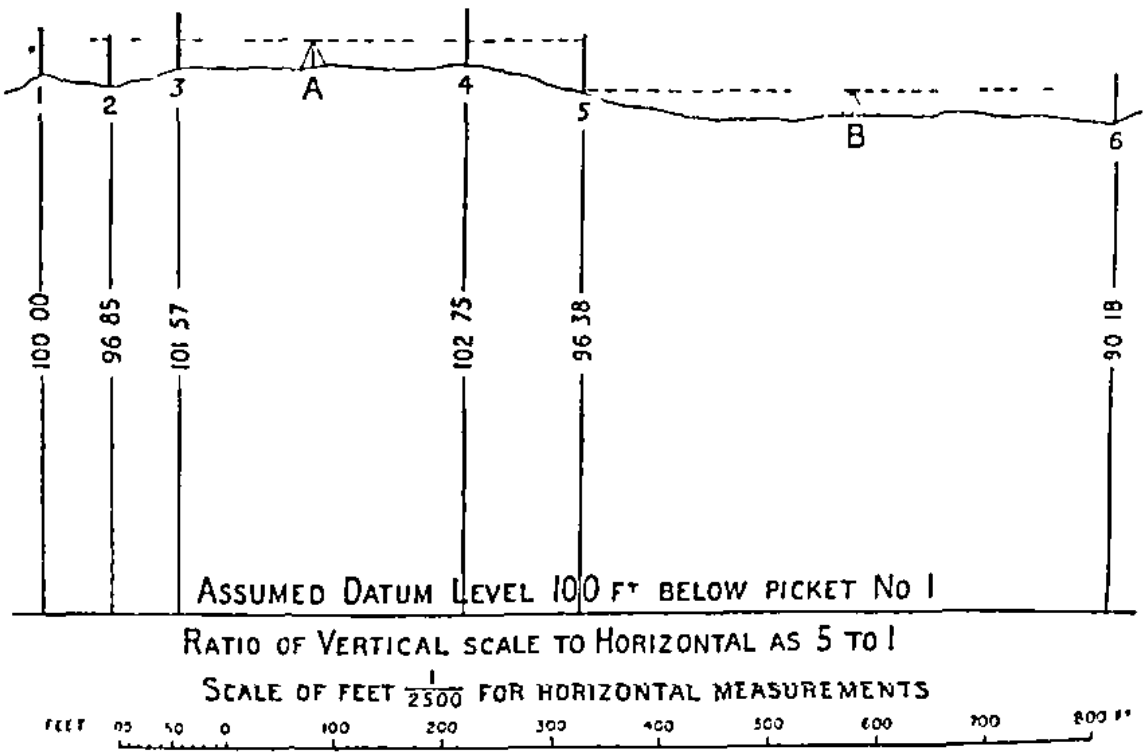


Fig 41

of the staff at 5, care being taken not to alter the position of the staff meanwhile, but merely to turn the required face towards the level

As regards the length of sights, it is advisable not to exceed 100 yards for accurate work with a 14 inch level For relatively unimportant work, the length is only limited by the power of the telescope used

In the operation represented in fig 41, where the levelling commenced at 1 and proceeded forward to the right, the reading of the staff at 1 would be called the "back reading" and the reading of the staff at 5 the "forward reading" The readings at 2, 3, and 4 are called "intermediate readings"

On setting up the level at B, the point 5 becomes the back station and point 6 the

* This is only strictly correct when the readings on the staff are taken at the same height above homogeneous ground as refraction varies with the altitude of the ray and is also influenced by the nature and temperature of the soil

Form 7

Number of Picket	Horizontal Distance in Feet	*Back* Reading	*Intermediate* Reading	*Forward* Reading	Height of Instrument	*Reduced* Level	Remarks
1	0	5 98 6 28			104 98	100 00	Assumed
2	63		9 13 9 43			96 83	
3	146		4 41 4 71			101 57	
4	399		3 23 3 53			102 7	
5	504	0 61 0 91		9 60 9 90	96 91	96 38	
6	1008			6 81 7 11		90 18	
&c	&c					&c	
	Totals	13 78		33 42			
				− 13 78		Heights from above Column of Reduced Levels—	
	For double reading deduct 1s			2 19 64			
	Total amount of fall			9 82		Picket 1	100 00
						Picket 6	90 18
						Total fall	9 82

forward station Similarly each forward station becomes a back station when the instrument is moved forward The stations are called 'back" and "forward' with reference to their relation to each other on the line of levels, and not as regards the instrument which might be to the side and before or behind both

For ordinary levelling operations the form of field book on p 83 will be found generally convenient the entries refer to fig 41 —

In this case two readings have been taken at every picket one on each side of an Ordnance Survey pattern staff This insures greater accuracy, as the difference of two readings at any picket must be a constant if the readings are correctly taken and if the staff holder is careful not to knock the picket or press it into the ground while swaying the staff on it

For rough work it is sufficient to take single readings on a staff, but when it is graduated on both sides, great care must be taken to ensure that the same side is always made to face the instrument

In the above field book form the "reduced level' of picket No 1 is assumed as 100 feet and the heights of all the points along the line of levels are referred to a hypothetical datum plane passing 100 feet below picket No 1

It is convenient that the datum level should be lower than any part of the section so that all measurements may be taken above it

The horizontal distance of each picket from the starting point is entered in column 2 of the field book form, and is measured by chain or tape the deduction for the degree of slope being made by holding the chain horizontally when measuring up or down hill

The entries in columns 3, 4, and 5 are the readings of the levelling staff at the 'back,' 'intermediate, and forward stations respectively

The height of the instrument' is entered in column 6 and is obtained by adding the back reading to the reduced level' of the back station or starting point thus the height of the instrument at A — 100 00 + 5 98 = 105 98 and at B = 96 38 + 0 61 = 96 99

The reduced level of an intermediate or of a forward station is entered in column 7, and is found by adding the back reading' to the "reduced level of the station on which the back reading is taken (shown in column 6 as ' Height of instrument') and subtracting the intermediate or forward reading from this Thus the "reduced level of picket No 4 would be 105 98 3 23 = 102 75 feet and of picket No 5, 105 98 – 9 60 = 96 38 feet above datum level

When it is only required to find the difference of level between two terminal points, it is only necessary to record the back and forward readings at the various stations, and the difference of then sums will give the required difference of level, if the sum of the back readings is greater than the sum of the forward readings, then the difference of level is a rise and vice versa If the levelling operation is carried back to the starting point, it is clear that the sum of the back readings will be equal to the sum of the forward readings, if the work is accurately performed

This method of finding the difference of height between two terminal points is usually called back levelling and is useful for checking a series of levels taken in greater detail or in closing a detailed series on to the starting point or on to the nearest known level such as a bench mark of the Ordnance Survey

In extensive levelling operations it is usual to leave permanent marks, called "bench marks on objects such as milestones and walls, and to record their exact heights for future reference

In Ordnance Survey maps the levels of various bench marks are figured with their height in feet and decimals of feet above mean sea level at Liverpool which is the datum to which all altitudes in this survey are referred

The Ordnance Survey bench marks are of this pattern $\overline{\text{A}}$, cut about half an inch deep into the vertical face of brick or stone structures the exact point of reference being the centre of the V shaped cut in the horizontal line

Levelling with the Theodolite

Section of ground may be taken with the theodolite more expeditiously, though less accurately, than with the regular level Thus —

Let the theodolite be set up as shown in the figure and its telescope directed parallel to the general slope of the hill Observe this vertical angle with all precautions for accuracy proper to the operation

Keeping the telescope clamped in this position note the successive readings of a levelling staff held by an assistant at the various points which will best define the irregularities of the

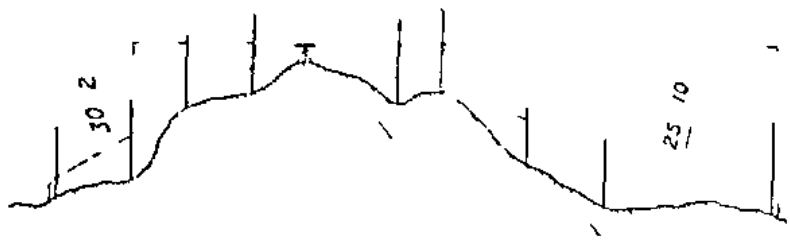


Fig 12

section, the height of the theodolite and the horizontal distance between these points being measured A section can be drawn thus

Draw the horizontal line passing through the telescope Protract the observed angle of inclination (as shown in the figure) On the horizontal line set off the measured distances to scale Draw vertical lines from these points cutting the hypotenuse Beneath each point thus found set off the staff reading being the level of the ground where the foot of the staff stood for each observation

Should the staff be so distant that the markings are illegible a system of signals can be agreed upon, so that the assistant can move a visible mark along the face of the staff until signalled correct, the assistant can then note the reading

CHAPTER IX

HEIGHTS

The datum to which all heights should be referred is mean sea level For the determination of M S L see p 30

Heights may be determined by any one of the methods in the following list, the methods are given in order of their accuracy —

(i) By levelling
(ii) Trigonometrically (by vertical angles with a theodolite)
(iii) By clinometer (for short distances)
(iv) By barometer (mercurial or aneroid)
(v) By hypsometer (boiling point thermometer)

As regards accuracy (i) a line of good (not geodetic) levels should not produce an error of 0 1 foot per mile or 1 foot in 100 miles or 2 feet in 400 miles (The error may be assumed to increase as the square root of the distance)

(ii) In principal and secondary triangulation it is found that for any given ray of 30 miles or so an error of say 1 or 2 feet may be expected, hence we might expect an accumulated error of about 4 to 8 feet in 500 miles In topographical triangulation the accuracy of the heights will largely depend on the nature of the signals used In rapid triangulation under favourable conditions the error might be 10 feet in 200 miles

(iii) Clinometer heights are only used for short rays up to 2 miles and depend on neighbouring trigonometrical heights, each clinometer height will be correct within 2 or 3 feet

(iv) Barometer heights should be used in dependence on level or trigonometrical heights, judiciously used heights may be determined with an aneroid barometer within 10 or 20 feet Absolute determinations with a barometer will give large errors similar to those resulting from the use of the hypsometer

(v) Hypsometer heights depend on the actual air pressure at the moment, the hypsometer is necessarily a rough instrument, an error of $\frac{1}{10}^{\circ}$ Fahrenheit corresponds roughly to an error in height of 55 feet When every precaution has been taken, we may assume that a hypsometer height taken inland in a new country is liable to be at least 100 feet in error

For determinations of level heights see Chapter VIII
trigonometrical heights, see Chapter III
clinometer heights, see Chapter VI

Barometer Heights Barometer heights are frequently of great use in places where no trigonometrical station can be fixed such as in forests, valleys and deep ravines Barometer heights should always, where possible, be used on level or trigonometrical heights Thus suppose a trigonometrical station to be on the top of a 2,000 foot hill, suppose, as often occurs that the adjoining valleys are thickly wooded it is nevertheless very desirable to fix some heights in the valley This is best done by reading the barometer and thermometer on the top of the hill then reading them at various points in the valley, and then if possible reading them again on the top Aneroid barometers are most convenient for the purpose

Use of the Aneroid Barometer —Barometers should not be used near the limit of their range thus a barometer graduated to 5,000 feet should not be used much above 4,000 feet

Barometers should be tapped gently with the nail or a pencil before reading

Barometers take some little time to record the correct reading if a change of altitude has been rapidly made they should therefore be given a rest of a few minutes

They should always be read in the same position either when horizontal, or vertical with the needle on a level with the eye, which should be always in the same relative position to the needle to avoid the effect of parallax

The thermometer (in the shade) should be read at the same time as the barometer

If possible get a new certificate for each barometer in use or compare with a mercurial barometer to ascertain index error

For determining differences of height with an aneroid barometer see Tables V and VI

Use of Tables —

If β be the reading of barometer at lower station in inches,

β' " upper " ,

t " Fahrenheit thermometer at lower station,

t' " " " upper "

A the number in Table V corresponding to t and t',

C " " " VI " latitude,

make $D = \log \beta - \log \beta'$,

then $\log D + A + C = \log$ difference of altitude in feet

Example —In Oct 81 the aneroid barometer at the lower station read 29 81 inches at the upper station 25 55 The readings of the thermometers in the shade were 63° and 50 5 F

What was the difference of altitude?

Log 29 81 =	1 47436
Log 25 55 −	1 40739
D −	0 06697
Log D =	$\bar{2}$ 82588
A	4 80339
C −	1 99973
Log h =	3 62900
h −	4256 the required difference of height (in feet)

When time does not allow of this computation a good aneroid will give fair indications of differential heights taken within a short interval of time, if the scale of heights given in feet is used

Hypsometer Heights —The hypsometer, or boiling point apparatus, consists of a thermometer graduated from 180° to 215°, a spirit lamp boiler, and a telescopic tube which screws on to the top of the boiler, and in which the thermometer, supported by a rubber washer, is placed when in use The boiler should be about a quarter full, and the telescopic tube so adjusted that the bulb of the thermometer is just clear of the water When the water boils the steam ascends through the tube and causes the mercury to rise When the mercury becomes stationary, read the thermometer, and at the same time take the air temperature with an ordinary thermometer

To compute the difference in altitude between two stations by boiling point observations, take from Table VII the numbers opposite to the boiling points at the two stations The difference between these numbers is the difference in height when the mean temperature of intermediate air is 32 F When the temperature differs from 32°, the difference between the

numbers obtained from Table VII must be multiplied by the multiplier given in Table VIII for the given temperature

The third column of Table VII gives a ready means of comparing the readings of the aneroid with those of the hypsometer

When observations are only taken at the upper station and its absolute altitude has to be determined the mean barometric reading for the time of the year reduced to the sea level in the locality must be taken as the reading of the lower station The best approximations to the true values will be found in the isobaric charts given in 'Hints to Travellers

Whenever the observations at the two stations under comparison are not simultaneous, or when the mean barometer is taken in place of the lower station, the correction for the diurnal variation must not be omitted In the tropics there is a regular diurnal oscillation amounting to one tenth of an inch approximately, the maximum daily readings occuring at about 9 a m and 9 p m, and the minimum readings about 3 a m and 3 p m In other respects the barometer is very steady

Determinations of height by the hypsometer can only be looked upon as very rough approximations The determination is affected by atmospheric changes by errors in graduation of the thermometer, by errors in reading, by the purity of the water used, and by other factors

As an illustration of the discrepancies to be expected in the determination of the height of an inland station by this means, the following list of hypsometric values of the height of Lake Tanganyika is given —

Baumann	2 886 feet
Stanley	2,755 ,,
Hore	2,749
Cameron	2 709 ,,
Stairs	2,690 ,,
Wissmann	2,670 ,,
Popelin	2,663 ,,
Reichard	2,558

the mean value being 2,713 and the range 328 feet It is not known what the true value is

CHAPTER X

CONTOURING AND HILL SKETCHING

A Contour is the representation on a map of an imaginary line on the ground joining all immediately adjacent points which are the same height above mean sea level. For small areas a contour may be considered to be the outline of the intersection of the surface of the ground with a horizontal plane.

Contours vary in accuracy from deliberately surveyed contours determined by instrumental levelling to sketch-contours drawn in by eye, such sketch contours are called **form lines**.

In determining the accuracy necessary for the contouring of a map the principal factor is the scale of the map. Suppose, for instance, that it is required to show the hill features in a plane table survey on a scale of ½ inch to 1 mile, it would be waste of time to attempt any instrumental contouring. Hill features on such a scale must be generalized, and it is sufficient to show them by form lines controlled by scattered heights on the hills and in the valleys. On the other hand a 1 inch map such as the Ordnance Survey 1 inch map can show contours with great exactness and they may be fixed by instrumental levelling or by using the water level or may be approximate contours determined by clinometer.

Methods of Contouring.—The principal methods of contouring, using the term in its widest sense are —

(1) With theodolite or level.
(2) With water level.
(3) With clinometer.
(4) With aneroid barometer.
(5) By eye (sketch contouring).

(1) **A small Theodolite** (used as a level) and a contouring staff 8 feet long provided with a sliding vane are required, and pickets as in the operation of levelling.

The contourer begins by choosing a bench mark of known height as near the required altitude as possible and levelling from it up or down till he has established a point on the contour and marked it by a *picket driven in the ground at the correct height*. The instrument is then set up nearly on the same level as the picket and at a distance of about 10 chains, beyond which a correction would be required for the curvature of the earth. The staff is held on the picket and the vane raised or lowered till it is intersected by the cross hairs of the telescope, it is then clamped, and the staff with the vane fixed at this height is then moved along the contour and set up at every change in the form of the ground the assistant who holds it being directed into position by a signal from the contourer at the instrument. A mark is made at each station, and when a point is reached at about 10 chains from the instrument (or nearly the same distance as the first picket) another picket is driven, and carefully adjusted to the correct height. The instrument is now moved and set up again in a similar position to the second picket as it was to the first, the vane of the staff is re-adjusted on the new picket, and the process of marking out the contour continued.

Where the vertical interval is small more than one contour may often be marked out without shifting the position of the instrument if the staff is long enough. Too much should not, however, be attempted at one time.

In marking out it often happens that "isolations," or small detached contours on the level of the main contour, are passed, and care should be taken that they do not escape

observation examination of the horizon in all directions with the telescope will point out ground where isolations will probably be found Should this be close to the main contour the isolation may be marked from one of the ordinary positions of the instrument, but when it is distant a point on it must be found by levelling it in the ordinary way

When a sufficient length of the contour is marked the contourer plots it on the map and fixes the points marked on the ground either by traverse or by chaining as in ordinary chain survey or on a plane table by intersection and resection, the latter method being more suitable for the smaller scales

(2) **The Water Level** is an instrument of great simplicity which never requires any adjustment As it has no telescope it is impossible to take long sights with it and it is of course, not susceptible of minute accuracy On the other hand, no gross errors can creep into work with this instrument It is easy to improvise a water level

Plate XII shows the pattern of water level in use on the Ordnance Survey The distance between the bottles is 1 foot the length of tripod when closed is 3 feet 1 inch The tripod has one leg which can be lengthened for setting up on a hill side A prismatic compass can be fitted to a projection between the bottles The bottles are partially filled with coloured water through a small opening at the top of the tube frame, a cap fits over the opening The bottles are connected above and below with hollow tubes Weight of level 4 lbs 2 ozs

To use the instrument it is best to look diagonally across the two bottles say from the right edge of the near bottle to the left edge of the far bottle, and get the bottles in such a position that the distant object comes between the two edges

The level is to be placed at the starting point of the contour which has been determined previously by levelling or by careful clinometer work The sight vane on a staff is to be adjusted to the height of the water in the bottles, and the staff man sent on with it some 400 or 500 feet or to any change in direction of the contour, the level man signs him right or left until the vane is on a level with the top of the coloured water in the bottles A picket may now be driven in by the staff man and the position of the picket is determined either—

On a plane table by forward bearings and resection
By the prismatic compass and chaining or prism

The level man now moves up to the picket and proceeds as before In contouring round a hill an excellent check is obtained by closing on the starting point

(3) **Deliberate Method of Contouring with the Indian Clinometer and Plane Table**—To carry out this method two men are required viz one plane tabler and one flagman and it is necessary that three fixed points should generally be in sight and that the plane tabler should always set up his table at the same height above the ground

A convenient way of doing this is for the plane tabler to always set up his table to the level of some point on his person say, for instance one of the buttons of his coat, but if this is not considered sufficiently accurate he can carry a plumb line of fixed length The flagman carries a small disc or board and notes the height of the table so as to hold up his disc always at that height

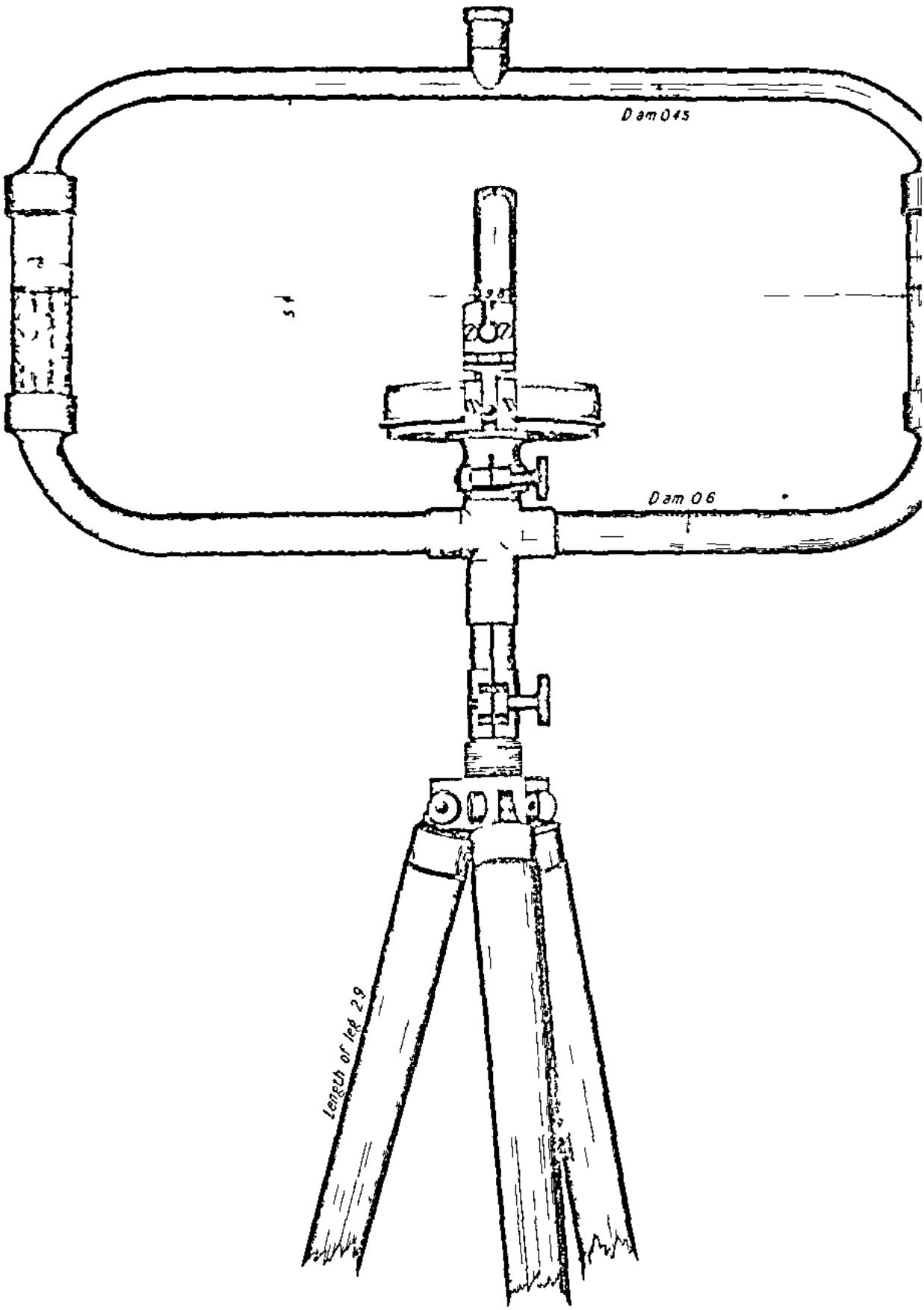
The plane tabler sets up his table at station 0 the starting point of the contour, and interpolates his position He then levels his clinometer and sends on the flagman approximately along the contour line and when the latter has gone sufficiently far ahead he aligns him by means of his clinometer until he is on the same level as himself

The plane tabler takes a ray on the flagman and moves up to him He sets up his plane table at that point and again interpolates his position, while the flagman goes on ahead as before and so the work proceeds This will be found a very convenient method on large scales

Rapid Method of Approximate Contouring with Indian Clinometer and Plane Table—This is described in Chapter VI

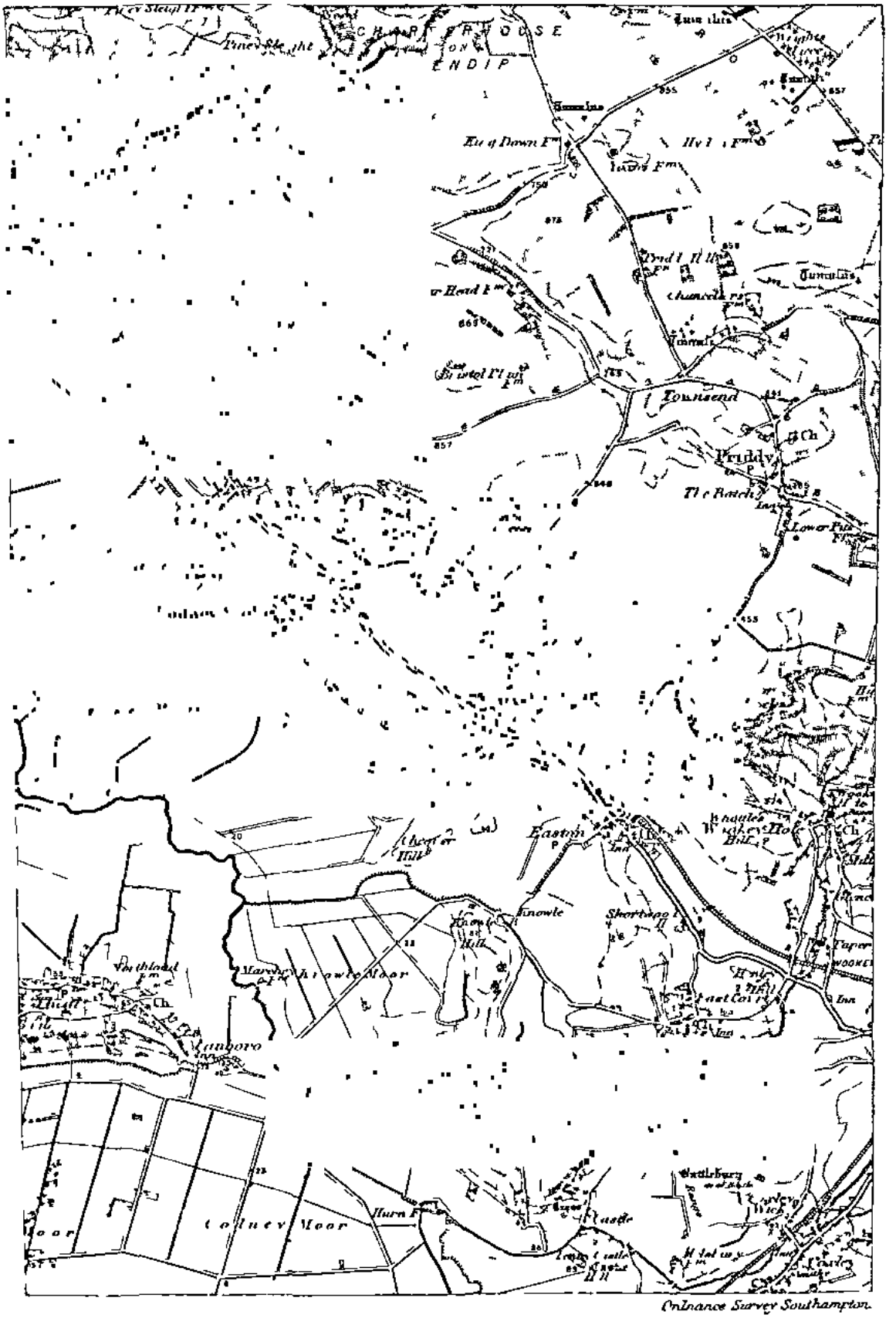
WATER-LEVEL

Ordnance Survey Pattern



ORDNANCE SURVEY

Scale - 1 Inch to 1 Mile



Ordnance Survey Southampton.

SHOWING THE COMBINATION OF CONTOURS AND VERTICAL HACHURES

(4) Contouring with Aneroid Barometer—Where the vertical interval of the contours is large say at least 25 feet, approximate contours can be put in by means of the aneroid barometer This is a particularly convenient method of approximate contouring for scales of $\frac{1}{2}$ inch to 1 mile, and a vertical interval of 100 feet, or 1 inch and an interval of 50 feet In variable weather this method cannot be used

The barometer should be carried loose in the pocket

Before reading it should be lightly tapped, in reading it should be held with the face vertical, the eye should always be in the same position relative to the needle to avoid the effect of parallax

A $2\frac{1}{2}$ inch barometer is a convenient size The scale of feet should be used The barometer should not be used near its extreme range, thus a barometer graduated to 5000 feet should not be used much above 4000 feet

In using the barometer to determine the approximate positions of contours, it is necessary to work between points of which the heights have been previously fixed Thus supposing the height of the top of a hill is known and also a height in the valley below, at the lower station set the instrument to the proper height, move up along any convenient spur, stopping where the barometer reading shows the required contour levels, fix these points on the plane table sketch in the neighbouring features, and close on the top of the hill If the reading differs from the known height of the top of the hill, a proportionate correction must be made to all the contours drawn in It is desirable that the distance between the fixed heights should not, as a rule, exceed a few miles and it is clearly necessary that the elapsed time between starting and closing should be as short as possible

Aneroid barometers do not at once take up the reading of a new height if a change of altitude has been rapidly made, a few minutes rest is necessary

(5) Sketch Contouring or Hill Sketching—As has been explained, on a small scale such as $\frac{1}{4}$ inch to 1 mile, it would be waste of time and money to determine contours instrumentally

The hill features are, therefore, sketched in by eye by means of **form lines** Form lines serve to show the shape of the ground rather than its exact height at any point, and on small scales it is obvious that the hill forms must be generalized In fact hill sketching on small scales is not a mechanical science with exact rules but partakes somewhat of the nature of an art, the hill sketcher must of course show the main features with accuracy, but it is impossible to show all the minor features

The summits of the hills, the ridges spurs, valley lines and streams will be accurately fixed, and the sketching will be controlled by a few trigonometrical (and in some cases barometrical) heights

In drawing the form lines it is desirable that the sketcher should observe a rule as to the number of lines to fit in for a given difference of level A very convenient rule is that the interval (in feet) between two adjacent form lines = 50 × number of miles to the inch Thus on the $\frac{1}{4}$ inch scale the vertical interval between successive form lines would be 200 feet Supposing for instance, that the sketcher was at a point which he knew or judged to be 1000 feet above the valley, he should draw five form lines below the one representing the crest of the hill

In hill sketching it is important to get on to the tops of hills ridges, and spurs The positions of these tops ridges and prominent points are fixed by plane tabling in the usual way, and the sketching of the hill features is carried on at the same time as the fixing of the detail The form lines need not be continuous Plates VI and VII are examples of hill sketching with form lines

CHAPTER XI

MAP PROJECTIONS AND GRATICULES

A map projection is the system on which the terrestrial meridians and parallels are represented on paper

A graticule is the network of lines representing meridians and parallels on paper, the term is usually applied to the network of meridians and parallels plotted for topographical work in the field

The term *projection* though sanctioned by long usage, is an unfortunate one It gives the beginner the idea that map projections are arrived at in the same way as the projections treated of in solid geometry Now the great majority of useful map projections are not obtained in any geometrical way A map projection is to be treated as the representation on a plane by any law of the terrestrial meridians and parallels in fact any definite system of drawing the meridians and parallels is a map projection

Before dealing with the general subject of map projections a subject which every topographer should have some acquaintance with we will describe the projections used in the field

It is obvious that since the surface of the earth is curved no portion can be represented on a plane with entire truthfulness It is evident also that the smaller the portion to be represented the more nearly will it be represented truthfully If for instance we represent



Fig 43 *

on paper a portion of the earth s surface extending 30 from north to south and 30 from east to west and draw meridians and parallels as straight lines, then the portion ABCD of the earth s surface is represented by the trapezium *abcd* in which *ab bc, ad cd* are the rectified lengths of AB BC AD CD

Now it can be shown that if AB BC CD AD do not exceed 30 then the surface ABCD can be represented by the rectilinear figure *abcd* on scales of $\frac{1}{4}$ inch to a mile and under without causing the topographer to make sensible errors If the parallels were drawn on paper as portions of circular arcs cutting the meridians at right angles, the result would be still more accurate But in the field it is inconvenient to plot circular arcs and the topographer must as a rule be content to plot his graticules with straight lines

A graticule should be drawn on *every small scale map* which as a rule, *should be bounded by meridians* and *parallels* The object of the graticule is to identify positions to enable new points to be plotted to enable maps to be compared with each other, and to facilitate joining maps of the same scale together

It is not very important what the intervals are The following would be suitable —

On a scale of $\frac{1}{4}$ inch to a mile the meridians and parallels should be drawn for every $\frac{1}{2}$ degree
On a scale of 1 inch to a mile the meridians and parallels should be drawn for every $\frac{1}{4}$ degree
On a scale of 1 inch to a mile the meridians and parallels should be drawn for every $\frac{1}{8}$ degree

* The convergence of the meridians is much exaggerated in this figure

Example of Plotting a Graticule—It is required to plot the graticule of a map on a scale of $\frac{1}{4}$ inch to 1 mile, between 10° and 11° N lat and 25° and 26° E long

From Table X., by simple proportion, take the values in *miles* of the 30′ lengths of meridians and parallels Divide these by 4 to get the lengths in inches

The diagonals of the squares are obtained as shown at the foot of Table X

Thus

$$BE = \sqrt{(8\cdot59 + 8\cdot51 \times 8\cdot50)}$$
$$= 12\cdot09 \text{ inches}$$

Now, having all the necessary data, take the plane table or map and draw the straight line AB (fig 44) for the central meridian

Measure AC CB the lengths of 30 of latitude, then with centre B and radius BE

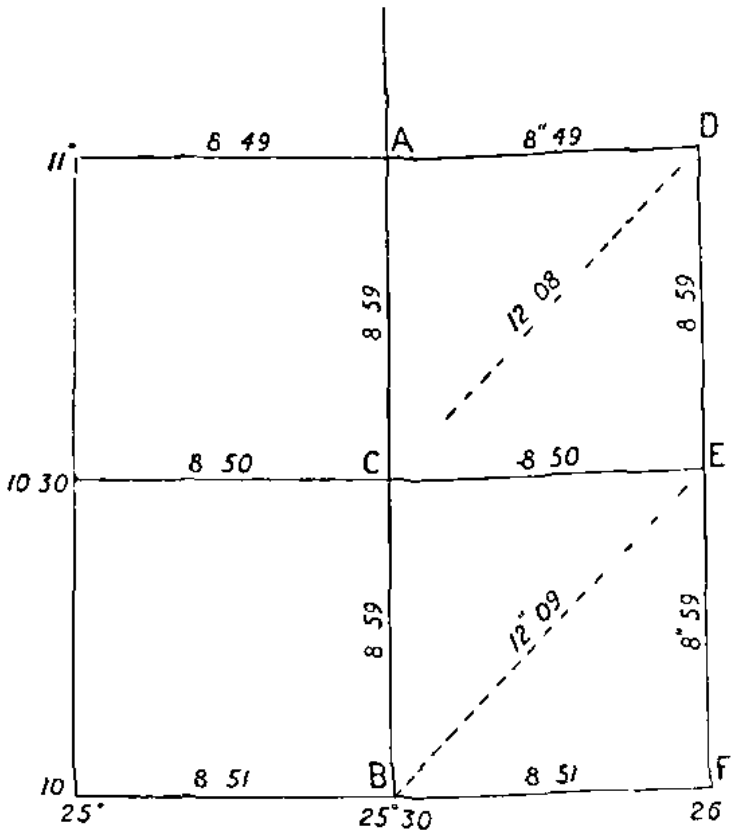


Fig 44

(diagonal) intersect a circle with centre C and radius CL (30 of longitude) Similarly for the other trapeziums

The result will be a graticule in which the meridians converge, and the parallels are concave to the pole

Second Example of Plotting a Plane Table Graticule—Suppose it is required to plot a graticule on a scale of $\frac{1}{4}$ inch to 1 mile Limits 30 and 31 S 25 and 26 L

Proceed as follows (fig 45) —

Draw a straight line ABC down the middle of the paper to represent the central meridian 25° 30 L

Look out in Table X the length of 30 of latitude from 30 to 30° 30′ This is 34 440 miles, or on this scale 8 61 inches, mark this length CB From 30° 30′ to 31 is found in the same way to be 8 61 inches, mark this BA

Next look out the length of 30 longitude on parallels 30° and 30° 30, viz, 7 50 and 7 46 inches

Then the length of the diagonal of the northern quadrilaterals

$$= \sqrt{\{(8\ 61)^2 + 7\ 50 \times 7\ 46\}} = 11\ 41 \text{ inches}$$

In a similar way it is found that the diagonal of the southern quadrilateral is 11 37 inches

Plane Table Graticule

Dimensions in inches for a scale of 4 miles to 1 inch

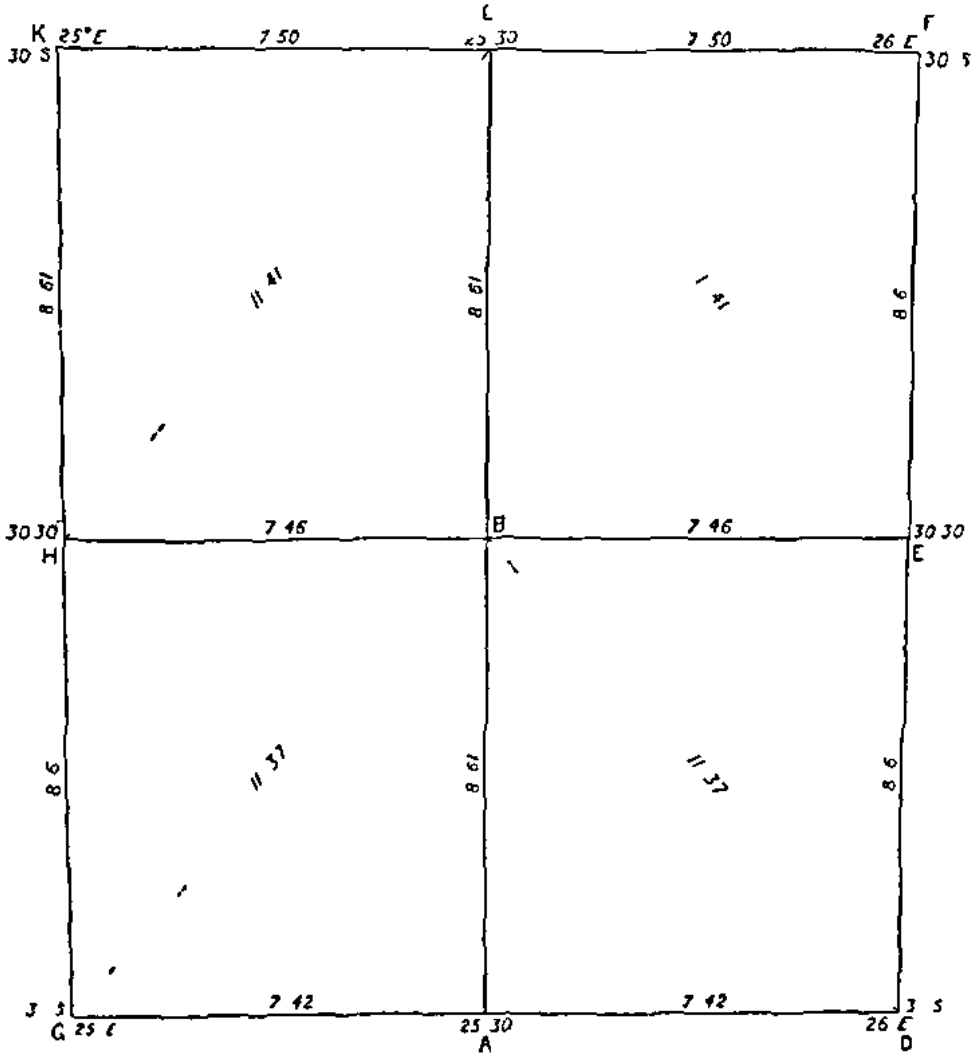


Fig 45

Now with centre C describe a circle of 11 41 inches intersect a circle with centre B and radius 7 46 inches thus fixing F and so on for the other points F, D G H, K

This method can be used for graticules on all topographical scales and for any intervals between the meridians or parallels

But to save labour in plotting graticules on the scale of 2 miles to 1 inch (a very useful topographical scale) Table IX has been prepared and from this the lengths of 15 spaces on meridians and parallels and the lengths of the diagonals can be taken directly This table is not to be used for other scales or other intervals

The field projection above described is to be considered as a rectilinear approximation to a conical projection It is all that a topographer absolutely requires in the field, but if it is

possible it is better (though not actually central) to plot the parallels as portions of circular arcs Labour saving tables for the purpose are The Construction and use of Marginal Lines for Maps' J O Farrell 1862, a War Office pamphlet 'On the Projection of Maps' by Major L Darwin R E and 'Tables for a Polyconic Projection of Maps' published by the United States Coast and Geodetic Survey

We now proceed to the general discussion of the subject of map projections The remainder of this chapter need not be read by the beginner

General Discussion of the Subject of Map Projections

The term map projection is sometimes misunderstood to mean a projection by means of straight lines from the earths surface on to a plane cylindrical or conical surface It is actually a term of much wider meaning Any representation on a plane by any law of the network of terrestrial meridians and parallels is a map projection and the great majority of useful map projections are not arrived at in any obvious geometrical way

It is necessary to bear in mind that, in general, a map projection is not a simple geometrical projection but the result of any definite system of drawing the earths meridians and parallels

There is a common idea that because there can be no perfect plane projection, all projections are equally bad or good an idea encouraged by the customary geometrical way of looking at the question Now the choice of a projection for a map is in general by no means a matter of indifference Projections may indeed be considered as graphic representations of certain properties of the curved surface, and if we know the special purpose of the map we also know the special property or quality which it is most important to represent truthfully

Useful theories of map projection are based on this fact that although it is impossible to represent on a plane surface any portion of a spherical or spheroidal surface with entire truthfulness yet we may select some quality or property of the curved surface and represent that accurately

For instance, there is a whole group of projections in which areas are correctly represented, another group in which there is no local distortion another group which preserves the azimuths from a central point one projection which preserves distances and azimuths from a central point one projection in which circles are still represented by circles whilst in most projections we can represent at least one line correctly in addition to other properties

There is also a class of projection in which no general property is accurately represented but all properties are represented fairly well a sort of golden mean

Field Projections

All map making is divided into two parts—work in the field and work indoors The former includes surveys explorations and reconnaissances the latter is a matter of drawing reducing, or compiling

Field Projections

First Large scale cadastral surveys such as $\frac{1}{500}$ maps of the Ordnance Survey or the 16 inch to the mile maps of the Survey of India are always based on a triangulation plotted by rectangular co ordinates latitude and longitude are not usually marked if they were the resulting projection would be that known as Cassinis Each sheet represents such a very small part of the earths surface and the boundaries are so near the central meridian that the matter need not be gone into further

Secondly Rapid explorations usually result in maps of a rough and ready order, most interesting but not most accurate The intrepid explorer draws a thin red line across a

continent, and there is little on each side of it If his march is east and west, he should use a simple conical projection, if north and south, a polyconical, and if in a diagonal direction, a so-called secant conical projection

Thirdly What projection should be used in the field by the topographer who works on scales varying from $\frac{1}{10000}$ to $\frac{1}{500000}$? As the difficulties evidently increase as the scale decreases, we can deal with the smaller scale

When the plane-tabler looks along the sight rule, any points which are bisected by the central vertical thread are considered to be on the same straight line That is, great circles are represented by straight lines Hence, considering this condition only, the plane-table is on the gnomonic projection

But the plane-tabler also expects that the scale shall be the same all over the map

If we only consider one point, and set up the plane table at this point, all rays from this point are to represent great circles, and the scales of all the rays are to be the same This gives the equidistant zenithal projection

If the plane-table is set up at other points, we get conflicting conditions, which, in theory, are best reconciled by Airy's projection, but in practice are approximately satisfied by some form of conical projection, provided that the area of the plane table does not exceed about 1 square degree

In the field it is inconvenient to plot such flat arcs as are required for the parallels, it is therefore customary to substitute for them rectilinear inscribed polygons, or, which comes to much the same thing, to plot, instead of a small portion of the curved parallel, a straight line of the same length

The resulting projection may be known as the field rectilinear projection, it should not be used where the extent of latitude is more than 2 degrees

There is a case on record in which a survey party commenced work on Mercator's projection, which is, of course, entirely unsuited for land surveys

List of Projections

We can now deal with the more general and interesting question of the projections used to represent much larger portions of the earth's surface, or even the whole of it

Projections have been termed —

a **Orthomorphic** (or *conform*, or *conformal le*) —In these the scale is the same in all directions round a point in its immediate neighbourhood. It follows that very small areas are similar in outline to the originals on the earth's surface It also follows that the meridians and parallels intersect at right angles, though the fact that they intersect at right angles does not show that a projection is orthomorphic Mercator's is a projection which belongs to this group, so does the stereographic

b **Equal Area** (or *equivalent*, or *surface-true*) —In these, equal areas on the map represent equal areas in reality, i e, areas are correctly represented, though distances and angles are not Bonne's modified conical projection belongs to this group

c **Perspective**, a name which explains itself The eye may be imagined to be inside, outside, or on the surface of the earth The gnomonic projection is perspective

d **Zenithal**.—In these the azimuths round a central point to all other points are correctly represented and equal distances from this point represent equal distances in reality Perspective projections are zenithal though all zenithal projections are not perspective The equidistant projection belongs to this group

e **Conical**, which can be imagined as drawn on the surface of a cone (not necessarily *projected* on to the cone)

f **Cylindrical**, which can be imagined as drawn on the surface of a cylinder. Mercator's is cylindrical

/ **Conventional**—Those which are projected by arbitrary rules for convenience of drawing The globular projection is conventional, so are polyconics

These terms do not strictly represent classes of projections as they are not all mutually exclusive nor do they comprise all possible projections and to treat them as classes would be to fall into his error who divided the human race into Frenchmen red haired people, and cannibals

Thus we may have an orthomorphic cylindrical projection (Mercator's) or an equal area cylindrical projection (Lambert's) or an equal area zenithal projection (Lorgna's), and so on (But a projection cannot be both orthomorphic and equal area which would imply a perfect representation) The seven terms given are in fact just descriptive terms

The following is a list of the thirty principal projections, a description of each is given on pp 100 to 111

Orthomorphic —

1 Mercator's (cylindrical orthomorphic),
2 Transverse Mercator's (Lambert's first),
3 Conical orthomorphic (Lambert's second),
4 Circular orthomorphic (Lagrange's) Also the stereographic (17)

Equal Area —

5 Cylindrical equal area (Lambert's third),
6 Transverse equal area (Lambert's fourth)
7 Modified conical equal area (Bonne's)*,
8 *Sinusoidal equal area* (Sanson Flamsteed),
9 Polar equal area (Werner's),
10 Simple conical equal area (Lambert's fifth),
11 Conical equal area (Albers'),
12 Zenithal equal-area (Lambert's sixth—called Lorgna's)
13 Pectilinear equal area (Collignon's),
14 Homalographic equal-area (Mollweide's)

Perspective —

15 Orthographic
16 Central or gnomonic,
17 Stereographic,
18 Minimum error (Clarke's),
19 Jamess,
20 La Hire's

Zenithal —

21 *Equidistant zenithal*
22 Projection by balance of errors (Airy's)
Also the zenithal equal area (12)
And perspective projections (15 20)

Conical —

23 *Simple conical*,
24 Conical with rectified meridians and two standard parallels sometimes wrongly called 'secant conical
25 Simple polyconical
26 Rectangular polyconical,
Also Nos 3, 7, 10, and 11

* Sometimes though wrongly called Flamsteed's Modified

Cylindrical —

27 Simple cylindrical,
Also Nos 1, 2, 5, 6 and 29

Conventional —

28 Globular
29 Projection by rectangular co ordinates (Cassini's),
30 Field rectilinear
Also Nos 25 and 26

This is not a complete list of all the projections which have been in use, there are a number of others (especially perspective and conventional projections) which have been proposed or used, but they are not now of any importance, and their interest is only historical

Those interested in the subject will find a very complete account, both technical and historical, in an admirable work, entitled "Traité des Projections des Cartes Géographiques," A Germain, Paris A Bertrand, Editeur, Libraire de la Société de Géographie

The Choice of Projections

The choice of a projection falls under one of the following cases —

(1) *For field work* This has been discussed
(2) *For a single sheet map*,
(3) *For a series, which is to be capable of being accurately fitted together*,
(4) *For a series without the last condition*

(2) *Single sheet maps* —

This second case includes any map, though it may be made up of several parts, which is meant to be used as a unit The Cape Colony $\frac{1}{6000000}$ map is an example This case also includes all atlas maps All possible projections are available though all are not equally suitable for the special purpose in view For instance, statistical maps should be on equal area projections great circle charts on gnomonic projections and so on

A single-sheet map of Africa may be taken as an example and the following is a preliminary selection —

Equal area	Sanson Flamsteed or Zenithal Meridian (Lambert's)
Zenithal	Balance of Errors (Airy's) or Equidistant meridian
Conical	Simple polyconical or Rectangular polyconical
Orthomorphic	Mercators or Stereographic meridian
Perspective	Minimum error (Clarke's) or Orthographic meridian

Of these Mercators is out of the question for any land purpose

If the map is a political or statistical map, one of the equal area projections should be taken and of these the zenithal is the best, and Sanson Flamsteed the easiest to draw

If the map is for general purposes we may reject equal area and orthomorphic projections as being extreme cases and the polyconic projections as conventional, and finally choose from

Balance of errors (Airy's)	No 22
Minimum error perspective (Clarke's)	No 18
Zenithal equidistant	No 21

These are all good projections for the purpose

(3) *A One Projection Series* —

The third case is that of a series of maps which are to be capable of being accurately fitted together, i.e. which are to be on one projection. This case, which is practically very convenient, can only be used for a comparatively small part of the earth's surface and on medium scales (i.e. smaller than topographical and not so small as atlas scales).

We may take as a typical country for this treatment Africa south of the Zambesi and as a typical scale 1 : $\frac{1}{6}$. It is not absolutely necessary, but it is convenient, to bound the sheets by meridians and parallels. All this points to the use of a conical projection, and one of the best for the purpose is that form of conical projection in which the meridians are their true lengths and in which the errors of scale along the extreme parallels and parallel of maximum error are made equal. In the case of S. Africa the errors on the parallels mentioned are less than $\frac{1}{2}$ per cent. whilst the scale along the meridian is correct throughout.

(4) *A Topographical Series* —

The fourth case is that of a series of maps of which each sheet is independent, the sheets are not meant to fit accurately together, and the accuracy of each sheet is the principal consideration, i.e. the case of ordinary topographical maps.

Each sheet will be constructed on its own central meridian, and the projection (as for the field) will be a conical projection. But on account of the smallness of the area dealt with simple or rectangular polyconic, give sensibly the same results. The present War Office system is the rectangular polyconic, p. 110, and it does very well for topographical scales.

Note.—When the country is of small extent in either latitude or longitude topographical maps may be projected on one projection as in Case 3 above. Ordnance Survey one inch maps of England, for example, are a series on Cassini's projection, and the extreme error due to the projection does not amount to $\frac{1}{50}$, i.e. less considerably than may be expected from the distortion of the paper.

$\frac{1}{1000000}$ *Map* —

The question of the projection to be chosen for the universal 1 : $\frac{1}{1000000}$ map is interesting, and Africa may be taken as an example.

First, it is clear that a general projection for the whole of Africa is out of the question on such a scale.

Next we *may* construct each sheet independently, and this may sometimes be the best system, but some difficulties would be found in fitting the sheets together since each will represent some 24 square degrees.

Perhaps the best system is a compromise: special areas such as Egypt, Nigeria, S. Africa, &c., should be treated as units, each on the special projection best suited for its particular case. This course would have the balance of local advantage which is the chief thing to consider, and the projection can be so chosen that the resulting error is negligible. The only objection to this occurs when it is required to fit on sheets of an adjoining block. This can be obviated by arranging that the sheets shall well overlap the boundary.

Projections Used for Some Important Maps

Conical Orthomorphic (Lambert's second). Generally known as Gauss's. (No. 3.)

Used for a map of Russia published by the Geographical Society of St. Petersburg in 1862.

Modified Conical Equal area, known as Bonne's. (No. 7.)

Adopted in 1803 by the Depôt de la Guerre for the map of France.

Ordnance Survey 1 inch, ½ inch, ¼ inch of Scotland and Ireland.

Ordnance Survey 10 mile maps of Scotland and Ireland
Indian Atlas 4 miles to 1 inch
Cape Colony $\frac{1}{800\,000}$

Orthographic (No 15)
French map of Africa $\frac{1}{2\,000\,000}$, 1895, where its defects are very marked

Central or Gnomonic (No 16)
Some charts have been published on this projection by the U S Hydrographic Department

Zenithal Projection by Balance of Errors (Airy's) (No 22)
Ordnance Survey 10 mile map of England

Conical with rectified Meridians and two Standard Parallels (No 24)
Ordnance Survey $\frac{1}{1\,000\,000}$, 1904
Survey of India Indian and Adjacent Countries, $\frac{1}{1\,000\,000}$, 1904

Simple Polyconic (No 25) U S Coast Survey maps

Rectangular Polyconic (No 26) Intelligence Division, War Office maps

Projection by Rectangular Co-ordinates or Cassinis (No 29)
Ordnance Survey 1 inch, $\frac{1}{2}$ inch, and $\frac{1}{4}$-inch of England
" " 6 " of The United Kingdom
" " $\frac{1}{500}$ " "

Brief Description of the Thirty Principal Projections

Orthomorphic Projections

1 **Mercator's,*** or cylindrical orthomorphic

In this projection the meridians and parallels are straight lines at right angles to one another

The meridians are spaced at their equatorial distances

The distance of any parallel from the equator is —

$$\frac{a}{M}\left\{\log\tan\left(45^\circ+\frac{l}{2}\right)-e^2\sin l\quad\frac{e^4\sin^3 l}{3}\qquad\right\},$$

where a and b are the semi axes,

$$e=\frac{\sqrt{a^2-b^2}}{a},$$

M the modulus of common logarithms, l is the latitude

The scale at any point is the same in all directions, and small outlines are represented without distortion A straight line represents a loxodrome or line of constant true bearing, the projection is therefore universally used at sea, it is of no value for land surveys A loxodrome continuously pursued describes an endless spiral round the pole

2 **Transverse Mercator's**, or transverse cylindrical orthomorphic (Lambert's first) †

Mercator's projection may be considered as developed on a cylinder touching the earth along the equator, imagine this cylinder turned round so as to touch some chosen meridian The lines which formerly represented meridians now represent great circles at right angles to the chosen meridian, and the lines which represented parallels now represent small circles parallel to that meridian It is not necessary to consider this further

3 **Conical Orthomorphic Projection** (Lambert's second), generally called Gauss's

* Mercator, born A D 1512, died 1594
† Lambert German mathematician born 1728 died 1777

In this projection the parallels are represented by concentric circles and the meridians by their radii Two selected parallels are of their proper lengths, but the lengths of the other parallels and of the meridians are determined by the following law, treating the earth as a sphere —

If z_1, z_2 are the co-latitudes of the selected parallels

$$\text{let } \lambda = \frac{\log \sin z_1 - \log \sin z_2}{\log \tan \frac{z_1}{2} - \log \tan \frac{z_2}{2}},$$

then the angle two meridians make with each other

$$= \text{true difference of longitude} \times \lambda,$$

then if r is the required radius of a given parallel (of co-latitude z) l a constant which defines the scale

$$r = l \left(\tan \frac{z}{2}\right)^{\lambda}$$

This is a remarkable and useful projection* Small outlines are correctly represented, and the scale is the same in all directions round any point The scale along two parallels is correct and is consequently correct in their neighbourhood in every direction Between the selected parallels the scale is very slightly too small outside them it is too large It has been used for a map of Russia and is very suitable for large areas having a great extent in longitude

4 **Circular Orthomorphic Projection** (Lagranges)

In this both meridians and parallels are represented by circular arcs More interesting to the mathematician than useful to the map maker

The stereographic projection is orthomorphic See No 17

Equal-area Projections

5 **Cylindrical Equal area Projection** (Lambert's third)

If the earth is considered a sphere this is the simplest of all projections Imagine a cylinder to circumscribe the earth touching it at the equator and from every point on the earth let a straight line be drawn at right angles to the earth's axis and produced backwards to intersect the cylinder When the cylinder is unrolled the meridians and parallels are clearly straight lines at right angles to one another and the distance of any parallel from the equator is equal to $a \sin$ lat when a is the radius

It follows from the elementary geometry of sphere and cylinder that the projection is equal area

This projection is only useful for maps which do not extend more than a few degrees from the equator

6 **Transverse Cylindrical Equal area Projection** (Lambert's fourth)

If the cylinder touches the earth along a meridian and points are projected as above then, treating the earth as a sphere if x, y are the co-ordinates of a point l, ι its latitude and longitude

$$x = \sin \iota \cos l,$$
$$\tan y = \tan l \sec \iota$$

The meridians and parallels can be drawn by giving ι and l respectively constant value

This projection can be used for countries having a great extent in latitude and but little in longitude It is not, however, the best for the purpose

* This last expression may be taken as giving the whole group of orthomorphic conical projections of which this is a particular case Mercator's is another

7 **Modified Conical Equal area Projection** (Bonne's), sometimes called the modified conical or Bonne's projection and known in France as "projection du dépot de la guerre This, with its two modifications (8 and 9), is an important projection

Imagine a cone having the same axis as the earth to touch it along any selected parallel, imagine the cone spread out and a radius of this parallel taken as the central meridian Along this central meridian on each side of the parallel, measure the true rectified distances to the other parallels Through these points describe circles having the same centre as the chosen parallel and along each parallel measure the true distances to the successive meridians

The projection is clearly equal area, since all of the small elements between any two parallels bounded by two infinitely close meridians are equal to each other, and to the corresponding elements on the earth's surface

The true spheroidal shape of the earth has been taken account of

If l_1 is the latitude of the selected parallel, and l of any other parallel, the radius of the latter is r cosec l_1 + the rectified arc of meridian between l and l_1 Where $r = \frac{180}{\pi} \times$ length of 1 of chosen parallel This can be found from geodetic tables

The projection has the following properties —

(1) It represents areas correctly
(2) Parallels are their true lengths
(3) The meridians cross the chosen parallel at right angles

The meridians are not simple curves, though so easily constructed

The projection has been much used in France, and the $\frac{1}{500\,000}$ map of Cape Colony published by the Surveyor General is also on this projection also the Ordnance Survey 1 inch maps of Scotland and Ireland

The less its extent in longitude the better It is frequently used in ordinary atlases for countries for which it is not suited—Asia, for example

8 **Sinusoidal Equal area Projection** (Sanson's) —Sometimes, though wrongly called Flamsteed's or Sanson Flamsteed

If Bonne's cone (No 7) touches the equator, it becomes a cylinder, and each parallel becomes a straight line at right angles to the central meridian cutting it at the true distance from the equator Along each parallel distances are measured from the central meridian equal to the portion of the arc of the parallel represented

Assuming the earth a sphere each meridian becomes a sine curve, hence the name of the projection But it is clearly equally easy to plot the true spheroidal lengths The general remarks on the last projection apply to this It is a good equal area projection for the whole of Africa

9 **Polar Equal area Projection** (Werner's)

If Bonne's cone touches the pole, the cone becomes a plane The parallels are then incomplete concentric circular arcs with the pole as centre, the central meridian is still a straight line, which is cut by the parallels at true distances The meridians as before pass through points on the parallels at true distances from the central meridian measured along the arc

This projection though interesting is of little use It is not possible to use it for Polar regions and is clearly inferior to the two previous projections for other parts of the earth's surface

10 **Simple Conical Equal area Projection** (Lambert's fifth)

In this projection the parallels are concentric circles of which the pole is the centre the meridians are radii The radius of each parallel is

$$2a \sec \frac{z_1}{2} \sin \frac{z}{2},$$

when a is the earth's radius, θ the co-latitude, and θ_1 the co-latitude of a selected parallel, which is then correctly represented The angle any two meridians make with each other is $\alpha \cos^2 \frac{1}{2}$ when α is the difference of longitude

The cylindrical equal-area projection is *not* a particular case of this because here we have the condition that the pole is the centre of the circular parallels

The properties of this projection are —

(1) It represents areas correctly ,
(2) The meridians cut the parallels at right angles ,
(3) The selected parallel is correctly represented
(4) It is easy to draw

The objection to it is that it misrepresents distances both along the parallels and along the meridians It cannot be used near the poles nor for countries having a great extent in latitude

If in the above we put $\theta_1 = \theta$ the radius of each parallel is $2a \sin \frac{\theta}{2}$, the meridians are *then inclined at their true angles to each other* *(See No 12)*

11 Conical Equal-area Projection (Albers)

In this projection any two selected parallels are correctly represented The projection consists of concentric circles with radii for the meridians but the pole is not now the centre

If l_1 l are the chosen latitudes r_1 the radii on paper, put $l = \frac{1}{\sin \frac{l_1 + l}{2} \cos \frac{l_1 - l}{2}}$

a being the earth's radius

Then $r_1 = l a \cos l_1$

$r = l a \cos l$

the inclination of two meridians $= \frac{\text{angular difference of longitude}}{l}$ and if r is the radius of any other parallel of latitude l $r = 2 a l (\sin l_1 - \sin l) + r_1$

The pole is now represented by the arc of a circle Two parallels are correctly represented and the properties are otherwise the same as those of the preceding projection Except for very large areas it does not differ materially from No 24 where representation of areas is important it should be used in preference It should not be used near the pole It would make a good projection for Central Asia

12 Zenithal Equal-area Projection (Lambert's sixth) Sometimes though wrongly called Lorgna's

This is a particular case of 10 Meridians are represented by straight lines at their true angles to each other The parallels are circles of which the meridians are radii If θ is the co-latitude of any point and a the earth's radius or better the radius of curvature at the pole the radius of any parallel is

$$2 a \sin \frac{\theta}{2}$$

As described it may be called the polar equal-area projection

The same projection can however be applied to any part of the earth's surface if we *imagine great circles to radiate from* some selected point in the same way as the meridians radiate from the pole The meridians and parallels can be drawn by a transformation of spherical co-ordinates In the special case where the central point is on the equator we have (assuming the earth spherical)—

If θ is the angular distance of any point from the centre, l α the latitude and longitude of this point,

$$\cos \theta = \cos \alpha \cos l$$

If A is the azimuth of this point at the centre, tan A = sin α cot l, A is then truly drawn and the distance θ is represented by

$$2a \sin \frac{\theta}{2}$$

The properties of this projection (which is on the spherical assumption) are—

(1) It is zenithal, *i e* azimuths are correct at the central point and equal distances are represented by equal distances ,
(2) It is equal area
(3) There is but little deformation for 30° from equator or central meridian

It is a very good projection for a single sheet equal area map of Africa

13 **Rectilinear Equal area Projection** (Collignon's)

The meridians are straight lines which radiate from the pole and the parallels are parallel straight lines cutting the central meridian at right angles

Interesting but of little use

14 **Homalographic Equal area** (Mollweide's) Sometimes called Babinet's

The parallels are parallel straight lines and the meridians are ellipses, the central meridian being a straight line at right angles to the equator which is equally divided

The distance of any parallel from the equator is $\sqrt{2} \sin \delta$ where $\pi \sin lat = 2\delta + \sin 2\delta$

The whole sphere can be represented in an ellipse of which the major axis is twice the minor

Perspective Projections

Generally speaking these projections are of no value for land surveys

The principal consideration is the position of the point of sight The projection plane is always supposed to be at right angles to the line joining this and the earth's centre, the distance of this plane from the centre only affects the scale

15 **Orthographic Projection** —In this the point of sight is supposed to be infinitely distant, and the perspective rays consequently at right angles to the projection plane If the plane of projection is the equator, the result is the polar orthographic, if a meridian, a meridian orthographic and if any other plane, a horizontal orthographic

In the latter case which is the most general, it is clear that the central meridian is a straight line and all other meridians and parallels are ellipses, obviously only a hemisphere can be represented From the nature of the case it is a pictorial projection, and from its simplicity it is a good deal used in popular works It is not the best perspective projection for large areas and for practical purposes is of little use The laws of its construction are very obvious

It has been used for the French $\frac{1}{5\,000\,000}$ map of Africa The distortion on the extreme sheets, *e g* St Louis, is very marked It is a projection to be avoided

16 **Central** or **Gnomonic Projection** —In this projection the eye is imagined to be at the centre of the earth As before we may have polar, meridian, or horizontal, central projections In the latter case, which is the most general, the meridians are straight lines which meet at the pole, the parallels are conic sections The term gnomonic was applied in ancient days to this projection because the projection of the meridians is evidently a similar problem to the graduation of a sun dial If θ is the angle any meridian makes on paper with the central meridian,

λ the inclination of the projection plane to the earth's axis,

α the difference in longitude of the meridians,

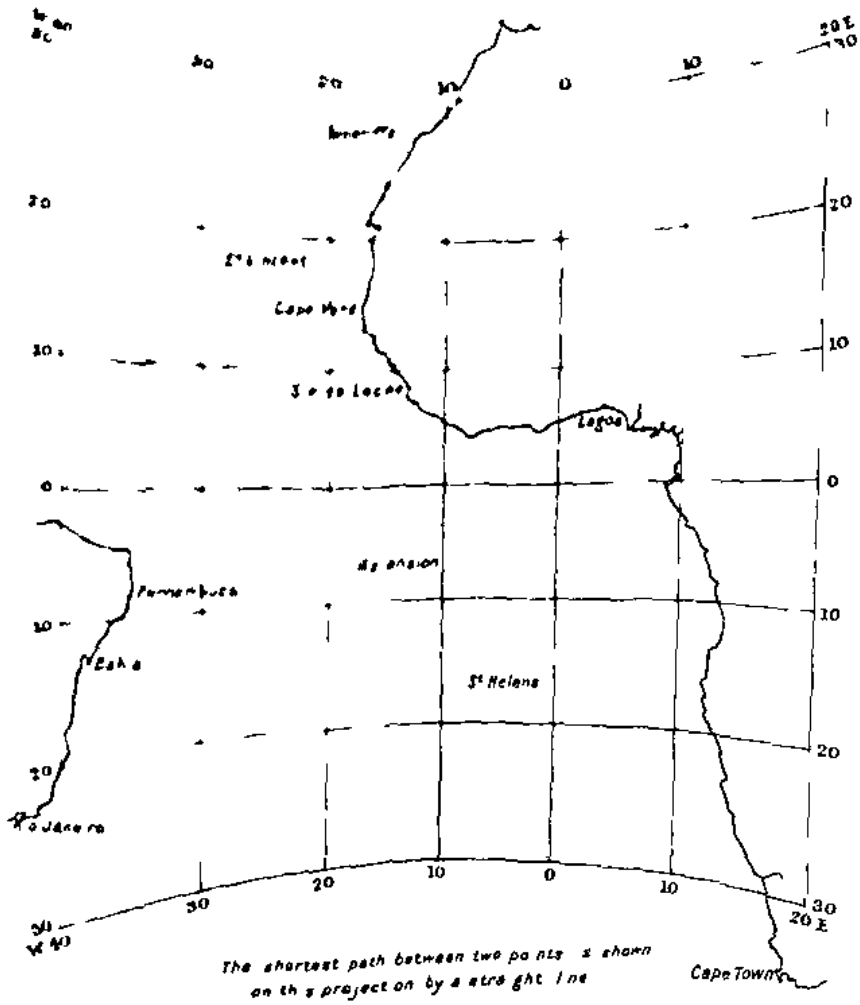
$$\tan \theta = \sin \lambda \tan \alpha ,$$

Part of the

ATLANTIC OCEAN

on a

MERIDIAN GNOMONIC PROJECTION

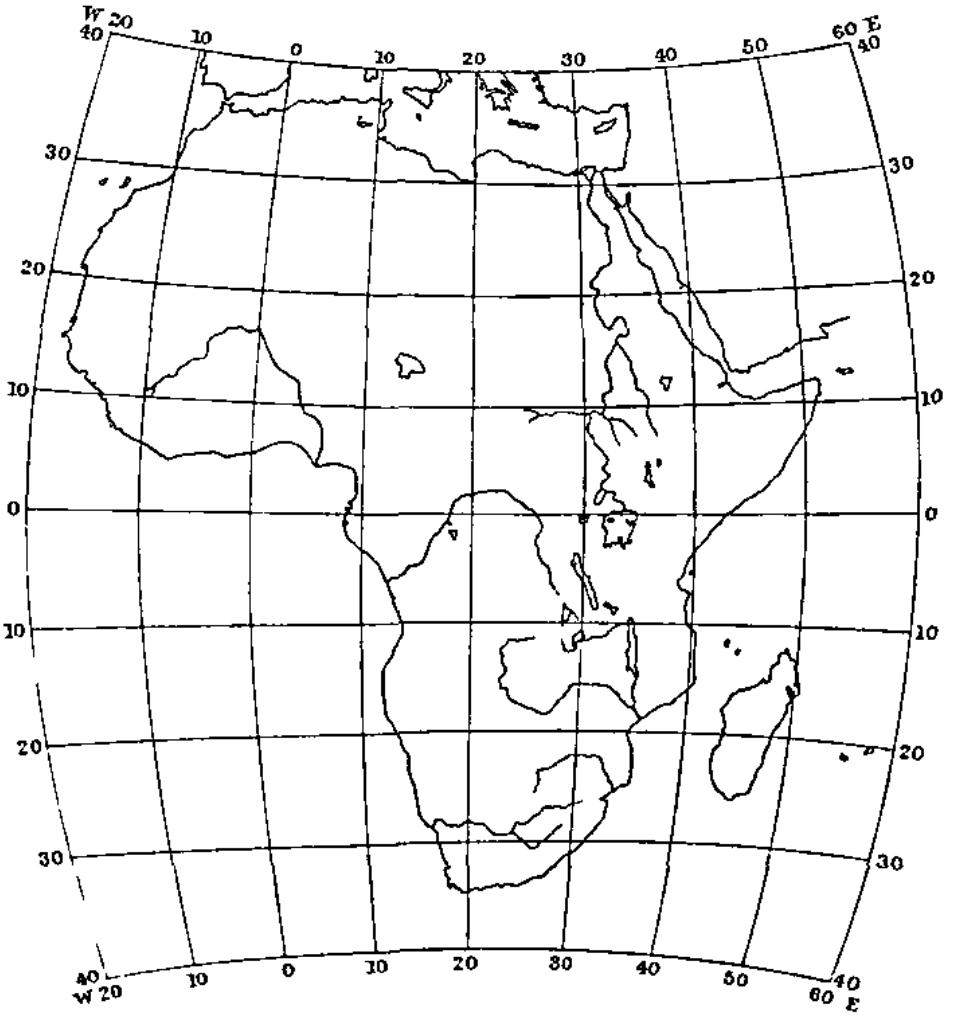


The shortest path between two points is shown on this projection by a straight line

AFRICA

on

CLARKE'S PERSPECTIVE PROJECTION



The distance of the point of sight from the centre of the earth is 1·625 x radius

and if l is the geocentric latitude of any other point, the distance from the equator along the meridian is

$$n\frac{\sec\alpha \sin l}{\sin(l+\alpha)}, \text{ where } \tan\alpha = \cot\lambda\cos\alpha, \text{ and } n \text{ is a constant defining the scale}$$

The equator is of course a straight line at right angles to the central meridian

The special property of the projection is that all great circles on the sphere (*i.e.* shortest lines) are represented by straight lines There is no projection which accurately possesses this property for the spheroid but one which does so very nearly is that which results from the intersection of terrestrial normals with a plane In this case the normal sections between two points, either on the same parallel or the same meridian are strictly represented by straight lines

The central projection is useful at sea for star charts and for the study of direct routes in great countries

An example is here given of part of the Atlantic Ocean on a meridian gnomonic projection (Plate XIV)

17 **Stereographic Projection** —In this the eye is imagined to be on the surface of the sphere which is supposed to be hollow and the surface represented is that of the opposite portion of the sphere The projection is orthomorphic, and has the remarkable property (on the spherical assumption) that circles are represented by circles It has of course, three aspects, polar meridian and horizontal In the latter case which is the most general, the central meridian is a straight line the others are circles intersecting at the pole The parallels are circles but are not concentric The graphic construction is simple As it is only used for general maps of the hemisphere on very small scales and not much for these, there is no need to consider the compression of the earth

18 **Minimum Error Perspective Projection** (Clarke's) *—In this projection (due to Colonel Clarke) the point of sight is outside the sphere and the distant surface is that to be represented The position of the point of sight is chosen so that at each point the sum of the squares of the errors of scale in two directions at right angles to each other shall be a minimum over the whole surface In other words the total misrepresentation is a minimum The surface to be represented is that cut off by a plane parallel to the projection plane, and the boundary is therefore a circle

If u is the spherical arc between any point and the adopted centre, h the distance of the point of sight from the centre l a constant defining the scale, then the distance at this point from the centre (on the map) is

$$\frac{l \sin u}{h + \cos u}$$

The following table shows the value of h for several values of β (the spherical radius of the map) —

β	h
40°	1 625
54	1 61
90	1 47
108	1 40
113½	1 367

19 **Sir Henry James's Projection** —This is a particular case of Clarke's projection in which the spherical radius of the area to be represented is 113½ , in this case h 1 367

* Colonel A R Clarke, C B , R E , F R S

(*As originally described by Sir H James, h was taken as 1 5, which does not give the minimum error*) The total area represented is about two-thirds of the earth's surface

20 **La Hire's Projection** —A perspective projection in which the point of view is outside the sphere at a distance from the centre equal to $\left(1 + \frac{1}{\sqrt{2}}\right) \times$ radius The middle point of the radius of the map of a hemisphere, therefore, represents the middle point of the opposite quadrant It is used for maps of a hemisphere, but has no great merit It is sometimes confused with the globular projection, which is a conventional one (No 28)

Zenithal Projections

21 **Equidistant Zenithal Projection** —In this projection, any point on the sphere being taken as the centre of the map, great circles through this point are represented by straight lines of the true length to scale, and intersect each other at the true angles There may thus be polar, meridian and horizontal equidistant zenithal projections

The position of the intersection of any meridian with any parallel is given (on the spherical assumption) by the solution of a simple spherical triangle

Thus if γ_1 is the co latitude of the centre of the map (longitude 0),

" " any other point

α " *longitude of* " "

A " required azimuth

c " " spherical distance

Let $\tan \theta = \tan \gamma_1 \cos \alpha$, then $\cos c = \cos \gamma_1 \sec \theta \cos (\gamma \sim \theta)$ and $\sin A = \sin z \sin \alpha \operatorname{cosec} c$

The projection is neither orthomorphic nor equal area, the scale in the direction of the centre is always correct and at right angles is less than 5 per cent in error at 30° from the centre It would make a good projection for a single sheet map of Africa, and is especially useful for polar maps *

22 **Zenithal Projection by Balance of Errors** (*Airy's*) —*At any point of a zenithal* projection we may consider two scales one along the radiating straight line which represents a great circle and one at right angles to this

If these two scales are equal at each point, though they differ from point to point, the result is an orthomorphic projection—the stereographic (No 17)

If the product of the two scales is constant, the result is the zenithal equal area projection—Lambert's sixth (No 12)

But we may deal with them in a different way, and make the sum of the squares of the errors of the two scales at each point a minimum over the whole surface to be represented The result is Airy's projection, which we are now dealing with, in this the total misrepresentation is a minimum

If β is the spherical arc from proposed centre to proposed circumference, u the spherical arc of any point from the centre, then the distance of this point from the centre on the map is

$$2 \cot \frac{u}{2} \log_e \sec \frac{u}{2} + C \tan \frac{u}{2},$$

where

$$C = 2 \cot^2 \frac{\beta}{2} \log_e \sec \frac{\beta}{2}$$

All this is on the assumption that the earth is spherical

* The earliest known instance of the use of the Polar Equidistant Zenithal Projection occurs in a treatise by Clavenius written about A D 1510

This projection is, so to speak, the golden mean between an orthomorphic and an equal area projection. *It has been used for the Ordnance Survey 10 mile map of England.*

The zenithal equal-area projection, Lambert's (No. 12), and perspective projections (15 to 19) have been discussed.

Conical Projections

These are really developments on a conical surface, not projections on to the surface.

23. **Simple Conical Projection.**—Imagine a cone to touch the earth along any chosen parallel, the cone and the earth having the same axis. Unroll the cone; then the radius of the chosen parallel is $n \cot l$, where n is the normal terminated by the minor axis. Along this parallel measure the true lengths of the degrees of longitude (for the parallel in question), and join the apex of the cone and these points by straight lines—these are the meridians. The other parallels are circular arcs, concentric with the chosen parallel, and distant from it the true lengths of the rectified arc of the meridian.

This projection is unsuited for a country having a great extent in latitude, but it may stretch any extent in longitude. When the chosen parallel is the equator, the projection becomes the *equidistant cylindrical projection* (27), a projection of no value. When the chosen parallel is the pole, the projection becomes the *polar equidistant zenithal projection*, a very valuable projection already described (No. 21).

Note.—It is possible, though it has never been done, to construct transverse conical *projections in which the cone touches some parallel to a meridian.* In the same way it is possible to have transverse secant conical projections.

Again, these cones may be oblique, the pole of the small circles being neither at the earth's pole nor on the equator.

24. **Conical Projection, with 2 Standard Parallels.*** This is one of the most useful of all projections. (It is sometimes wrongly called "secant conical.")

Two selected parallels are represented by concentric circular arcs of their true lengths; the meridians are then ruled. The degrees along the meridians are represented by their proper lengths, and the other parallels are circular arcs through points so determined, concentric with the chosen parallels.

This construction evidently fixes the position of the centre of the parallels, for if $p_1 p$ are the true lengths of the chosen parallels, m the length of the intervening meridian (all of which can be taken from geodetic tables), then $h = \frac{p - p_1}{m} \times \frac{180}{\tau}$, where h = ratio between the inclination of two meridians on paper, and their true difference of longitude.

The parallels may be chosen arbitrarily from a consideration of the country to be mapped, but it is better to adopt one of the following methods:—

24*a*. The absolute errors for a given difference of longitude along the centre and extreme parallels may be made equal. This is Euler's projection. For the purpose of choosing the *projection it will be sufficient to treat the earth as a sphere, and in the construction to plot* the true spheroidal lengths of the meridian arcs.

Or (24*b*) the errors of *scale* on these parallels may be made the same as follows:—if c, c^1 are the co-latitudes of the extreme parallels, the distance in degrees of the centre of the parallels from the pole, h the ratio between the inclination of two meridians and their difference in longitude,

$$\frac{h(\quad + \quad)}{\sin c} \quad 1 - \frac{h(\quad + c^1)}{\sin^{\ 1}} - 1 \quad 1 - \frac{h\left(\quad + \frac{c + c^1}{2}\right)}{\sin \frac{c + c^1}{2}}$$

from which h and are easily found.

* The earliest known instances of the use of one of the axes of this projection occurs in maps of the two hemispheres by Ruysch, dated A.D. 1508.

Applying this to South Africa south of the Zambesi, taking the extreme parallels as 18° and 34° S., $h = 439$, $= 52° 7$, and the error of scale on the extreme and mean parallels is 0·0049 *i.e.* less than ½ per cent. or less than may be expected from ordinary contraction of paper.

On (24*c*) as suggested by Colonel Clarke, the mean length of all the parallels may be made correct still keeping the meridians their true length.

This is equivalent to equating the total areas of the zones, and must be combined with another condition for example, that the errors of scale on the extreme parallels shall be equal. (This is not the same as Airy's projection No. 11 in which the meridians are not kept their true length.) We then have

$$z = \frac{c^1 \sin c - c \sin c^1}{\sin c^1 - \sin c}, \quad h = \frac{\cos c - \cos c^1}{(c^1 - c)\left(z + \frac{(c + c^1)}{2}\right)}$$

in the case of South Africa, as above,

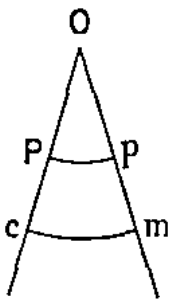
$$h = 440, \quad z = 52° 7,$$

i.e. practically the same result as 24*b*.

It is easy to imagine other variations, for instance, we may consider the maximum error instead of that of the mean parallel (24*d*). This projection was used for the $\frac{1}{1\,000\,000}$ Ordnance Map of the British Isles. There is no difficulty in working out the projection for the spheroid.

As an example of the choice of a conical projection we may take the case of South Africa, south of the Zambesi, the limits being 15° S. lat. to 35° S. lat.

To save labour, in the preliminary calculations the earth will be treated as a sphere.



Let *c* be the co-latitude of any parallel which is represented by *cm*, let P correspond to the pole, let OP = *z*, and the angle *com* = *hu*, where *u* is the true difference of longitude of the meridians *oc*, *om*, *Pc*, *pm* are their true lengths.

Then the error of scale along any parallel is $1 - \frac{h(z + c)}{\sin c}$. This is a maximum when $\tan c = c$.

Now, let it be a condition that the scale errors on the extreme parallels shall be equal, then the largest error will be a minimum when these two errors are equated to that on the parallel of maximum error.

Then

$$h\left(z + 75 \times \frac{\pi}{180}\right) \Big/ \sin 75 - 1 = 1 - h\left(z + 55 \times \frac{\pi}{180}\right) \Big/ \sin 55 = 1 - h(z + c)/\sin c,$$

where

$$\tan c - c = z.$$

From these equations we get

$$z = 56° 62$$
$$c = 64\ 66$$
$$h = 424,$$

and the maximum error of scale is less than 0·7 per cent. It occurs on the parallels of 15°, 25° 20′ and 35° S. *The errorless parallels, to the nearest degree, are those of 18° and 32° S.*

To plot the projection of which the elements have been thus determined we shall use the true spheroidal lengths, making the parallels of 18° and 32° S. errorless, this will slightly alter the value of *h* as follows —

The true length of the meridian between 18° and 32° S. is 963·70 miles.

The true length of 1° on the parallel of 18° S. is 65·808 miles.

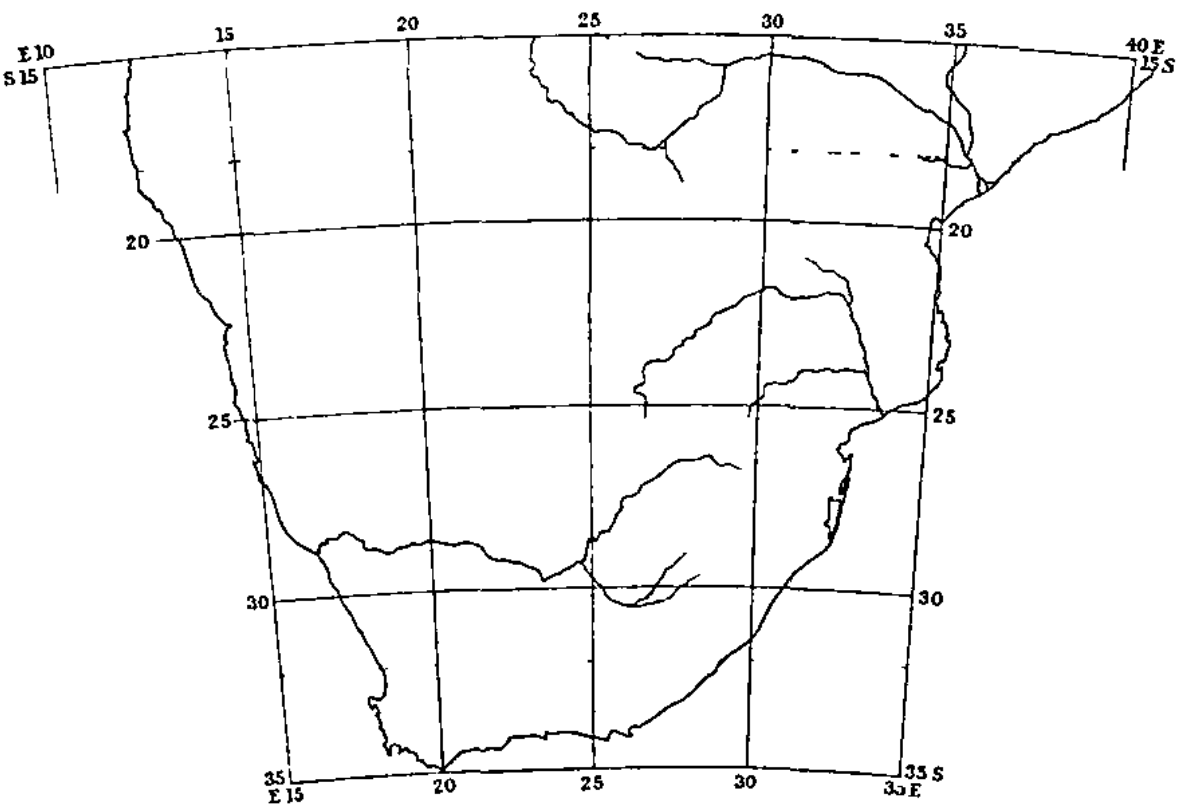
" " " " " 32° S. is 58·720 "

whence $h = 421$, which does not differ materially from that found above.

SOUTH AFRICA

on

A CONICAL PROJECTION WITH RECTIFIED MERIDIANS AND TWO STANDARD PARALLELS



Scale 400 miles to 1 inch

The meridians and two parallels (18° and 32° S) are true to scale

The radius for parallel 32° is now easily found to be 7983·7 miles.

The radius for parallel 35° is this—the length of the meridian between 32° and 35°, 7983·7 − 206·7 = 7777 miles.

The length on the map of 1° of longitude on 35° S. is now

$$7777 \times 421 \times \frac{\pi}{180} = 57{\cdot}143$$

The true spheroidal length is 56·728 in error of about 0·7 per cent.

The radii of the other parallels are obtained in the same way.

Next to calculate the coordinates for plotting. Take the parallel of 35° S.

The radius of this parallel is 7777·0 miles.

Take the meridian of 25° E. as the axis of y, and the intersection of this meridian with the parallel of 35° S. as the origin.

To determine the coordinates of the point 35° S., 30° E. (difference of longitude = 5°).

Angle between consecutive meridians on map = $\theta = 421 \times 5 = 2105'$.

Then

$$x = 7777 \times \sin 2105' = 2565 \text{ miles}$$

$$y = 7777(1 - \cos 2105') = 123 \text{ miles}$$

The following table gives the results.

Conical projection for S. Africa.
Coordinates in miles.
Origin point 35° S., 25° E.

Latitude S.		Longitude 5°	Longitude 10°	Longitude 15°	
35°	x	0	285·7	701·1	The parallels 18° and 13° S. are obtained in a similar manner.
	y	0	−5·3	−21·0	
30°	x	0	298·3	86·2	
	y	344·2	339·0	312·6	
25°	x	0	310·9	721·5	See Plate XVI.
	y	688·7	683·9	665·9	
20°	x	0	323·6	741·7	The projection is symmetrical, and the values are the same as in the portions W. of 25° E.
	y	1032·7	1026·8	1008·3	
15°	x	0	336·2	762·0	
	y	1376·5	1370·3	1351·8	

25 **Simple Polyconical Projection.**—In this projection which is a conventional one any parallel is represented by a circular arc of a radius not but where is the normal terminated by the minor axis. The central meridian is a straight line through the centres of the parallels which are then true distances apart measured along this meridian. The other meridians are curves which cut the parallels at the true distances, measuring along the parallels. Thus the meridians do not cut the parallels at right angles.

The projection is best suited for countries having a great extent in latitude and little in longitude. The meridian curves are sometimes for convenience replaced by the rectilinear inscribed polygons.

The great usefulness of this projection and of the rectangular polyconical projection consists in the fact that it is easy to construct universal tables since each particular parallel has always the same radius (r cot lat)

Single sheets not exceeding in latitude four degrees when plotted on either system do not materially differ in any of the principal qualities from sheets plotted on specially devised conical projections such as 3 11, or 24 (*b*) (*c*) or (*d*) But this only applies to small areas and independently plotted sheets The best tables to use are those published by the United States Coast and Geodetic Survey — Tables for a Polyconic Projection of Map 1900

Polyconical projections should not be used for large areas and are especially unsuited for maps having a great extent in longitude

26 **Rectangular polyconical projection** sometimes called the **rectangular tangential** The parallels are formed as in the last projection but the meridians in this case are curves which cut the parallels at right angles The lengths along the parallels are consequently not true

This projection is described in the War Office pamphlet On the Projection of Maps by Major L Darwin RE 1890 A geometrical construction (due to the late Mr O Farrell of the Ordnance Survey) determines the intersection of the meridians and parallels (See War Office pamphlet which contains the necessary tables or Encyclopædia Britannica)

For small areas it does not differ appreciably from the simple polyconical It is best suited for countries having a great extent in latitude and not much in longitude It will also do well for a topographical series each sheet being plotted independently

The conical orthomorphic, Lambert's (No 3)
The modified conical equal area Bonne's (No 7)
The simple conical equal area Lambert's (No 10)
The conical equal area Albers (No 11) have been described

Cylindrical Projections

27 **Simple Cylindrical Projection** — The parallels and meridians are straight lines at right angles to each other The lengths along the meridians are correct and those along some selected parallel A projection of no value

Mercator's (1),
Transverse Mercator's (2)
Cylindrical equal area Lambert's (5)
Transverse ditto (6)
have been described

Conventional Projections

It is rather difficult to draw the line between regular and conventional projections, but the distinguishing mark of the latter is that they are devised for simplicity of drawing and not for special geometrical or analytical properties. The globular projection is certainly conventional and it is probably fair to call polyconical projections conventional

Ancient conventional projections are often more arbitrary than these, though sometimes of historical interest they are of no practical importance An account of them will be found in Gerland

28 **Globular Projection** — A conventional projection of a hemisphere in which the equator and the central meridian are two straight lines at right angles their intersection is the centre of the circular bounding The meridians cut the equator at equal distances and are

arcs of circles passing through these points and the poles The parallels are arcs of circles which cut the central and extreme meridians at equal distance

This name is sometimes incorrectly given to La Hire's perspective projection (20) and also equally incorrectly to the polar equidistant zenithal projection (21)

It differs however, but little from La Hire's It is used in popular atlases but has no claim to be treated seriously

29 **Projection by Rectangular Co ordinates** —Sometimes called Cassini's or Cassini Soldner's Any point on the earth is fixed if we know the length of a perpendicular from it on to some fixed meridian and the distance of the foot of this perpendicular from some fixed point on the meridian On this projection these spheroidal co ordinates are plotted as ordinary plane rectangular co-ordinates

The perpendicular spoken of is really a plane section of the surface through the given point at right angles to the chosen meridian and may be briefly called a great circle Such a great circle clearly diverges from the parallel The divergence of latitude in seconds is approximately

$$\frac{s^2}{2\rho} \tan\lambda \sec^2 l$$ where s is its length ρ that of the radius of curvature to the meridian λ the normal terminated by the minor axis λ the latitude of the foot of the perpendicular

The difference of longitude from the meridian in seconds is $s \sec\lambda \cos^2 l$

The resulting error consists principally of an exaggeration of scale north and south, and is approximately equal to $\frac{s^2}{2\rho}$ it is practically independent of the extent in latitude

This projection should not be used when the map extends more than say, 200 miles from the central meridian It is on this projection that Ordnance Survey Inch maps of England are drawn and also the 6 inch Ordnance Survey maps of the United Kingdom and for these comparatively small areas the projection is a very suitable one

30 **Graticules and Field Rectilinear Projections** —*These have been described* (see p 93)

CHAPTER XII

THE REPRODUCTION OF MAPS IN THE FIELD

It is important that the Intelligence Division of an army in the field should possess the means of reproducing maps and sketches The most suitable methods where large numbers of copies are required are lithography and zincography In the former, the printing surface is as its name implies is stone, in the latter zinc

Every officer employed with a survey and mapping section should possess some knowledge of these methods of the equipment and personnel which would be available and of the time which would be required for the work, though it may not be essential for him to be an expert lithographer

In the South African War of 1899 1902 the Survey and Mapping Sections supplied themselves with stones and lithographic presses which worked admirably at Orange River Bloemfontein and Pretoria

The experience gained in this war has resulted in a new equipment In the heavier equipment stone is carried in preference to zinc

The former is of course much heavier than zinc, and is also fragile but this disadvantage is compensated for by the greater ease with which it is worked especially under service conditions

It is considered that any photographic process except sun printing is unsuitable for use *in the field*

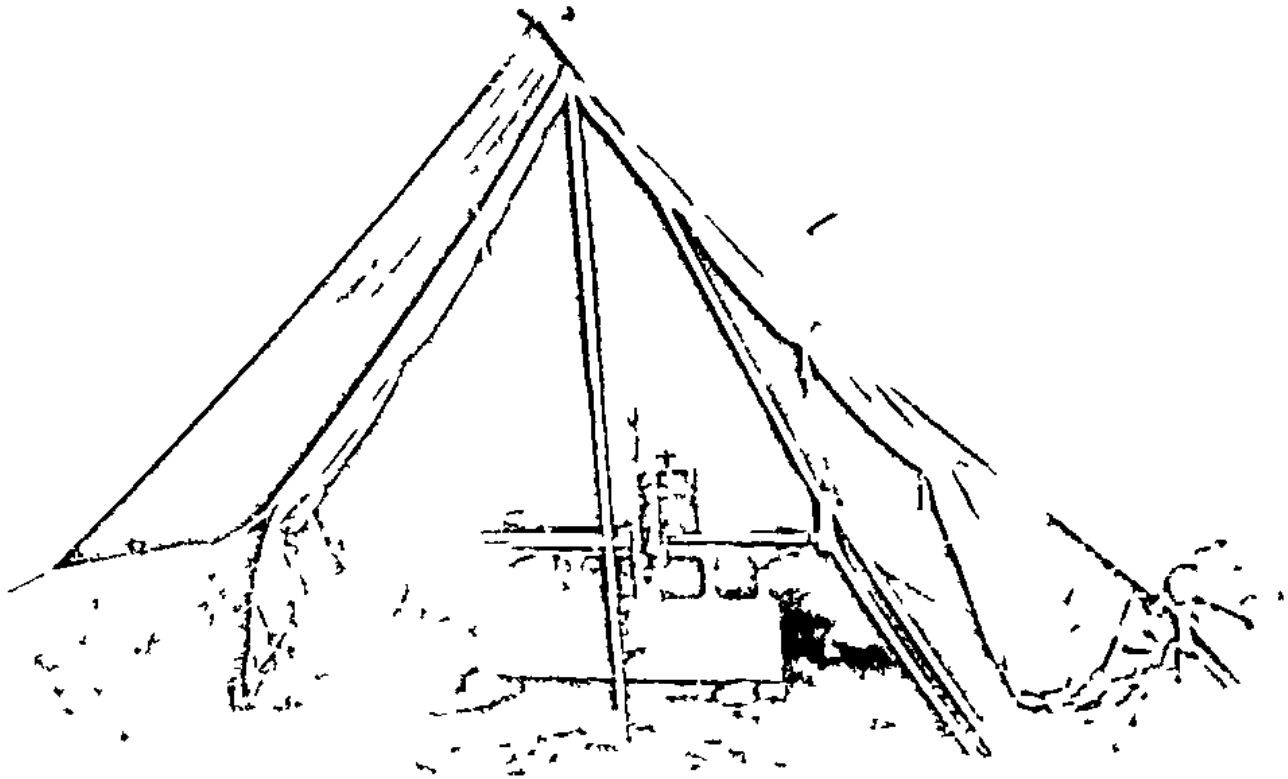
The recently approved Field Lithographic Equipment consists of a portable press, and the necessary stores as well as a tent Four double faced stones are carried, and the whole equipment with the exception of the tent is carried in six boxes details of which are given in the following table —

DETAILS OF FIELD LITHO EQUIPMENT (No 1)

Number of Box	Contents	Measurements	Weight lb oz
1	Full small press	4 ft × — × 1	401 8
—	Half full stones	— × 1 0½ × 10	0
3	Ditto	— × —	— 0
4	Liquid	— 0 × 1 8 × 1 2	197 13
—	Various	— × 1 10 × 1 3	11 1½
6	Ditto	— 1 × — 1 × 1 1	1 11
Total weight of equipment			1 201 0½

This equipment which can be reduced on emergencies, is intended to be carried in any ordinary cart or waggon and will reproduce maps up to 18 × 23

A light field litho press weighing about 190 lbs, capable of reproducing maps up to double foolscap size or, 13 × 16, has also been designed and approved



Field Lithographic Press (for Cale Translot)

Zinc plates will be used with this press which is intended for mule transport

The personnel required for the lithographic equipment is two lithographic draughtsmen and two lithographic printers

The draughtsmen are specially trained in the art of drawing reversed on stone or zinc but have nothing to do with the actual printing of the plans which is done by the printer

Rates of Work—A skilful draughtsman should be able to trace in transfer ink, a map of enclosed country with a fair amount of lettering and detail, at a scale of 1 inch to 1 mile at the rate of 10 minutes per square inch If required to draw direct on to the stone or plate, double this length of time would be necessary

A printer should be able to print about 40 copies of the same map in an hour under ordinary circumstances

Lithography and zincography are methods of reproducing maps or plans in greasy ink, in large numbers by mechanical means from stone or zinc Both methods depend on the fact that stone and zinc are to a certain extent porous and capable of absorbing both water and grease Where a grease spot exists water is repelled and *vice versâ*

If a drawing in greasy ink, or transfer as it is called, be laid face down on a clean stone and subjected to pressure the grease leaves the paper, and is absorbed by or takes on to the stone or zinc If the stone or zinc plate be then damped and a roller charged with a greasy ink be passed to and fro over its surface the ink will only adhere on the lines of the drawing Should a piece of clean paper be placed on the stone or plate and passed through the press it will lift some of the ink and a reproduction of the original picture will be obtained By damping and rolling up alternately a very large number of copies can be produced

Preparation of Transfers

The first step in the reproduction of a map unless it is to be drawn direct on to the stone or plate is the preparation of a transfer that is to say a copy of the plan or map in greasy ink

The ink used for this purpose is known as litho writing ink and is applied with ordinary pen ruling pen or brush It is obtained in sticks and prepared for use by warming the bottom of a saucer rubbing the ink on it long with water and stirring up Its chief constituent is some form of soap i.e. a substance of a greasy nature which has been acted upon by an alkali and which can be subsequently rendered greasy by the application of an acid

The transfer would usually be traced on a specially prepared paper known as **tracing transfer paper**

Where an alteration in scale from that of the original is required the enlargement or reduction would first be drawn on ordinary paper in pencil and then traced in litho writing ink on tracing transfer paper

Drawings in litho writing ink should not be blotted or rubbed

Preparation of Stone

The Stone used in lithography is a kind of lime stone and comes from Bavaria

It is ground with a levigator and silver sand passed through a 40 mesh sieve This gives a level surface, and removes old work

Polish with pumice stone and water

Polish with snake stone and water

Wash with cold water

Transferring Litho Writing Ink Transfer Made on Ordinary Paper to Stone

The stone is placed in front of a fire to warm

The transfer, which should be freshly prepared, is placed face downwards on a clean piece of paper and damped from the back with a sponge wetted with dilute nitric acid (1 in 80) about 4 times at intervals of 2 or 3 minutes The object of the acid is to convert the ink from the soluble to the insoluble form it also renders the paper more pliable The acid must not be strong or it will rot the paper If the ink were soluble it would wash off the stone The impression would probably roll up but it would not be so strong, and the lines possibly rotten, *i.e.*, broken

The warmed stone is then placed in the press and the transfer face down on it Grease takes more readily on a warm than on a cold stone

The transfer is pulled through the press half a dozen times with light pressure, transfer damped scraper or stone reversed in case pressure is not equally distributed over the surface of the stone and pulled through another six times

These operations are repeated till transfer is damp throughout Transfer is removed composition washed off with cold water and the stone gummed in

Light pressure has to be used as the composition on the paper is soft and might smash

The transfer is then carefully removed from the stone, which is then gummed in with a gum solution of the consistency of thick treacle The stone is then allowed to dry and cool The gum fills up the pores of the stone where clear of ink, when once dried cannot be removed with water It prevents the lines from spreading, and lessens the chance of scum, that is to say it prevents the printing ink from the roller taking all over the stone The gum is then washed off from the surface of the stone with a sponge and the ink is strengthened by rolling up and damping alternately If a hot stone is rolled up the ink may spread in spite of the gum and as it dries quickly scum might appear A stone should always be damp while being rolled up

The stone is then gummed again cleaned up where necessary with the point of a knife or piece of snake stone and etched

The etching solution is dilute nitric acid (about 1 to 80), such as will give a little roughness on the teeth but no effervescence on the stone It is applied with a sponge followed up with a second sponge with water The stone is then cleaned with a damping cloth gummed again to replace any gum destroyed by the acid and allowed to dry

The object of etching is

1 To prevent the work from spreading
2 To prevent scum appearing on the white portions
3 To leave the work in slight relief and to prevent fine work from filling up with ink

Printing

The ink used for printing is composed of burnt linseed oil lamp black and a pale varnish (as under)

It is bought ready ground but for use is thinned down with lithographic varnish

Chalk printing ink is a superior kind of litho printing ink used for fine work

The ink is applied with a roller This is made of calf skin flesh side outwards over two layers of flannel fastened on to a wooden cylinder

When using black ink the roller need not be washed but it should be scraped about three times a day

The stone is washed to remove surface gum, and if the ink has had time to get hard (8 or 9 days with average ink) it is removed with turps. The stone is then dumped with a cloth, and rolled up with the roller charged with ink. For fine work the ink should be thick.

The paper is put down to "**lays**," *i.e.*, marks or lines drawn as a guide on the stone with printers' lead, a mixture of lead and antimony. These lays do not wash out, and, not being greasy, do not take the printing ink. The stone should be damp when the lays are drawn.

Only paper of inferior quality requires damping to soften it, and allow it to press better into the work.

The right side (*i.e.* smooth side) should be used.

The paper having been laid on the inked stone is pulled through press once, with moderate pressure, and removed.

The stone is damped and rolled up again after every impression is taken.

If work is stopped although only for a short time, the stone should always be gummed in.

Drawing on Stone Direct

To draw on stone direct needs special training, as the drawing has to be reversed.

The outline at least would be usually laid down from a tracing by means of red chalk paper in a similar manner to that employed for duplicating balls, &c., with carbon paper. The wrong side of the tracing would, however, be uppermost. This outline is called an offset or faint.

The stone should be clean and free from scratches.

The outline is inked in with litho writing ink, all, except the actual portion being inked in, should be covered over to prevent the chalk dust from being rubbed off by the hand or arm.

When the drawing has been completed the stone is flooded with a mixture of gum and dilute nitric acid (1 in 60).

Solution washed off, stone gummed and dried. Then oiled, washed with turps, damped, rolled up, cleaned, etched, washed, gummed and dried. It is then ready for printing from.

Alterations on Stone

Wash off the gum with water. Take out any part to be removed as lightly as possible with snake stone or knife, and wash with water. Blot. Make the correction in litho writing ink. Allow ink to dry. Gum. Wash off gum. Roll up. Etch. Gum in, gum and dry.

If an addition has to be made on a part where nothing has yet been drawn the process is:—wash off gum with water. Wash with citric acid (1 in 80) to cut gum out of stone, wash with water, and draw in new work as before.

Printing in More than One Colour

When a map has to be printed in more than one colour a **keystone** has first to be prepared for printing, and on it is laid down all the details of the complete map.

Two lines or **lays** are drawn across the plate at right angles to each other, to mark where two adjacent sides of the paper are to rest.

These lays are marked as follows:—

Where the lays will come, wash off gum with water. Apply citric acid (1 in 80), dry with blotting paper. Draw lays with litho writing ink in the manner just described for additions on stone.

In printing the offset the keystone is allowed to dry after being rolled up so as to lessen the chance of the paper stretching or contracting For the same reason glaze board or enamelled paper should be used If these are not procurible use a bit of stout paper which has just been pulled through the press

The **offset** is then dusted over with red chalk powder and the surplus shaken off

The offset is then laid on a stone prepared in the usual way to receive a transfer, and pulled through the press This leaves the chalk on the stone The portions required in one colour are then drawn in in litho writing ink, as described in drawing on stone

The marks of the lays are cut with a knife and filled in with common ink

A colour stone is prepared for each separate colour, a fresh offset being required for each stone

When this is done the keystone is prepared for work by removing all the detail which is not required in black in the manner described for alteration

Before printing from the colour stones the black ink must first be washed off with turpentine and the stone rolled up with the coloured ink

The roller used is similar to the black litho roller except the smooth side of the skin is outwards as this makes it easier to clean

The lightest colour is printed first and the print is placed accurately on the next stone, and so on until all the colours have been printed

Register Great care is necessary that the paper is layed accurately to the lays on each stone or the colours will overlap

ZINCOGRAPHY

The preparation and putting down of transfers on to zinc is done in the same way as on to stone

The plates are usually obtained with a smooth surface (termed plumbed) Before use they are grained with fine sand the plate being kept wet and the graining done with a muller

Printing On removal of the transfer the plate is etched with a solution of gum, galls and phosphoric acid The solution is allowed to act for ½ to 1½ minutes, producing a fine layer of phosphate of zinc It is then washed off and a gum solution, to which ½ oz of etching solution to 1 pint has been added This solution is slightly thinner than that used for stone The plate is fanned dry, damped, sprinkled with oil followed by turpentine and rubbed with a piece of flannel It is then rubbed over with a turpentine cloth and rolled up with ordinary litho ink which takes all over the plate owing to the presence of the turpentine Water is then sprinkled on the plate which is rubbed with a cloth This causes the ink to leave the plate except on the lines The plate is again rolled up gummed in and fanned dry Gum washed off and plate rolled up It is then ready to take the first impression Plates should always be gummed in and fanned dry whenever it is necessary to stop work even for a short time

The number of impressions which can be obtained from a zinc plate depends on a variety of circumstance but usually from 500 to 1,000 should be obtained From stone the number would run into the thousands

SUN PRINTING

When the lithographic equipment is not available for the multiplication of maps in the field recourse must be had to sun printing

There are several papers now on the market which are suitable for this purpose and although this method is not nearly so satisfactory or expeditious as lithography, there is a very great advantage in the gain in the lightness of the equipment required

The most suitable paper for this purpose is **Bemrose No 5, Brown Process,** to be had from Bemrose and Sons, 4, Snow Hill, London It is made in three qualities, viz —

E 101 thick
E 100 thin tough
E 102 linen

The Prints produced by this method are either white on a deep chocolate ground, or chocolate on a white ground The former would be produced by printing from a tracing, the latter by printing from a negative print made on the thin paper (E 100)

A tracing on tracing cloth or paper should be made from the original It should be drawn with Indian ink, made as thick and opaque as possible Creases and folds should be avoided It is possible to print direct from an original, unless made on very thick paper, but the printing is of course slower than with a tracing

The tracing is placed in a printing frame, face to the glass and the sensitized paper laid over it, prepared side next to the tracing, the felt pad and back of frame next in succession, care being taken that the paper is in perfect contact with the tracing

The frame should be placed in the sun if possible for ¼ to 8 minutes The print should be examined at intervals and removed from the frame as soon as the detail is completely visible

The print is next placed in water for 3 to 5 minutes, and then in a bath of hyposulphite of soda, 1 oz to 3½ pints of water, for ½ to 1 minute or, if preferred, the hyposulphite can be applied with a brush or sponge

The print is then well washed and dried

The paper is supplied in rolls of 11 yards, width 26, 30 and 40 inches, sufficient developer is supplied with each roll

For quick work two men would be required, one to expose the prints, and the other to develop and wash them

The following apparatus would be required (cost about £3) —

1 printing frame 26 × 21
2 zinc baths, 28 × 21
1 developing brush
1 tin case for sensitive paper 26 long,
1 bucket or can for water,
1 pot for developing solution,
1 roll of ordinary tracing paper

The price of the paper per roll of 11 yards is as under —

Thick	7 0/	30 wide,	9 , 40 wide
Thin	5 3/	7	„
Linen		21s	„

CHAPTER XIII

BRITISH AND FOREIGN GOVERNMENT MAPS AND SURVEYS

National Surveys—A good topographical map is such a vital military necessity, that the initiative in the matter of national surveys has in nearly every country, been taken by the army. This is the case in the United Kingdom, India, France, Germany, Italy, Spain, Austria, Russia and other countries.

Mapping & Sketching—The necessity for a topographical map having been realised, the method of its formation would become the next point for consideration. It would occur to any officer accustomed to sketching (as are the officers of most armies) that a workable map might be formed by combining military sketches. As an instance of the effect of such a system we may quote the state of the maps of India before the year 1802. These maps were compiled from sketches and were subsequently tested by the results of the accurate survey. In the short distance across India in the latitude of Mysore the maps so compiled were found to be 40 miles in error.

Another instance may be quoted the compilations made in Burma after the annexation in 1886. A vast amount of sketching was carried out by officers during the operations, these sketches were compiled; the result, though better than nothing at all, was highly unsatisfactory.

Akin to these were the compilations made from farm surveys during the South African War of 1899–1902. These were reported by many generals to be worse than useless. They gave, however, an abundance of names and served to show the location of farms and the lines of railways. The hill features shown on them were quite unreliable, which will not surprise those who have seen the original farm surveys from which they were compiled.

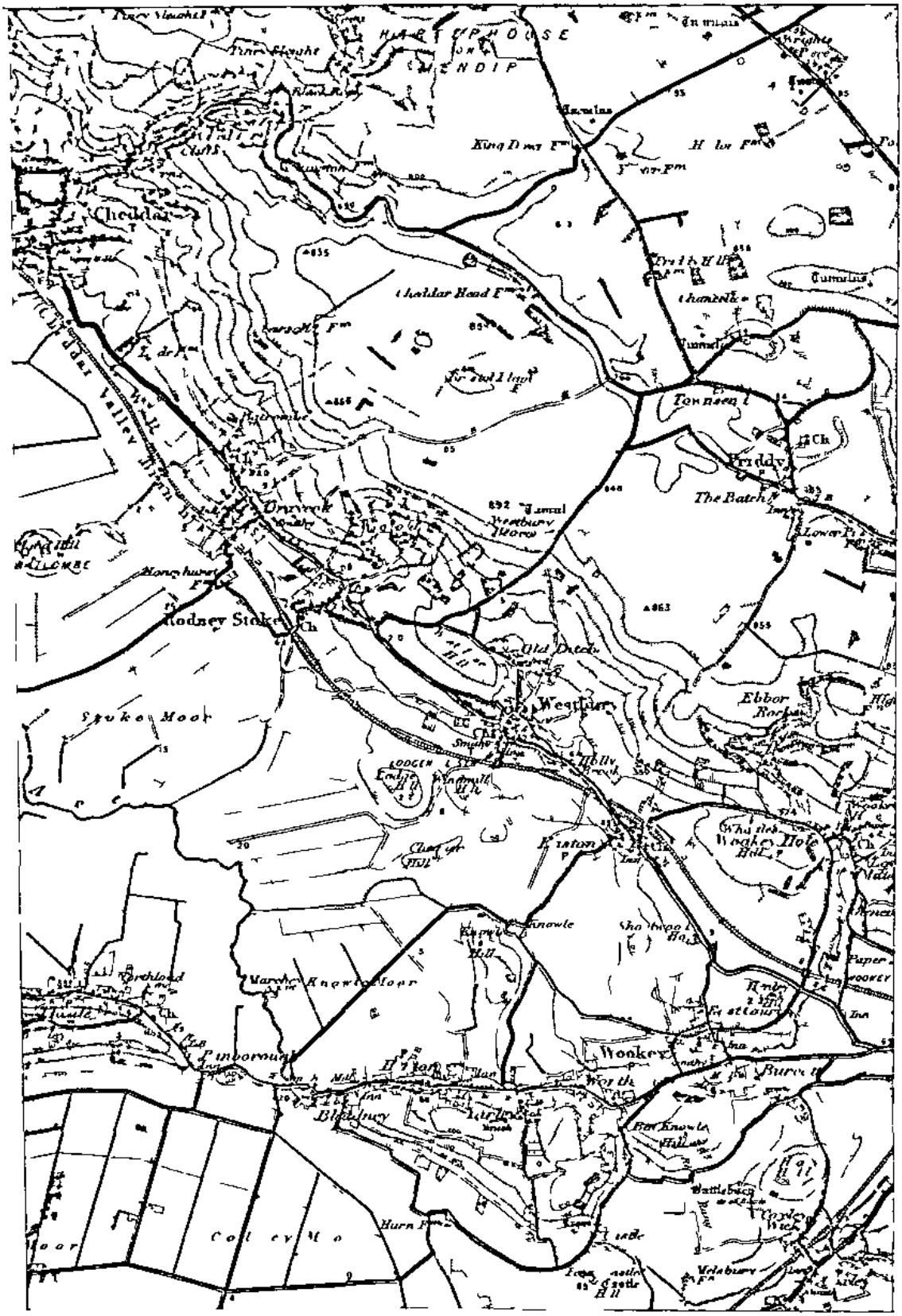
Another instance of the futility of combining sketches to make maps is the present condition of the maps of most British possessions in Tropical Africa. Indeed all experience demonstrates the fact that *no system of detailing in combination of sketches, and no compilation of previously unconnected traverses, whether sketched, surveyed or from plans, will result in a trustworthy topographical map.*

The Ordnance Survey—*In the United Kingdom* the first step towards the production of a topographical map was taken in 1747, two years after the rebellion in the Highlands. General Watson, D.Q.M.G. to the Duke of Cumberland's forces, conceived the idea of making a map of the Highlands; this was subsequently extended to the rest of Scotland. Various schemes were now advocated for the accurate mapping of the whole kingdom, but it was not until 1783 that the Ordnance Survey may be said to have come into existence by the measurement by General Roy of a base line on Hounslow Heath, and it is to be noticed that the whole work was undertaken by soldiers, the working party being furnished by the 12th Regiment, the reason given by Roy being that, 'not only was this obviously the most frugal method, but also because soldiers would be more attentive to orders than country labourers.'

The subsequent history of the Ordnance Survey is in brief.—Until 1824 work was almost entirely confined to the 1 inch scale. At that date the 6 inch map of Ireland was commenced, in 1840 the same scale was commenced for Great Britain. The map of Great Britain on a scale of 1/2500, approximately 25 inches to the mile, was commenced in 1854. This is periodically revised, so that no sheet is more than 15 years out of date. The second revision is now in progress in England and Scotland. The same scale was commenced in Ireland in 1869, almost half Ireland being completed. The interest of the 25 inch map for sailors lies in the fact that

ORDNANCE SURVEY

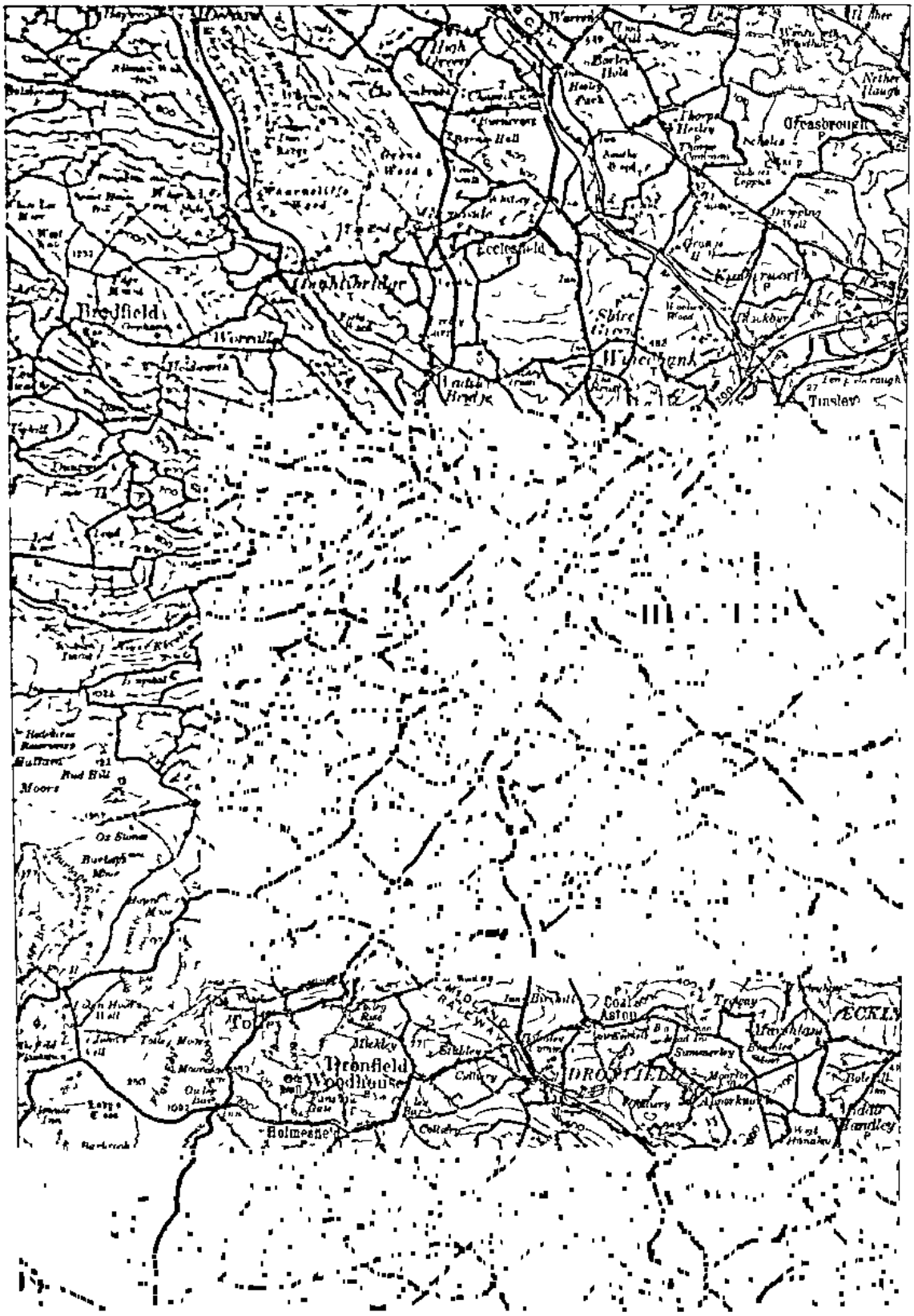
Scale - 1 Inch to 1 Mile *(Coloured)*



SHOWING THE COMBINATION OF CONTOURS AND VERTICAL HACHURES

ORDNANCE SURVEY

Scale. - 2 Miles to 1 Inch 126720



[illegible]

[illegible] inch, ½ inch, ¼ inch, [illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

[illegible]

The Survey of India.—Like the Ordnance Survey the Survey of India owes its origin [illegible] Military Department. After the fall of Tippoo Major Lambton submitted a [illegible] Trigonometrical Survey of the Peninsula. Actual work was commenced in [illegible].

Major [illegible] was succeeded by Sir George Everest. The whole [illegible] survey now exists was the creation of Everest's brain,' [illegible] Department. The first attempt at a topographical survey was made by Colonel Mackenzie who surveyed some 40,000 square miles in the Deccan between 17° and 18°. Everest was succeeded by Sir Andrew Waugh in 1843, and from this time the most extensive topographical surveys took place. The names of Capt. Robinson and Capt. Montgomerie are specially to be remembered as topographers.

It was Capt. Robinson that we owe the present accurate method of using the plane table. It [illegible] impossible even to mention the vast numbers of topographical maps of the Survey of India. They [illegible] measure a total of about 2,000,000 square miles and vary in scale from 4 inch to 1 inch to the mile. Generally speaking a new province is surveyed first on the 4 inch scale, and subsequently [illegible] on the 1 inch. The system of surveying on service has been brought to a high degree of excellence. Perhaps the most interesting of recent surveys is the 1 inch work carried out during the operations in China. A preliminary edition of this was published in 1901. The special merit of the Indian topography lies in its frontier work. no [illegible] have produced more accurate maps under such difficult conditions.

South Africa.—*In South Africa the only topographical map which existed on the* outbreak of war in 1899 was a 1 inch map of a small area north of Ladysmith. This map had been rapidly made [illegible] years before. Both the time and means allowed for its construction were inadequate.

Foreign Maps.*—The principal topographical maps of other countries are —

Austria, $\frac{1}{75000}$. Hills are shown by contours and vertical hachures, the latter are coarse and heavy. Not a good example of a topographical map.

Belgium, $\frac{1}{20000}$, in colours, hill features shown by contours. $\frac{1}{40000}$, military map of Belgium. The hill features are badly defined by feeble contours in brown which are difficult to follow.

France, $\frac{1}{80000}$. 'Carte de l'Etat Major,' the staff map of France, engraved on copper, hills shown by vertical hachures. Similar to but inferior to the black edition of the Ordnance Survey 1 inch (Plate XXIII).

The coloured $\frac{1}{50000}$ map of Algeria and Tunis, prepared by the Service Geographique de l'Armee. Hill features shown by contours at 10 metre interval and by shading with an oblique light. These are excellent maps (Plate XX).

* See Pamphlet by Col. Sir John Farquhar on K.C.B. on Foreign Topographical Maps.

The $\frac{1}{100\,000}$, "Carte Vicinale" Hill features shown only by stump, difficult to read except in hilly country

Germany, $\frac{1}{100\,000}$, engraved on copper, printed in black, somewhat inferior to the Ordnance Survey 1 inch

$\frac{1}{-5\,000}$, "Positions Karte," the maps of Prussia, Baden, Saxony and Wurtemberg on this scale are good clear maps

Italy, $\frac{1}{100\,000}$ contours at 50 metres with vertical hachures (Plate XXV)

Russia, $\frac{1}{-2-0}$, or "3 verst" map, engraved on copper, printed in black Hills shown by vertical hachures when there are any $\frac{1}{1\,-\,00}$ or 3 verst maps of the Balkan Peninsula Hills shown by contours in brown, and the contours are somewhat close, otherwise a good clear map

Spain, $\frac{1}{50\,000}$, in colours, contours at 20 metre intervals

Switzerland, $\frac{1}{-5\,000}$, and $\frac{1}{50\,000}$, contours brown, detail black, beautiful maps

United States, $\frac{1}{62\,500}$, $\frac{1}{-5\,000}$, and $\frac{1}{50\,000}$, according to population of country In colour, contours in brown, water, blue Very excellent maps (Plate XXI)

Analysis of Scales of Foreign Maps—We can now analyse the scales used Where two maps of a country are of equal importance they are both put down in the accompanying list —

	Scales	
The United Kingdom	1 by	63,360
"		126,720
India		63,360
"		253,440
Austria		75,000
Belgium		10,000
"	"	160,000
France		80,000
"		50,000
Germany	"	100,000
"		25,000
Italy	"	100,000
Russia		126,000
Spain		50 000
Switzerland		25,000
"		50 000
United States	"	125 000
Mean, about 1 by		90,000

Here is a list of the scales of the principal topographical maps of the world, most of which I have seen, and it is sufficient to show how important it is that officers should accustom themselves to the use of small scales The same opinion would have been arrived at on the merits of the case by considering those instances in which maps are used in war, and the purposes which they have to serve Even in the case of a small country like England it is simply impossible that an army could make any general use of 6 inch maps—the 6 inch map of England is over 15 000 square feet in area

ORDNANCE SURVEY

Scale 4 Miles to 1 Inch *(Coloured)*



Uses of Maps in War—The uses to which maps are put in war are —

(1) For strategical purposes,
(2) For finding the way,
(3) To give the Commander of a force topographical information concerning roads, villages, woods, hills, streams, bridges, ferries, railways, and water supplies, &c.,
(4) To enable a general outpost, offensive or defensive position to be taken up,
(5) And generally to convey information which cannot be given at the moment by the eye alone

It is clear that, as a general rule, large scales are not required

Analysis of methods of showing hill features—It is worth noting that most government maps represent hill features by a combination of contours and shade, contours and vertical hachures, or by contours alone. On very small scales the contours become generalized form lines which may be replaced by vertical hachures. As regards the intervals of the contours, the following list gives the number found by multiplying the contour interval in feet by the scale in inches to the mile *

France,	$\frac{1}{80000}$	41
,,	$\frac{1}{80000}$	52
Prussia,	$\frac{1}{500}$	41
Baden, Bavaria, Wurtemberg,	$\frac{1}{500}$	81
Italy,	$\frac{1}{50000}$	20
,,	$\frac{1}{100000}$	102
Spain,	$\frac{1}{000}$	81
U.S.A.,	$\frac{1}{0}$	50
,,		20
O.S. 1 inch		50
,, Colonial		50
,, 1 inch		100
	Mean	57

We may therefore say that the weight of authority is in favour of a contour interval of about 50 feet for a 1 inch scale and for other scales in proportion, thus 100 feet for a ½ inch map, &c.

These same results might have been arrived at on the merits of the case. All practical topographers know that in ordinary country the contours on the Ordnance Survey unshaded 1 inch map are not sufficiently close to show the ground. It should be added that the rule of 50 feet for a 1 inch scale is a tacit rule on which the form lines of the small scale Survey of India maps are made (*e.g.*, on the transfrontier ¼ inch maps the form lines may be considered to be 200 feet apart.

These considerations have led to the decision to adopt the same rule for military sketching, both on its own merits, and because sketches will necessarily be used in conjunction with Government maps. The rule may be stated thus —The contour interval in feet is found by dividing 50 by the number of inches to a mile in the scale.

To sum up the analysis of this list of maps —

* Switzerland (an exception under 1 on account of its mountainous character) has the following intervals for the $\frac{1}{25000}$ map: 10 metres; for the $\frac{1}{50000}$ map 10 metres.

The modern topographical map will be on a scale of about $\frac{1}{100\,000}$ or from $\frac{1}{2}$ inch to 1 inch to 1 mile

The hills will be represented by a combination of contours and shade

The intervals of the contours will be given by the rule*

$$\frac{50}{\text{No. of inches to the mile}}$$

The map will be printed in colours

The Layer System.—Another means of showing the relief or hill features of a tract of country is by layers or tints. In this system the height above sea level between any two selected contours, is indicated by a special tint or colour. Thus a light tint say of yellow, will represent all the ground between sea level and the 200 ft. contour, a somewhat darker tint will show the ground between the 200 and 400 ft. contours and so on. Mr. Bartholomew's excellent tinted half inch maps of the United Kingdom (based on the Ordnance Survey) are well known.

A few others maps on this system have been published. Amongst them may be mentioned

Austria,	$\frac{1}{75\,000}$	11 tints, 9 of brown, 2 of green
Sweden	$\frac{1}{100\,000}$	13 tints, light yellow to dark brown

No system can rival this as a means of showing broadly on small scales the absolute and relative heights of the main features. Its disadvantages are, that it gives a stepped appearance to the map, that the darker shades obscure the detail, and that it gives very little idea of the steepness of the hill slopes.

Medium country on a scale of 2 miles to 1 inch may perhaps be considered to be equally well represented by contours and shade or by layers, and the effectiveness of the latter method increases as the scale decreases.

"Metric" Scales.—In the British Empire the question sometimes arises as to whether the scale shall be in inches to the mile or shall be a metric scale in which the denominator of the fraction is some definite number of thousands. For instance, shall we choose

$$\frac{1}{2}\text{ inch to 1 mile } \left(\frac{1}{126\,720}\right) \text{ or } \frac{1}{125\,000}?$$

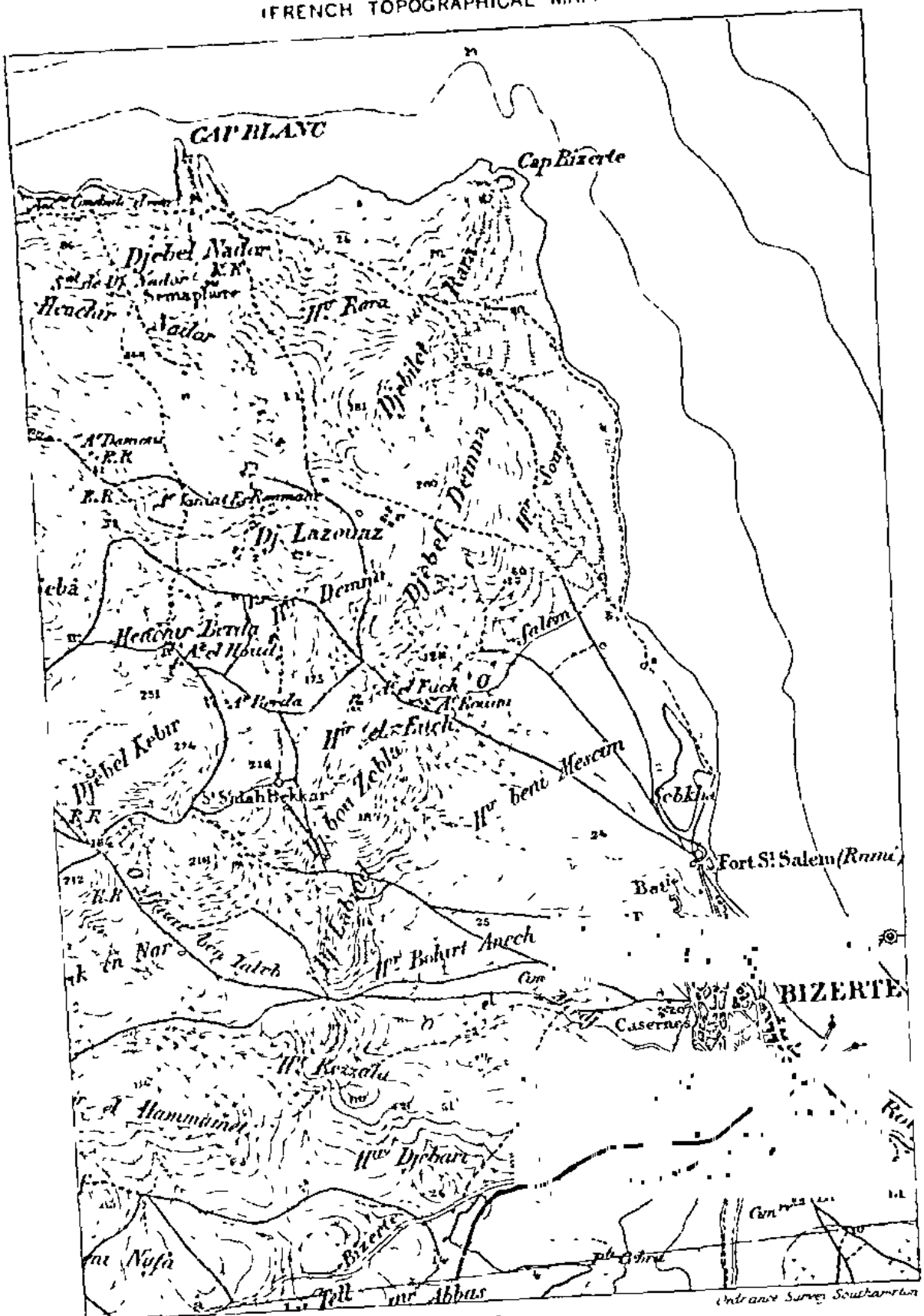
The answer may as a rule be given in favour of $\frac{1}{2}$ inch to the mile. This statement at once brings up a definite mental picture of the relationship between the length on the map and that on the ground in terms of two most *familiar units*. *The other involves a considerable* effort to realize, and is indeed only justifiable where the metric system is in use. When we adopt a metric system and have got into the habit of thinking in centimetres or kilometres then and not till then should our maps be drawn on a metric scale.

Plates XVIII. to XXV. are examples of some of the more important small scale maps of the United Kingdom, France, Germany, the United States, Switzerland and Italy.

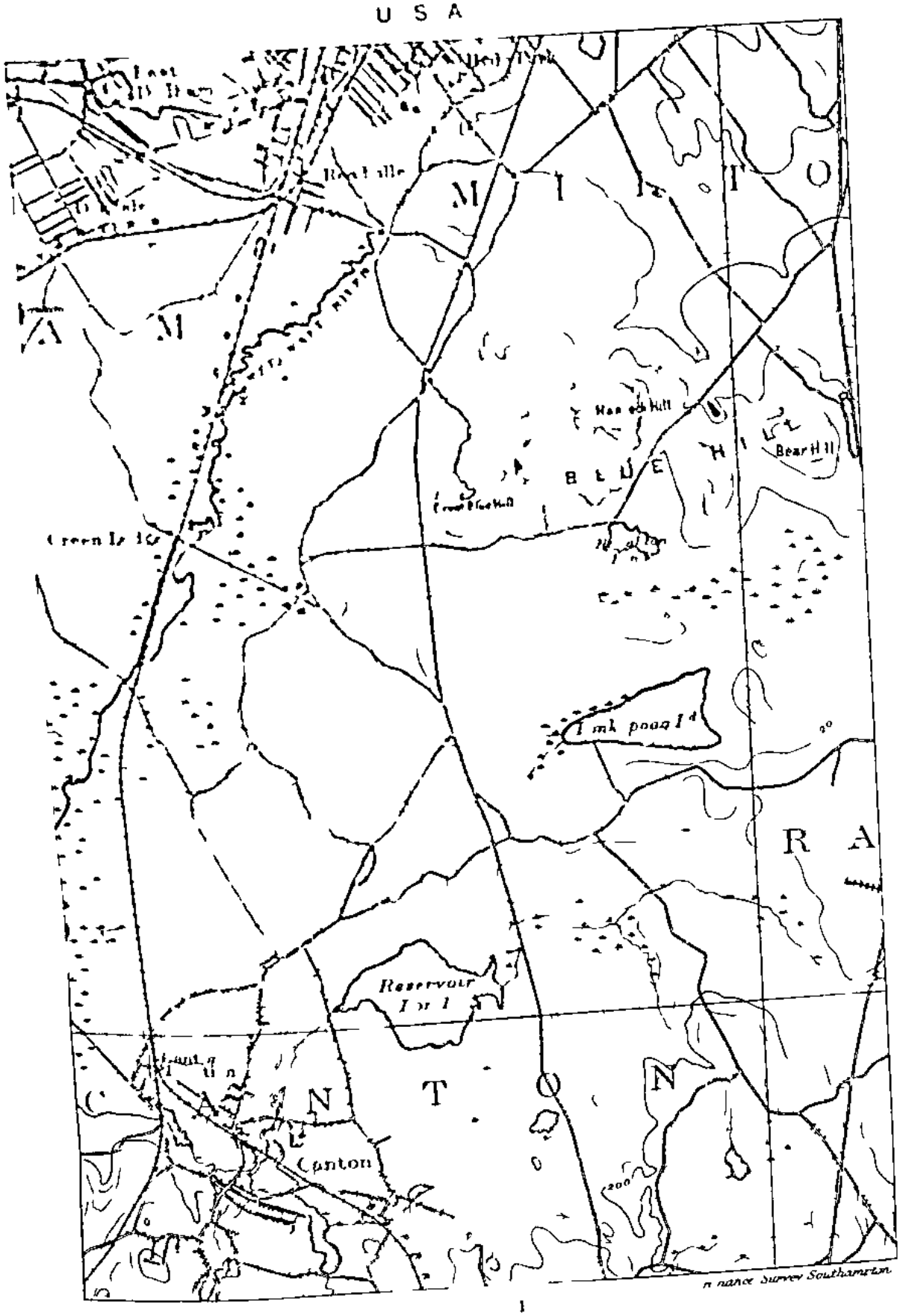
* Or a 20 metre interval for usual cases of $\frac{1}{1\,000}$.

" 20 " $\frac{1}{100\,000}$.

BIZERTA
(FRENCH TOPOGRAPHICAL MAP)

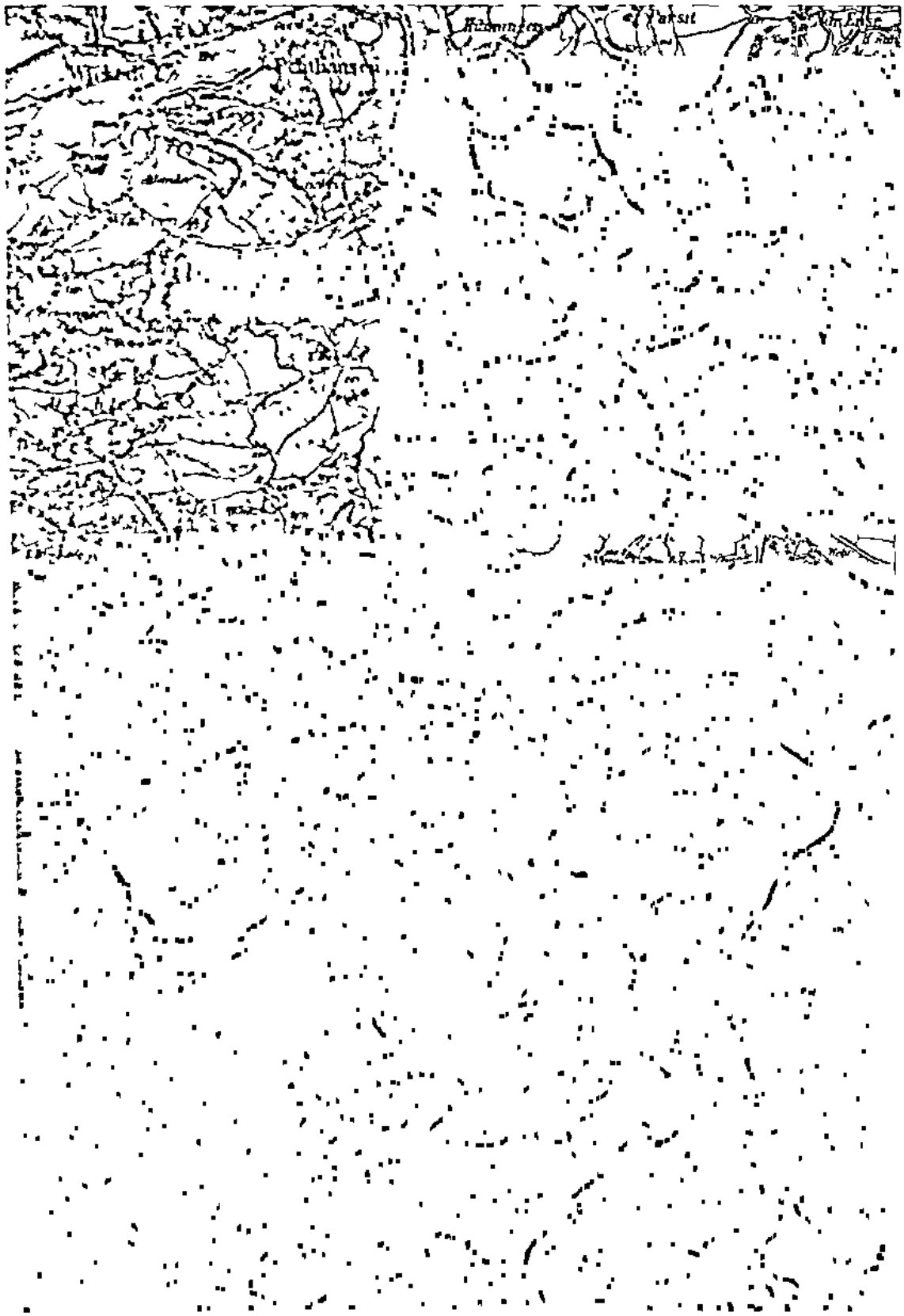


1



CONTOURS AT 20 FEET INTERVALS

GERMANY

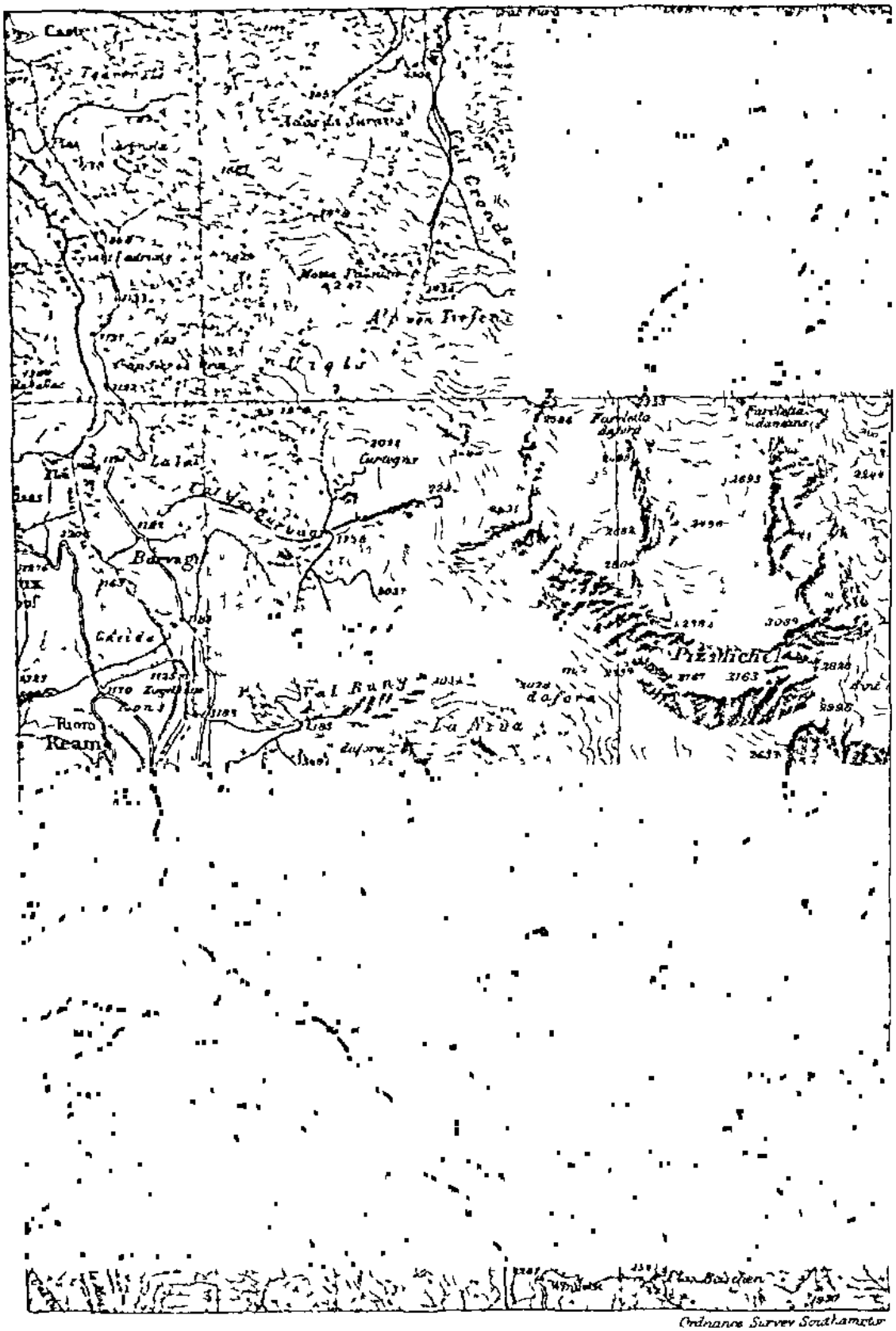


Scale $\frac{1}{100\,000}$

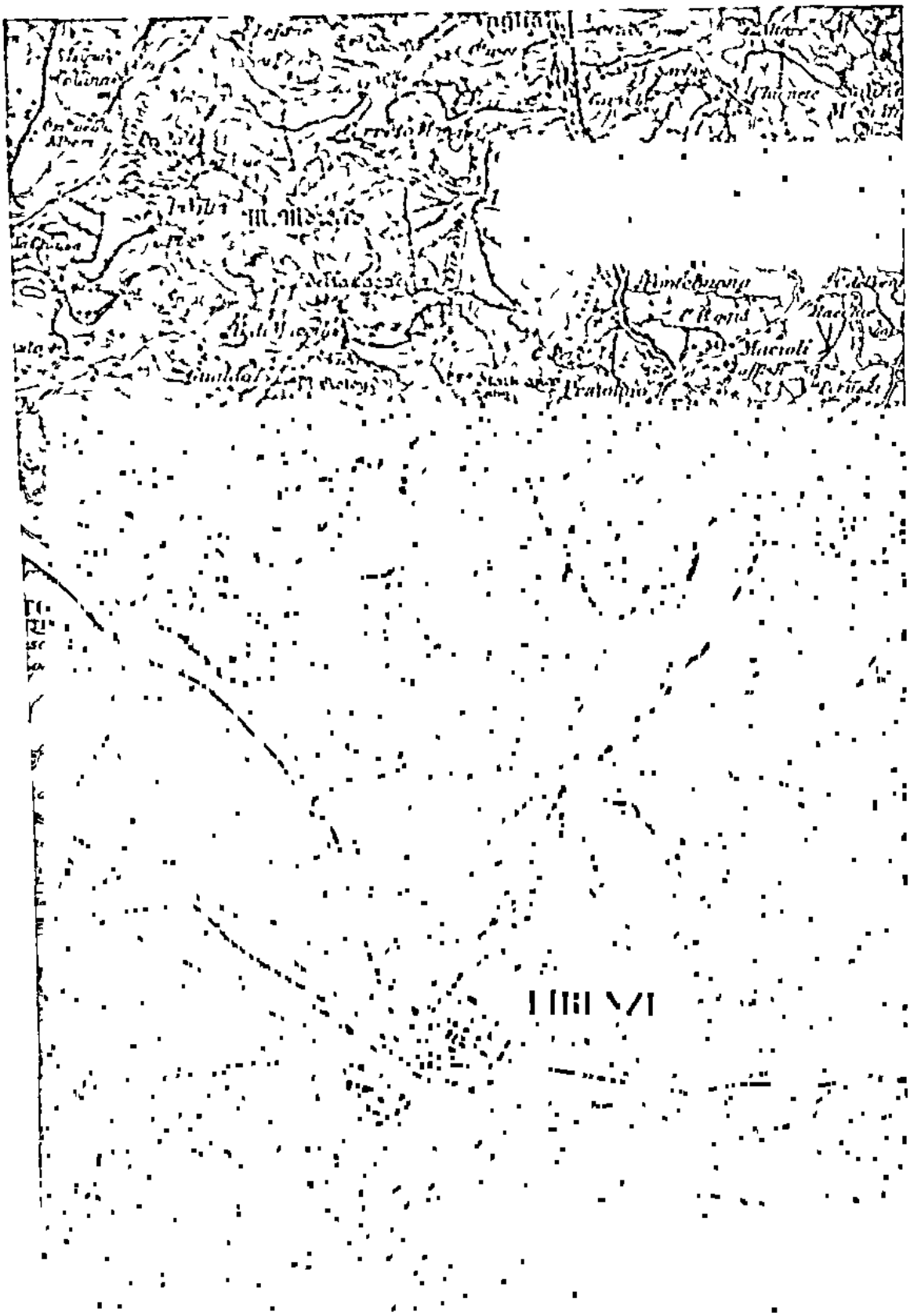


Scale $\frac{1}{80\,000}$

SWITZERLAND



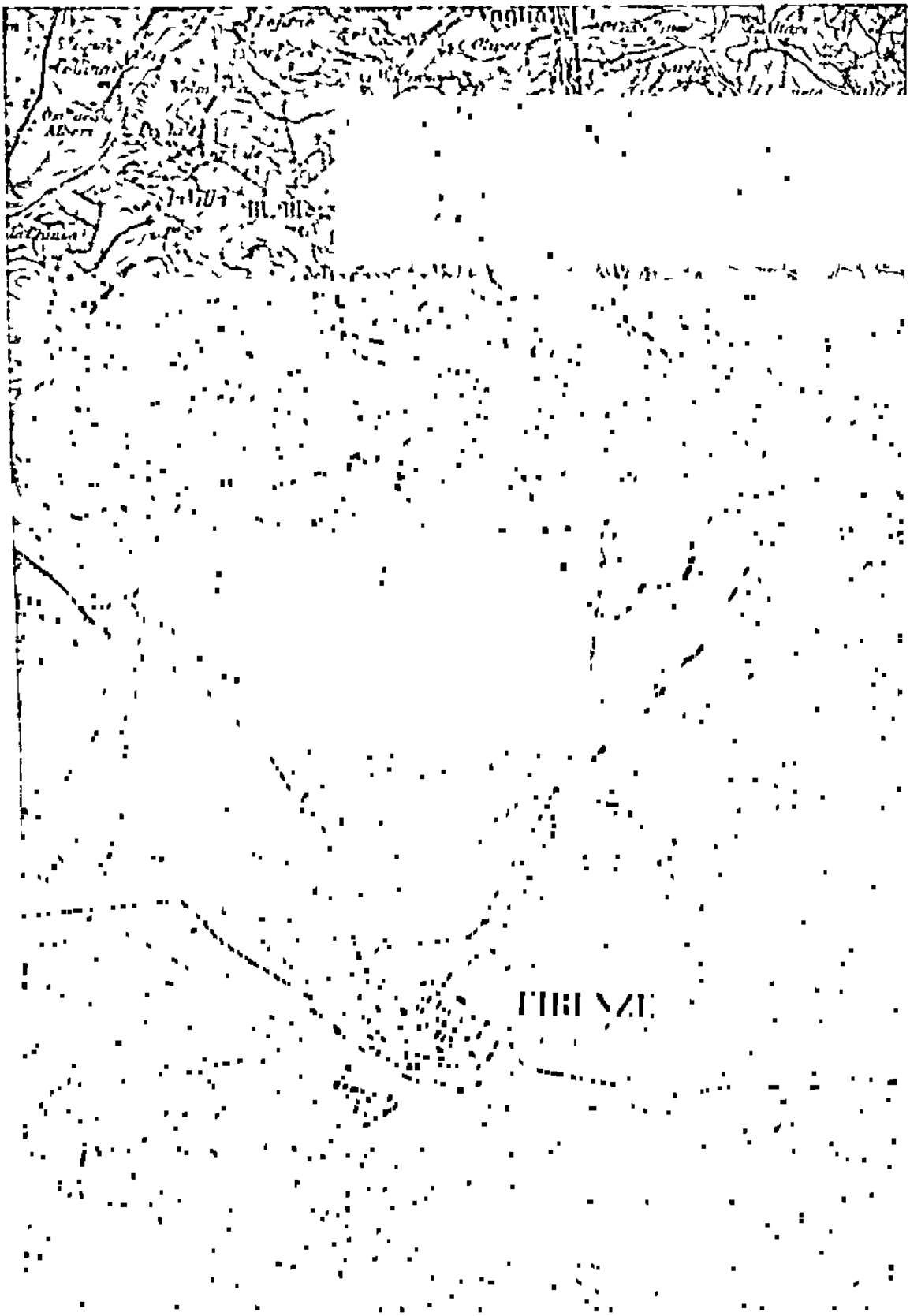
Scale $\frac{1}{50\,000}$



Scale $\frac{1}{100\,000}$

CONTOURS AT 50 METRE INTERVAL

ITALY

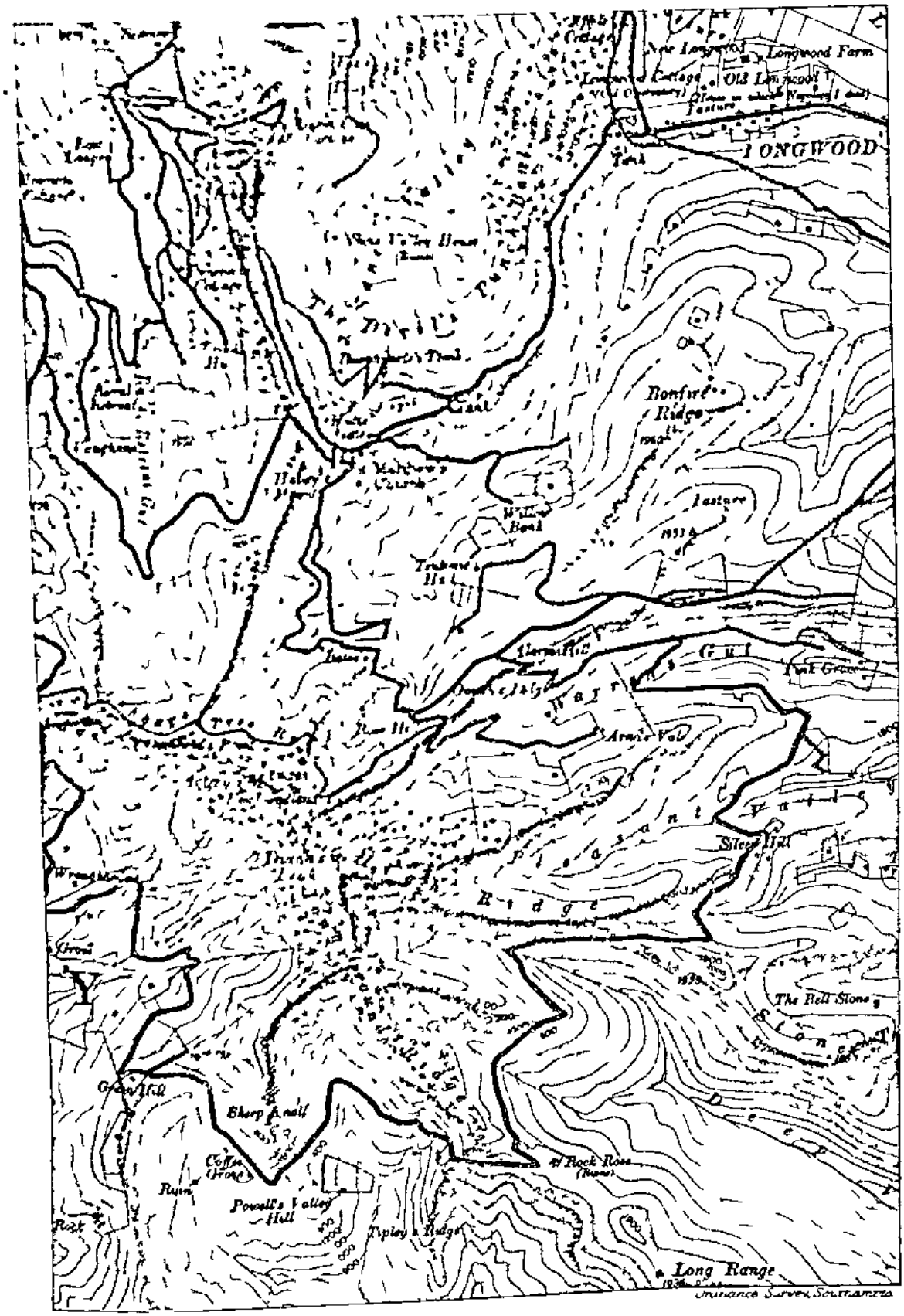


Scale $\frac{1}{100\,000}$

CONTOURS AT 50 METRE INTER

ST. HELENA

Scale – 2½ Inches to 1 Statute Mile



CHAPTER XIV

FIELD ASTRONOMY

SECTION I GENERAL CONSIDERATIONS

The Heavens [illegible] of the heavens would appear to be that of a vast concave [illegible] the fixed stars. This great concave sphere is called [illegible]

[illegible] are produced by the revolution of the *earth* on an [illegible] of the heavens are on the prolongation of this axis.

[illegible] of the heavens is a great concave sphere imagine at its [illegible] small sphere of practicable dimensions, and while the celestial sphere is [illegible] the earth revolves on its axis. Now although appearing to be about the [illegible] of the earth the distances of the celestial bodies are enormously. Thus, the [illegible] from the earth of the moon is 238 833 miles of the sun is 92 900 000 miles and [illegible] of the nearest fixed star is 5 000 000 000 000 miles while the distances to the planets [illegible] of practical importance upon our mutual positions in our several orbits.

Reduction of Observation to a Common Datum point.—A second in arc is equivalent to [illegible] from any point on the moon the angle subtended by two points one mile apart on the earth's surface may be as much as one second of arc.

Hence the necessity in observations of the sun moon and planets—stars are too far off to be affected—of reducing the observations taken to what they would be at the centre of the earth, so that astronomical tables may be of universal use while they are at the same time kept within reasonable bounds in size, and this involves a knowledge of the shape and size of the earth.

Besides the *diurnal motion* there is the *annual motion* of the earth to be taken into account, and this leads us to the consideration of the Solar System.

The Solar System

The Solar System is composed of the sun, the planets (of which there are about 600 very small ones and 8 large ones) and their accompanying satellites.

Some of the planets are accompanied by secondary planets or bodies called *satellites* which revolve round their particular planets just as the system of planets revolves round the sun. The planets and their satellites are opaque non luminous bodies and only shine by the light of the sun being reflected from them and thus they can only be seen when this reflected light can be seen, or when they come between an observer and some luminous body like the sun.

The Solar System may be more particularly described as consisting of —

1. The Sun the central body.
2. The four inner planets—Mercury Venus Earth and Mars.
3. The small planets or asteroids of which nearly 600 are known to be revolving between the orbits of Mars and Jupiter.
4. The four outer planets—Jupiter, Saturn Uranus and Neptune.
5. The satellites of the planets, the Earth has one called the *Moon* Mars has two, Jupiter has six, Saturn, nine, Uranus four, and Neptune, one.

Kepler's Laws—The laws of planetary motion are three in number as follows —

1 The orbit of each planet is an ellipse having the sun in one focus

2 As the planet moves round the sun its radius vector (*i e*, the line joining it to the sun) passes over equal areas in equal times

3 The square of the time of revolution of each planet is proportional to the cube of its mean distance from the sun

When a planet is furthest from the sun it is said to be in *aphelion* when nearest in *perihelion*

The major axis of a planet's orbit is called the *apse line*, or *line of apsides*, and that of the

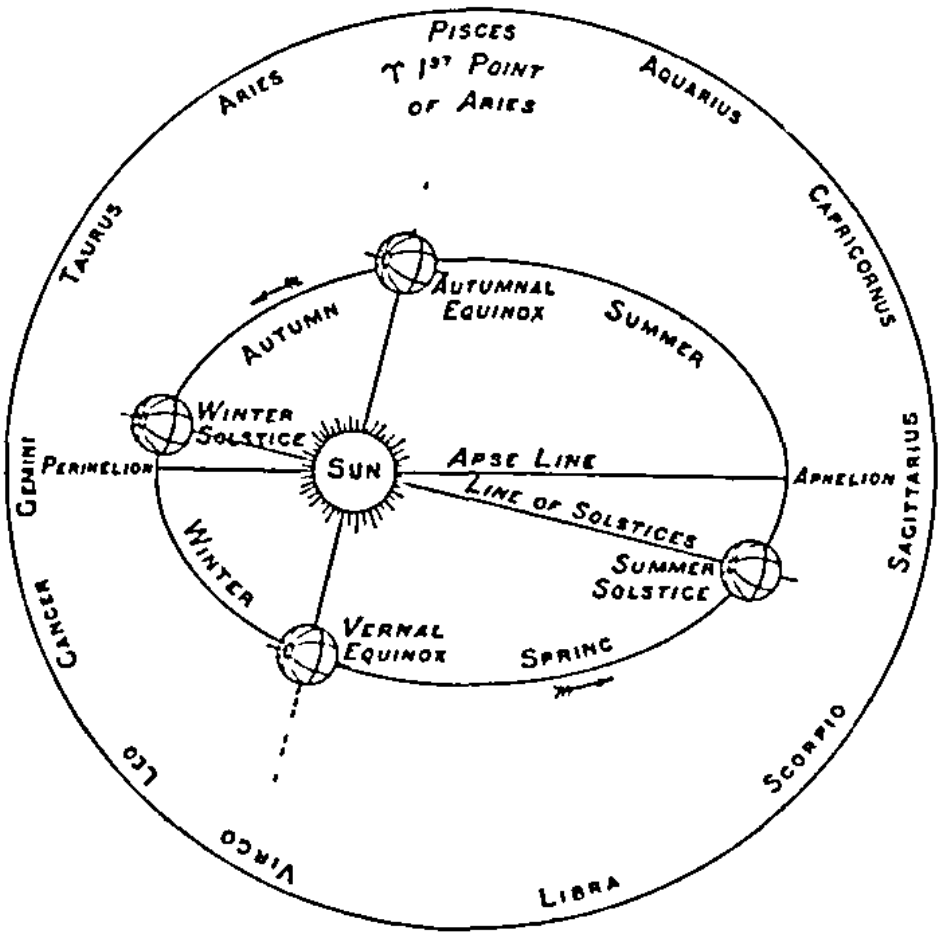


Fig. 46

earth's orbit is known to be revolving in space 11" 78 annually (as measured at the sun's centre) in the direction of the earth's orbital motion

Motion of Planets in the Solar System—All the planets revolve round the sun in the same direction viz, contrary to the motion of the hands of a watch when viewed from the north side of the plane of the earth's orbit Nothing certain is known of the axial rotation of Mercury, Venus Uranus Neptune, or the minor planets The other planets rotate on their axes in the same direction as they revolve round the sun The satellites move round their respective planets in the same direction, except the satellites of Uranus the satellite of Neptune and the newly discovered ninth satellite of Saturn the motions of these are retrograd

The axis of each planet is inclined to the plane of its orbit at a nearly constant angle, it has a proper secular motion, but practically remains for a considerable interval of time parallel to itself during the motion of the body through space

The orbits of all the planets are not in the same plane, but those of the principal planets lie in planes within 9° on either side of the plane of the earth's orbit, which plane is called *the ecliptic*

The Moon

Motion of the Moon —The moon moves round the earth in a path inclined at 5° 8′ 40″ to the ecliptic, and takes 27d 7h 10m to make a complete revolution with reference to a star The movement of the moon in the heavens is from west to east

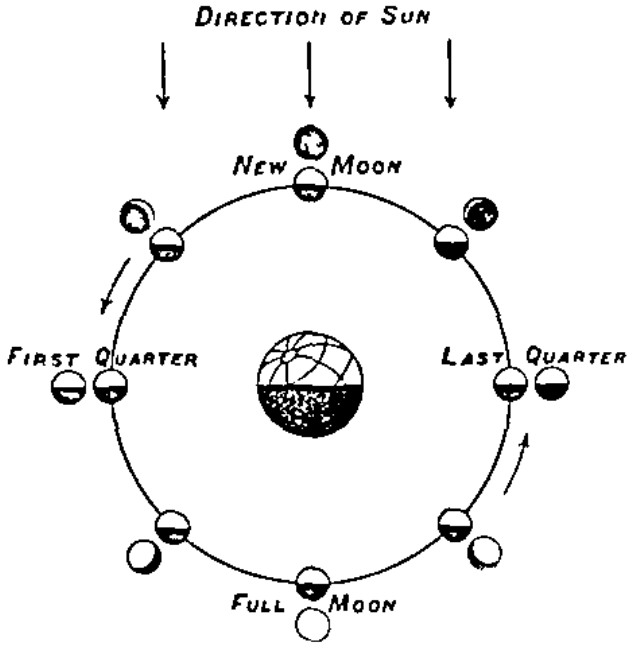


Fig 47

The Phases of the Moon are shown in fig 47, where the unshadowed portion of the outer row of moons shows its successive appearance as seen from the earth

The Stars

The great number of stars visible even to the naked eye renders it impossible to distinguish each by a particular name, and thus the stars have been arranged in groups, called *constellations*, for the purpose of more readily distinguishing them, and each group or constellation is given a name

An idea of **the position of the various constellations** can be best obtained by reference to a celestial globe, map or 'star chart'

To distinguish the stars of a constellation from one another, Bayer, in 1603, assigned to each of the stars in every constellation a letter of the Greek alphabet, the brightest being α, the next β, and so on The name of the constellation was put after each letter When the Greek letters were exhausted recourse was had to the Roman alphabet and these two alphabets fully answered the purpose at the time The order of the letters was intended to indicate the relative brilliancy of the stars in the same constellation, without reference to those in other parts of the heavens, thus α *Aquarii* is a star of the same magnitude as γ *Virginis* Since this

system was introduced some of the stars have changed in brightness Sometimes when there are two near stars of nearly equal magnitude, the numerals 1 and 2 are affixed to them in their order of right ascension as χ^1 and χ^2 *Tauri*

Flamsteed gave numbers to the stars observed by him in each constellation, the numbers were given according to the order of their right ascension, and have nothing to do with their brilliancy This method of naming stars is often used

Proper Names of Principal Stars —Some of the principal stars of the first two magnitudes have also received particular name, thus —

α	Canis Minoris	is called	Procyon,
α	Lyræ	,	Vega,
α	Bootis	,	Arcturus,
α	Canis Majoris	,	Sirius,
α	Aurigæ	,	Capella,
α	Tauri		Aldebaran

etc

The Pole Star —The star nearest the north pole of the heavens is known as the north polar star The north polar star at present is α *Ursæ Minoris* and is about 1½° from the pole, which distance will diminish in about 150 years to about ½°, and then it will increase again until the present pole star will be too far from the pole to serve as such Thus the pole star varies 4600 years ago α *Draconis* fulfilled this office and in 12 000 years α *Lyræ* will become the pole star This change of the pole star is due to *precession*

Distance of Stars —We can best form an idea of the immense distances of the stars by considering the time which light takes to travel from them to the earth Thus, the time the light of the sun takes to travel to the earth is 8¼ minutes whilst Vega is distant 30 light years and Pollux is 50 light years

The **annual parallax** of a star is the angle subtended at the star by the mean radius of the earth's orbit

For the nearest star the annual parallax is less than 1″

Parallax all known displacements in the apparent position of a star due to the earth's motion in its orbit each star appears to have a small motion of its own which is called **proper motion**

Stars have been classified into *orders* or *magnitudes* of brightness and the so "**magnitudes** are given in the Nautical Almanac For all stars there included, under the heads of Mean or Apparent Places of Stars Those of the sixth magnitude are about the smallest visible to the naked eye The largest telescope reveals stars down to about the 17th magnitude

Notation

In practical Astronomy the following notation is usually adopted —

A	Azimuth	L A N	Local apparent noon
E	Equation of time	G A N	Greenwich apparent noon
L	Latitude	L M N	Local mean noon
L A N or R	Right ascension	G M N	Greenwich mean noon
R O	Refracting object	h	Altitude
T	Chronometer (watch) time of observation	I	Index correction
		t	Hour angle
L S T	Local sidereal time	♈	First point of Aries
G S T	Greenwich sidereal time		Declination
L A T	Local apparent time	ζ	Zenith distance
G A T	Greenwich apparent time	λ	Latitude
L M T	Local mean time	φ	Latitude
G M T	Greenwich mean time		

SECTION II.—DEFINITIONS, ETC.

Celestial Sphere.—In the same way as circles are made use of as a means of measuring angle, so in spherical trigonometry a sphere is employed. Therefore we may conceive the concave bowl of the heavens as a measuring sphere with the earth at the centre. This sphere is called the *celestial sphere*, and its diameter may be any size (see HZIeN, fig. 48).

The Axis of the Earth is that diameter round which it rotates daily. Its extremities are called N. and S. pole. This axis produced cuts the celestial sphere in the N. and S. poles of the heavens (see PN, fig. 49).

The Terrestrial Equator is a great circle of the earth whose plane passing through the centre is perpendicular to the axis. This plane produced cuts the celestial sphere in the *celestial equator*. The terrestrial and celestial equators are in the same plane referred to generally as the plane of the equator (see EQ, fig. 49).

The Zenith is the point in the celestial sphere vertically above the observer's position (see Z, fig. 48).

The Horizon is a plane cutting the celestial sphere at 90° from the zenith (see HER, fig. 48).

The Meridian plane of a place is the plane passing through the poles and that place.

The Celestial Meridian is a great circle formed in the celestial sphere by the extension of the meridian plane. It clearly passes through the poles of the heavens and the zenith (see HZPeN, fig. 48), E. and H. are the N. and S. points of the horizon.

The Prime Vertical is the plane through the zenith at right angles to the meridian, and cuts the horizon in E. and W. points.

The Elevated Pole is that pole which is above the horizon.

The Longitude (L) of a place is the arc of the equator intercepted between the meridian of a place and any standard meridian such as Greenwich from which all longitudes are measured E. or W. up to 180° of arc or 12 hours of time.

The Latitude (ϕ or λ) of a place is the inclination of the normal (or plumb bob) to the plane of the equator and is N. or S. (+ or −) according as the place is N. or S. of the equator.

The Ecliptic is the great circle in which the celestial sphere is cut by the plane of the earth's orbit. It is therefore the apparent path of the sun among the stars.

The Obliquity of the Ecliptic is the angle which the plane of the ecliptic makes with the plane of the equator and amounts to 23° 27′ at present.

The points where the ecliptic and equator intersect are called **the equinoxes** and the intersection of their planes is called **the line of equinoxes**.

The Vernal Equinox is the point at which the sun crosses the celestial equator from south to north (about March 21st).

The Autumnal Equinox is the point at which the sun descends—about September 23rd—from the northern to the southern side of the equator.

The Solstices are the points of the ecliptic 90° from the equinoxes, and are distinguished as summer and winter (*vide* fig. 46).

Astronomical Coordinates

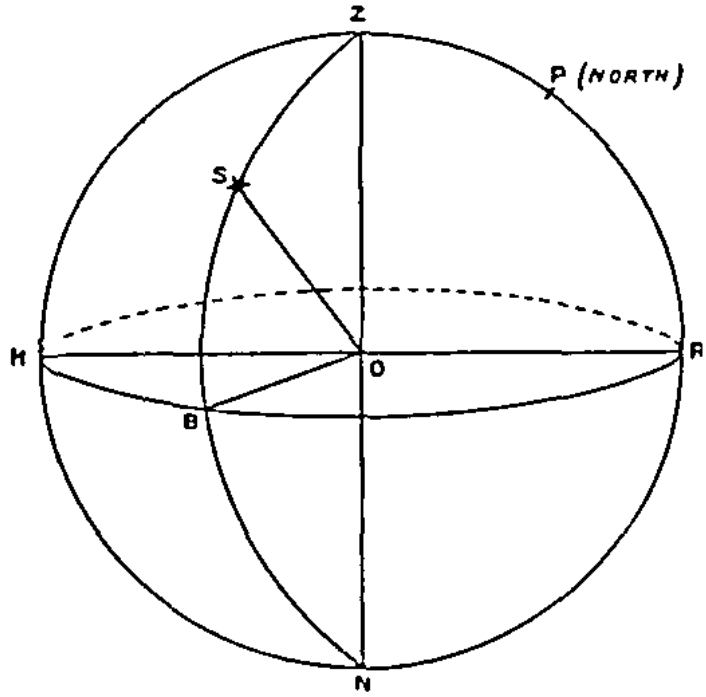
In order to fix the position of any heavenly body at a given instant, it is necessary to employ some system of coordinates. For field astronomy two such systems are employed —

(1) { Altitude / Azimuth

(2) { Declination, / Hour Angle, } or { Declination / Right Ascension

(1) Altitude and Azimuth

The Altitude (h) of a heavenly body is the arc of a great circle through the zenith and the heavenly body intercepted between that body and the horizon (see SB in fig. 48)



The plane of the paper is supposed to coincide with the plane of Meridian

Fig. 48

It is clear that the angle SOB would also represent the altitude and this angle can whenever the heavenly body is visible, be observed with the theodolite.

Great circles passing through the zenith are called **vertical circles**.

The Zenith Distance (ζ) is the complement of the altitude, *i.e.*, $90 - h$ (see ZS in fig. 48).

In working out certain computations which involve *zenith* or *zenith distance*, care must be taken with the algebraical sign of the zenith distance. It is usual to call

Meridional zenith distance (ζ) $^{+}_{-}$ when the heavenly body is $^{S}_{N}$ of zenith.

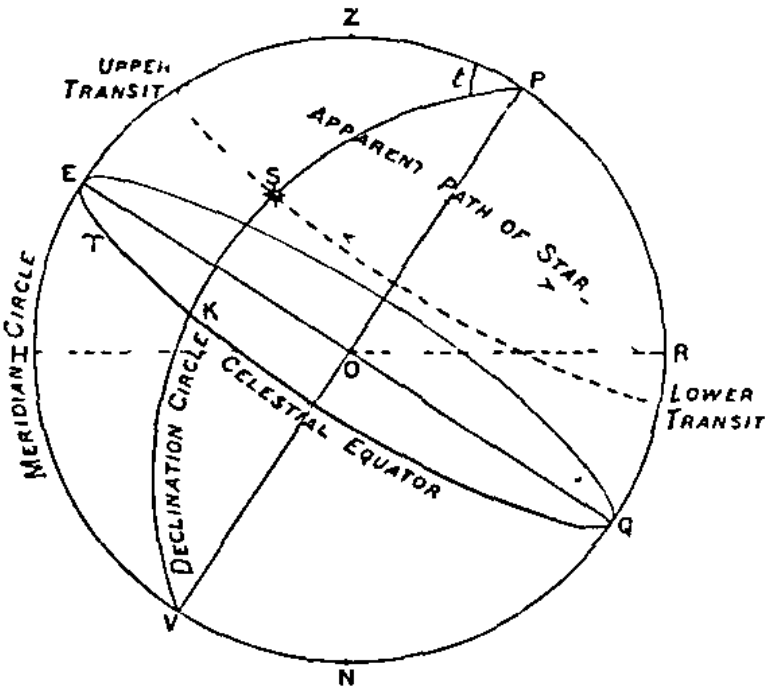
Culmination.—When a heavenly body attains its highest altitude it is said to be at its upper culmination. At that its lowest altitude it is at its lower culmination. The latter in many cases, would not be visible as it would be below the horizon.

A star is said to be **at elongation** when it is in such a position that the angle at S in the astronomical triangle PSZ becomes a right angle, *i.e.* when the plane of the vertical circle ZS becomes tangential to the diurnal path or circle of the star

The Azimuth (A) of a heavenly body is the angle between the meridian plane of the observer and the vertical plane passing through the body For astronomical purposes azimuth is measured the nearest way from the meridian plane Thus in fig 48 the azimuth of S = angle EOK = angle PZS

(2) Declination and Hour Angle

The Declination (δ) of a heavenly body is the arc of a great circle through the poles and the body intercepted between the plane of the equator and the heavenly body It is



The plane of the paper is supposed to coincide with the plane of Meridian

Fig 49

measured from the equator to the poles in degrees 0 to 90° and termed N or S (+ or −) according as the body lies north or south of the equator (see SK, fig 49)

The declination of the sun is given for every day of the year on pages I and II of each month in the 'Nautical Almanac' and that of the principal stars (pp 324 to 452) for every 10th day of the year

An inspection of these tables will show that the sun's declination varies from approximately 23½° N to 23½° S but that the stars vary very slightly during the year

The Polar Distance (*p*) of a heavenly body is the complement of its declination *i.e.* (90 − δ) it is styled N or S polar distance (N P D) or (S P D) according as it is measured from the N or S pole (see P S in fig 49)

The Hour Angle (*t*) of a heavenly body is the angle at the pole between the *meridian* of a place and the declination circle through the heavenly body (see angle I P S, fig 49) It is usually measured westward from the meridian from 0° to 360°, or 0h to 24h, one hour being equivalent to 15° of arc From fig 49 it is clear that this angle is the same as the

arc of the equator intercepted between the meridian and declination circle, also measured westward

In this system in place of the hour angle the right ascension of the heavenly body may be used

Right Ascension

Right Ascension (R A or $\mathcal{R}$) of a heavenly body is the arc of the equator intercepted between the first point of Aries and a declination circle through the body (see Υ K, fig 49) It is reckoned in time *eastwards* from 0 to 24 hours

The R A and declination (δ) of all the principal heavenly bodies are tabulated in the 'Nautical Almanac,' which gives their values at particular instants of time for the Greenwich meridian *as if they were seen from the centre of the earth*

Astronomical Triangle

A heavenly body at any moment forms a triangle with the zenith and elevated pole (see fig 50) the sides being arcs of the meridian ZP, the vertical circle ZS, and the declination circle PS

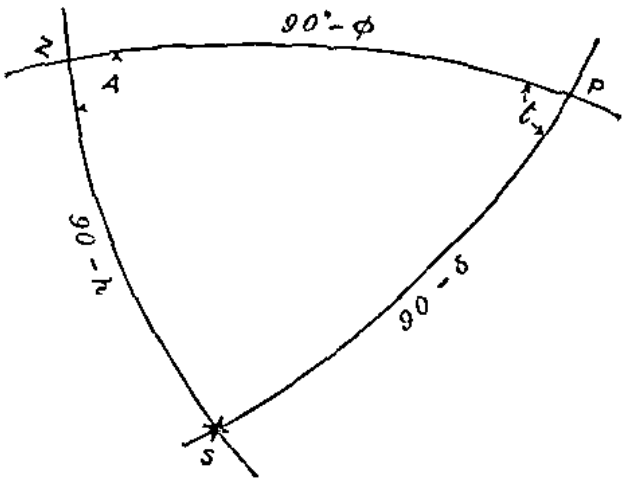


Fig 50

Now in fig 49 the arc FZ is the latitude ϕ of the observer, hence PZ is equal to $90 - \phi$, or co-latitude The latitude is always known approximately, or can be found from one of the methods described later

The side PS, or polar distance, is equal to 90 – declination, and its value can be found from the 'Nautical Almanac'

The side ZS or zenith distance, is equal to 90° – altitude, and h the altitude can always be observed, whenever the heavenly body is visible, with the theodolite

The angle at Z is the azimuth

The angle at P is the hour angle (t) *

The angle at S is the parallactic angle

Given any three of these, the others can be deduced For formulæ, &c, see Section III

NOTE.—It will be easily seen from fig 49 that **the latitude of a place is equal to the declination of the zenith or the altitude of the pole**

* More correctly as drawn 360° – hour angle

Hour Angle and Time (t)

When any point of the celestial sphere is on the meridian of an observer, that instant is designated the *transit* of that point over the meridian also the *meridian passage* and *culmination* In one complete revolution of the sphere about its axis every celestial body crosses the meridian twice It is therefore necessary to distinguish between the two transits The meridian is bisected by the poles of the heavens The transit over that portion which contains the observer's zenith is the UPPER TRANSIT, and the transit over the other portion is the lower transit At the upper transit the hour angle (expressed in time) of a heavenly body is 0 hours, at the lower transit its hour angle is 12 hours (see fig 49) A knowledge of the hour angle of a heavenly body at any moment will on account of the uniform rate at which it varies, at once give the time that it will take to reach the meridian if it be on the east side of it or the time elapsed since it crossed the meridian if it be on the west side In other words, if a clock be so regulated as to go 24 hours between two successive transits of any heavenly body and to read 0h 0m 0 at its upper transit, *the hour angle of the heavenly body* (t) *would be the time shown by the clock*

A sidereal day is the interval of time between two successive (upper) transits of the first point of Aries, γ, the true vernal equinox over the same meridian It is divided into 24 hours, each hour into 60 minutes, and each minute into 60 seconds When γ is on the meridian the sidereal time is 0h 0m 0 and it is *sidereal noon* at that place, and the sidereal time at any instant is the hour angle of γ at that instant reckoned from the meridian westward, 0 to 24 hours

From the definition of right ascension it is clear that all stars will succeed each other across the meridian in the order of their right ascensions

An apparent or solar day *is the interval between two successive transits of the sun's* centre across the same meridian and **apparent time** (AT) at any instant is *the hour angle of the sun* measured westwards throughout the circle expressed in time ($15^\circ = 1$ hour)

Now if the orbit of the earth were a circle with the sun in the plane of the equator and in the centre, this apparent day would give us a constant interval of time, but since the orbit is an ellipse and since it is inclined to the equator these intervals are continually varying day by day, and to obtain a measure of the day that is uniform and at the same time corresponds fairly well with the recurrence of day and night the average length of all the solar days of the year is taken and used is the *mean solar day* This is the day to which ordinary clocks and watches are regulated, and it is adjusted so as to bring 12 noon as near to the time when the sun is on the meridian as possible for every day of the year

Mean Time —The *mean solar day* is thus regulated by a fictitious or *mean* sun and is the interval between two successive transits of the *mean sun's centre* across the same meridian, the interval being divided into 24h 0m 0 *Mean time* (MT) *at any instant is the hour angle of the mean sun's centre at that instant*

Astronomical Time —Since the ordinary division of the civil day into two periods of 12 hours each is somewhat ambiguous and inconvenient for astronomical purposes, the day (apparent mean, or sidereal) is conceived by astronomers to commence at noon, and is divided into 24 hours the hours being subdivided as usual into minutes and seconds

Equation of Time —As the mean sun is an entirely fictitious assumption, we have no phenomenon by which we can directly observe its progress We are therefore reduced to observing the motion of the real sun, and by knowing the interval between the real and fictitious sun at any instant, we are enabled to arrive at the mean time at that instant This interval is called the *equation of time* (E), and is defined as the difference between apparent and mean time, or the angle at the pole between the hour circles passing through the centres of the true and mean sun, expressed in time

The variation in the equation of time is due to the two following causes —

(1) The obliquity of the ecliptic,
(2) The eccentricity of the earth's orbit

Firstly—Neglecting the effect of the eccentricity of the earth's orbit (*i e*, supposing the orbit a circle, and therefore by Kepler's Laws, that the earth moves uniformly along it) and for convenience imagining the sun to move round the earth with a uniform velocity, then (see fig 51) let a mean sun, M be made to move along the equator with the same velocity as the true sun T moves in the ecliptic, the two passing through ♈ (the vernal equinox) at the same instant Now when the true sun is at T the mean sun will be at M, where ♈T = ♈M and if T^1 be the point where the hour circle through T cuts the plane of the equator, then T^1M will measure the angle between the hour circles of T and M, and therefore the equation of time

A little consideration will show that T and M will coincide (*i e*, will lie in the same hour circle) only at the equinoxes and solstices and that from equinox to solstice M will be ahead of T, and behind it from solstice to equinox

The maximum difference between the true and mean suns, on account of the obliquity of

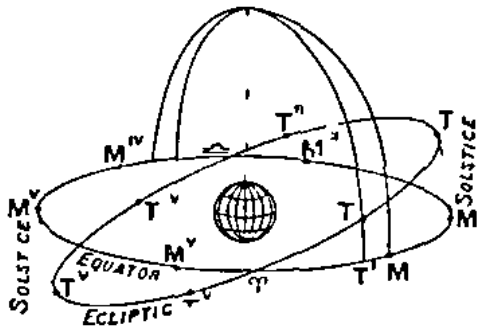


Fig 51

the ecliptic is about 10 minutes and occurs about the 5th February, 7th May, 8th August, and 8th November

Secondly—Neglecting the obliquity of the ecliptic, Kepler's second law tells us that the sun would appear to move fastest when the earth is at perihelion (see fig 46) and slowest when at aphelion. Hence a true sun would be ahead of a mean sun from perihelion to aphelion, and *vice versâ* on the return journey

Any point of the orbit may be taken as the starting point of the two suns, but one has been chosen which will cause the equation of time at any period of the year to be nearly a minimum With the point so chosen, the greatest difference due to the elliptical form of the earth's orbit is about 7 minutes

A combination of the above two causes of variation gives the following data —The equation of time vanishes (*i e*, the hour circles passing through the mean and true suns, coincide) four times in the year, and one of them having been fixed on the 24th December, the others fall necessarily on the 15th April 15th June, and 31st August, its maximum positive and negative values as applied to AT, and their respective amounts are as shown below, and occur about the dates given against them

	minutes
10th February	+14 26
14th May	− 3 51
26th July	+ 6 16
2nd November	−16 21

The value of F is given in the 'Nautical Almanac' for every day of the year at apparent and mean noon at Greenwich

We have seen (p 131) that the sun's hour angle (t) at any particular instant and place is the apparent time at that place

Now the difference of the hour angles of any celestial body at two places at the same instant is equal to the difference of longitude between those places It follows therefore that the difference of the solar times of two places at one instant is equivalent to their difference of longitude

Thus if

T_0 = Greenwich time
T – local time
L – longitude of place,

then $T_0 = T \pm L$ (+ or − according as longitude is west or east) this equation being true *whatever time is used* whether solar or sidereal as long as T_0 and T are *both of one kind* of time

Mean and Apparent Times

In converting apparent into mean time or *vice versa* we use the formula —

$$M T - A T \pm E,$$

where M T = the mean time
A T = the apparent time
E – the equation of time (+ or − according as it is additive to or subtractive from the apparent time)

Example 1 —In longitude 30° 45 W on December 7th civil date the L M T chronometer marks 3h 14m 13·5s (A M) and is fast 2m 18·7s what is the G M T ?

	h	m	s	
L M T chronometer −	3	14	13·5	A M
Chronometer correction = −		2	18·7	
Local mean time Dec 7th −	2h	48m	54·8s	A M
L M T, Dec 6th =	14	48	54·8	
Longitude (in time $\frac{30\ 45}{15}$) +		3	0	
the G M T = Dec 6th	16h	51m	54·8s	

And the civil time is Dec 7th 4h 51m 54·8s A M *

Example 2 —In longitude 60 W, local apparent time May 24th 1903 3h 12m 10s what is the local mean time ?

	h	m	s
L A T = May 24th	3	12	10
Longitude in time − +	4	0	0
G A T May 24th	7h	12m	10s

The value of F here required is that of the Greenwich instant corresponding to the local time instant 3h 12m 10s

* In the further examples unless A M or P M is inserted astronomical time will always be understood

From the 'Nautical Almanac' of 1903 we get E at G A N, May 24th, = 3m 27 64s, and the hourly variation = + 0 2 seconds

Hence at the given G A T instant

E 3m 27 64s + (0 2 × 7 21) − 3m 29 08s and is subtractive

	h	m	s
Thus since L A T − May 24th	3	12	10
and E =		3	29 08
L M T − May 24th	3h	8m	40 92s

The Year

The unit of measurement for large intervals of time is the *year*

The *solar year* (sometimes called Tropical or Equinoctial) is measured between two successive transits of the sun through the mean vernal equinox, that is to say, the interval in time taken by the earth in describing the whole of its orbit around the sun

There are not, however, an exact number of *mean solar days* in the year, the following being given by Bessel, the accepted authority —

One solar year = 365 2422 mean solar days

Mean and Sidereal Times

Since in the time the earth has described the whole of its orbit round the sun the latter has made one transit less over any given meridian than the first point of Aries—

366 2422 sid days = 365 2422 mean solar days

1 , = 0 99726957 ,,

or 24 hours S T = 23h 56m 4 091s M T

1 hour S T = 1h M T − 9 8296s M T (i)

and 1 hour M T = 1h S T + 9 8565s S T (ii)

Equation (i) shows the *retardation* of M T on S T and (ii) the *acceleration* of S T on M T

Tables to facilitate the conversion of the *intervals* of one species of time into *intervals* of the other are given in the 'Nautical Almanac'

Example—Convert 18h 4m 51s S T units into M T units

	h	m	s
By 'Nautical Almanac' p 576, 18h S T =	17	57	3 07 M T
4m ,, =		3	59 34 ,,
51s ,, =			50 86 ,,
M T equivalent required =	18h	1m	53 27s

Conversion of Mean into Sidereal Time and *Vice Versâ*

In practical astronomy we are constantly requiring to compute the S T corresponding to a given M T, or *vice versâ*

In such a conversion, it is necessary to refer to some *epoch* which is given in terms both of mean time and of sidereal time

Two such epochs are given in the 'Nautical Almanac,' viz —The S T of mean noon (p II) and the M T of sidereal noon (p III), *i e*, the M T of transit of the first point of Aries both at Greenwich

The *interval* of the known time, which has elapsed since the epoch, is then to be converted into an *interval* of the other time by means of the tables (see example), and the result added to the time of the epoch (given in 'Nautical Almanac') will complete the computation

Now, as the epochs in the 'Nautical Almanac' are given for Greenwich time and date, if the instant we wish to convert is given in local time, it is necessary to reduce the given local time to its equivalent Greenwich instant

This process thus depends on the value of L S T of L M N, and this can always be obtained from the G S T of G M N (given on page II, 'Nautical Almanac') by correcting the latter for the divergence in time between the M T clock and the S T clock, which has occurred in the interval elapsed between the M N at Greenwich and the M N at the locality

The difference in *rates* between the two times (M T and S T) may be taken at 9 86 secs per hour (see equation (11) p 134), and the elapsed interval in time is the difference in longitude, therefore the above correction = 9 86 secs × longitude in hours and is additive in W longitude and subtractive in E longitude

Example I —Conversion of Sidereal Time into Mean Time

On the 1st of May, 1898, in longitude 15 L the L S T is 20h 41m 12 65s What is the L M T ?

		h	m	s
Sidereal time to be converted	=	20	41	12 65
G S T of G M N	= 2 37 44 58			
Correction for acceleration at 9 86s per hour of long + for W − for E	= − 9 86			
L S T of L M N	=	2	37	34 72
Sidereal interval from L M N	−	18	3	37 93
M T equivalents: hours	=	17	57	3 07
mins	−		2	59 51
secs	=			36 90
93	=			93
M T interval from L M N, or local M time		18	0	40 41

Example II —Conversion of Mean Time into Sidereal Time

On the 1st June, 1898, in longitude 60 W the L M T is 10h 15m 20 73s What is the L S T ?

		h	m	s
Mean time to be converted	−	10	15	20 73
S T equivalents: 10 hours		10	1	38 56
15 mins	−		15	2 46
20 secs	−			20 05
73	=			73
Sidereal interval from L M N	−	10	17	1 80
G S T of G M N, 1st June	= 4 39 57 81			
Correction for acceleration at 9 86s per hour of long + for W − for E	− + 39 44			
L S T of L M N		4	40	37 25
Local sidereal time	−	14	57	39 05

Sidereal and Apparent Times

In computing sidereal time from apparent time, the A T may be first converted into M T and from this the S T computed, or a more direct way may be used by means of the sun's apparent R A

Thus

$$\textit{for the sun} \quad \text{ST} = \text{RA} + t = \text{RA} + \text{AT},$$

where t is the hour angle

SECTION III —THE APPLICATION OF SPHERICAL TRIGONOMETRY TO PRACTICAL ASTRONOMY

It will be seen that at any moment the sun or star in question will form with the zenith and elevated pole a spherical triangle of which the sides will be portions of great circles of the celestial sphere

The sides of the triangle have already been shown to have values as follows —PZ the

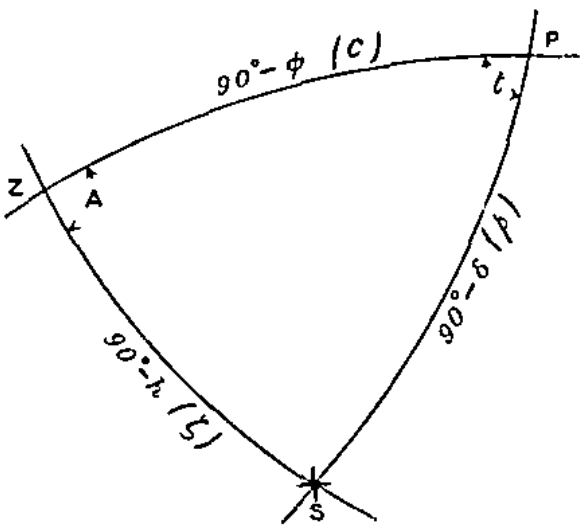


Fig 52

co-latitude $(c) = 90 - \phi$, ZS, the zenith distance $(\zeta) = 90 - h$, and PS the polar distance $(p) = 90 - \delta$

Also the angle at P = hour angle (t) required for time and the angle at Z – azimuth

Knowing any three of the above elements the remainder can be deduced

Then by the general formula for a spherical triangle we get

$$\tan \frac{t}{2} = \sqrt{\frac{\sin (S - p) \sin (S - c)}{\sin S \sin (S - \zeta)}},$$

$$\tan \frac{A}{2} = \sqrt{\frac{\sin (S - c) \sin (S - \zeta)}{\sin S \sin (S - p)}},$$

where

$$S = \frac{p + c + \zeta}{2}$$

Put for c its value $(90 - \phi)$ and for ζ, $(90 - l)$, then if $S = \frac{h + \phi + p}{2}$, we obtain the following —

(i) For time $\tan \frac{t}{2} = \sqrt{\sin (S - h) \sec (S - p) \operatorname{cosec} (S - \phi) \cos S}$,

(ii) For azimuth $\tan \frac{A}{2} = \sqrt{\sin (S - l) \sin (S - \phi) \sec (S - p) \sec S}$

Solution of Right angled Spherical Triangles—The formulæ for the solution of right-angled spherical triangles are very easily written down by 'Napier's Rules of Circular Parts'

In a right-angled spherical triangle there are 5 so-called 'circular parts' viz, 2 sides, the complements of the two angles, and the complement of the hypotenuse, the right angle being left out of consideration

These are written down in the 5 divisions of a circle in the order in which they occur in the triangle, any one may be taken as the middle part, then the two on either side are called the adjacent parts, and the other two the opposite parts, then the rules are—

Sine middle part = product of tangents of the adjacent parts,

" " " = " cosines of the opposite parts

Thus in a triangle ABC where C is the right angle, we have the following figure —

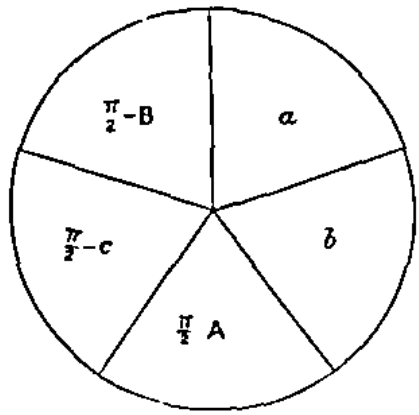


Fig 53

Star at Elongation—Another method of obtaining azimuth is to observe a star at "Elongation' i e, when the angle S of the triangle PZS is a right angle

In this case we have

$$\cos t = \tan p \cot c,$$

or (i)

$$\cos t = \tan p \tan \phi$$

Again

$$\sin p = \sin c \sin A,$$

$$= \cos \phi \sin A,$$

whence (ii)

$$\sin A = \sec \phi \sin p$$

From (i) the time of elongation can be computed and (ii) gives the azimuth of the star

Sun or Star on the Prime Vertical—It is sometimes desirable to observe a heavenly body when it is on or near the Prime Vertical In this case the angle at Z will be a right angle

$$\cos t = \cot p \tan c,$$

or (i)

$$\cos t = \tan \delta \cot \phi,$$

also

$$\cos p = \cos \zeta \cos c,$$

or

$$\sin \delta = \sin h \sin \phi,$$

whence (ii)

$$\sin h = \sin \delta \operatorname{cosec} \phi$$

Here (i) gives the time of crossing the Prime Vertical and (ii) gives the altitude of the body at that instant See plates XXXIII, XXXIV

SECTION IV—ELEMENTS FROM THE 'NAUTICAL ALMANAC'

The Nautical Almanac'* supplies us with the data necessary for the solution of problems in field Astronomy

When the time of observation, for which the quantities are required, is exactly one of the instants for which the required quantity is put down in the 'Nautical Almanac' then we have only to take out this quantity, but as a rule this time falls between two of the instants in the 'Nautical Almanac' and, as a mere inspection of this book shows that the quantities in it are continually changing we see that a reduction is necessary when the data are required for any instant of time differing from that for which the quantities are registered This reduction is done by *interpolation* and to facilitate this interpolation, the 'Nautical Almanac' contains the rate of change or alteration of the quantities

When dealing with with the sun and stars, interpolation by first differences, called *simple interpolation*, is generally sufficient

Example—Let it be required to find the declination of the sun at 6 o clock p m on a certain day, when at noon $\delta = +\ 12^\circ\ 10\ 0$, and is increasing at the rate of 9 seconds an hour

The result will be $12^\circ\ 10\ 0 + (9 \times 6) - 12^\circ\ 10\ 54$

We have seen that difference of longitude corresponds with difference of time, therefore as the data given in the Nautical Almanac' are for Greenwich noon they have to be corrected for any other place according to its longitude

Generally for obtaining a quantity for a certain *local time* we reduce that time to its corresponding *Greenwich* time and take out the quantity accordingly

The following should be specially noted —

For each month page I, 'Nautical Almanac,' gives data for G A N
" " page II, " " " " G M N

The R A of a star does not practically alter in 24 hours, therefore the R A of a star given in the 'Nautical Almanac' for any date is accepted as its R A at any other locality on the same date, or within 24 hours of it

* The Nautical Almanac' is sometimes called the 'Astronomical Ephemeris' (ἐφήμερος daily); an ephemeris is properly a table of daily positions of the heavenly bodies

The data commonly required in field astronomy are as follows —

(1) **Sun's R A and δ at time of observation** To find either of these assume your longitude as nearly as possible, turn it into time and add it to your L M T if you are W of Greenwich, subtract it if E

This result is the G M T of observation for which R A or δ can be found in the Nautical Almanac,' page II of each month

Example—In Longitude 15° E required the R A of sun at 10 hours on May 1st, 1903

L M T =	10 hours
Correction for longitude = −	1 ,,
G M T =	9 ,,

	h	m	s
R A of sun at G M N May 1st	= 2	30	6 23
Correction due to G M T *i e* 9 hours after noon − 9 × 9 5°s	=	1	25 68
R A at time of observation	= 2	31	31 91

The variations in 1 hour for R A δ and E are only given on page I Nautical Almanac for apparent time quantities These figures however are equally applicable to the mean time quantities on page II

(2) **Equation of Time** Find G T of observation as above and take out E, by simple interpolation, from the column on page I or II of the month in Nautical Almanac according as it is required for A T or M T Particular attention must be paid to the heading of the columns of the Nautical Almanac from which the sign + or − will be obtained

(3) On page II in the first column is G S T of G M N its hourly variation is 9 86 seconds (see p 134)

On page III of the month in Nautical Almanac is a column headed *Transit of the First Point of Aries* This is identical with G M T of G S N its hourly variation is 9 83 seconds (see p 134)

(4) **The R A and δ of the stars** These are given for all the more important stars under the head *Apparent Places of Stars* They are arranged in the order of their right ascensions for every ten days of the year, and eight stars near to each pole are further detailed for every day of the year Care must be taken to notice the sign N or S against the head of the column for declination It signifies north or south of the equator

It sometimes happens that there are two transits of a star in one day since the sidereal day is shorter than the solar day When this occurs on any day on which the R A and δ are given in the Nautical Almanac both are given in small figures and when the double transit occurs *on an intermediate day* the date alone on which it takes place is given in small figures In the latter case the procedure for interpolation is fully described in the *Explanations* at the end of the Nautical Almanac

The quantities given for R A and δ in the Nautical Almanac under the heading *Mean Places of Stars should not be used in computations*

The Tables I II, and III (near the end of Nautical Almanac) for determining the *latitude by observation of the Pole Star out of the meridian* may be used to derive quantities from by simple interpolation

The computation is as follows —

From the observed altitude of *Polaris* corrected for refraction &c is subtracted 0 1 0

To this reduced altitude the further corrections are applied (1) Table I with argument L S T of observation, (2) Table II with argument L S T and altitude (3) Table III L S T and date

Sun or Star on the Prime Vertical—It is sometimes desirable to observe a heavenly body when it is on or near the Prime Vertical In this case the angle at Z will be a right angle

$$\cos t = \cot p \tan c,$$

or (i)

$$\cos t = \tan \delta \cot \phi,$$

also

$$\cos p = \cos \zeta \cos c,$$

or

$$\sin \delta = \sin h \sin \phi,$$

whence (ii)

$$\sin h = \sin \delta \operatorname{cosec} \phi$$

Here (i) gives the time of crossing the Prime Vertical and (ii) gives the altitude of the body at that instant See plates XXXIII, XXXIV

SECTION IV—ELEMENTS FROM THE 'NAUTICAL ALMANAC'

The 'Nautical Almanac'* supplies us with the data necessary for the solution of problems in field Astronomy

When the time of observation, for which the quantities are required, is exactly one of the instants for which the required quantity is put down in the 'Nautical Almanac,' then we have only to take out this quantity, but as a rule this time falls between two of the instants in the 'Nautical Almanac' and, as a mere *inspection of this book shows that the quantities in it are* continually changing we see that a reduction is necessary when the data are required for any instant of time differing from that for which the quantities are registered This reduction is done by *interpolation*, and to facilitate this interpolation, the 'Nautical Almanac' contains the rate of change or alteration of the quantities

When dealing with with the sun and stars, interpolation by first differences, called *simple interpolation* is generally sufficient

Example—Let it be required to find the declination of the sun at 6 o'clock p m on a certain day, when at noon $\delta = +12^\circ 10' 0''$, and is increasing at the rate of 9 seconds an hour

The result will be $12^\circ 10' 0'' + (9 \times 6) = 12^\circ 10' 54''$

We have seen that difference of longitude corresponds with difference of time, therefore as the data given in the 'Nautical Almanac' are for Greenwich noon they have to be corrected for any other place according to its longitude

Generally for obtaining a quantity for a certain *local time* we reduce that time to its corresponding *Greenwich* time and take out the quantity accordingly

The following should be specially noted —

For each month page I, 'Nautical Almanac' gives data for G A N
" " page II, " " " " G M N

The R A of a star does not practically alter in 24 hours, therefore the R A of a star given in the 'Nautical Almanac' for any date is accepted as its R A at any other locality on the same date, or within 24 hours of it

* The Nautical Almanac' is sometimes called the 'Astronomical Ephemeris' (ἐφημερίς daily); an ephemeris is properly a table of daily positions of the heavenly bodies

Approximate Details of Certain Theodolites

Instrument	Weight of with Box	Weight of Stand	Price	Telescope Powers	Readings of Verniers	Average Bubble Value	Details
	lbs	lbs	£ s d				
3 inch Transit Theodolite (Vernier)	11	5	22 10 0	about 12	1	1 div 1	
5 inch Transit Theodolite (Vernier)	26	10	31 0 0	12 to 18	30	1 div 30	
6 inch Transit Theodolite with Micrometer Microscopes to horizontal and vertical circles	30½	12	42 0 0	16 to 20	10 (estimate to 1")	Vert bubble 1 div 5" plate bubble 1 div = 30"	With transit axis level and aluminium star sights
6 inch Transit Theodolite (Vernier)	35	10	36 10 0	12 to 18	20	1 div = 20"	With transit axis level

A transit theodolite has already been described and instructions given for its adjustment and setting up (p 15)

Notes on the Theodolite when used in Field Astronomy —

1 All altitudes should be taken on both faces

2 Note whether the eye piece used reverses horizontally or vertically or both

3 When observing the sun the dark glass should be used

4 For observations to stars it is necessary to light up the field of the telescope This may be done in two ways (1) By using the axis lamp which fits on to a small bracket, and reflecting through the axis of the theodolite lights up the field The result generally is far from satisfactory A more certain method is as follows (2) A piece of white paper about 1 inch wide is fitted to the object end of the telescope by means of an elastic band and bent slightly over the object glass On this paper is directed the light from any small lamp held at the side of the theodolite The reflection from the paper then lights up the interior of the telescope A bicycle lamp answers very well for the purpose

Care must be taken to throw just enough light on the field to show up the cross wires without obscuring the star

The 3 inch transit theodolite given in the list is a very good little instrument but is recommended more for rapid triangulation than for astronomical work However for rapid exploration azimuths and latitudes may with care be obtained to within 30"

TIME KEEPERS

The time keepers used in field astronomy are either **box chronometers** or **chronometer watches**

A box chronometer is invaluable for stationary work or work on ships, but is not suited for land journeys

* Where weight is not a consideration of the first importance a 6 inch Transit Micrometer Theodolite costing about £50 and weighing about 70lbs is to be preferred especially for astronomical work

A keyless half chronometer watch is recommended for work in the field These watches are less expensive than pocket chronometers are less liable to get out of order, and more are easily repaired They may be carried in the pocket under conditions of rough usage short of actual violence The watches used by the R G S have backs and faces to screw off, and caps to fit on the winding button Such a watch costs from £20 to £30

Both box chronometers and chronometer watches may be regulated to keep either sidereal or mean time

Star Atlas Maps and Charts

A set of star charts is given at the end of this book

From these or similar charts, the *relative* positions of the various stars are seen at once, and then their positions in the heavens can be found by referring these positions to imaginary lines joining well defined stars or groups of stars and following these lines in the heavens

In using a star chart the observer may be supposed to be standing (as he is in reality) at the centre of the celestial sphere, in which case the chart approximately represents the stars as seen when looking upwards When the chart is therefore placed on the table the stars will appear in their proper relative positions but the E and W points will be reversed with regard to the *true* E and W

All observations should be worked out on set forms a sufficiency of which is an important aid to the topographer The following books are required for working out observations —

An Angle Book (for booking observations in the field)
The 'Nautical Almanac' or other Ephemeris for current and *next* years
Book of logarithms *
Astronomical Tables (refraction &c —see Tables XIV –XVI)
Computation forms (see Forms K P)
Star Charts (see Plates XXX –XXXIII)

SECTION VI —OBSERVATIONS

Observations in field astronomy consist of determinations of the altitude of the sun or star for latitude and time or for azimuth the horizontal angle between some 'referring object' and the sun or star, in addition, at the same instant

A Star through the theodolite appears as a bright point It is only necessary therefore to bisect the star with the centre horizontal cross wire of the theodolite when taking altitudes and with the vertical wire when taking horizontal angles Use the same part of the wire on each face

The Sun however is a large body, and hence, in order to make all observations possible of comparison the centre must be observed As however we cannot tell the precise instant the wire of the theodolite crosses the centre we are reduced to observing one edge or 'limb' as it is called For altitudes, the time of contact of the horizontal wire with the upper or lower limb as seen through the theodolite is noted In the same way, when taking the horizontal angle between some 'referring object' and the sun the right or left limb is observed by making a contact with the vertical wire

* It saves an enormous amount of time and trouble to use a logarithm book which gives the logarithms of the trigonometrical functions for each second of arc e g Shortridge's Logarithms

In order to do away with the necessity for applying a correction for the sun's semi diameter, an equal number of observations on opposite limbs are made, that is, "upper" and "lower" for altitudes, and "right" and "left" for azimuth angles

It is advisable to record the limbs in the Angle Book as they *appear* through the telescope, and state which way the eye piece reverses This last, however, is not always necessary, if the "pairing" of observations is strictly adhered to

As already explained, *collimation errors are eliminated by taking an equal number of* observations on each "face" of the theodolite No altitude obtained from a theodolite on one "face" only is of any value

DETERMINATION OF TIME

Time by Single Altitudes

We have seen that time, either sidereal or solar, is dependent on the hour angle of the 1st point of Aries or of the sun Since we are able by means of astronomical observations of the sun, to compute its hour angle, the solar time is readily found, and so with a star

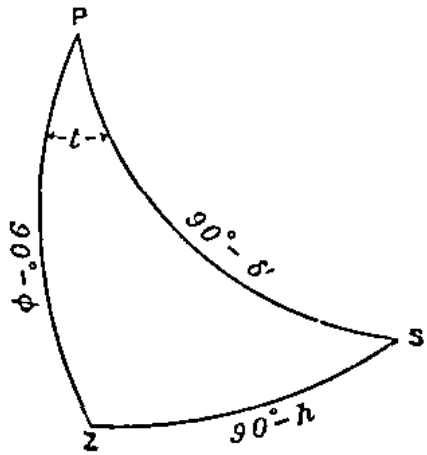


Fig 54

Time is known when we have determined the hour angle of the sun or a star If we adjust a theodolite so that the centre wire describes the plane of the meridian, the determination of the instant of passage of sun or star (with a knowledge of the R A) gives the simplest way of computing the time But this is rarely possible in the field However since we are able by an observation of altitude of sun or star, when some distance from the meridian to deduce its hour angle, we have a ready means of determining the time at the instant of observation

An examination of the astronomical triangle PSZ (see fig 54) shows us that the value of the hour angle ZPS depends to a great extent upon the side ZS for of the other sides PZ is constant, and PS varies only slightly with the change of declination during the time taken in making an observation Now ZS is the complement of the altitude and thus in a position of the heavenly body such as is expressed in the above figure the hour angle changes in accordance with the changes of the altitude

Obviously, so far as concerns accuracy of observation the most favourable period to observe altitudes for time will be when they are changing as rapidly as possible *i e*, when for

a given change of altitude the corresponding alteration in time is as small as possible, for as in all observations certain imperfections and inaccuracies are to be expected, we must choose a period for our observations when these errors will have the least injurious effect on our results

Selection of Stars—*In selecting a star for the determination of time by single altitudes choose one on or near the Prime Vertical (*i.e.*, nearly E or W) It is easy to show that small errors in the observed altitude, or in the assumed latitude produce the least effect upon the computed time when the star is on the Prime Vertical *See Table on p* 160

For convenience of observation, and to avoid excessive refraction, the star should have more than 15 and less than 45° altitude

When a star is on the Prime Vertical, it necessarily follows that its declination must be of the same name (*i.e.* additive for N and subtractive for S lat), and less than the latitude of the place of observation

The diagrams on Plates XXXIV and XXXV show at a glance the Hour Angle of a heavenly body when on the Prime Vertical and its Altitude at that instant The position of a star at any instant can be found from a knowledge of its R A (*i.e.*, L S T, of transit) and declination The Nautical Almanac and star charts should therefore always be consulted

Example —It is required to take observations at about 8 P M in lat 40° N Now on looking up the G S T of G M N (p II, 'N A') and correcting it at the rate of 9 86 secs per hour of longitude (W additive E subtractive), we find the L S T of L M N to be 10h 25m 30s and therefore the sidereal time of 8 P M is 18h 25m 30s The star chart shows a large star with declination 25 N and R A 14h 55m 30s

Referring to Plate XXXIV it will be seen that with this declination and in latitude 40 a star will cross the P V 3h 45m before and after meridian transit The star will therefore be on the P V in the west at 18h 40m 30s L S T that is at 8 15 P M local watch time

The time at which the observation should be made is thus easily found and it is seen from Plate XXXIII that the star has a suitable altitude at that instant, in this case 41°

At or near the equator, the above rules cannot be applied, but any star whose meridional zenith distance $(\pm \phi) - (\pm \delta)$ does not exceed 15° may be used

Pairing Observations—When taking observations for time (and also for azimuth), one set should be taken on an east star, and one on a west star Stars should therefore be selected beforehand to enable the observer to make the observations consecutively

Time should be found by either of the methods hereafter described to an accuracy of less than one second of time

Chronometer Error—The object of the observation is to obtain and record *the error of the chronometer*, which for any instant is the difference between the time it shows and the time it should show, this error being styled *fast* when it is ahead of proper time, and *slow* when it is behind

The error of the chronometer thus obtained is that *at the mean of the times of observation* Thus moment should be noted to the nearest minute

Data Required.—For this purpose, besides our observed altitude, we must know two other elements one of these must be PZ, the co-latitude, the other PS the polar distance, which can be derived from the 'Nautical Almanac

A small error in the assumed latitude, and even a considerable error in the assumed longitude would produce no practical error in the result

* The selection of a star near the Prime Vertical is a counsel of perfection Practically all that is required is to select a star well to the East or West and between 15° and 45° in altitude

The following equation is used in the computation for time (see p 136) —

$$\tan \frac{t}{2} = \sqrt{\cos S \sin (S - l) \operatorname{cosec} (S - \phi) \sec (S - p)}$$

where

$$S = \frac{h + \phi + p}{2}$$

Let ϕ always positive and p reckoned from the *elevated* pole

NOTE —If a number of observations of the same star at the same place are to be individually computed it will be most readily done by the fundamental equation

$$\cos t \quad \frac{\sin h - \sin \phi \sin \delta}{\cos \phi \cos \delta}$$

here ϕ and δ are constant for all the observations and it only remains to compute sin l

Instructions for Observing (*General*) —For precision several altitudes will be taken and the mean of these with the corresponding mean of the times noted will be taken for computation If the time assumed is much out the computation must be repeated with new functions obtained by means of the corrected time

The most favourable position for the observer for taking this observation is on the equator, the worst at either of the poles

When the latitude is undetermined a small error in its assumed value has no appreciable effect on the results of the observation if the stars taken are near the prime vertical (see p 160)

To eliminate instrumental errors errors of refraction and assumed functions, observations must be taken in pairs on either side of the zenith, in the case of the sun by morning and afternoon observations in that of the stars by two stars one east and one west of the meridian

With Theodolite —When observing the sun adjust the instrument turn the telescope on the sun and make contact with the upper or lower limb on the centre horizontal wire noting the time of observation and the readings of both ends of the level and of the vertical circle, next change face and make contact with the other limb, noting readings as before

The procedure for observing a star is the same except that the observations are taken by allowing the star to make its own passage across the centre horizontal wire near to the vertical wire Four* observations complete a set half on each face of instrument, thus F R F L, F L F R

Time by Equal Altitudes

If a star, the declination of which is constant during the observation be observed at the same altitude before and after transit over the meridian it is obvious that the hour angles of the star at both instants of observation must be equal to each other though on opposite sides of the meridian, and that the mean of these instants will give the actual time that the star is on the meridian

As a star rises in altitude we may record an instant (say t) which by our time keeper corresponds to the time that the star reaches a certain altitude then by waiting till the star has crossed the meridian and descends to the same altitude and again recording the instant (say t) we can find the moment of transit which should have been $\frac{t + t}{2}$ A comparison of this time with the R A of star would determine for us the error of our time-keeper

This method of equal altitudes is independent of an accurate knowledge of latitude or declination or of errors in the graduation of the instrument It is (with a star) very simple

* Clearly all that is absolutely necessary is F R F L

in its procedure but requires a clear sky for a considerable interval of time, and for altitudes less than about 45° it is liable to variations on account of changes in temperature, and, therefore, of refraction

When the sun is used with this method, a correction has to be made for the change of declination that occurs between the times of observation before and after the passage over the meridian

Having obtained the mean of the two times of observation, it may be corrected to the time of apparent noon *i e*, time of transit by the following formula —

$$\frac{\pm t \times d\delta}{15}(\tan\phi \operatorname{cosec} t - \tan\delta \cot t),$$

where

t — half the interval between the two observations,

$d\delta$ = the change of declination in one hour,

δ — the declination of the sun when on the meridian

This correction is positive when the sun is leaving the elevated pole, negative when it is approaching it

In observation by equal altitudes of both stars and sun, instead of one observation only being made each side of the meridian it is necessary, for precision to obtain a set as in observing for absolute altitudes The instrument must be set forward and readings taken at intervals of 10, 20, or 30 minutes of arc, on the upward journey of the heavenly body, and to these readings the vernier can be easily adjusted on the downward journey of the sun or star The mean time of each set of observations will then be used as if they were the instants corresponding to one pair of altitudes only

Comparison of Watches

Suppose it is intended to compare a chronometer watch (*a*) and a chronometer watch (*l*) The observer A watches the seconds hand of (*a*), while B watches (*l*) When the seconds hand of (*a*) appears to cross a definite division, A makes a rap on the table, B notes the time of this by (*l*) to the nearest $\frac{1}{10}$th second

B then signals in a similar manner to A, who notes the time of the signal

They then change watches and go through the same procedure

The mean of these four determinations will give a very fair comparison

Comparison of Box Chronometers

In order to get a good comparison, it is desirable that at least one of the chronometers should be sidereal, if the others are mean, and *vice versâ*

Box chronometers always tick half seconds

As the difference of the two times, sidereal and mean, is approximately 10 seconds an hour and the clocks tick half seconds, a coincidence will occur every 3 minutes

Place the two chronometers on the same table, and take up the time on one counting one half two half three, &c When the coincidence appears exact, while still counting, note the time shown by the other chronometer

Comparison of Watch and Chronometer

Owing to the fact that a watch beats five times in 2 seconds, it is impossible to get a satisfactory coincidence It is therefore best to compare them in the same way as two watches

DETERMINATION OF AZIMUTH

To determine the direction of the meridian line or the azimuths of any number of points from a station, it is usual to select some well defined terrestrial object suitably situated to

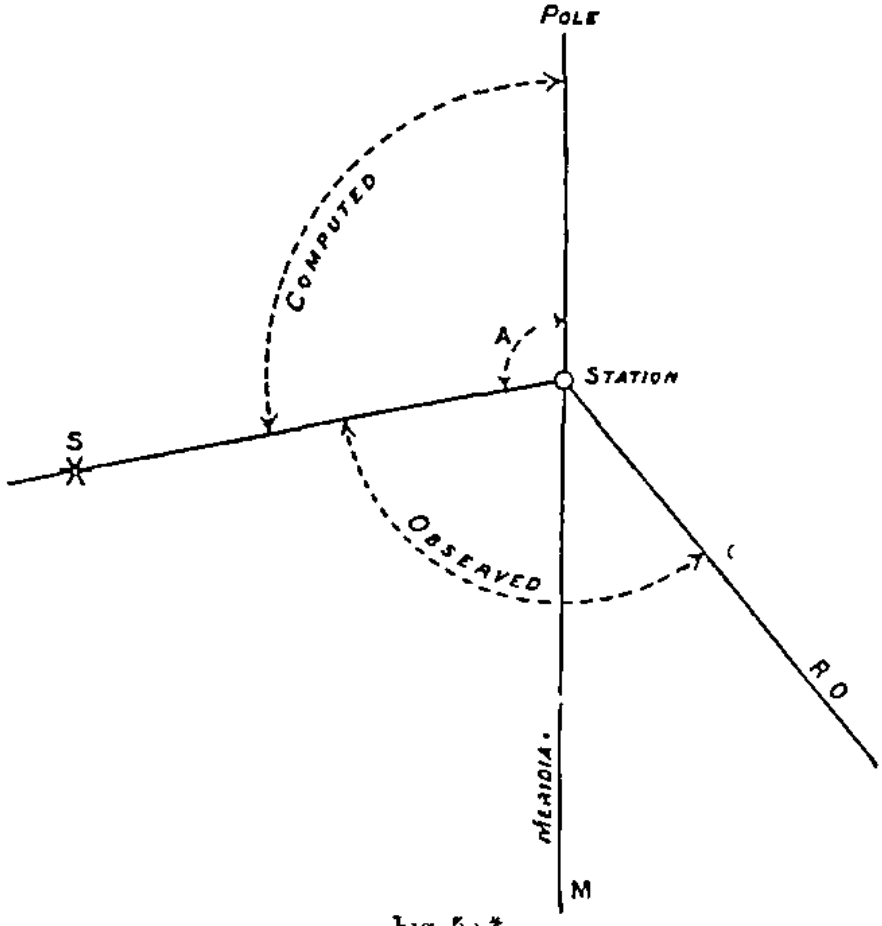


Fig 55 *

which all azimuth angles can be referred Such an object is called "**The Referring Object**" (R O)

In all **astronomical observations for azimuth** the procedure adopted is, by means of an observed altitude, to *compute* the azimuth (A) of the sun or star (S) (see fig 55) and to *observe*, at the same time, the azimuthal angle between the R O and the sun or star From these two angles (one *computed* and the other *observed*) it is simple to deduce the azimuth of the R O

The computed azimuth is always measured from the elevated pole, the shortest way

If we can determine the precise instant a heavenly body is on the meridian the determination of azimuth is simple, and can be done by measuring the horizontal angle at that instant between the heavenly body and the R O

But, when on the meridian, a heavenly body is moving at the greatest possible rate in azimuth, so this method is impossible and it is necessary to select a time for observing when a small error in altitude or time will have the least possible effect on the result

Stars should be observed for azimuth at or near elongation, and sun or stars on or near the prime vertical As regards the latter practically all that is required is to choose a star well to the east or west and between 15° and 45° in altitude

* Azimuths used for the purposes of triangulation as described in Chapter III are measured from the South by the West Thus if the deduced azimuth of the R O in fig 55 were 150 the azimuth used for triangulation would be 330 (the North being the elevated pole in this case)

AZIMUTH BY OBSERVATION OF SUN OR STAR EAST OR WEST

As regards the selection of stars for observation by this method the condition that they are to be well to the E or W necessitates their selection being made in the same way as those required for the determination of time (*q v*)

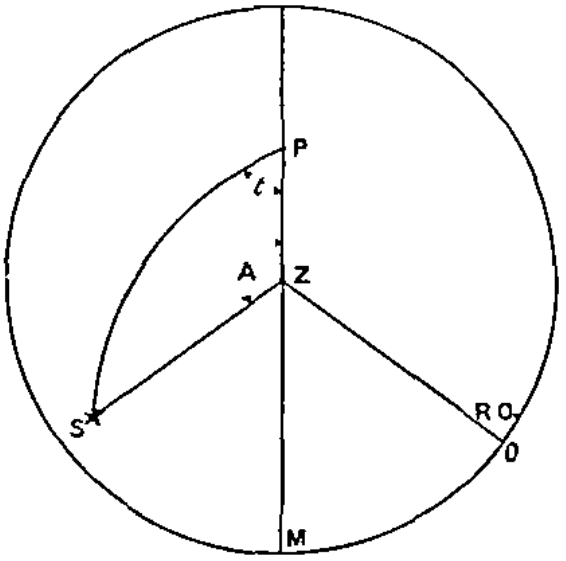


Fig 56

For the purposes of the determination of azimuth the theodolite having two circles a horizontal (or azimuthal) and a vertical (or altitude) circle has particular advantages

In fig 56 S represents the sun or star O the referring object and P the pole

We can *observe* the angle SZO with the theodolite and there only remains for us to *compute* the angle SZP *i e* A or the azimuth of the sun or star

In the astronomical triangle we have the following quantities —

$$\begin{aligned} PS &= 90 - \delta, \\ PZ &= 90 - \phi \\ ZS &= 90 - h \\ \text{Angle } SPZ &= t \end{aligned}$$

It is required to compute the value of the angle SZP, this can be done with either of the two following sets of data —

(*a*) The three sides as above

(*b*) The two sides (90 $-$ ϵ) (90 $-$ ϕ) and included angle "t"

Astronomical Form 3 utilises the data (*a*) in the following equation and can be employed with either sun or star observations —

$$\tan \frac{A}{2} = \sqrt{\sec S \sec (S - p) \sin (S - \phi) \sin (S - h)}$$

where

$$S = \frac{h + \phi + t}{2}, \text{ and A is the angle SZP}$$

Instructions for Observing for Azimuth —The RO selected should be suitable for intersection with the cross wires and as far off as possible, so that solar focus may be used At night the RO will be a light not less than 400 yards off

In all cases care must be taken that the lower plate remains clamped throughout the set of observations

It is not advisable or necessary that the R O should read exactly zero

In all azimuth observations an endeavour should be made to take as many observations on one "swing" as on the other "swing"

The observed altitudes and azimuths are simultaneously recorded

The times are not absolutely necessary except for sun observations (to correct δ) but are usually recorded, as then a fair value for time (which is always useful) can be computed on Astronomical Forms 1 or 2 from the observed altitudes

The procedure in observing **a star** for azimuth is as follows —

Note the reading of the R O on the horizontal arc and turn the telescope on the star, take an observation with the intersection of the centre cross wires and note the time, the readings of both ends of the bubble, and of the vertical and horizontal arcs Now reverse the telescope, and take another observation of the same star, noting time bubble readings and vertical and horizontal arcs, as before, then read the R O This completes one set of observations on a single star

The procedure for obtaining *simultaneous* azimuth and altitude readings **with the sun** is as follows —

Place the *horizontal* wire in *advance* of the limb to be observed and allow it to make its own contact just before the moment of contact keep the *side* limb to be observed in contact with the *vertical* wire by means of the slow motion screw, just as the contact with the horizontal wire is completed remove the hand from the vertical wire slow motion screw note the time and then read level error, vertical and horizontal angles

The following order of observations should be followed —

Read R O
Observe (as above) the right upper limb
Reverse the telescope
Observe (as above) the left lower limb
Read R O

This completes one set of observations

A rough diagram should always be drawn in the angle book, showing the relative positions of the observer sun or star and referring object, and also the meridian line

In rapid triangulation it is frequently of the greatest importance to determine the azimuth of some side of the triangulation In such cases it is often convenient to determine this by observations of the sun in the afternoon Three sets should be taken, and each set worked out independently, so as to obtain a check

Azimuth by Circum Polar Star at Elongation

A Circum polar Star useful for this observation is one with a polar distance of less than 10° As already explained a star is at elongation when the angle at S in the triangle PZS is a right angle

The time of elongation is computed from the formula $\cos t - \tan \phi \tan p$ Then the angle between the R O and the star is observed at this time

The azimuth of the star can be computed for the same moment from the formula $\sin A = \sec \phi \sin p$

It is sufficient to take an observation on each face within a few minutes of the computed time of elongation Only the times and horizontal angles need be recorded Thus the observations would be —Face right, R O, star Face left, star, R O With a quick observer these might be repeated

The means of the angles between the R O and the star can then be taken, provided that in ordinary latitudes no time differs from that of elongation by 5 minutes either way This gives a range of 10 minutes for observing

The angle A is then added to or subtracted from this observed angle to obtain the azimuth of the R O A rough diagram should be drawn

The altitude of the star at elongation is given by, $\sin h = \sin \phi \sec p$

The method is an easy one, both as regards observing and computing and gives good results provided the time limits are not exceeded

The computation is so simple that no example is thought necessary

Rough Methods

The foregoing observations occupy considerable time in both observing and computing, and a shorter and simpler method of obtaining azimuth is sometimes necessary

There are two such methods of obtaining an approximate azimuth by circum polar stars, at culmination and at elongation these are as follows —

Circum-polar Star at Culmination (rough)

Compute the chronometer time of upper or lower transit of Polaris, or some other known circum polar star As this time approaches, bisect, with the central wire of the telescope, the R O and read the horizontal arc Then at the computed instant of the star's culmination bisect the star with the central wire and read the arc Observe the R O again The difference between the reading of the star and the mean of readings of R O will give the azimuth of R O E or W

Repeat the process with other circum polar stars if required

Circum polar Star at Elongation (rough) —Assume the elongation to be *about* 6 hours from the time of transit easily found from the R A given in the 'Nautical Almanac'

As nearly as possible *at this time* take a set of observations to obtain the horizontal angle between the R O and the star

Now the azimuth of a star at elongation is obtained from the relation $\sin A = \sin p \sec \phi$

A fair value for the azimuth of the R O is obtained, therefore, by adding or subtracting the angle A from the *greatest* of the observed angles, according as the elongation is E or W

In the northern hemisphere there are two stars, α and δ, *Ursæ Minoris*, which come to elongation at intervals of approximately 6 hours from each other One of these can therefore always be found at elongation in the first half of the night In the southern hemisphere there are two suitable stars *β Hydri* and *β Chamæleontis* each about 12 from the pole, and of the third and fourth magnitude respectively

A plan of the constellation *Ursa Minor* is given in fig 57 which may assist in the identification of the several stars

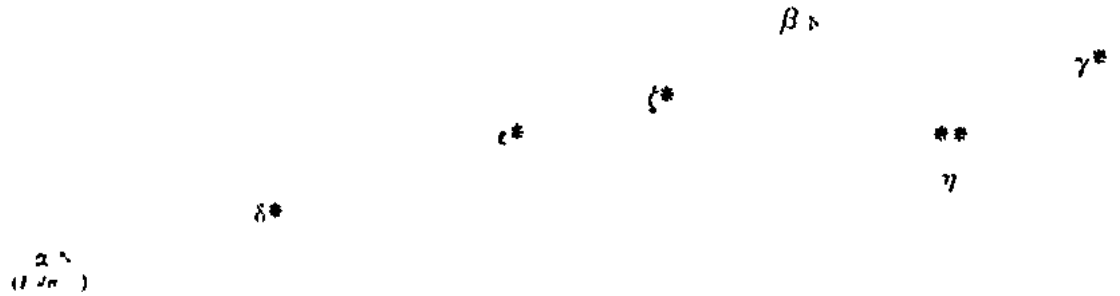


Fig. 57

Ursa Minor

The elements of all these seven stars, except η which is a double star, are given in the 'Nautical Almanac'

DETERMINATION OF LATITUDE.

General Remarks

In fig 58, in which the plane of the paper is supposed to coincide with the plane of the meridian —

It is evident that the *latitude of a place* is equal to the *declination of the zenith* EOZ

It is also the *altitude of the pole* NOP, for in fig 58, ZE = latitude of the place = ϕ, and

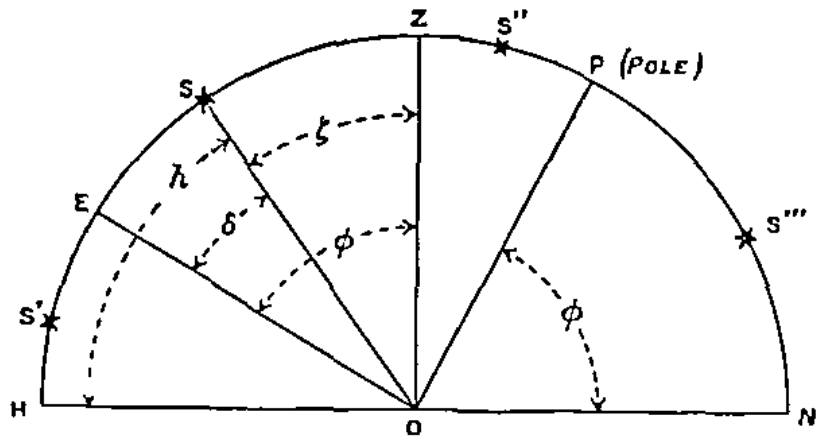


Fig 58

therefore PZ = 90 − ϕ, but PN = 90 − PZ Hence PN or PON, which is clearly the altitude of the pole, is equal to ϕ

Let h = altitude of a heavenly body

ζ = meridian zenith distance This is $\frac{+}{-}$ when the heavenly body is $\frac{S}{N}$ of zenith

δ = declination
ϕ = latitude of place } These are $\frac{+}{-}$ when $\frac{N}{S}$ of equator

Then it is clear from the figure that $\phi = \zeta + \delta$

If the heavenly body be—

If at S ζ is $+ve$, δ is $+ve$
If at S ζ is $+ve$, δ is $-ve$
„ S ζ is $-ve$, δ is $+ve$
„ S ζ is $-ve$,* and δ is 180—true δ

In the first two cases the altitude (h) is observed while facing south
„ last „ „ „ „ „ north

Now suppose the observations are made in *south* latitude (see fig 59) Then if the heavenly body be at S we have $\phi = \zeta + \delta$, whence giving ζ and δ their *proper signs*, ϕ if south must come out negative

From the above results it will be seen we get the following general formula giving ϕ, ζ, and δ, their proper signs —

$$\phi = \zeta + \delta \quad \ldots \ldots \ldots \ldots \quad (1)$$

* δ is here measured from E through the zenith and elevated pole, and is equivalent to the angle S ″ OE, that is to say when a star is taken at its *lower* transit the δ is obtained by taking the supplement of the value given in the 'Nautical Almanac'

We have thus an easy method of determining the latitude, viz —by measuring the altitude of any celestial body at the exact moment when it is on the meridian, δ being obtainable from the 'Nautical Almanac,' if we know the approximate Greenwich time of observation

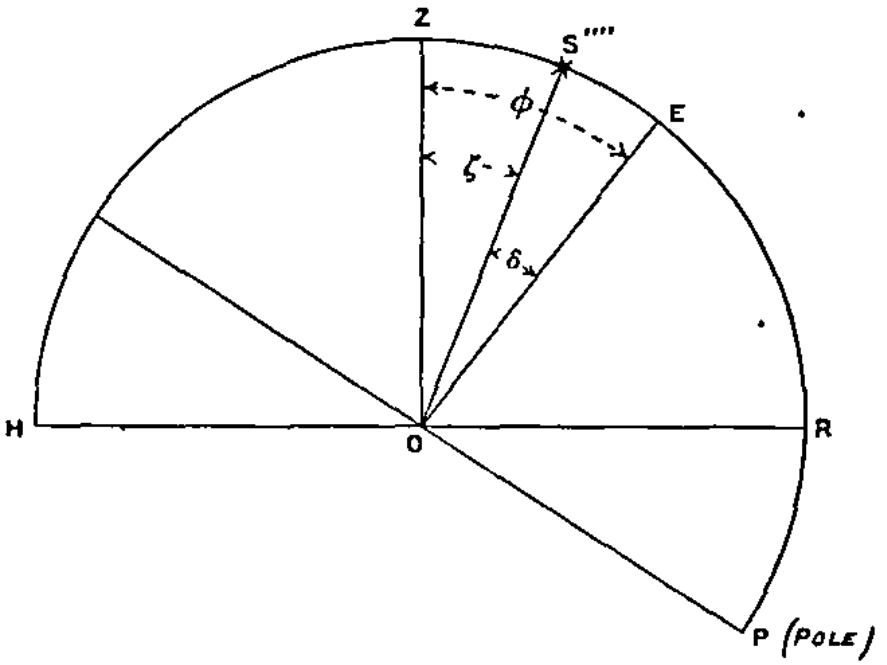


Fig 59

Latitude by Meridian Altitudes

This is the simplest way of determining latitude though not the most accurate

First calculate the *time of transit* of the sun or star (see p 153)

Then, having adjusted the theodolite, commence observing a minute or so before the time of transit and take a series of altitudes F R, F L, F L, F R, F R, F L, &c, noting the times The mean of the pair of observations (F R and F L) nearest to the time of transit is to be taken as the observed meridian altitude Or, if the error of the watch is not accurately known the pair which gives the *greatest* altitude must be taken (In the case of the sun, the correction for semi-diameter must first be applied in order to ascertain this)

Correct the meridian observed altitude so obtained, for level error, refraction (and parallax in case of the sun) and from this obtain the true meridian zenith distance (ζ) Then, as before —

$$\phi = \zeta + \delta \qquad \text{(taking care of the signs)}$$

To get good results from meridian altitudes, the following rules should be observed —

(1) No altitude should be less than 40°

(2) Equal numbers of North stars and South stars should be observed

(3) The North and South stars should be balanced, *e g*, if a North star of altitude 40 is observed, try and find a South star of the same altitude

It is clear that a sun altitude will be unbalanced and that a latitude by meridian altitude of the sun can only be an approximation

Latitude by Circum Meridian Altitudes

When a number of altitudes are observed very near the meridian, they are called *circum meridian* altitudes

This method is an accurate and satisfactory one

Each altitude reduced to the meridian gives nearly as accurate a result as if the observation were taken on the meridian

It can be shown by investigating the formula that near the meridian, the correction varies as the *square* of the hour angle and not simply in proportion to the time Hence it is that near the meridian we cannot reduce a number of altitudes by taking their mean to correspond to the mean of the times as is done (in most cases without sensible error) when the observations are remote from the meridian We are obliged therefore to reduce *each* altitude separately and take the mean of all the results

(*a*) The zenith distance should not be greater than 50° and under no circumstances less than 10°

(*b*) The hour angles should not as a rule, exceed 10 minutes

(*c*) The closer the meridian (and therefore the more rapidly the observations are taken) the better will be the results

(*d*) Equal numbers of North stars and of South stars should be observed

(*e*) The North and South stars should be balanced

Selection of Stars—When selecting stars care must be taken to choose those which transit at a convenient time The stars chosen should have zenith distances less than 50°, and greater than 10° This can be found from the equation

$$\zeta = \phi - \delta$$

by giving ϕ an approximate value and carefully looking to the signs of ζ, δ and ϕ The altitude (h) of the star at transit will be 90 ζ

Time of Transit—The time of meridian transit is obtained in the case of a star, from the R A given in the Nautical Almanac which is the same thing as the L S T of transit This last can be reduced to L M T from a knowledge of the G S T of G M N p II 'Nautical Almanac (see Astronomical Form 4)

With the sun the L M T of transit is obtained from the *equation of time* (p I, Nautical Almanac') corrected for longitude If a sidereal clock is used the L S T of transit will be the R A of the sun as given in the Nautical Almanac corrected for longitude (see Astronomical Form 5)

Practical Hints on Observing for Latitude

Programme of Work—Before commencing observations for latitude an observer should make out a programme of the observations he intends to take determining the approximate time of each by his watch and selecting such stars as will enable him to carry out his programme at convenient hours

As the travelling rate of the chronometer can rarely be depended on observations for time should always form part of the programme these can be taken at any convenient time while waiting for the culmination of latitude stars

For example in latitude 40 N on the 1st January observations are required for latitude The sidereal time at mean noon on that day is 18 h 50 m and supposing we wish to begin at dark and complete the observations before 10 30 P M we must choose stars for latitude which culminate between 0 h and 5 h 30 m sidereal time

The zenith distance of a star at culmination is found from the equation $\zeta - \phi \quad \delta$ where the signs of the several quantities must be carefully attended to

Then knowing that the latitude is approximately 40 0 and looking out the declination of α Cassiopeæ from the 'Nautical Almanac we obtain the approximate zenith distance of this star thus —

$$\begin{array}{rr} \phi & + 40 \quad 0 \\ \delta & + 55 \quad 58 \\ \hline \phi - \delta = \zeta - & - 15 \quad 58 \text{ north of the zenith} \end{array}$$

Similarly we shall find for—

α Arietis	ζ = + 17	3 south
ε Cassiopeiæ	ζ = − 23	9 north
α Tauri	ζ = + 23	42 south
Polaris	ζ = − 48	45 north
β Orionis	ζ = + 45	19 south

forming three pairs of approximately equal north and south zenith distances.

As regards the times of transit.—If the watch is M T look out in the 'Nautical Almanac' the G S T of G M N and correct this for longitude at the rate of 9·86 seconds per hour (W + E −). This will give the L S T of L M N. Now the R.A. of the star is its L S T of transit, hence the difference of the R.A. and the L S T of L M N gives the sidereal interval from L M N which can then be reduced to a M T interval and used with a M T watch (corrected for any known error). If the watch shows S T, no computation is necessary except to apply any known error.

The programme can then be drawn up as below entering altitudes instead of zenith distances.—

Time	Star	Mag.	Aspect	Altitude	Remarks.
h m					
5 44	α Cassiopeiæ	Var.	N	74 2	For latitude at upper meridian.
6 31	Polaris	2·2	N	41 15	
6 58	ε Cassiopeiæ	3·6	N	67 51	
7 11	α Arietis	2·0	S	2 28	
9 39	α Tauri	1·0	S	67 18	
10 19	β Orionis	0·3	S	41 41	

E. and W. stars suitably placed for time observations can be observed between the observations to α Arietis and α Tauri.

Instructions for Observing Latitude.—The observer should commence observing altitudes about 15 minutes before the transit, reversing the telescope after the *first* observation and then after *each pair* of observations.

In the case of the sun altitudes are taken to the upper and lower limbs alternately.

The observations should be continued till it is quite evident that the sun or star is falling and that some 10 minutes has elapsed since transit.

As the altitudes are changing very slowly contacts have to be made by the slow motion screw.

At the time of observing then set the vertical circle to the proper altitude (h) and turn the telescope a little to the east of the meridian, the star should then be in the field of the telescope. The altitudes of the star on both faces are recorded in the *first pair*, and the star is easily found by setting the vertical circle to these altitudes approximately.

The most favourable series of observations can afterwards be selected to compare from as no greater accuracy can practically be obtained by computing from a large number of observations in preference to six or eight well situated near the meridian.

It is not necessary to have an equal number of [illegible] either side of the meridian, but the better they are *balanced* the better will be the results. For example, three observations on one side of the transit and five on the other may be said to be well balanced.

The Chronometer Error or correct local time at the mean of the observed times must be known and is usually obtained by an independent set of observations (see p. 143)

The chronometer error has to be applied to the *true time* of transit to obtain the *chronometer time of transit*

The *Rate* of chronometer is practically only required when the chronometer or watch used is unreliable, or when the *interval* between the time of transit and the time at which the chronometer error was determined exceeds one or two hours

Example.—Error of watch determined by set of observations for time at 20h 5m 0s was found to be 2m 20s *slow*

Rate of watch ascertained to average about 1 3s per hour, *gaining*

Mean of times of transit 24h 10m 0s on the same day

We have therefore —

Watch gained in elapsed interval 4 1h × 1 3s = 5 3s

Watch *error at time of transit* = 2m 20s less 5 3s

= 2m 14 7s *slow*

In observation with a star the chronometer error is generally obtained by an independent set of observations, within one hour or less of the circum meridian altitude observations, and any good ordinary watch may be relied on to keep sufficiently accurate time for such a small interval without any correction for *rate*, but it is advisable to ascertain the rate in case it should be unusually high No good ordinary watch should gain or lose more than 12 seconds per diem

The notation and formulæ employed in the computations for latitude by circum meridian altitudes are as follows —

ϕ = latitude N or S ζ = mean zen dist δ = dec at mean of times of obsn

ϕ_1 = approx lat ζ_1 = approx mer zen dist

$m = \dfrac{*2 \sin^2 \frac{t}{2}}{\sin 1}$ Z_1 = correct do do do

m_1 = mean of the values of m (computed separately for each hour angle)

$$\phi_1 = \delta + \zeta_1 \text{ and } \phi = \delta + Z_0$$

$$Z_0 - \zeta_0 \quad A m_0 \text{ and } A = \frac{\cos \phi_1 \cos \delta}{\sin \zeta_1}$$

As regards signs, treat A and m_0 as +ve Z_0 must be less than ζ_0

In this method of reducing circum meridian altitudes the computation of the correction Am_0 can be repeated a second time with the computed values for the latitude and zenith distance, instead of the *approximate* ones ζ_1 and ϕ_1, and a closer result obtained

Astronomical Forms 4 and 5 provide for the computation of latitude from circum meridian altitudes of the star and sun respectively

Latitude by Pole Star

When the correct local time and the approximate longitude are known the latitude may be found from observations of the altitude of the *Pole Star* at any time

To obtain the correct local time it is usual to take an independent set of observations for *time*, either immediately before or after the observations for latitude

The following formula is employed —

$$\phi = h - p \cos t + \tfrac{1}{2} p \sin 1 \sin^2 t \tan h$$

The hour angle t is to be deduced from the sidereal time, and the star's right ascension by the formula—

$$t = \text{S T} - \text{R A}$$

Calculation Form 8 provides for the reduction of observations by these formulæ, and also by Tables I, II, and III at the end of the 'Nautical Almanac' The latter tables are useful when great accuracy is not required, but when precision is necessary it is best to work out the

* See Table XVI.

formula given above, as interpolation in the tables can only be accurately done by means of second differences—a somewhat lengthy calculation

Latitude by Rough Methods

A useful method of finding latitude which does not entail a knowledge of the declination of any celestial body is the following —

The latitude of a place is equal to the altitude of the pole at that place Hence if we take a circumpolar star and observe its altitude at both upper and lower transit the mean of these altitudes (corrected for refraction, &c) will give at once a value for the latitude of the place Since however two such observations at upper and lower transit must necessarily be separated by a period of 12 hours, it is not always practicable to make them

A single observation of the altitude of a star at time of its transit gives the latitude readily by the formula—

$$\phi = \zeta + \delta,$$

but it must be recollected that when the star is observed at its lower transit, δ then is taken as the supplement of the declination given in the 'Nautical Almanac

Another rough method has already been described on p 152

SECTION VIII —GENERAL PRACTICAL HINTS IN FIELD ASTRONOMY

(*a*) Before taking observations for *time* or *azimuth* suitable stars one E , and one W , may be selected from the star chart or else stars may be picked up east and west of the observer in the sky It is necessary of course to know the names of the stars used In every case where observations for *time* are taken, comparison of watches should be made, either before or after observation

(*b*) For *latitudes* the altitude and chron time of transit of the star must be worked out previous to observation (see p 153 and Ex Form 6)

(*c*) Before commencing work an observer should make out a programme of the observations he intends to take determining the approximate time of each by his watch, and selecting such stars as will enable him to carry out his programme at convenient hours

(*d*) Observations should always be made in pairs, with face right and left alternately, so as to eliminate collimation and level errors

The same principle should be adopted in selecting stars for observation, thus for *latitude*, pairs of stars of opposite and approximate equal zenith distance should be observed and for *time* and *azimuth* pairs of stars east and west

(*e*) A booker should always be employed if possible

(*f*) Observations should be made in the following sequence —

1st The observer carefully sets up and adjusts the theodolite

2nd The observer informs the booker what the observation is for and the name of the star used The booker enters these in the angle book and also the following data the approximate watch correction, the thermometer and barometer readings the value of one division of the vertical circle level the place date and referring object when required

3rd The observer gets the star into the field of the telescope telling the booker to 'stand by' On making a contact the observer says 'up' *

4th The booker takes the time and records it

5th The observer reads out the level readings always giving that at the eye end of the theodolite first Thus 'E, 7 4 , O 5 2'

6th The observer reads out the vertical angles, C and D verniers

7th The observer reads out the horizontal angles A and B verniers

* Some observers find it better to use a word beginning with a dental consonant such as 'up'

(*j*) The looker must always repeat the readings after he has written them down to show that he has got them correctly

The looker should remind the observer each time he is about to observe what face should be used and for sun observations what limb (upper, lower right or left) he is to take To simplify this the limbs and face to be used should be written down in the angle book in their proper order for the particular observation before observing

(*k*) The only occasion where both vertical and horizontal angles are simultaneously recorded is for azimuth observations Computation Form 4 The method of making the contacts has already been explained p 149

(*l*) After observing everything required by the angle book form should be inked in and the book signed This is to ensure that no necessary data are omitted

IDENTIFICATION OF STARS

When making observations of the stars for time latitude or azimuth it is very helpful to be able by a mere inspection of the heavens to pick out the star previously determined on for observation or at any rate the constellation in which that star exists

This involves a knowledge of the relative positions of the larger stars in the different constellations

Star charts are as a rule on stereographic or globular projections and do not represent satisfactorily the relative positions of stars

For this reason a short description of the positions of some of the principal stars is given

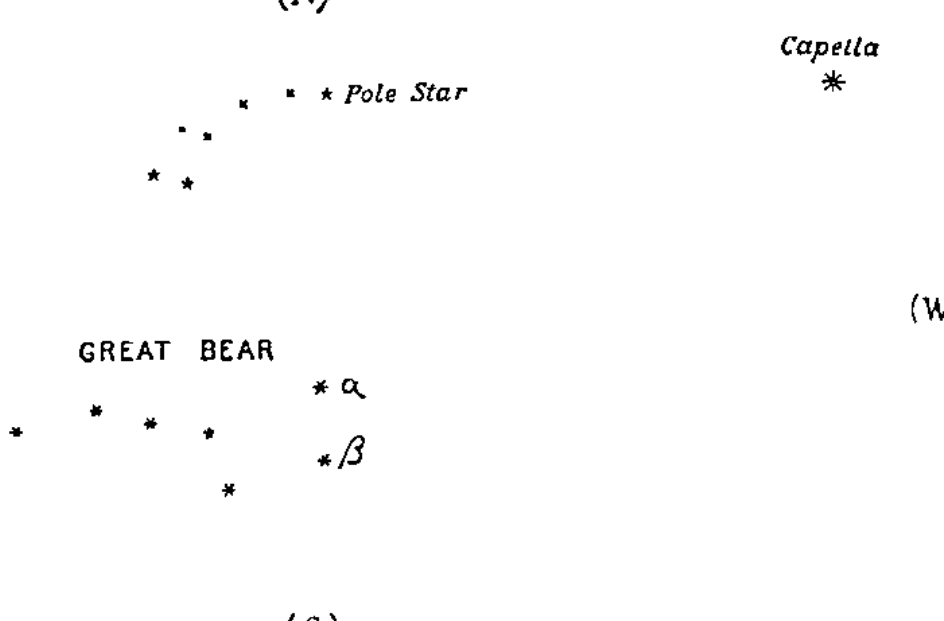


Fig 60

It must be understood that when speaking of a straight line between two stars what is meant is the portion of a great circle of the celestial sphere intercepted between and passing through those stars A little consideration will show that owing to the position of the observer being at the centre of the sphere a diagram of what is seen will have the E and W points interchanged

The angular distance between two stars can be very fairly accurately estimated, if one compares it with half the distance from the point in the heavens above the head to the horizon which of course represents 45°

(1) Referring first to the constellation 'Ursa Major or "Great Bear,' the two stars α and β point nearly to *Polaris* or the POLE STAR The Pole Star itself forms the end of the tail of the "Little Bear or "Ursa Minor'

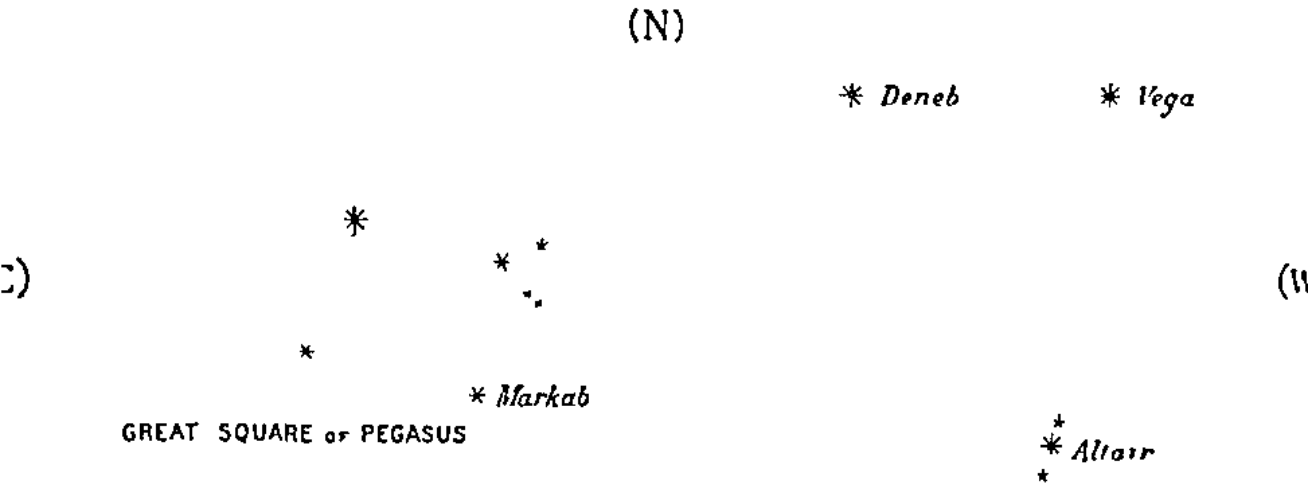


Fig 61

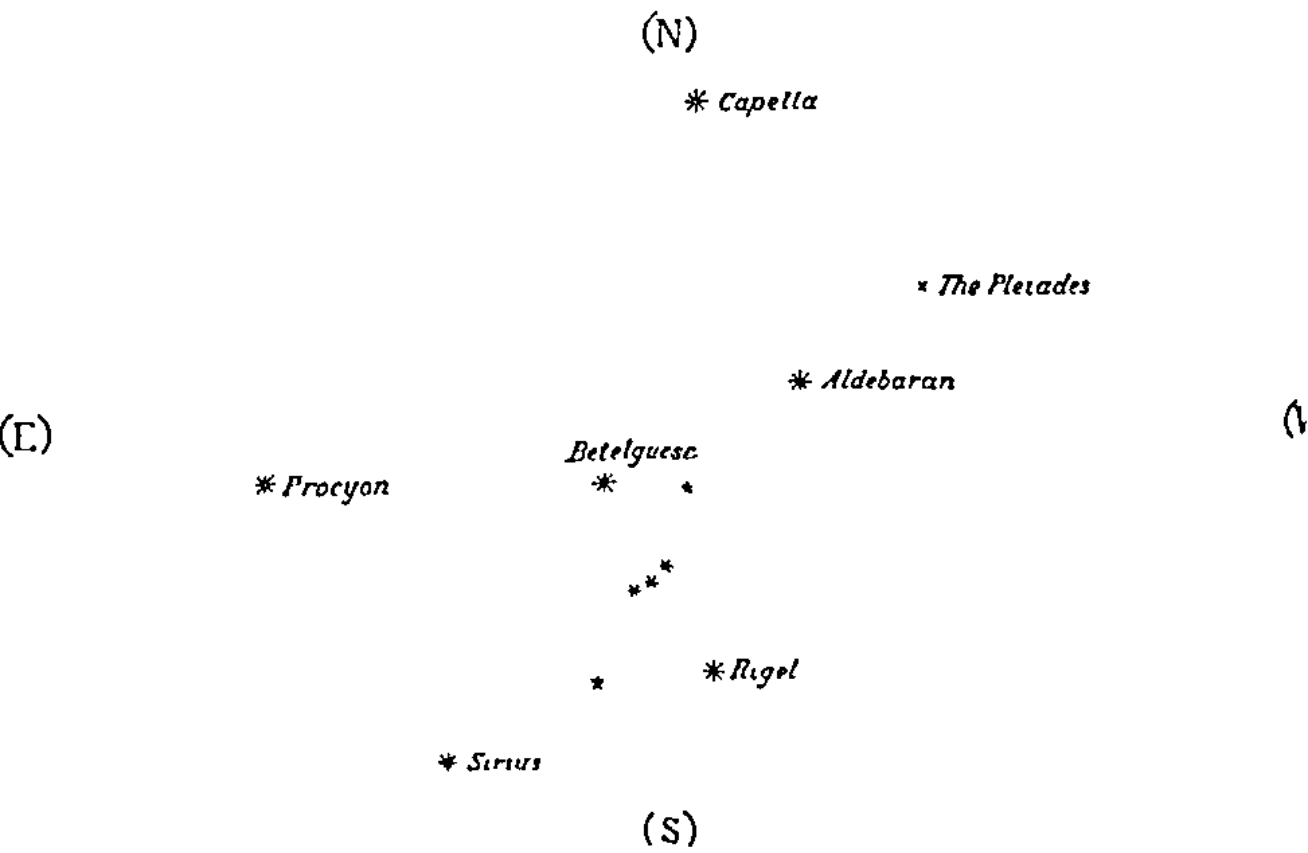


Fig 62

The stars α and β of the "Great Bear" are generally known as the pointers

(2) If the curve formed by the tail of the "Great Bear" be continued away from the pointers, the bright star ARCTURUS or α *Bootis* will be seen at about 30° from the end of the tail

(3) A line drawn from the Pole Star perpendicular to the line from the Pointers passes through CAPELLA or α *Aurigæ*, which is distant about 50° from the Pole Star

(4) A line from the Pole Star through the last star but one of the tail of the Great Bear will, if produced, pass through SPICA or α *Virginis* This star will be found to be about 30° beyond Arcturus

(5) In a line with the pointers, on the opposite side of the Pole Star, and distant about 60° from it, will be seen the "Great Square of Pegasus" formed by three stars of that constellation, and one, nearest the Pole, belonging to "Andromeda" The star at the opposite corner is called MARKAB

(6) Midway between the "square" and the Pole Star will be noticed the constellation "Cassiopeia," formed by five stars in the shape of a W

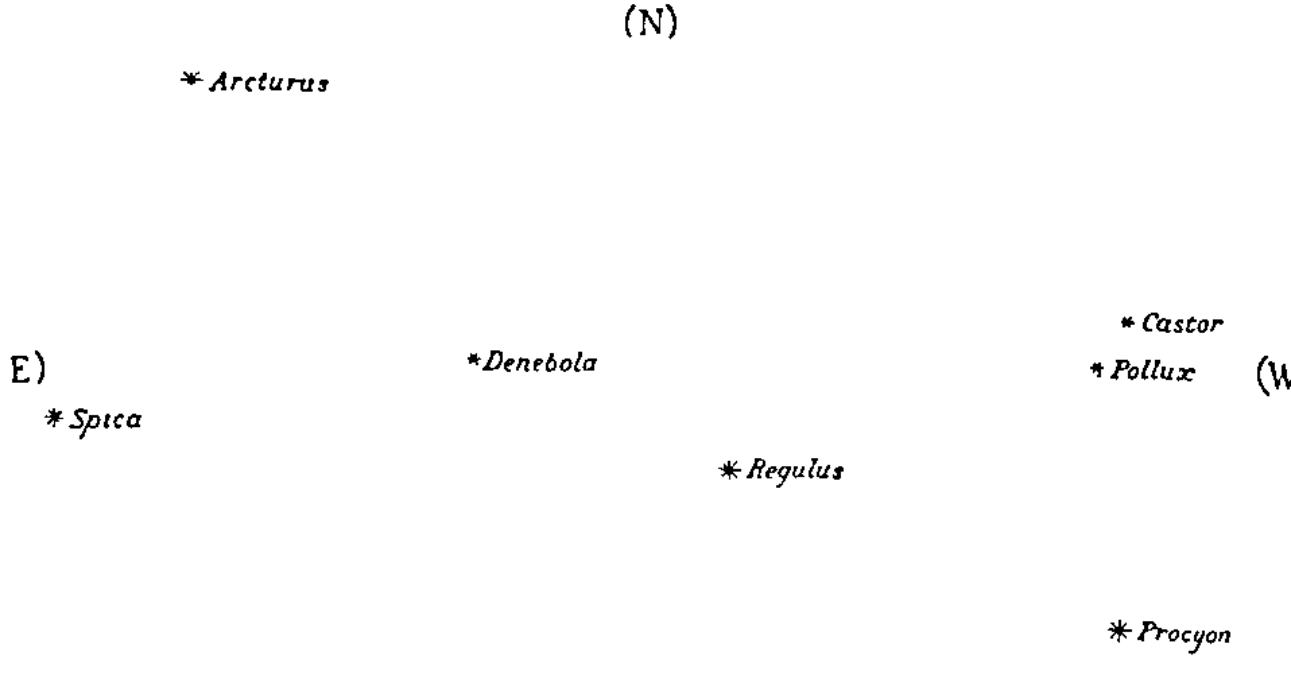


Fig 63

(7) A diagonal drawn from the S E to the N W corner of the square, if produced, will pass through DENEB or α *Cygni* at about 40 distance from the square

(8) If that line be continued another 25 still further, and at 10° to the right of it, VEGA or α *Lyræ*, a large white star in the Lyre, will be seen

(9) At about 35° to the south of Deneb and Vega will be seen ALTAIR or α *Aquilæ* This star is situated between two smaller stars, and forms, with Deneb and Vega, what is very nearly an isosceles triangle, with Altair at the apex

(10) A line from the Pole Star through Capella will touch RIGEL, a star in "Orion," distant about 65° from Capella This line also passes between two other bright stars, ALDEBARAN or α *Tauri*, 10 to the west, at about 30 from Capella, and BETELGUISE in Orion, 10° to the east, at about 40 from Capella

(11) A line from Aldebaran through "Orion's Belt" passes close to SIRIUS or α *Canis Majoris* the brightest star in the heavens, and at about an equal distance on the other side of the belt This star, with Rigel, Betelguese, and Aldebaran, forms a trapezium, having "Orion's Belt" in the centre of it

(12) At about 50 to the east of Betelguese will be seen PROCYON or α *Canis Minoris* This star, with Betelguese and Sirius, forms a very nearly equilateral triangle

(13) About 30° due north of Procyon will be seen CASTOR, which, together with POLLUX, 5 to the S E of Castor, are the two well known second magnitude stars in "Gemini"

(14) At a distance of 45° eastwards is seen REGULUS or α *Leonis* This star forms the apex of an isosceles triangle with Castor and Procyon

(15) Continuing the line from Procyon to Regulus, at about 30° beyond the latter will be seen DENEBOLA, a second magnitude star also in Leo

(16) It will be noticed that Denebola forms an equilateral triangle with Arcturus and Spica The positions of these last two have already been referred to

(17) 30° from the Southern celestial pole is the well known constellation the Southern Cross, the cross being formed of 4 stars (2 first mag, 1 second, 1 third) The star nearest to the pole is α, that furthest away is γ When the line α, γ is in a vertical plane these stars are approximately on the meridian

(18) 40° south of Sirius is α Argûs (CANOPUS), a first magnitude star

(19) Canopus, the Southern Cross, and ACHERNAR (α Eridani), form a right angled triangle with the right angle at Canopus Achernar is about 40° distant from, and transits about 5 hours before, Canopus

(20) CANOPUS, ACHERNAR, and FOMALHAUT (α Piscis Australis) are in a line and nearly equidistant, being about 40° apart

---

Effect on determination of Time (by single altitudes) of error of 10″ in observed Altitude See p 144

Azimuth from N	90°	75° or 105°	60° or 120°
	seconds	seconds	seconds
Latitude 60°	1 33	1·38	1 54
40°	0 87	0 90	1 00
20°	0 71	0 73	0 82
0°	0 67	0 69	0 77

Effect on determination of Time (by single altitudes) of error of 10′ in assumed Latitude.

Azimuth from N	90°	75° or 105	60 or 120
	seconds	seconds	seconds
Latitude 60	0 00	0 [illegible]	0 77
40	0·00	0 24	0 40
20	0·00	0 19	0 11
0°	0·00	0 18	0 38

EXAMPLES

OF

ASTRONOMICAL OBSERVATIONS.

Specimen Page of Angle Book

(5455)

Instrument

Observations for Time

To Sun

Place R F Institute

Date 2 5 01 (Lv

B 1 99

The 50

Va e d I D v f La e 0

Mer (or M T) C r n No 1

Appro x Chron Error n (or M T) = h m s 0 8 1 s w

Ra e I f r ng (jct (R O)

Mi x Lo g I h m s 0 7 9

M gn t o l nring

Apparent Name or Object	Face	VERTICAL ANGLES C Vernier		D		Means of C and D			Level L	O	Chron Times T l	m	s	HORIZONTAL ANGLES (for Azimuth only) A Vernier	B	Means of A and B	Angle Diff FRO and Star	Means of Pairs (with P O)
		°				°								°		°	°	°
O	L	3	6	0	6	30	3	26	15	7	0	11	45					
O	R	6	3	0	3	0	24	27	30	0 10	0	1	0					
O	R	6	0	0	54	0	27	5	30	4	0	1	1					
O	L		0	0	0	0	25	0	0	0 1	0	18	34					

With Sen

Eyepiece errors — No

Horizontally

Vertically Y

NOTE The d figures are tho e wh h would be en ered at t e me of observ ng The blue fig res as soon after observ ng as po s ble

Ob r A B C

Re o ler X Y Z

Specimen Page of Angle Book

Instrument ...

Observation of ...

Year ... Star ... Bar ...

Place ... Time ... Mean ... Approx. Error in ... Min.

Date ... Value of 1 Div. of Level ... Magnet Bearing

Approx. Limb of Object	Face	VERTICAL ANGLES C Vernier	D	Means of C and D	Level E	Level O	Chron. Times T h	m	s	HORIZONTAL ANGLES (for Azimuth only) A Vernier	B	Means of A and B	Angle Diff. of R.O. and Star	Means of Pairs (with R.O.)
		° ′ ″		° ′ ″	″					°		°		°
R.	L	11 43 0	11 43 0	11 43 0	+0.10	10	10	46	1					
	R.	1 43 4	1 43 0	1 43 0	1	1	10	49						
	R.	1 43	1 43	1 43	3	5	10	0						
	L.	343 5 4	5 43 16	1 43 17	10	0	10	51	43					

With fewer Eye-piece reference —

Horizontally — — — —

Vertically — — — —

NOTE.—The red figures are those which would be entered at the time of observing. The blue figures as soon after observing as possible.

Observer A B C

Recorder — X Y Z — — —

(9455)

Instrument

Observation for Azimuth

To Sun

Face Right

Date

Approx Lat

Referring to Star

Magnetic Bearing

VERTICAL ANGLES

Clock Times

HORIZONTAL ANGLES (for Azimuth only)

Apparent Limb or Object	Face	Vernier	Mean of Seconds	Level	Clock Time	Vernier	Mean of A and B	Angle Diff (R and Star)	Mean of Pairs (with R)
		°	°		h m s		°	°	°
R ⊙	1								
⊙	1	11 41 11	41 3	½ ½	9 1 1	7	6 17	5 5	1 50 4
⊙	2	18 6	18 46	1 ½	4 19	47	1 1	4 4 1	
L ⊙	R					45 3 4	3 3	4 3 3	45 45

Wind SE

Temperature —

Horizontally Visible

Weather No

Notes: Tripod [illegible] with wide red [illegible] of [illegible] Theodolite [illegible] upper [illegible] suffer observing [illegible]

Observer

Recorder

165

Specimen Page of Angle Book

Instrument ....

Observations for ... *...

To ~~Instrument~~ Star ... ... Bar ... ... ~~A.T. (or M.T.)~~ Chron No ... Rate h m s

Approx Long From ... h m s

Ref'ring Object (R.O.)

Flow ... Tier ... Approx Chron Error on ~~A.T. (or M.T.)~~ 9 1 33 (W)

Date ... Value of 1 Div of Level ...

Magnetic Bearing

Apparent Limb or Object	Face	VERTICAL ANGLES C Vernier			D		Means of C and D			Level E	Level O	Chron Times T h	m	s	HORIZONTAL ANGLES (for Azimuth only) A Vernier	B	Means of A and B	Angle Diff of R.O. and Star	Means of Pairs (with R.O.)
		°	′	″	′	″	°								°			°	° ′
*	I														} Rejected				
	II	11	4	3	4	4	48	1	33	6									
	I	4	0	4	0	54	48	0	31	5	4		1	58					
	II	4	2	2	2	4	48	2	34	5	4			9					
	I	11	7	5	6	4	48	7	31	4									
	II	11		14	0		48	7	31				1						
	II	4			0	0	48	0	46	5	4			49					
	I	4	0	10	0	7	48	0	6	5	4			9					
	II	11	3		3	2	48	0	30	6			4	10					
														5	} Rejected				

* Worm Screw

Eyepiece reverses —

Horizontally ... ...

Vertically ... ...

Note.—The red figures are those which would be entered at the time of observing. The blue figures as soon after observing as possible.

Observer A B C

Recorder X Y Z ...

Specimen Page of Angle Book.

Instrument

Observations for Latitude

To Sun ~~or Star~~

Place R E Institute

Date 1871 [illegible]

Bar 30 ·00 "

Ther

Value of 1 Div of Lev l 1"

S T (or M T) Chron N

Appx Chron Error on S T (or M T) " Rate h m s 0 0 00 fast

Appx Long [illegible] h m s 0 0 0

Referring Object (R O)

Magnetic Bearing

Apparent Limb or Object	Face	VERTICAL ANGLES C Vernier °	'	"	D °	'	"	Means of C and D °	'	"	Level E	Level O	HORIZONTAL ANGLES (for Azimuth only) Chron Times T h	m	s	A Vernier °	'	"	B °	'	"	Means of A and B °	'	"	Angle btw R O and Star °	'	"	Means of Pairs (with R O) °	'	"
○	I	299	46	8	46	13	59	46	1	"	"																		
○	R	299	30	0	30	0	60	0	4	4																			
○	R	99	9	40	9	8	0	0	3	0	0																		
○	I	40	0	0	0	0	60	0	19																				
○	I	39	48	40	48	40	59	48	4	6	0																		
○	R	1	31	10	30	10	60	0	5		0																		
○	R	00	1	0	31	40	59	0	34	0	0																		
○	I	40	17	30	18	10	0	1	5	7																			

Specimen Page of Angle Book

Instrument ____ _ _ _

Observat ns fr La ____

To ~~____~~ Star ____ Bar ____ S-~~Time~~ M T Chron No 37 Rate

Place ____ Q ____ Ther 42° Approx Chron Error on ~~Time~~ M T) 0 3 24 fast

Date ____ Value of 1 Div of Level 13 ____

Approx Long E or W 0 - 0

Referring Object (R O) ____

Magnetic Bearing

Adjacent Limb or Object	Face	VERTICAL ANGLES: C Vernier	°	′	D	″	Means of C and D	°	′	″	Level: E	O	Chron Times, T: h	m	s	HORIZONTAL ANGLES (for Azimuth only): A Vernier	°	′	″	B	″	Means of A and B	°	′	″	Angle Diff of R O and Star	°	′	″	Means of Pairs (with R O)	°	′	″
⊕	I	271	°	15	27	10	271	3	12	7	5	7	3	4																			
	II	91	3	19	0	12	91	33	3	6	8		8	1																			
	I.	271	12	9	19	23	271	42	3	4	8		11	0																			
	II	271	42	0	43	21	271	42	3	5	5		16	33																			

* With Sun

Face reversed ____

Horizontally ____

Vertically ____

NOTE.—The red figures are those which would be entered at the time of observing. The blue figures as soon after observing as possible

Observer A B C

Recorder X Y Z.

EXAMPLES

OF

ASTRONOMICAL COMPUTATIONS.

Time by Altitudes of Sun

From Page 1 Angle Book

	°	′	″		h	m	s
Vert Ang'es	23	26	15	Times	20	13	45
	24	27	30		20	15	20
	27	5	30		20	17	15
	25	0	0		20	18	34
Totals	99	59	15		81	4	54
Means	24	59	49		20	16	13½

Level Correction *

	E	O
	5	7
	0	10
	4	7
	0	12
Totals	9	36

Correction

$$\frac{(36-9)}{8} \times 20$$

$$= + \frac{27 \times 20}{8}$$

$$= + 1' \ 7 \ 5$$

	°	′	″	
	24	59	49	
+	0	1	8	
	25	0	57	Correct mean observed altitude

* With micrometer theodolites the level should be read to one place of decimals

Form K.—(S.M.I. Astronomical Form 1.)

Time by Altitudes of the Sun

These portions are only to be used when the Chronometer keeps Sidereal Time

Place ____ Lat. N ____ ° ____ ′ ____ ″ ____ W } G.M.T. / G.S.T. } Chron. No. ____ Bar. ____

Date ____ ____ h ____ m ____ s ° ____ ′ ____ ″ ____

Page and Book ____ Approx. Time Fast / Slow ____ ° ____ ′ ____ ″ } Approx. Chron. Corr. on G.M.T. } 0 8 15 s Ther. ____

ELEMENTS

T. M. Table II. N.A.

° ′ ″ L. ____ Sun's Hor. Par. F. + H. ____ } * L.S.T. of L.M.N. ____

Table II. N.A. Page ____ Line ____

† Mean of Odd Times 10 14 5

Approx. Chron. Corr. Slow + Fast − ± 0 8 15

L.S.T. (Approx.) ____

* L.S.T. of L.M.N. ____

Sun's Hor. Par. H. ____ M. ____ S. ____

M.T.F. ____

L.M.T. of Observation (Approx.) } ____ h ____ m ____ s

Long. W. (+) or E. (−) ± 0 ____ m

G.M.T. of Mean of Observed Times } ____ h

‡ Interpolations from G.M.N. ____

POLAR DISTANCE

This is reckoned from the *Elevated Pole* 90 ± δ

For Dec. δ at time of observation see below

Dec. δ Name ____ ° ____ ′ ____ ″

90 0 0

Polar Dist. p ____ ° ____ ′ ____ ″

If the Lat. (φ) and Dec. δ are of the same name δ is *greater* than φ, p from 1st of different name and 1st to 90°

DECLINATION

Dec. (δ)

At Greenwich Noon N ____ ° ____ ′ ____ ″ 4 4m 7 4 (Page II. N.A.)

Hourly Variation (Page I. N.A.) × ± − 0 3 1

‡ Interpolations from G.M.N. ____

At mean of Odd Times N ____ ° ____ ′ ____ ″ 4 4 35 7

EQUATION OF TIME

m s

± + 3 4s 1 (Page I. N.A.)

± + 0 1

± + 3 51 3

REFRACTION

″

Refn. due to Alt 4 1

Corr. for Bar ± 0 0

Corr. for Temp ± 0 0

Refraction 4 1

PARALLAX

°

Hor. Par. (Page I. N.A.) × / ____

cos ____

Par. in Alt 0 8 1

FORMULA AND COMPUTATION

$$\tan\frac{t}{2} = \sqrt{\cos s \sin(s-l)\operatorname{cosec}(s-\phi)\operatorname{cosec}(s-p)}$$

where $s = \frac{l+\phi+p}{2}$

The Lat. (φ) is *always* positive and p is reckoned from the *Elevated Pole*

From Angle Book ° ____ ′ ____ ″

Observed Mean Altitude		5 0 0 7	
Refraction	= −	0 2 4 1	
Semi-diam.	±		
Parallax	− +	0 5 1	
True Alt. (*l*)	=	4 1	
Lat. (φ)			
Polar Dist. (*p*)	−	5 1 1 6	
2			
s	−	5 10 8	Log cos 9 9 999
s − *p*	=	4	Log sec 10 001 1 6
s − φ	=	0 5 8	Log cosec 10 081 11
s − *h*	−	5 0 5	Log sin 8 91 80 1
			2 19 4
			Log tan $\frac{t}{2}$ 9 1 111
			$\frac{t}{2}$ = ° ′ ″ 94 00 4
			t in arc = 51 40 5 8
			t in time = h m s 3 1
If before noon subtract from			24 0 0
L.A.T. of Observation		=	20 0 40
Equation of Time ±		= +	0 3 51 3
L.M.T. of Observation		=	20 4 31 8

Not required with M.T. Chron.

Sidereal Equivalents	*Hrs* ____	____
	Mins	
	Secs	
Sidereal Interval from L.M.N.		−
* *Before L.S.T. of L.M.N.*		
L.S.T. of Obs.		

† Chron. Time of Obs. = 19 11

Chron. Slow + Fast − on G.M.T. } = h m s 9 13

Time by Altitudes of an E Star

From Page 2, Angle Book

	°	′	″		h	m	s
Vert. Angles	15	11	14	Times	10	46	12
	15	40	50		10	48	32
	15	53	55		10	50	2
	16	1	17		10	51	43
Totals	62	47	16		43	16	29
Means	15	41	49		10	49	7 25

Level Correct on

E.	O.
20	10
15	15
19	12
10	20
Totals 64	57

Correction

$$\frac{(57 - 64) \times 5''}{8}$$

$$= - \frac{7 \times 5''}{8}$$

$$= - 4''$$

	°	′	″	
	15	41	49	
−	0	0	4	
	15	41	45	Correct mean observed altitude

Form I —(S M E Astronomical Form 2)

Time by East and West Stars

STAR E or W Lat (ϕ) N or S ° ′ Bar
Time T m s Approx Long E or W s Tier ″ ″
Date
Page in Angle Book M T Chron No Date Approx Corr s

Tan $= \sqrt{\cos s \cdot \sin s \cdot \sin(s-\phi) \sec s \cdot \sec(s-p)}$

where $s = \frac{h+\phi+p}{2}$ with ϕ always taken positive and p reckoned from the *Elevated Pole*

h = Altitude p = Polar Distance

COMPUTATION

		° ′ ″
From Angle Book		
Measured Alt	−	1 11 45
Corr for Refn	−	7
True h		15 3 8
Lat (ϕ)	−	51 3 0
Polar Dist (p)	=	5 3 7
	2	1 23 54 1
s		0 31 54
$s-p$	−	25 51 47
$s-\phi$		54 48 54
$s-h$	−	16 28 46

Log cos = 9 1 9 6
Log sec = 0 0 0 0 0
Log cosec = 1 0 0 0 0 0
Log sin = 9 9 9 9 4
2 19 9 9 3
Log tan $\frac{t}{2}$ 9 4 9 6
$\frac{t}{2}$ = ° ′ ″ 54 12 9
t in arc 5 0 1 48 1
3 11 0 57 3
t in time ± − h m s 1 4 19 1
(− E or + W)
RA of Star 1 8 9

			° ′ ″
GST of GMN (page II N.A.)	=	1 m s 1 59 7 5	
Corr for Long at 9 86 per hour (E + W)	±	− 0 0 0 35	
*LST of LMT	=	1 59 03 9	

LST of Obsn 1 18 3
(*LST of LMN 1
Sidereal Interval from LMN 10 5 1
Civil Time Interval: MT Eq at Hrs 0 8 1 011
Mins 0 5 5 8 57
Secs 0 0 1 1
0 0 0
LMT of Obsn 10 0 43
From Angle Book Chron Time of Obsn 10 43
Chron Slow on LMT ± + m s 6 0

REFRACTION

		° ′ ″
Refn due to Alt	± =	− 3 1
Corr for Tier	± =	+ 0 0
Refraction		3 1

POLAR DISTANCE

		° ′ ″
Decl (δ) N or S	± =	1 90 0 0
Polar dist (p) or 90 ± δ	−	85 3 7 7

NOTE — p is reckoned from the *Elevated Pole* if the Lat and Dec are of the same names *subtract* from 90° and if of different names *add* to 90°

Azimuth by the Sun.

From Page 3 Angle Book

	°	′	″		h	m	s
Vert Angles	31	41	17	Times	19	51	21
	32	41	14		19	54	9
Means	32	11	15 5		19	52	45

	h	m	s	
Chron watch is approx	0	3	29	slow
L M T of observation is	19	56	14	

Level Correction

	E	O
	3 5	7·5
	7 5	4 0
Totals	11	11 5

Correction

$$\frac{(11\ 5 - 11) \times 10''}{4}$$

$$= + 1'' 25$$

	°	′	″	
	32	11	15 5	
+	0	0	1 3	
	32	11	16 8	Correct mean observed altitude

Form M—(S M E Astronomical Form 3)

Azimuth by Sun or Star with the Theodolite

Star or Sun ——— Lat. ϕ N/S ——— Chron. ——— R.O. Greenwich ———

Page and Art. Book ——— Mirror Long. E/W ——— Time ———

Place ——— Var. ———

Date ——— Time ——— Mag. Bearing ———

Tan $\frac{A}{2}$ = $\sqrt{\frac{\sin(s-\phi)\sin(s-p)}{\sin s \sin(s-h)}}$ where $s = \frac{h+\phi+p}{2}$

A = Horizontal Angle between True North and the Sun or Star

In each formula the Lat. ϕ should be taken with the *pos.* sign whether N. or S. and Polar Distance (p) is then to be reckoned from the *Elevated Pole*

ELEMENTS

			h	m	s
Index Error					
Corr. for Par.	±				
Corr. for Temp.	±				
Refraction	−				
Horr. Par. (page I. A.) × Cos. Alt.	−				
Parallax in Alt.	−				
GST of GMN (Page II. A.)		−			
Corr. for Long. at 9.86 sec. per hr. (+ W. − E.)		=			
LST of LMN		=			
LST of Obsn.		=			
Sid. Int. from LMN		=			
MT Equivalents (Hrs, Mins, Secs)					
LMT of Obsn. (If MT Chron. used this is taken direct from Angle Book)		−	19	6	11
Long. E. (−) or W. (+)	±	−	0	0	9
GMT of Obsn.		=	19	4	2
Int. from GMN in Hrs.		−	4	10	
			°		
Decl. (δ) at GMN (N. or S.)	±	+	19	45	51
Hourly Var. (Log ——) × Int. from GMN	±	− +	0	0	0
Dec. (δ) of Sun or * at time of Obsn.	±	− +	19	45	51
			90	0	0
Polar Dist. (p) or 90 − ($\pm\delta$)		−	0	11	49

WITH SUN OBSNS. ONLY (omitted in MT Chron.)

NOTE — p is reckoned from the elevated pole if ϕ and δ are of *like* names δ will be *negative* and $p = 90 + \delta$

COMPUTATION

FROM ANGLE BOOK

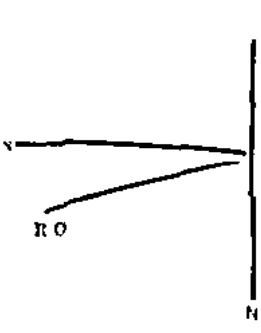
Mean Obsd. Alt.		11	10	9
Corr. for Refraction	−	0	1	1
Corr. for Parallax	+	0	0	7
True Alt. h		0	9	
Lat. ϕ		1	5	0
Polar Dist. p	−	0	11	4
		153	45	17

s	−			3
$s-p$		0	4	1
$s-\phi$				5
$s-h$	−	41	4	30

Log sec = 10.0139009
Log sec = 0.0000098
Log sin = 7
Log sin = 81 51
20.1 6089
Log tan $\frac{A}{2}$ = 10.0 91.0
$\frac{A}{2}$ = 49 12 11
A = 98 24 22
= 1 49 41
− 0 4 4

A good Fixed R.O. and * (or Sun) (from Angle Book)

† AZIMUTH of R.O. from *Elevated Pole*



† NOTE — Azimuth for trigonometrical purposes should be measured from the South (by West). It is best ascertained above data by consideration of a figure showing the relative positions of Star, Pole and R.O.

LATITUDE by Circum meridian Altitude of Star

		h	m
October 7th, 1897, "ϵ Pegasi,"	R A =	21	39
G S T of G M N	=	13	6
		8	33
Chron Correction	+	0	4
Approx Chron Time of Transit		8	37

NOTE —This computation is made before observation and guarded in the angle book

From Form 4 Chron Time of Transit (T_0) = 8 h 36 m 37.5 s

From Angle Book Page 4 Chron Times (T)	Hour Angles ($T - T_0$)	Values of m (Vide Table XVI)	Face	From Angle Book, Page 4, Vert Angles
h m s	m s	′		° ′ ″
8 29 12	− 6 55.5	94.1	R	48 1 33
8 31 58	4 39.5	42.6	L	48 0 31.5
33 39	2 58.5	17.4	L	48 1 14.5
36 26	0 11.5	0.1	R	48 2 51
38 5	+ 1 27.5	4.1	R	48 2 51.5
40 49	4 11.5	34.5	L	48 0 46
42 39	6 1.5	71.3	L	48 0 6
46 10	9 32.5	178.7	R	48 0 30.5
	Totals	442.8		10 24
	Means	55.3		48 1 18

Level Correction

F	O
6	6
8	4
8	4
5	7
5	7
8	4
8	4
6	6
Totals 54	42

Correction

$$= \frac{(42 - 54) \times 15''}{16} = -11'.2$$

	°	′	″	
	48	1	18	
−	0	0	11.2	
	48	1	6.8	Correct mean observed altitude

Form N -(S M L Astronomical Form 4)

Latitude by Circum Meridian Altitudes of Star

Star | Approx Lon E/W | Page in Angle Book

Date | Ht of Eye | M T of Obs | Error ± | Rate ±

Approx Chron

NOTE —Chron T of Transit and mean value of

COMPUTED CHRON TIME OF TRANSIT (T_0)

Long Mean

Long Mean Time of Transit

Add Sub Corr for Long

Mean Time of Transit

Add Sub Corr for Rate

LMT of Transit

Chron Error on GMT Fast + Slow

Chron Time of Transit T_0

LAST of Transit

MEAN ZEN DIST ζ

Refraction due to Obsd Mean Alt

Corr for Par

Corr for Ther

Refraction Corrected

Obsd Mean Alt (From Angle Book)

Refraction (see above)

True Mean Alt (h)

ζ_0 Mean Zen Dist (90 − h)

NOTATION AND FORMULÆ

ϕ = Lat N or S

ϕ_1 = Approx Lat

δ = Dec at Mean of Times of Obn

ζ_0 = Mean Zen Dist

ζ_1 = Approx Mer Zen Dist

Z_0 = Correct Mer Zen Dist

$\frac{2\sin^2 \frac{t}{2}}{\sin 1}$ (Values found in Table XVI See above note)

m_0 = Mean of Values for m

$\phi_1 = \delta + \zeta$ and $\phi = \delta + Z_0$

These Eqns hold good in all cases if the signs of the functions ϕ δ and ζ are carefully attended to as follows —

Lat and Dec are $\frac{+}{-}$ when $\frac{N}{S}$ of Equator

Zenith Dist is $\frac{+}{-}$ when the Star is $\frac{S}{N}$ of Zenith

Z_0 $\zeta_0 - A_{m_0}$ and $A = \frac{\cos\phi_1 \cos\delta}{\sin\zeta}$

APPROX LATITUDE (ϕ)

From Angle Book

Greatest Obsd Alt

Refraction (use that for ζ)

Approx Mer Alt

ζ (Approx Mer Zen Dist)

Dec (δ)

Appx Lat $\phi = \delta + \zeta$

COMPUTATION FOR TRUE LATITUDE (ϕ)

Log cos ϕ

Log cos δ

Log cosec ζ

Log A

Log m_0 (m_0 =)

Log A m_0

A m_0

A $_{m_0}$

ζ_0 or Mean Zen Dist

Z_0 or (ζ_0 − A $_{m_0}$)

Dec (δ) N

Lat $\phi = \delta + Z_0$

LATITUDE by Circum meridian Altitudes of Sun

		h	m	
Equ of Time, 15th July, 1897	= +	0	6	(Page I, N 1)
Chron Correction	= +	0	1	
Approx Chron Time of Transit	=	0	7	

NOTE —This computation is made before observation and guarded in the angle book

From Form 5 Chron Time of Transit (T_0) = h m s 0 6 40 7

From Angle Book Page 5 Chron Times (T)	Hour Angles ($T - T_0$)	Values of m (Vide Table XVI)	From Angle Book, Page 5, Vert Angles
h m s	m s	′	° ′ ″
23 59 14 5	− 7 26 2	108 6	59 46 10 5
23 62 35	4 5 7	33 0	60 9 47 5
65 11	1 29 7	4 4	60 0 36
67 5	+ 0 24 3	0 3	60 20 19
68 48	2 7 3	8 8	59 48 40
71 2	4 21 3	37 2	60 19 50
72 14	5 33 3	60 6	59 47 54
74 23	7 42 3	116 5	60 17 50
Totals 193 0 32 5		369 4	480 31 7
Means 0 7 34		46 2	60 3 53 4

Level Correction

E	O
7	2
4	5
3	6
7	2
6	3
5	5
5	5
7	2
—	—
Totals 44	30
—	—

Correction

$$= \frac{(30 - 44) \times 15'}{16} = -13' 1$$

	° ′ ″	
	60 3 53 4	
−	0 0 13 1	
	60 3 40 3	Correct mean observed altitude

Form 0 (S M T Astronomical Form 3)

Latitude by Circum Meridian Altitudes of Sun

Place

Date

Appx Lat F — W (Long)

Time

Page in Angle Book

MT or ST { No ?
Error ± 0 0 56 8 Fast
Chron { Rate ±

COMPUTED CHRON TIME OF TRANSIT (T_0)

Sun R A (Page I N A)		
Corr for Long (Hr Hr Var for 4 m) if Long E W	} ±	
Chron Error ± Fast Slow		
Chron of Transit		

		h m s
I A T for L A N		4 0 0
Equ of T (see Page I N A)	±	+ 0 5 43 91
Corr for Long*	±	— 0 0 0 009
L M T for L A N (Time of Transit)		0 5 4 9
M T Chron Error Fast + Slow	±	— + 0 0 56 8
Chron Time of Transit T_0		0 6 40 7

† NOTE — Mean Values for are specially computed on a separate sheet of paper

Values for are found in Table XVI

If a Series proceeded and some of the Hour Angle Intervals are greater (or over 10 minutes) all of them should first be converted into Mean Time Intervals before taking out values of n from the tables

MEAN OF HOUR ANGLES ($T - T_0$)

		h m s
From Angle Book		
Mean Time of Transit T_0		0 0
Mean of Hour Angles $T - T_0$	±	+ 0 0 3

NOTE — If is greater than

* The Corr — Long in Hours × Hourly Var of Eqn of Time (Page I N A)

In E Longs if Eqn of T is increasing numerically the Corr should be given a contrary sign to that of the Eqn of T and vice versâ

In W Longs if Eqn of T is decreasing numerically the Corr is given the same sign as the Eqn of T and vice versâ

TIME INT OF OBSN FROM G M N

		h m s
G M T of G A N Eq of T (p I N A) — Long in Hrs × Hourly Var of Eqn of T (see Note *)	±	0 0 0 0
L M T of L A N (or Corr Eqn of T) Long Add if W subtract if E)		
G M T of L A N Mean of Hour Angles (see above)	±	+ 0
Int of Mean of Obsn Times from G M N		0 4 25

Logarithm of Interval in hours

DECLINATION

Dec at G M N (Page H N A)			1 7 0 9
Hourly Var (Page I N A) 24·00 × 07 Interval in Hrs from G M N	}	±	— 0 0 1 8
Dec (δ at Mean of Times N or S)		=	1 27 5 1

COMP FOR APPX LATITUDE (ϕ_1)

		°
From Angle Book		
Greatest Obsd Alt		— 60 0
Refraction (use Refr for ζ_0)	=	— 0 0
Semi Diam	±	— 0 1 5
Approx Mer Alt ude		60 4
		90 0 0
ζ Approx Mer Zen Dist	=	+ 9 5
Dec (δ)	=	+ 21 7 0
Appx Lat $\phi = \delta + \zeta$		+ 51 23

NOTATION AND FORMULÆ

ϕ Latitude N or S — ζ_0 Mean Zen Dist
ϕ — Approx Lat — ζ — Appx Mer Zen Dist

$$\frac{s\ s\ f}{s\ h\ l} = \text{see Note } \dagger) \qquad Z_0 \text{ Correct Mer Zen Dist}$$

δ — Dec at Mean of Times of Obsn

$_0$ — Mean of Values of (for each hour angle)

$\phi \quad \delta + \zeta_1$ and $\phi \quad \delta + Z_0$

The Eqns hold good in all cases if the signs of the functions ϕ δ and ζ are carefully attended to as follows —

Lat and Dec are $\frac{+}{-}$ when $\frac{N}{S}$ of Equator

Z is $\frac{+}{-}$ when the Sun is $\frac{S}{N}$ of the Zenith

$$Z_0 \quad \zeta_0 - \text{Mean A} \quad \frac{\cos\phi \ \cos\delta}{\sin\zeta}$$

COMP FOR MEAN ZEN DIST (ζ_0)

		°
From Angle Book		
Obsd Mean Altitude		60 3 40 3
Refraction	—	0 0 3 0
Parallax	+	0 0 4 35
True Mean Altitude	—	60 3 1 7
		90 0 0
ζ_0 Mean Zen Dist	± =	+ 21 6 47 7

REFRACTION & PARALLAX

Refrn due to Alt	d 3	0 0 1
Corr for Bar		—
Corr for Ther		+ + +
Refraction		0 3 0
Hor Par × cos Alt	×	4 35
Parallax in Alt	=	

COMP FOR TRUE LATITUDE (ϕ)

Log cos ϕ	=	9 0
Log cos δ		9 9 883
Log cosec ζ	=	10 30193
Log A		10 06 99
Log $_0$(0 46)		1 66 64
Log A $_{m_0}$	—	1 7 63
A $_0$		63 s Secs
A $_0$		0 0 64 3
ζ_0	+	3 56 4 7
Z_0 or $\zeta_0 - $ ($_{m_0}$)	— +	3 55 59
Dec δ	+	1 27 35 1
Lat $\phi = \delta + Z_0$		51 3 29 0 N or S

Latitude by Altitudes of Polaris

From Page 6, Angle Book

	°	′	″		h	m	s
Vert Angles	51	37	12 5	Times	7	3	54
	51	39	39 5		7	8	12
	51	40	29 5		7	11	0
	51	40	55 5		7	16	33
Totals	206	38	17		28	39	39
Means	51	39	34 2		7	9	54 8

Level Correction

F	O
7	5
4	8
4	8
7	5
22	26

Correction

$$+ \frac{(26 - 22) \times 15}{8}$$

$$= + \frac{4 \times 15''}{8}$$

$$= + 7'' 5$$

	°	′	″	
	51	39	34·2	
+	0	0	7 5	
	51	39	41·7	Correct mean observed altitude

Form P.—(S.M.I. Astronomical Form 6)

Latitude by Altitudes of "Polaris"

Place _____ Approx. Lng. E. or W. _____ h m s Bar 0 2

Date _____ No. 1 Tier 4

Page in Angle Bk. _____ Chronometer Slow or Fast of G.M.T. { Error m s ( ) Rate

ELEMENTS.

		h	m	s
G.S.T. at M.N. preceding Long. (page II. of N.A.)				
Increase in 12 hours	±	0	0	0.3
L.S.T. at G.M.N.				

COMPUTATION BY FORMULA

$$\phi = A - p\cos t + \tfrac{1}{2}p^2\sin^2 1'' \sin 1'' \tan A$$

This computation gives more accurate results than those obtained by use of N.A. Tables

POLAR DISTANCE (p)

		°	′	″
Dec. (δ)	=	89	45	0.8
		90	0	0
p (90° − δ)	=	1	14	9
p (in seconds)	=			44

HOUR ANGLE (t)

		h	m	s
Obsd. L.S.T.	=		13	14
R.A. of Star	=	1		
t in time (S.T. − R.A.)	± =	+ 18	0	48.6
If t is negative subtract from 24 hrs.	= +			
		°		
t in arc	=	4	8	

REFRACTION

Refn. due to Obsd. Mean Alt. (Angle Book)	=		1	
Corr. for Bar.	± =	+	0	4
Corr. for Tier	± =	+		
Refraction Corrected	−		4	1

TRUE ALTITUDE (h)

		°	′	″
Obsd. Mean Alt. (Angle Book)	=	51	34	11
Corr. Refraction	= −		4	1
True Altitude (h)	=	51	39	4.6

Log p (p in seconds)	=	3	18	1
Log cos t	=	9	31	37
Log 1st Corr.	=	2.9	01	11
1st Corr. (in seconds)	=	0	3	
Log p	= −	0	01	61
Log sin t	=	9		
Log p sin t	=	7	010	
Log $\tfrac{1}{2}$ sin$^2 1'' = 2 \times$ (Log p sin t)	=		60	0
Log tan A	=	1	1	1
Log sin 1″ †	=	1	8	
Ar. comp. Log 2 †	=	1	0	
Log 2nd Corr.	=	1	1	
2nd Corr. (−1 second)	= +			
True altitude	= +	1	3	1
1st Corr. (opposite sign to cos t) (If t is in 2nd or 3rd Quadrant cos t is +)	± =	0	1	14
		1		5
2nd Corr. (always add)	− +	1	0	
Latitude N. or S.	−	1	24	04

† log sin 1″ = 6·685 49

Ar. comp. Log 3·089 00

COMPUTATION BY TABLES IN NAUTICAL ALMANAC

		°		
True Alt. (h) (see above)	=	1	8	
Subtract	=	0	1	0
Reduced Alt.	=	1		
With argt. L.S.T. h 13m 15s 1st Corr.	± = −	0	13	4
Approx. Latitude	=	1	1	13
With argt. L.S.T. and True Alt. 2nd Corr.	− +	0	0	
With argt. L.S.T. added to 3rd Corr.	= +	0	1	1
Latitude N. or S.	=	1		1

CHAPTER XV

LATITUDES AND AZIMUTHS

On expeditions and boundary commissions it is frequently impossible to keep up a regular triangulation Recourse may then be had to the device known as 'latitudes and azimuths'

Suppose A and B to be the two mutually visible points If a latitude is observed at A and the azimuth AB is determined and then subsequently the latitude of B is determined it is clear that provided that there is a considerable amount of northing and southing in the line AB values can be obtained for the length AB and the difference of longitude between A and B either graphically by drawing on a plane table or better, by means of a calculation

Degree of Accuracy —Obviously no very great degree of refinement can be obtained by this method We will analyse the error which will result in a fairly favourable case Let the azimuth of AB be about 45 let latitudes be observed at A and B with a probable error of 3 Then the probable error in the range of latitude is $3\sqrt{2}$ and the probable error in the length of AB = $3\sqrt{2} \times \sqrt{2} = 6$ or 600 feet Now suppose AB to be about 40 miles the

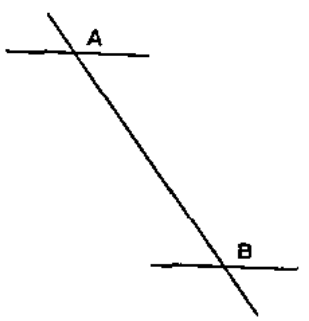


Fig 64

ratio of error in the length of AB = $\frac{600}{40 \times 5\,280}$, or $\frac{1}{352}$ Now, although this is a large error as compared with trigonometrical errors it is smaller than would usually result from any rapid system of traversing

The most favourable case is that of a journey nearly north and south with long runs Latitudes and azimuths should rarely be attempted with runs of a greater azimuth than 45° from N or S

Supposing the explorer on a rapid march is fixing his framework by this means when he observes a latitude and azimuth he should take a round of angles to all likely hills anywhere near to his probable line of march very often he cannot predict the hill which he is likely to visit next Even with this precaution he may find either that he cannot visit or cannot identify with sufficient accuracy any hill included in his round of angles from his first station He must then give up the idea of identifying the hills previously observed to and must observe a latitude and take an azimuth from any convenient hill *back* to his first station, on which he should if possible have erected some cairn or pole or mark

Latitudes and azimuths were freely used on the march of the Afghan Boundary Commission as is shown on Plate VIII

They were also much employed in the exploration of the southern frontier of Abyssinia in 1902 03

Computation.—Let A and B be two stations at which latitudes have been observed and at A the azimuth of AB has been determined.

Let the difference of the two latitudes in seconds $\Delta\lambda$

Let the azimuth of AB at A α

It is required to find

(i.) The length of the line AB c

(ii.) The difference of longitude of A and B in seconds of arc ΔL

Let the azimuth at the middle point of AB $\alpha + \frac{\Delta\lambda}{2} - \alpha$

Let the mean latitude of A and B λ

Let the difference of longitude determined approximately (from a plane table, or rough method) Δl

Then

$$\frac{\Delta\lambda}{2} = \frac{\Delta L}{2} \sin\lambda , \qquad (1)$$

Now apply this value of $\frac{\Delta\lambda}{2}$ to λ (remembering in which way the meridians converge) and thus obtain α

Then for the required difference of longitude

$$\Delta L = \frac{\rho}{\nu} \tan\alpha \sec\lambda , \Delta\lambda \qquad (2),$$

where $\log \frac{\rho}{\nu}$ is the value of Q in Table I. (for the *mean* latitude)

Also, for the length AB,

$$c = \Delta\lambda \sec\alpha \rho \sin 1 \qquad (3)$$

where $\log \rho \sin 1$ is the arithmetical complement of P in Table I. (for the *mean* latitude)

CHAPTER XVI

LONGITUDE

The Longitude of a place is the angle made by its meridian plane with some one fixed meridian plane arbitrarily chosen and is measured by the arc of the equator intercepted between these two meridians

Longitudes are reckoned east or west of the fixed meridian up to 180

The fixed meridian in use in all British territories is that of Greenwich

Since the earth makes a complete revolution once in 24 hours it is clear that each meridian is moving round at the rate of 15° an hour we may therefore describe the relative positions of two meridians in arc or in time We may say, for instance that the longitude of a place is 30 E or 2 hours E

Now as has been explained in Chapter XIV , the local time is measured by the angle at the celestial pole between the local meridian and the mean sun and the local sidereal time is the angle between the local meridian and the First Point of Aries

It follows that the difference in longitude of two places is the difference at any instant, of their local times mean or sidereal

The longitude of a place may be determined by any one of the following methods –

(1) Triangulation	Relative methods
(2) Exchange of telegraphic signals	
(3) Latitudes and azimuths	
(4) Transport of chronometers	
(5) Occultations of stars by the moon	Absolute methods
(6) Moon photographs	
(7) culminations	
(8) altitudes	
(9) Lunar distances	
(10) Eclipses of Jupiter s satellites	

TRIANGULATION

(1) **Triangulation** is by far the best of all these methods, not only on account of its accuracy but also because the process is itself necessary for the detail survey Even in wooded countries such as parts of Burma it is still usually possible to triangulate, and the accumulated error even when it is impossible to erect signals will only amount perhaps to some 5 seconds of arc in 100 miles The method has been fully explained in Chapter III If however the longitude of the starting point is not known it must be determined by telegraph chronometers or by some absolute method

A good example of the combined use of several methods is afforded by the Nyasa Tanganyika Boundary Survey of 1898 The head of the transcontinental telegraph line had, at that time reached a point (Nkata) near the shore of Lake Nyasa about 140 miles south of the starting point of the boundary (which was on the lake) and some 1900 miles from Cape Town

The difference of longitude between Cape Town observatory and Nkata was determined by exchange of telegraphic signals on three nights and a good value obtained

Fourteen chronometers were now transported backwards and forwards between Nkata and

kambwe near the starting point of the boundary. From this point a continuous triangulation was carried out along the whole length of the boundary zone (over 200 miles) to Lake Tanganyika.

EXCHANGE OF TELEGRAPHIC SIGNALS

(2) **Exchange of Telegraphic Signals.**—*For a description of the refined determination* of differences of longitude by telegraph for geodetic purposes by means of chronographs, the reader is referred to any standard work on geodetic methods; we shall here describe the simple means used to obtain telegraphic differences of longitude with sufficient accuracy for map making.

Let A and B be two stations which are connected by telegraph and of which it is required to determine the difference of longitude.

Arrangements must first be made to insure direct communication between A and B, this may involve the use of relays. The line must be free of all traffic during certain hours of the night, and there must be a telegraph operator at each end.

At each end there must be a good box chronometer, one of these should be a mean time chronometer and the other a sidereal time chronometer. The reason for this is, that if both were sidereal or both mean time chronometers, the intervals between the beats of the chronometer would be constant, and there would be no coincidences.

The chronometer should be on the same table (in tent, hut, or house) as the telegraph key, and close to it, so that the person sending signals can easily read the chronometer.

Before commencing the exchange of signals, a programme should have been arranged between A and B.

A convenient programme is as follows:—

Signals to be exchanged on three nights.

Each night's work to consist of at least one set of signals sent in each direction.

Unsatisfactory sets to be repeated.

Each set of signals should be preceded by a rattle on the key about 30 seconds before the set begins. Each set should end with a rattle. A message should be sent at the end of a set to ask if it was received all right.

Each set of signals to last 5 minutes.

Each set to begin at 0 seconds. Succeeding signals to be sent at 10 seconds, 20 seconds, 30 seconds, 40 seconds, 0 seconds, 10 seconds, &c., omitting the 50th second.

When the key is depressed to send a signal it should be kept down for 2 seconds.

Receiving.—The chronometers should beat half seconds, and in receiving signals it is necessary to count mentally the beats of the chronometer, thus: one, half, two, half, three, half, &c. If now the signal from the other end should arrive, say, between half and two, the person receiving must judge whether it was 1·6, 1·7, 1·8, or 1·9, if he is doubtful he should say 1·8. It requires a little practice to judge the intervals.

If the chronometers beat half seconds a coincidence will occur every three minutes, at a coincidence the chronometer beat and the signal will sound together, the receiver will then say 'up', the beat and signal will sensibly coincide two or three times running.

Before and after exchanging signals, observations for time should be taken. These observations should be made either with a portable transit instrument or with a theodolite, if with the former, two N. stars and two S. stars before and the same number after, if with a theodolite, two E. and two W. stars before and the same number after.

The box chronometer should not be moved from the table on which it rests during the operations, any movement will tend to give it an irregular rate.

Its error should be determined by transit instrument or theodolite as laid down, each

moment of transit or intersection being referred to the chronometer in one of the following ways —

By having a recorder at the chronometer, and

(i) Putting up a temporary telegraph line a few yards long from instrument to hut and sending signals by key,

(ii) By shouting up to recorder or

(iii) The time may be transferred by stop watch this is only suitable for use with a theodolite which must be near the hut

The next morning after an interchange of signals each station should send a message to the other station —

My local mean (or sidereal) time of first signal sent was (to tenths of seconds)

My local mean (or sidereal) time of first signal received was "

The list of received signals should now be inspected there should be a slow progressive increase or decrease in the decimals any obvious mistake should be corrected

The difference between the means of the corrected local times of receiving and sending is the difference of longitude in time This is burdened with two errors in addition to instrumental errors (1) Rate of transmission of signal along the wire this is eliminated by sending the same number of times in each direction and is very small (2) Personal equation Every observer records a transit intersection or signal a little too early or too late This error is best eliminated by exchange of observers from one end of the line to the other when half the work has been completed This is not usually practicable in topographical work

In view of the existence of personal equation it must be expected that a telegraphic difference of longitude determined as above described will be in error 3 to 5 of a second of time or in equatorial regions 150 to 250 yards

(3) **Latitudes and Azimuths** —See Chapter XV

TRANSPORT OF CHRONOMETERS

(4) **Transport of Chronometers** —Suppose that it is required to ascertain the difference of longitude between two places A and B Determine the error of a chronometer at A on local time and also determine the rate of the chronometer *i.e.*, the amount which it gains or loses in a day Now transport the chronometer to B and determine its error on local time at B Since we know the error at A and the rate we can also at any instant find the local time at A compare this with the local time at B at the same instant the difference of these two local times is the difference of longitude between A and B *

As an example —

At A at 9 1 M November 3 1903 the chronometer was 2 minutes 5 6 seconds fast gaining 1 4 seconds a day

At B at 10 45 1 M November 4 1903 the same chronometer was 4 2 seconds slow what is the difference of longitude?

The interval in time between the two determinations is 1 day 1 75 hours = 1 07 day

The rate = 1 4 seconds the chronometer has therefore gained 1 4 seconds × 1 07 seconds = 1 5 seconds

The difference of longitude is therefore —

m	s
2	5 6
+0	4 2
+0	1 5
2	11 3

and B is east of A 0 32 49 5

* It is clear that the difference of the local times is the same as the difference at the same instant of the errors of the two chronometers on local time

In practice it is found that for land journeys box chronometers give unsatisfactory results for such work good keyless half chronometer watches costing from £24 to £30, are the best

Experience shows that the rate of a watch at rest is not the same as its rate when being transported it is therefore desirable when possible to ascertain the travelling rate of the watch This may be done by sending the watch out for a march every day, the march to last as long as it is expected marches will be on the return journey After 3 or 4 days a fair rate will be obtained The travelling rate in this sense includes the rate when at rest at night

When every precaution has been taken it will be found that a single watch is very variable in its rate It is thus necessary to carry several five is a good number Each watch should be known by some distinctive letter or number One watch should be used for the time observations and comparisons with all the others should be made before and after the observation

Watch Comparisons—Watches usually beat 5 times in 2 seconds, and the comparison of two watches by ear is difficult the following is a useful method —Let A and B be two observers X and Y two watches Let A take watch X and B watch Y A should make a sharp tap on the table when the seconds hand of X is exactly by eye on some definite second B should record the position of Y to the nearest tenth B now signals to A in the same way and A records X and B now change watches and repeat the operations There are now four values for the difference between the watches and the personal equations of the observers are all constant eliminated

Return Journeys—If a watch be transported from a place A to a place B and then immediately carried back to A and if its errors on local time before starting at A, on arrival at B and on return to A be determined a very good value of the difference of longitude A to B can be found

For if no halt is made at B beyond the ordinary nights rest, the travelling rate can be found by dividing the difference between the errors at A (starting and returning) by the number of days which elapsed

If a halt is made at B the rate at rest should be determined and applied for the period of the halt

Chronometer Journeys by Sea—Sometimes it is necessary to determine the difference of longitude of two places on the sea coast or connected by a navigable river, or on one of the great African lakes In such a case as many box chronometers as can be obtained should be carried and the method of return journeys as above described, should be adopted

Variations in Rate—Watch rates are variable, and the only way to eliminate the effects of such variability is to carry a large number of watches The attached table (p 188) will serve to show the variations which may be expected as judged by comparisons of four watches on a journey in E Africa

LONGITUDE BY OCCULTATION OF A STAR

(5) **Longitude by the Occultation of a Star**—We now come to the determination of longitude by *absolute* methods The rapid movement of the moon amongst the fixed stars gives the means of determining by their relative positions the Greenwich time at the moment of observation, and the difference at the same instant, between the Greenwich time and the local time is the longitude, in time, E or W of Greenwich

These *absolute* determinations of longitude depend only upon observations made on the spot and the best of all absolute methods is undoubtedly the occultation of a star

The *apparent* movement of the moon in the heavens from east to west does not take place at the same rate as that of the stars, but is slower, in other words the *relative*

TABLE of Daily Comparisons of four watches carried from River Sabi to River Limpopo and back, between September 8th and September 28th, 1892

Differences between Watches

1 and 2	Δ	1 and 3	Δ	1 and 4	Δ	Dates
m s		m s		m s		
+ 0 29		+ 0 13		+ 0 34 5		8th Sept
	12		4		11 5	
17		9		23		9th „
	6		8 5		13 5	
9		0 5		9 5		10th „
	8		14		7 5	
0		− 0 14 5		− 0 17		11th „
	12		10 5		16	
− 0 12		25		33		12th „
	11 5		11		19 5	
23 5		36		52 5		13th „
	12		11 5		19 5	
35 5		47 5		1 12		14th „
	13 5		9 5		15	
49		57		27		15th „
	10 5		10 5		18	
59 5		1 7 5		45		16th ,
	10		9		17	
1 9 5		18 5		2 2		17th „
	10 5		8		16	
20		26 5		18		18th „
	11		8		12 5	
31		34 5		30 5		19th „
	15		3 5		10 5	
46		38		41		20th „
	7		16 5		30	
53		54 5		3 11		21st „
	9		6 5		13	
2 2		2 1		24		22nd „
	6		10 5		30	
8		11 5		54		23rd „
	1 5		3 5		30	
9 5		25		4 24		24th „
	11 5		4		16 5	
21		29		40 5		25th „
	10 5		7 5		14 5	
31 5		36 5		55		26th ,
	3		16 5		28 5	
34 5		53		5 23 5		27th „
	10		8		15	
44 5		3 2		38 5		28th „

Comparisons on this journey were only made to the nearest half second

movement* of the moon among the stars is from west to east at a rate of about one diameter per hour

It follows therefore that in the course of its monthly revolutions round the earth the moon shuts out for a time from the view of an observer on the earth's surface certain of the fixed stars The disappearance of a star behind the moon's disc is called its immersion and the re-appearance its emersion, and it follows from what has been said that the immersion will always take place on the eastern limb of the moon and the emersion on the western

Data for these phenomena are given in the Nautical Almanac under the heading 'Elements of Occultations' together with the G M T of their occurrence as they would be seen from the earth's centre The G M T of the phenomena as observed from any station on the earth's surface can be computed having given the latitude and approximate longitude of the station, and thus by observing the L M T at which the phenomena actually occur the difference of time, and therefore of longitude, between the station and Greenwich is determined

To observe an occultation it is desirable to know beforehand the approximate L M T at which it will take place at the observer's station

This can be done roughly by applying the approximate longitude of the station (in time) to the G M T of conjunction in R A of the moon and the star (which is given in the Nautical Almanac), *adding* the longitude if it is east and *subtracting* if west

Two hours before the time so found the telescope should be directed at the eastern limb of the moon and search should be made for any star (the magnitude being known as a great assistance) approaching it from a distance equal to one or two diameters of the moon

There can be little difficulty in identifying the star, owing to the rarity with which these phenomena occur, and a star chart is unnecessary for the purpose

Parallax in R A will have a considerable effect on the time at which the occultations will take place, and with a little practice the observer will be able to save himself a good deal of waiting by studying its probable effects

Thus he will be able to say whether the hour found from the 'Nautical Almanac' will be accelerated or retarded, and roughly how much simply by ascertaining whether the moon will be to the east or west of the meridian respectively, and how far

It is evident, however, that this system of waiting considerable periods of time for an occultation (the actual occurrence of which will in many cases be doubtful up to the last moment) will not commend itself to the skilled observer

A preferable method is to predict beforehand the circumstances of an occultation This can be done sufficiently correctly, the accuracy of the prediction depending on the exactness of the position of the observer's station assumed in the calculation

Thus it can be ascertained—1st, whether the occultation will take place at all, 2nd, the L M T of immersion and emersion, 3rd, the exact position of the moon at these instants, 4th, the points on the moon's disc (measured in degrees of arc from the moon's vertex or from its north point) at which the star will disappear and reappear, and 5th, whether the immersion and emersion will occur in the moon's bright or dark limb—a most important consideration in actual practice

A method for predicting the circumstances of an occultation is given in the "explanation" of the 'Nautical Almanac,' and there is also a graphical method devised by Colonel S C N Grant, C M G, R E, which is explained further on

In 1896 several quantities (η, p^1, q^1) were added to the "Elements of Occultations" in the 'Nautical Almanac,' and Mr A C D Crommelin uses these quantities graphically in an

* Of course the moon has a second relative movement among the stars from N to S and *vice versâ* corresponding to its changes of declination the latter cause is also responsible for the circumstance that the range of fixed stars which are at one time or another occulted is such a wide one

adaptation of Grunt's method (published in pamphlet form by the Royal Geographical Society) and thereby considerably reduces the labour required in applying the latter

One can now, with a little practice predict the whole of the circumstances of an occultation in a quarter of an hour, and the times of immersion and emersion will be found to be correct within 2 or 3 minutes An example of such a prediction is appended

Longitude by the observation of a single occultation cannot ordinarily be depended upon to within less than about 1 second of time (15 seconds of arc or a quarter of a mile on the equator) and therefore whenever possible, more than one phenomenon should be observed at the same place To get full benefit from the accuracy of the method it is necessary to obtain from some fixed observatory the *observed* declination and right ascension of the moon during the night in question so as to correct the co-ordinates given (by prediction) in the 'Nautical Almanac differences even in the second place of decimals of seconds in these quantities appreciably affect the result of the calculation

Another disadvantage possessed by this method of ascertaining longitudes consists in the scarcity of suitable occultations that are visible at any one place during the year, and a large percentage of those that take place in every climate cannot be observed owing to the state of the weather

Thus in England during the winter months the heavens are generally obscured by clouds, and in the tropics climatic causes such as clouds the dust haze accompanying the Harmattan wind (which makes small stars difficult to see when in close proximity to the full moon), bring about many disappointments

In the Nautical Almanac about 150 stars are given for each month, the occultation of which is visible at some point or other of the earth's surface

In considering any one station however about half of these must be struck out owing to the station being outside the limits* of latitude (last column) within which, only, the occultation will be visible

Even now it by no means follows that because the station is within the stated limits of latitude the occultation will be visible there for in many cases among the stars that still remain the occultations will take place either in daylight or when the moon is below the local horizon to say nothing of the instances in which the occultations will be 'spoiled' by the effects of parallax both in declination and in right ascension more particularly the latter Generally about five satisfactory occultations only will be found to be visible at any one station each month, and in actual practice, with field instruments, dependence can only be placed on an average of two of these being observed

In Northern Nigeria, in 1903 the Anglo French Boundary Commissioners (having two sets of instruments at their disposal) waited two months at one place before a set of three occultations was obtained

The longitudes when worked out had an outside variation from one another of only 9 seconds of time At another place on the other hand, with the second telescope in use during the same period of time, three occultations were observed in a fortnight, the resulting longitudes having a maximum variation of three seconds

It should be stated however, that in all six cases the calculations were worked out without using the *observed* co-ordinates of the moon those predicted in the 'Nautical Almanac' only being available at the time

Occultation of a Planet—This observation can be made with field instruments, but it cannot be expected that the result will be as accurate as in the case of a fixed star owing to the appreciable time taken by the disc of the planet to disappear into or emerge from the moon and the consequent difficulty of judging the moment at which the *centre* of the planet comes in contact with the moon's limb

In making this observation accurately the times should be taken of the *immersion* of the

* Owing to possible accumulation of neglected quantities these limits should be extended by 1°

first limb of the planet into and the *exit* from of the second limb from the moon's disc, and a correction can then be applied for the apparent semi-diameter of the planet

In the calculation also the variations of right ascension and declination of the planet as well as its parallax have to be considered and further complications arise (especially when considering occultations of Jupiter Saturn and Saturn's ring) in determining the extent of illumination of the planet's elliptical outline

Practical Hint For field work a telescope with a 3 in or 3½ in object glass will be found suitable but care should be taken that the stand on which it is fixed is firm and if possible as an extra precaution against vibration the object end of the telescope should be secured to the stand by an arm working in conjunction with that attached to the eye end of the instrument for the purposes of elevation

During observation the telescope should of course be protected as much as possible from the wind by placing it inside a room or tent but or else within a building having a door or window facing the moon It will be found too that an eye piece of comparatively low power is preferable for use —

(*a*) For better definition

(*b*) To minimise the effects of vibration on the instrument

A diagonal eye-piece is more convenient than a direct one as it enables the observer by adjustment of the legs of the telescope to remain seated while waiting but it should be remembered that the image thus seen although upright is inverted in azimuth, and allowance should be made accordingly, when expecting an emersion

Stars of which the occultations are predicted are nearly all invisible to the naked eye being of the 5th 6th or 7th magnitude, for the most part

The error so small that even when seen through a powerful telescope it may be taken as a general rule that an immersion into or an emersion from the *bright* limb of the moon even when observed, cannot be depended upon for great accuracy of result Nor, of course can observations into or from the dark limb be made until some time after sunset or before sunrise, especially if the moon is in the west or east respectively—though as a matter of interest it may be stated that occultations of large stars are often observed in observatories in broad sunlight Generally speaking also if the moon is only 15° or less above the horizon, the observation will be impeded by haze

So much stress has been already laid on the scarcity of suitable occultations at any one place that it need hardly be said, when an opportunity occurs of observing one every precaution should be taken to ensure success, for example, observations for time should be made as shortly as possible before *and after* each phenomenon, so that the error of the chronometer on L M T may be known as nearly as possible

Also every timekeeper, however experienced, is always liable to make mistakes in booking times, when possible, therefore, there should be two timekeepers, with separate chronometers, which latter should be compared immediately after the observation

If this cannot be done the observer should use a stop watch as a check on the timekeeper, and the procedure would be as follows —

At the moment that the signal is given by the observer, he should start the stop-watch, then after the time has been booked by the timekeeper, the observer should go to the chronometer and stop his watch when the seconds hand of the chronometer has exactly reached some minute or half minute, the time indicated by the chronometer should then be written down, and the number of seconds shown by the stop watch subtracted from it

If the time thus arrived at is the same, within one or two tenths of a second, as that booked by the timekeeper, the latter may be accepted as correct

It should be borne in mind that an ordinary stop watch cannot be relied upon after it has been going several minutes

If an accurate stop watch is available, it would perhaps be simpler to start it from the chronometer at some exact minute shortly before the phenomenon is due to take place, and to then stop it at the moment the signal is given

The hours and minutes can then be booked from the chronometer, and the seconds and fractions of a second from the stop watch

As regards the calculation of longitudes from occultations there are several ways of doing this, all depending on the same principle

The method described in the 'Connaissance des Temps' for example, is different in form from that given in the Hints to Travellers,' which is taken from Raper, and an example of which is appended the latter will be found to give good results—although formidable in appearance it is not so in reality, and depends almost entirely on accurate arithmetic

In using it it should be noted that it is preferable to use five places of decimals in the $\log s$ instead of four only, ternary proportional logs to five places being given in Chambers' tables

In conclusion the attention of the beginner might with advantage be drawn to two points in this calculation —

(i) Care should be taken to *reduce to date* the assumed places of stars given in the Mean Places of Occultation Stars in the Nautical Almanac,' by adding (arithmetically) the quantities $\Delta\alpha$ $\Delta\delta$ (columns 4 and 5 in 'Elements of Occultations Nautical Almanac) to the R A and declination respectively given under 'Mean Places of Occultation Stars, Nautical Almanac'

It will be noticed that $\Delta\alpha$ is given in seconds of time and $\Delta\delta$ in seconds of arc

(ii) Table XVIII for reducing the observed latitude to geocentric latitude is based on Clarke's first figure (1858) the value for compression being $\frac{1}{293\cdot46}$

A compression of $\frac{1}{300}$ has been used in the following example, the value adopted makes an appreciable difference in the resulting longitude

In the calculation of longitude by occultations the value for the moon's semi diameter given on p III Nautical Almanac, should be diminished in the proportion of 15′ 34′′·09 to 15′ 32′ 65 or 93409 93265 The former value is the mean semi-diameter adopted for transits, and the latter that adopted for occultations'

If an accurate stop-watch is available, it would perhaps b chronometer at some exact minute shortly before the phenomer then stop it at the moment the signal is given

The hours and minutes can then be looked from the chr fractions of a second from the stop-watch

As regards the calculation of longitudes from occultations t this, all depending on the same principle

The method described in the 'Connaissance des Temps,' fo from that given in the 'Hints to Travellers' which is taken from is appended, the latter will be found to give good results—alth it is not so in reality, and depends almost entirely on accurate a

In using it, it should be noted that it is preferable to us $\log_{10}$ instead of four only, ternary proportional logs to five pl tables

In conclusion, the attention of the beginner might with points in this calculation —

(i) Care should be taken to *reduce to date* the assum "Mean Places of Occultation Stars in the (arithmetically) the quantities $\Delta\alpha$, $\Delta\delta$ (columns 4 tations, 'Nautical Almanac') to the R.A. and under "Mean Places of Occultation Stars, 'Nau

It will be noticed that $\Delta\alpha$ is given in seco of arc

(ii) Table XVIII for reducing the observed latitude on Clarke's first figure (1858) the value for comp

A compression of $\frac{1}{300}$ has been used in the following exa an appreciable difference in the resulting longitude

In the calculation of longitude by occultations, the valu given on p. III 'Nautical Almanac,' should be diminished in 15 32'·65 or 93109 93265 The former value is the mean ser and the latter that adopted for occultations'

COMPUTATION

OF THE

LONGITUDE OF BUSA

FROM THE

IMMERSION OF 76 LEONIS, ON MAY 6TH, 1903

Computation of the Longitude of Busa from the Immersion of 76 Leonis, on May 6th, 1903

		h m s
Clock times of Immersion	=	10 1 13 8
Watch slow	= +	0 10 8·0*
M T at Place	=	10 14 21 8
Approx Longitude F	= −	0 24 7 5
Corrected Greenwich Date	=	9 50 14 3

* *Error of Watch*

	m s
By a Leonis (W)	= 10 8 04 slow
By a Coronæ (F)	− 10 7 90 slow
Mean	= 10 7 97 slow

☽'s Semi diameter noon 6th	=	15 54 15 (p III N A)
Do midnight	=	15 50 54
12 hourly diff	=	0 3 61
3 61 × 9 837 + 12	=	0 2 96
☽'s Semi diameter for Greenwich Date	=	15 51 19

		′
☽'s Hor Parall noon 6th May	=	58 15 77 (p III N A)
Do midnight do	=	58 2 53
12 hourly difference	=	0 13 24
Now 9h 50m 14 3s = 9 837h		
9 837 × 13 24 + 12	=	0 10 85
☽'s Hor Parall for Greenwich Date	=	58 4 92
Correction for Latitude	= −	0 0 68 (Table XVII)
☽'s Reduced Hor Parall	=	58 4 24

		° ′ ″
Latitude	=	14 20 24
Reduction	=	0 5 30 9 (Table XVIII)
Geoc Latitude	=	14 19 53 1

		° ′ ″
☽'s Declination at 9h	=	2 25 35 0 (p VI, N A)
Correction	=	**0 8 58 37
☽'s Reduced Declination	=	2 16 36 63 N

		h m s
Star's R A		11 13 56 16 (*a*)
Correction	= +	0 0 1 90 (*b*)
	=	11 13 58 06

** Var in 1′ = 10 716
50 24 × 10 716 = 8 58 37

		° ′ ″
Star's Declination	= +	2 10 56 0 (N) (*a*)
Correction		0 0 14 9 (*b*)
		2 10 41 1

(*a*) (*a*) Mean Places of Occultation Stars, 'N A'
(*b*) (*b*) 'Δα Δδ in Elements of Occultation,' 'N A'

		h m s
Sid Time of G M N	=	2 52 40 13 (p II 'N A')
Acceleration (Table XXXI 'Hints to Travellers') 9h	=	0 1 28 71
50m	=	0 0 8 21
11s	=	0 0 0·04
Reduced Sid Time	=	2 54 17·09
M T at Busa	=	10 14 21 80
R A of Meridian	=	13 8 38 89
Do Star	=	11 13 58 06
Star's Hour Angle	=	1 54 40 83 W
	=	28° 40′ 12 45 (in arc)

		° ′ ″
Star's Declination	=	2 10 41″1
Arc (A C)	=	0 14 21 6 (+ Latitude and Declination are same name)
		2 25 2 7
Arc B	= −	0 1 32 57 (−, Hour Angle is less than 6 hrs)

Days Related Hor Parall *Prolog	4913
Co e Geoc Latitude	10 60°37
Sec Star Declination	10 00031
	1 09800

*Prolog of 14 1 84 Arc A

	= 4913
S	= 10 013 3
C e	= 11 4901C
Sec Stars Hor Angle	= 10 0 80
	1 98 01

*Prolog of 1 o° o7 Arc B

	= 1313
	= 10 013°3
C e	= 10 818 °
	8.10
	2
	1 C1804
	1 8 00 (n ta t)
Cot Stars Declin to	= 11 41984
	4 C1989

*Inverse of 0 0 °4 = Arc C

Prop rl De n on	°3 10 13	Co	9 9°962
) D l o	- 16 36 3	Co t	1 1 610
D ff e	0 6 33 o		
S lan ter	0 15 51 19		
D ff e	0 9 1 69	½ *Prolog	0135°
S	2 21 61	½ *Prolog	1 °10
			° 7161

9 °9°-	
1 1°C10	
°°40 (ur of 3 logs I to find Arc C)	
1 °99 1	

*Inverse of 1 48 of Part II

*Prolog of 0 83 Part I

Stars R A		11 13 °8 0°
		0 0 57 8° (Part I *Inverse o)
		11 13 0 °
		0 1 48 0 o (Part II + *B of Mer I)
s R A		11 14 48 34
D l l r	(	11 1 °9 8
D o	( )	11 15 9 38 {9 / 10 1 rs} (I V A)

D f b n l(	1 48 o	*P o o	1 9 1°
D (l( )	of	*Arithmetical complement of Prolog	8 0 °046
		Co tant	4 10
			°40 8

*Prolog of 50 15 °5 *x*

	I n s
H r f( )	9 J
x	0 0 1°.5
G M T of I r	9 50 15 °°
L M T of In r on	10 14 °1 80
D fferen e of Lo g t	°4 6 2°.5 L
	f 1 33 °°.5 E (n Arc)

* I f l Pr P l L r l) f
Tl l l l rot A c l l 3 p oc l
tl s Γ k l s f ra t t (f f l
T r A lu lt se o d Fl r lt ll e
fl l l ue l

NOTE For gr at r accur cy tl e *obse red* places of tl muon l o ll b obta n l fron Gre w h and ub t tute l n the bove n l t e resultin long tu le hou l l e u d at tl beg n ng n lo g tl e calcula t on econ l t m

Computation of the Longitude of Busa from the Immersion of 76 Leonis, on May 6th, 1903

		h m s
Chronometer of Immersion	=	10 1 13 8
Watch slow	= +	0 10 8 0*
	=	10 11 21 8
M T at Place	=	0 24 7 5
Approx Longitude	= −	
Corrected Green Date	=	9 50 14 3

* *Error of Watch*

	m s
By α Leonis (W)	10 8 04 slow
By α Coronæ (T)	10 7 90 slow
Mean	10 7 97 slow

☽'s Semi-diameter noon 6th = 15′ 54 15 (p III, 'N A')
Do midnight = 15 50 54

12 hourly diff = 0 3 61

3 61 × 9 837 ÷ 12 = 0 2 96

☽'s Semi-diameter for Green Date = 15 51 19

		′
☽'s Hor Parall noon 6th May	=	58 15 77 (p III 'N A')
Do midnight do	=	58 2 53
12 hourly difference	=	0 13 24
Now 9h 50m 14 3 = 9 837h		
9 837 × 13 24 ÷ 12	=	0 10 85
☽'s Hor Parall for Green Date	=	58 4 92
Correction for Latitude	= −	0 0 68 (Table XVII)
☽'s Reduced Hor Parall	=	58 4 24

		° ′ ″
Latitude	=	14 25 24
Reduction	=	0 5 30 9 (Table XVIII)
Geoc Latitude	=	14 19 53 1

		° ′ ″
☽'s Declination at 9h	=	2 25 35 0 (p VI, 'N A')
Correction	=	**0 8 58 37
☽'s Reduced Declination	=	2 16 36 63 N

** Var in 1′ 10 716
50 24 × 10 716 = 8 58 37

		h m s
Star's R.A.	=	11 13 56 16 (*a*)
Correction	= +	0 0 1 90 (*b*)
	=	11 13 58 06

		° ′ ″
Star's Declination	= +	2 10 56 0 (N) (*a*)
Correction	=	0 0 14 9 (*b*)
		2 10 41 1

(*a*) (*a*) Mean Places of Occultation Stars 'N A'

(*b*) (*b*) 'Δα Δδ' in Elements of Occultation 'N A'

	h m s
Sid Time of G M N	= 2 52 10 13 (p II 'N A')
Acceleration (Table XXXI 'Hints to Travellers') 9h	= 0 1 28 71
50m	= 0 0 8 21
14s	= 0 0 0 04
	= 2 54 17 09
Reduced Sid Time	= 2 54 17 09
M T at Place	= 10 11 21 80
	= 13 8 38 89
R.A. of Meridian	= 11 13 58 06
Do Star	
Star's Hour Angle	= 1 54 40 83 W
	= 28° 40 12 45 (in arc)

		° ′ ″
Star's Declination	=	2 10 41 1
Arc (A C)	=	0 14 21 6 (+, Latitude and Declination are same name)
		2 25 2 7
Arc B	= −	0 1 52 57 (−, Hour Angle is less than 6 hrs)
Prepared Declination	=	2 23 10 13

) s Reduced Hor Parall *Prolog = 49132
Co ec Geoc Latitude = 10 00037
Sec Stars Declination = 10 00031
1 09800

*Prolog of 14 21 84 = Arc A

= 49132
Sec = 10 01373
C s c = 11 42016
Sec Stars Hour Angle = 10 05680
1 08201

= *Prolog of 1 52 57 = Arc B

= 49132
= 10 01373
C sec = 10 31807
82402
2
1 64804
1 8200 (constant)
C t Stars Declination = 11 41984
4 64988

= *Prolog of 0 0 24 = Arc C

Prepared Declination 2 23 10 13
D's Declination 2 16 36 03
Difference 0 6 33 5
) s Semi diameter 0 15 51 19
Difference – 0 9 17 69
Sum 0 22 24 09

Co 9 99962
Constant 1 17610

½ *Prolog 64302
½ *Prolog 45240
2 27164 = *Prolog of 0 57 783 Part I

= 9 99962
– 1 17610
82402 (sum of 3 logs used to find Arc C)
1 99974

*Prolog of 1 18' 063 Part II

h m s
Stars R A – 11 13 58 06
– 0 0 57 783 (Part I – *Immersion*)
11 13 0 277
+ 0 1 48 015 (Part II +) *H* of Mcrid)

) s R A (*t*) 11 14 18 34?
Do preceding hour = (*n*) 11 12 9 85 { 9 hrs / 10 hr } (I V N A)
Do following hour = (*m*) 11 15 9 38

Difference between (*t*) and (*n*) = 0 1 48 502
Do (*n*) and (*m*) = 0 2 9 56

*Prolog 1 19? 012
*Arithmetical complement of Prolog – 8 07 0046
Constant = 177100
5408

= *Prolog of 50 15 55 – *x*

h m s
H r r f (*n*) = 9 0 9
x = 0 50 15 55
G M T of Immersion = 9 50 15 55
L M T *of Immersion* = 10 14 21 80
Difference of Longitude = 0 21 6 25 I
= 6° 1 33 7.5 I (in Arc)

* To find the Prolog (Proportional Logarithm) of TIME less than 3 hours or of ARC less than 3 proceed thus From 4 03342 subtract the logarithm of the TIME or ARC reduced to seconds The result will be the Prolog *required*

NOTE —For greater accuracy the *observed* places of the moon should be obtained from Greenwich and substituted in the above and the resulting longitude should be used at the beginning in doing the calculation a second time

*Example of Prediction of Occultation by Graphic Method

Let us examine the circumstances of the occultation of 76 Leonis on May 6th, 1903, at Busa (a French military post in the Western Soudan)

Latitude = 14° 25′ 24″ N (by observation)
Approx Longitude = 24m 7·5s E of Greenwich (in time)

Data —

76 Leonis, Magnitude 6·5		'Nautical Almanac,' "Elements of Occultations"
E. G.M.T. of conjunction in R.A.	− 9h 26m 58s	
Limits of latitude, 44° N. to 25° S.		
q_0 = + 0·1736		
p' = 0·5572		
q = − 1·845		

		h	m	s	
Assumed R.A. 1903	=	11	13	56·16	'Nautical Almanac,' "Mean Places of Occultation Stars"
Assumed Declination, 1903	= +	2	10	56·0 (or, N.)	

Reduction to Date —

$\Delta\alpha$	+ 1s·90	'Nautical Almanac,' "Elements of Occultations"
$\Delta\delta$ =	− 11·9	

There are two diagrams to be used. Plate XXVII. is †Grant's, and from it we obtain the parallaxes in declination and R.A. of the moon, which are transferred to Plate XXVIII. (Crommelin's) this second diagram being drawn on such a scale that the parallaxes found on Plate XXVII. can be entered on it unaltered. (It is in this that the advantage of Crommelin's adaptation of Grant's method is to be found.) On the second diagram the remainder of the work is done.

Plate XXVII. represents an orthographic projection of earth (OO, being the equator). The horizontal lines are parallels of latitude and the up and down lines hour circles.

In Plate XXVIII. the circle in the centre represents the moon, the radius of which is taken as being constant and 0·272 of the earth's radius.

Latitude.—It will be seen that Busa is situated well within the limits of latitude given in the data.

Moon. From p. IV. of the 'Nautical Almanac' for May, 1903, it will be seen that the meridian passage of the moon is at 8h 17m 24s G.M.T.

Now G.M.T. of occultation = 9h 26m 58s, from which it will be seen that the moon will be well up above the local horizon—in fact near, and to the W. of, the meridian.

The effect of the moon being to the W. of the meridian will be to *delay* the occultation which may be expected to occur about 10 P.M.

Sunlight.—Evidently at 10 P.M. the sun will not interfere with the observation.

Parallax. The effects of parallax in declination and in R.A. have now to be considered, and we come to the use of the diagram.

On Plate XXVII. draw a horizontal line DD, to represent the latitude of Busa 14° 25′ 24″ N. (If the place had a south latitude, DD would be drawn below OO.)

Draw a straight line through C, the centre of the diagram, to F, the point on the circumference of the circle representing the moon's declination at 9 or 10 P.M. on May 6th. (F would be below OO if the moon had a S. declination.)

Parallax in Declination.—Now from D, towards D, set off the moon's hourly angle at E, by Inspection, at the G.M.T. of conjunction in R.A., one hour later and two hours

* See a paper published by Mr. A. C. D. Crommelin published in 1902 in the Royal Geographical Society entitled "An Application of Mayer Orme's Graphical Method of Predicting Occultations to the Determination of Longitude." Also Crommelin's article in the British Nautical Almanac.

† Taken from a diagram by Colonel C. A. Grant, C.M.G., R.E.

later (Note —If the moon had been near the western horizon, the effects of parallax in R A would have been much greater, and we would have selected the hour angles at T_1, T T_3 instead of the above Similarly if the moon had been slightly to the *east* of the meridian we would have substituted the hour angles at 1_1 1 and 1_3 An indication of which hours to select is soon obtained with a little experience in predictions)

From these points on the line DD draw perpendiculars to CF, and call their lengths a, b, c Thus a b, c are the values of the parallax in declination at 1 T_1 and T and will be transferred direct a little later, to Plate XXVIII

Parallax in R.A —For the values of parallax in R A set off the same hour angles along the latitude line, but this time from D towards D , then Df D and Df will be the values of parallax in R A to be transferred to Plate XXVIII

We have now done with Plate XXVII It might be noted here, that if the hour angle exceeds 6 hours, in plotting the parallax in R A on the latitude line we first move outwards to the circumference of the circle and then count inwards again from that point, for the excess on 6 hours Also the feet of the perpendiculars a b c, will be to the *right* of C if the moon is above the horizon and to the *left* if it is below

Hour Angles —To find the hour angles at T_0, T_1 and T we proceed as follows —

		h	m	s	
9h 26m 58s (T_0)		9	26	58	
accelerated for 9h	−		1	28	71
accelerated for 26m	=			4	27
accelerated for 58s					16
		9	28	31	14
Sidereal time at G M N (May 6th)	−	2	02	10	13
Sidereal time at Greenwich		12	21	11	27
East longitude in time	+		24	7	5
Sidereal time at Base		12	45	18	77
		12	45	0	(nearly)

as seconds cannot be plotted on Plate XXVII

Moon's R A at T (p VI 'Nautical Almanac')		11	14	0	(nearly)
☽'s hour angle at T		1	31	0	W of the meridian

Now the variation in R A of the moon in 10 minutes at T 21 59s (about)
Variation in 1 hour = 129 5s 2m 9 5s
Whence ☽'s hour angle at 1 (1h 31m) + (1h)* − (2m 9 5s) 2h 29m (nearly)
Similarly ☽'s hour angle at 1 3h 27m (nearly)
Next in Plate XXVIII —
Make OG l_0† on the vertical line through O
Draw G_0M horizontally *to left* of G and equal to f
Then plot MG_1 l‡
Join G G_1 and produce it both ways marking off equal intervals G G_1 G_1G and G G_1 Then G G_1 G &c are the geocentric places of the moon at the intervals T T_1 T &c respectively

* = because ☽ is W of meridian + if ☽ is E of meridian
† When q is + G_0 is above O when q is − G_0 is below O
‡ q + G_1 M, l − G M

Next, to get the *apparent* position of the moon's centre at the e times as seen from the st tion under co sideration, we pl ot at G, G1 G the parallaxes in declination and R.A obtained in Plate XXVII

When the points marked off on the latitude line in Plate XXVII are *above* the "moon line" the parallaxes in declination are pl tted *d ownwards* from G, G1 G2, when *below*, the parallaxes are plotted upwards

Similarly, if the hour angles at T0, T1, T2 are *ea t*, the parallaxes in R.A. are plotted to the left of G, G1, G , if *we t*, to the right.

Then L0, L1, L2 is the *apparent* path of the moon's centre, as seen at the station

If this line cuts the circle in the centre of Plate XXVIII, the occultation will take place, and the points I, E, corre po nd to the immersion and emersion of the star respectively

To find the times at the e m tants, select that part of the scale (fig 2, Plate XXVIII) on which a distance equal to L0, L1 corresponds to 1 hour

It will be seen that the di tance L I corresponds to about 22m 20s Whence

	h	m	s
G, time of immersion =	9	26	58
+		22	20
	9	49	18
+		24	7 5
and L M T of immersion =	10	13	25 5 (Long E.)

(Note the actual L M T of immersion was ob erved to be 10h 14m. 21 8s)

Treating L1 L and L1 L2 similarly, we get the L M T of emersion = 11h 2m 20s.

Angles from Moon's Vertex.—The angles on the graduated arc in Plate XXVIII, at I and L2 are the angles from the moon's north point (always reckoned to the *left*) of immersion and emersion, (in the example 68° and 349°) respectively

It will be easier in the ob ervation to judge these angles by eye, however, if they are reckoned from the moon's vertex

Now, at the time T0 the line L0G0 pa ses through the zenith of the ob erver, and so by drawing a line through O, parallel to L0G0 we find that the vertex of the moon at T0 is 60 to the *left* of the north point

For exactness the line G0 G1 should be divided proportionally (at *g*) as L L1 is by the point I, and a line should be then drawn through O parallel to I*g*. We thus get the moon's vertex *at the instant of immersion*, which in the example is 64° to the *left* of the moon's north point

Whence the angle of immersion of the star is 68° − 64° = 4° to the left of the moon's vertex

Similarly, the angle of emersion is 349 − 70 = 279 to the left of the moon's vertex

Thus the occultation will occur as shown in fig 65 It will of course appear, if seen through the diagonal eye piece, as shown in fig 66

Moon's Limb—Illumination.—Further, we can foretell whether immersion and emersion will take place over the bright or dark limb of the moon

On page XII, 'Nautical Almanac' for May, 1903, under 'Phases,' we find that the moon is full on the 11th There fore on the 6th about moon's disc will remain unilluminated, the western limb being the first one

The immersion will therefore take place on the dark limb, at a point distant from the bright limb For all practical purposes this will be at a point, but it should be noted that if the path of the star is almost tangential to the moon's limb, it is possible that immersion may take place on the same limb, but at

In the field, each occultation would be observed and recorded, and the brightness of the limb will be recorded by estimating the

method is here given by which the angle that the terminator (*i e* the line joining the ends of the bright limb) make with the north point can be determined

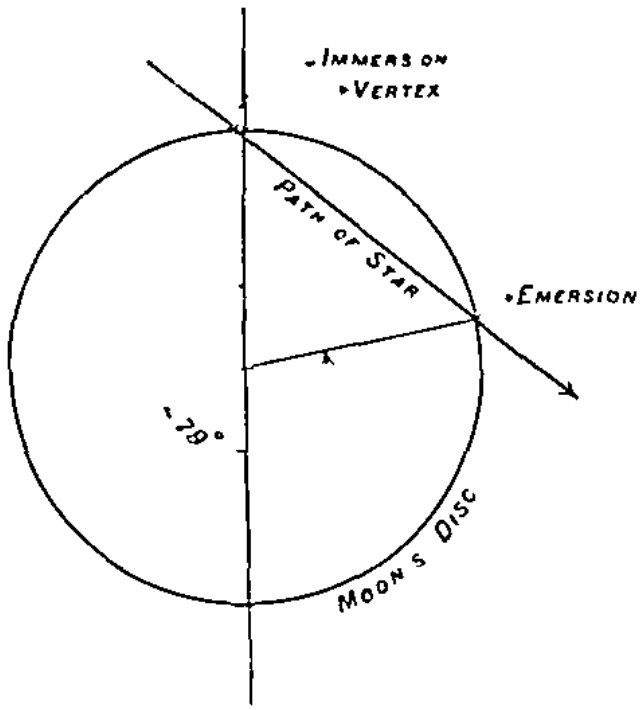


Fig 65

In the Ephemeris for Physical Observations of the Moon by Mr Crommelin published annually in the Monthly Notices of the Royal Astronomical Society the angle between the

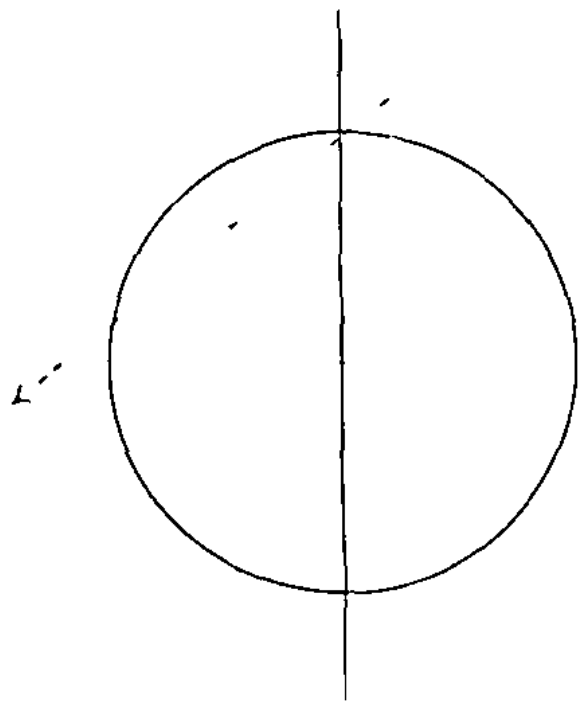


Fig 66

north *point* and the north *pole* of the moon is given If this ephemeris is available we could enter on Plate XXVIII the line joining the moons poles which for all practical purposes could

be taken as the 'terminator', for as the inclination of the moon's axis to the plane of the ecliptic is small, the junctions of the bright limb and dark limb will in general be near the poles, and it may be taken that the angle between them will never exceed 5°, except when the moon is very young or old, or almost full

An exact solution can be arrived at by the following computation —

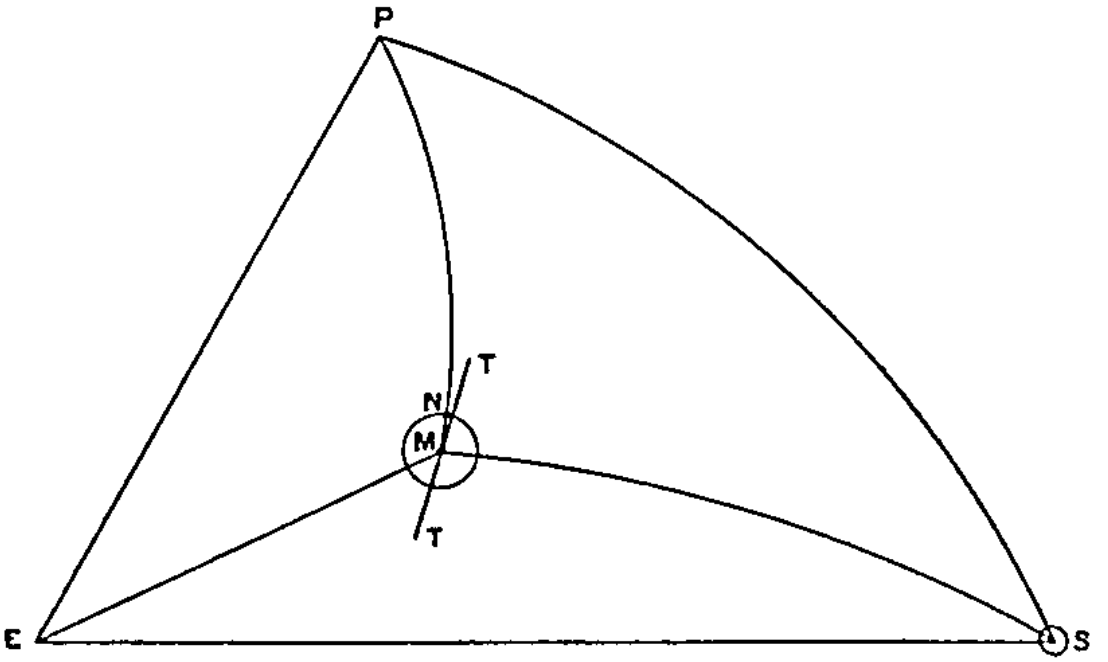


Fig 67

M is the moon, E the earth, S the sun, P the pole, and TT the terminator, at right angles to MS

Required to find the angle PMT —

Now, in the △ PMS, the two sides PM and PS (the north polar distances of the moon and sun) and the included angle MPS (difference of their R A) are known

Hence the triangle can be solved and PMS, and therefore PMT found (Note —N is the moon's north point)

To insert the amount of the illuminated disc on Plate XXVIII, use must be made of *Crommelin's ephemeris which gives the longitude of the terminator, or its distance from the* centre of the disc

Moon's Altitude—Plate XXVII can also be utilised to ascertain the *altitude* of the moon, at the instants of immersion and emersion as follows —

Measure a distance equal to I_{50}, G_{50} vertically upwards from C, in Plate XXVII, and note what parallel of latitude is reached (26° in the example)

This gives us the zenith distance of the moon, and the altitude

= 90° − zenith distance

= 90 − 26° = 64° for immersion

and = 90 − 38½° = 51½° for emersion

The foregoing explanation is rather a long one, as the intention has been to provide for every example that may occur

Summary.—In brief, the procedure is as follows —

On Plate XXVII draw the "moon line" and the latitude line and set off on the latter the various hour angles

Draw the perpendiculars for the parallaxes in declination

On Plate XXVIII plot $q\ p$, q, and the parallaxes in declination, and R A , and we thus get l_{ss} l_d, l.

The computation for longitude, from the *d red* immersion of the star dealt with in the prediction, is appended (*See* p 194)

LONGITUDE BY PHOTOGRAPHS OF THE MOON

(6) **Longitudes by Photographs of the Moon** —A photographic camera on a stable and rigid stand is set up so that the image of the moon is about in the centre of the plate, and a series of instantaneous exposures is made, allowing such an interval between the exposures that the moon images will not overlap , , from $1\frac{1}{2}$ minutes to $2\frac{1}{2}$ minutes according to the moon's age

After a set of say, seven moon exposures the camera is left untouched until bright stars of approximately the same declination as the moon have arrived at the same point in the heavens The camera is then opened for periods of 15 to 30 seconds and the stars allowed to impress their trails on the plate The star exposures should be repeated four or five times

There should be at least the trails of two stars on the plate The local time of each moon and star exposure must be known

From such a negative it is clear that the right ascension of each moon image can be determined, and hence the G M T and longitude The positions of the centres of the moon images and of the star exposures are measured by a micrometer and are referred to two co-ordinate axes approximately parallel and perpendicular to the meridian through the centre

The method in its present form is due to Major L H Hills, C M G , R I Somewhat similar, though less practical, methods had been previously suggested by Dr Schlichter in England, and Dr Runge in Germany For a complete discussion see the Memoirs of the Royal Astronomical Society Vol LIII , 1897, or 'Wilson's Topographic Surveying' Wiley and Sons, New York

The accuracy of the method in the field has not been satisfactorily determined, it is perhaps fair to assume that under ordinary conditions the probable error of longitude by one plate would be less than a minute of arc If time permitted the building of an isolated pillar, this could be reduced The actual error of the mean of five plates was found at Chatham (in 1894, 1895) to be 0 71 second or about 10 seconds of arc The measurements and calculations are laborious, and are not readily made during an expedition

LONGITUDE BY MOON CULMINATING STARS

(7) **Longitude by Moon Culminating Stars** —The moon moves so rapidly in right ascension that, if at any instant we can determine its right ascension we can from this determine the Greenwich time at that instant and hence the longitude Its right ascension at meridian transit can be most accurately found by the interval in sidereal time between its transit and that of some neighbouring well known star

Such stars are called moon culminating stars and are those which have nearly the same right ascension and declination as the moon A list of these will be found for each day of the year in the Nautical Almanac (p 456 *et seq*)

The observation must be made with a transit instrument or transit theodolite, set in the plane of the meridian The diaphragm of the instrument should be fitted with at least three vertical wires

To prepare for the observation select a star from those given in the list of moon culminating stars and note its R A Next determine the moon's R A at the moment of transit Use an approximate value for the longitude and multiply the difference in longitude from Greenwich in hours by the variation in moon's R A , if longitude is L, subtract this

from R A at Greenwich, if W, add The result will be the approximate R A of the bright limb at local transit Having the right ascensions of star and moon at transit (*i e*, the local sidereal times) the mean times can be computed if working with a M T chronometer

Next compute the setting for zenith distance of the star in the usual way ($\zeta = \phi - \delta$)

Having prepared this information beforehand, note carefully the sidereal times to the nearest tenth of a second of the transits of star and bright limb of the moon over each wire *From the e deduce the sidereal interval between the star's transit and that of the moon's* bright limb

Computation —In the 'Nautical Almanac,' the R A of the bright limb only is given, the R A of the other limb may be obtained by adding or subtracting twice the "sidereal time of passage of semi-diameter" It may be necessary to do this, since near full moon the limb changes from I to II (these figures in the 'Nautical Almanac' indicate the limbs which come first or last to the meridian), and the R A's taken from the 'Nautical Almanac' must be those of the limb observed

Take the R A's of the observed limb from the 'Nautical Almanac,' put them in order and take their differences as far as the fourth difference, thus —

	R A D's bright limb	Differences			
		1st	2nd	3rd	4th
Upper passage preceding day	A_{-2}				
		a_{-2}			
Lower " "	A_{-1}		l_{-1}		
		a_{-1}		c_{-1}	
Upper passage corresponding day	A_0		b_0		d_0
		a_1		c_1	
Lower following	A_1		b_1		
		a			
Upper "	A				

The first difference,

$$a_{-2} = A_{-1} - A_{-2}$$
$$a_{-1} = A_0 - A_{-1}, \&c$$

The second difference,

$$b_{-1} = a_{-1} - a_{-2}$$
$$b_0 = a_1 - a_{-1}, \&c$$

The R A of the moon's bright limb at transit in W longitude L will be

$$A_0 + n a_1 + \frac{n(n-1)}{1\ 2} l_0 + \frac{(n+1)(n)(n-1)}{1\ 2\ 3} c_1 + \frac{(n+1)(n)(n-1)(n-2)}{1\ 2\ 3\ 4} d_0$$

where $n = \frac{L}{12}$ L being expressed in hours

If the longitude is E, use the same formula but take the following list of R A's of moon's bright limb —

Lower passage two days before	A_{-2}
Upper passage preceding	A_{-1}
Lower " "	A_0
Upper corresponding day	A_1
Lower following	A_2

Then if the longitude is L, $n = \frac{12 - L}{12}$

An approximate value for the longitude will be known, assume two values for the longitude one a few (1 to 5) minutes greater than the approximate value, and one a few minutes less. Work out the R.A. of moon's bright limb for these two values and find by proportional parts what alteration must be applied to the smaller longitude in order that the right ascension by formula may agree with the right ascension by observation.

The smaller longitude so corrected is the longitude required. *Great care must be taken to apply the rule strictly according to the rules of algebra.*

As regards the accuracy of a longitude by moon culminations: an error of a second of time produces about 30 seconds error in the longitude. We may assume in the ordinary case an error of 1 second and a resulting error of 10 seconds of longitude. As a rule, only about eight observations can be taken in a month so that after a month's work the mean of the results would be about 3 or 4 seconds in error or say nearly 1 minute of arc.

(8) **Longitude by Altitudes of the Moon.**—A fair method, but one not often used. For the details see Manual of Surveying for India. An error of a second of time in an altitude will produce at least 30 seconds of time in longitude sometimes considerably more. An error of 1 second in zenith distance produces at least 2 seconds of time in longitude. With a small theodolite we may expect an error in time of ½ second and in arc (after four altitudes on two faces) of 5 seconds, so that the resulting error will be about $\sqrt{10 + 10^2}$, say 14 seconds of time.

(9) **Lunar Distances.**—A rough method, the observations cannot be taken with a theodolite.

(10) **Eclipses of Jupiter's Satellites.**—A very rough method.

These last two methods should never be used by the topographical surveyor or explorer.

NOTE.—It is of great importance that the explorer and surveyor should have clear ideas on the subject of the relative accuracy of the different methods available for determining longitude.

It should be understood that where longitude can be carried along by a triangulation this should always be done. Excellent results also can be got by telegraphic signals, the longitude of Mandalay was thus determined by Colonel Hobday, with an error of only 1·2 seconds of arc. (Such accuracy cannot, however, be always expected.)

Table showing the Terminal Error in Longitude which might be expected after a March of 300 miles in a Hilly Tropical Country

	Method	Probable error in longitude
Relative Methods	1 Triangulation	100 yards to ¼ mile
	2 Telegraph	⅛ to ¼ mile
	3 Latitudes and azimuths (N. and S.)	¼ mile
	4 Chronometers (5)	1 mile
Absolute Methods	5 Occultation	¼ mile
	6 Moon photographs (1 plate)	1 mile
	7 Moon culminations (8 nights)	1 mile
	8 Moon altitudes (1 night)	4 miles
	9 Lunar distance	10 miles
	10 Eclipses of Jupiter's Satellites	over 10 miles

CHAPTER XVII

THE THEORY OF ERRORS AS APPLIED TO TOPOGRAPHICAL WORK

An error of observation is the result of subtracting the true value from the measured value of a quantity Errors are of three kinds

(1) Mistakes as for example that which results from reading a micrometer head the wrong way, and booking say 38 instead of 22 seconds

(2) Systematic or constant errors as for example that which results from using a steel tape without applying the correction for temperature, or the constant personal error of an observer in estimating the moment when a star crosses a wire in a theodolite

(3) Errors which are neither mistakes nor systematic but which are the combined result of a number of small causes beyond the control of the observer, and which are subject to the laws of probability Thus in intersecting a luminous trigonometrical signal the observer at each intersection tries to put the wire through the centre of the light but the centre is an indefinite spot and no two intersections will be in precisely the same place

Or, to take another example suppose a base two miles long to be measured with a steel tape reading to hundredths of a foot it is clear that it is exceedingly unlikely that a series of measurements will give exactly the same values even when all the proper corrections have been applied

It is to this third class that the name **error** is strictly to be applied, and the following remarks deal only with such errors

Frequency of errors—The following will be found on consideration to be the laws which govern the frequency of errors —

(1) Small errors are more frequent than large ones

(2) Positive and negative errors are equally likely

(3) Very large errors do not occur

Thus in measuring a topographical base with a steel tape it is to be expected that a measurement will be some hundredths of a foot in error, it is somewhat less likely that it will be tenths of a foot in error and far less likely that it will be feet in error, also any measurement is just as likely to be in excess as in defect, and it is exceedingly unlikely that any measurement will be say, ten yards in error

From the second law it is clear that any expression giving the probability of an error of a given size will involve only even powers of the error

It is also clear from the first and third laws that if a curve is drawn of which the abscissæ represent the sizes of the errors and the ordinates the probability of such errors occurring the form of the curve would be that shown in fig. 68

If we imagine every finite error to be composed of an infinitely great number of very small equal elementary errors which are equally likely to be positive as negative, it can be shown that y the probability of the occurrence of an error x, can be represented by the expression —

$$\frac{h}{\sqrt{\pi}} e^{-h^2 x^2} dx \qquad (1)$$

where h is a constant

This expression gives a small probability for any error however large, and to this extent differs from experience. The probability of a large error derived from this equation is so

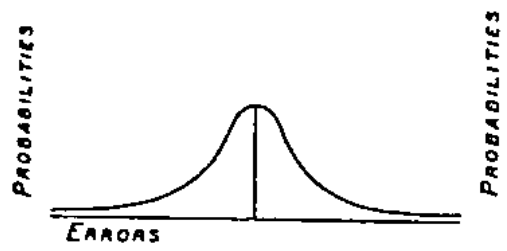


Fig. 68

small as to be negligible and results from the hypothesis that finite errors are the result of the algebraical sum of an indefinitely large number of very small elementary errors.

The probability that an error lies between two limits x_1 and x_2 is*

$$\frac{h}{\sqrt{\pi}}\int_{x_1}^{x_2} e^{-h^2x^2}\,dx \qquad (11)$$

Residuals.—If a number of measurements are made of the same quantity, the sum of the measured values divided by the number of measurements is the **mean** and a **residual** is the result of subtracting the mean from a measured value.

With a large number of observations the mean tends to become the true value, and the residuals the errors.

Probable Error.—In an indefinitely large series of errors the **probable error** is that error than which there are as many errors greater as there are smaller, *i.e.*, the chance that any error taken at random is greater than the probable error is the same as that it is smaller.

The Probable Error of the Arithmetic Mean of a series of observations

$$= 0{\cdot}674\sqrt{\frac{\Sigma r^2}{n(n-1)}},$$

when n is the number of observations and Σr^2 is the sum of the squares of the residuals.

The probable error is a valuable means of comparing the accuracy of sets of observations of the same class. Thus suppose two observers A and B have measured the same angle with the same instrument and have obtained the following results (seconds only are given) :—

A	r	r^2	B	r	r^2
47	0	0	48	3	9
49	2	4	46	1	1
50	3	9	49	4	16
42	5	25	41	4	16
48	1	1	47	2	4
46	1	1	39	6	36
Mean 47		$\Sigma r^2 = 40$	45		$\Sigma r^2 = 82$

The probable error of the mean of A's set is

$$0{\cdot}67\sqrt{\frac{4{\cdot}0}{30}} = 0{\cdot}78 \text{ and of B's set is } 0{\cdot}67\sqrt{\frac{8{\cdot}2}{30}} = 1{\cdot}11$$

A's set is thus the most reliable.

* NOTE.—For the investigation of this expression and of the Theory of Errors generally, see 'Text Book on the Method of Least Squares' Merriman.—J. Wiley & Sons, New York.

The means would be expressed as

$$47'' \pm 0\,78 \text{ and } 45 \pm 1\,11$$

Owing to the fact that it is very difficult to free observations of any kind from constant or systematic errors, the probable error obtained in this way is better considered as a test of the relative value of similar observations than as a statement of the amount by which the mean of a series is probably in error Thus the probable error of angles in a geodetic triangulation derived from the interagreement of observed values of the angles is generally smaller than that derived from a consideration of the triangular errors

Law of the Propagation of Error—*The probable error of the sum or difference of two quantities is equal to the square root of the sum of the square of their probable errors*, and so on for any number of quantities This rule is of frequent use in all kinds of survey work

As an example suppose that the probable error of a carefully measured base is ± 1 2 inches and that subsequently an extension is measured with a probable error of ± 0 7 inch then the probable error of the whole base will be $\sqrt{(1\,2^2 + 7^2)} = 1\,4$

The probable error of the arithmetic mean = probable error of a single observation divided by the square root of the number of observations

The probable error of the mean therefore varies inversely as the square root of the number of observations

Thus suppose the probable error of a determination of longitude by a single moon culmination is 3 miles, the probable error of the mean of the result of 9 culminations will be 1 mile

If the probable error of longitude from 1 lunar distance is 10 miles it will require 100 lunar distances to obtain a result with a probable error of 1 mile

Examples —

(1) *Latitudes and Azimuths*—Suppose that it is found impossible to measure a base directly, and it is decided to use one determined by latitudes at two stations and the observed azimuth of the ray between them It is required that this base shall have a probable error not greater than $\frac{1}{3000}$ The azimuth of the ray is about 45°, how long must the ray be?

The probable error of each observed latitude is about 1 , say; the probable error due to local attraction is about 2 , the probable error of the difference of the two latitudes will therefore be

$$\sqrt{(1 + 1 + 4 + 4)} = 3\,16 - 316 \text{ feet (about)},$$

and as the azimuth of the ray is 45°, this will produce a probable error in the length of the ray of $316 \times \sqrt{2}$ feet = 442 feet, and if the probable error of the length of the ray is not to exceed $\frac{1}{3000}$, the ray must not be less than 500×442 feet long or say 40 miles

(2) *Long Traverses*—American experience shows that the longitudinal error of a long traverse under favourable conditions is not greater than $\frac{1}{30000}$ Assuming that this error in the unfavourable conditions of the Gold Coast may amount to $\frac{1}{10000}$, and that a traverse is run approximately north and south, how long should the traverse be in order to obtain a check from latitude observations? The probable error of an observation for latitude with a zenith telescope may be put down as 0 1

The probable error due to local attraction is about 2 0

Total probable error in difference of latitude

$$= \sqrt{(01 + 01 + 4\cdot0 + 4\,0)} = 2\,83 \text{ or } 283 \text{ feet.}$$

If the latitudes are to be any check on the traverse, the probable error of their difference must not exceed that of the traverse, and the traverse must therefore not be shorter than 283,000 feet or 54 miles

Probable Errors of a Triangulation —If the probable error of each angle of a triangle is p then the probable error of the sum of the three angles is $p\sqrt{3}$

If the triangular error is the probable error of an angle is $\frac{e}{\sqrt{3}}$

In N triangles the probable error of an angle is $.67\sqrt{\frac{\Sigma e^2}{3N}}$, since the probable value of a triangular error is $.67\sqrt{\frac{\Sigma e^2}{N}}$

Example The following were the triangular errors of a chain of secondary triangles What is the probable error of an angle?

Triangular errors ( )

	e^2
2	4
5	25
3	9
4	16
6	36
1	1
4	16
3	9
2	4
6	36
4	16
0	0
5	25
7	49
—	—
	$\Sigma e^2 = 246$

The probable value of a triangular error $= .67\sqrt{\frac{246}{14}}$, and the probable error of an angle $= .67\sqrt{\frac{246}{42}} = 1''.62$

Adjustment of the Errors in a Net work of Long Traverses

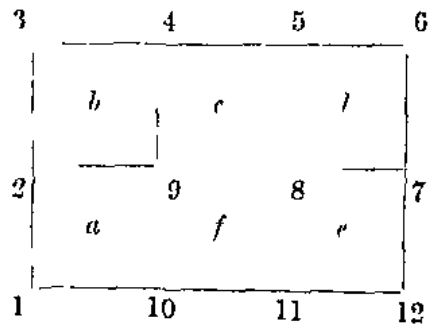


Fig 69

Let fig 69 be a diagrammatic sketch of a net-work of traverses, each line being 60 to 70 miles long.

Each traverse circuit is given a letter, *a*, *b*, *c* &c

Each latitude station has a number, 1, 2, 3, &c

Including the effect of local attraction each observed latitude has a probable error of about 1″·8

For the adjustment of the traverse errors, leaving out of consideration the observed latitudes

Thus —

For each traverse circuit such as *a*, we have, by computing round to the starting point, a closing error in the northings and southings, and one in the eastings and westings

Give each portion of the traverse from one junction point to the next an error *e* in the northings and southings, thus, $e_{10\text{–}2}$, $e_{2\text{–}3}$, &c

Then in each case such as *a*,

$$e_{10\text{–}9} + e_{9\text{–}8} + e_{8\text{–}10} = m, \text{ a known quantity,}$$

and so on for each traverse circuit, so that there will be *f* equations of this form, and by the ordinary method of least squares solve so that $e^2_{10\text{–}9} + e^2_{9\text{–}8} +$ &c is a minimum

Do the same with the eastings and westings

The result will be the most probable consistent solution of the problem, so far only as concerns the traverse adjustment leaving out of consideration the observed latitudes

Next, with some initial latitude, say of 1, *deduce latitudes of all the junction points* Compare these with the astronomical (observed) latitudes Now, by inspection we can probably tell —

(1) Whether there are any large local attractions shown by abrupt discordance at a point surrounded by concordances

(2) Whether a northing in an E to W traverse is more or less accurate than a northing in a N to S traverse

It should now be possible to weight the traverse amplitudes as compared with the astronomical amplitudes

Then starting afresh we have for any line, such as 9–10

Error of observed latitude 9 − error of observed latitude 10
− Error in traverse northing 9–10 = a known quantity,

and so on for the other lines, added to the condition that the sum of the 'weighted squares' of the errors is to be a minimum

Note — It is probable that this brief sketch of a particular case of an adjustment of errors by the method of least squares will not be very intelligible to those who have not studied the subject before It is however impossible, even in a book devoted to topographical surveying, to omit all mention of the subject which enters largely into the highest field of surveying, viz, geodesy And it is very desirable that at least some of the main principles of the theory of errors should be appreciated by the topographer

The following books may be studied —

'Treatise on the Adjustment of Observations" Wright New York 1884
"Method of Least Squares Merriman J Wiley & Sons New York 1884
'Geodesy" Col A R Clarke, C B, R E, F R S Clarendon Press 1880

Examples of the application of the theory will be found in—

The various volumes of the 'G T Survey of India"
Report on the Geodetic Survey of S Africa 'by Sir David Gill, K C B, F R S, 1896

TABLES.

Summary of Constants for Tables I II IX to XIII, XVII and XVIII

I n Clark Ast Exp (1858)

a = Equatorial Radius 20 926 348 feet

b = Polar Radius 20 855 233 feet

$\frac{a-b}{a}$ = Compression or Ellipticity $\frac{1}{294\cdot26}$

e = Eccentricity $\left\{\frac{a^2-b^2}{a^2}\right\}^{\frac{1}{2}}$

ν = Normal to meridian at latitude λ terminated by minor axis (or radius of curvature at right angles to meridian)

$= \frac{a}{(1-e^2\sin^2\lambda)^{\frac{1}{2}}}$

ρ = Radius of curvature to meridian at latitude λ

$= \frac{a(1-e^2)}{(1-e^2\sin^2\lambda)^{\frac{3}{2}}}$

Note.—In Clarke's later spheroid (1880) the values of a and b only differ from those given above by 140 feet and 138 feet respectively. These differences are so small that Table I based on Clarke's 1880 figure practically give the same results. The radii employed by the Survey of India differ from Clarke's by 3270 feet and 1520 feet respectively.

TABLE I.—Logarithms for facilitating the Computation of Terrestrial Latitudes, Longitudes, and Reverse Azimuths

Latitude	P: $\frac{1}{\rho \sin 1}$	Diff	Q: $\frac{\rho}{\nu}$	Diff	R: $\frac{1}{\nu\rho}$	Diff	S: $2 \sec\lambda \frac{\rho}{\nu}$	Diff	T: $\left(2\tan^2\lambda + \frac{\nu}{\rho}\right) \times \left(\frac{\cot\lambda \cos\lambda}{\nu}\right)$	Diff
	−		−	+	−	−		+		−
0 0	3 9 66580		1 9970132		8 38123		0 29807		Infinite	
		1		0		0		0		Infin
10	6584		0132		23		807		2 238·0	
		1		1		0		1		30101
20	6583		0133		23		808		1 93719	
		2		1		0		1		17607
30	6581		0134		23		809		76112	
		2		2		0		1		12191
40	6579		0136		23		810		63621	
		4		2		0		2		9187
50	6575		0138		23		812		53934	
	−	4	−	3	−	0		2		7914
1 0	3 9966871		1·9970411		8 38123		0 29814		1 46090	
		5		3		0		2		6689
10	6866		0444		23		16		39331	
		5		4		0		3		5793
20	6861		0448		23		19		33638	
		6		4		0		3		5108
30	6855		0452		23		22		28430	
		8		5		0		4		1·68
40	6847		0457		23		26		23802	
		7		5		0		4		4130
50	6840		046·		23		30		10732	
		9		6		0		4		3769

TABLE I.—Logarithms for facilitating the Computation of

Latitude		P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
	′										
2	0	− 3 9966831	9	− 1 9970468	6	− 8 38123	0	0·29834	5	1·15963	3466
	10	6822	10	0474	7	23	0	39	5	12497	3207
	20	6812	11	0481	7	23	0	41	5	09290	2984
	30	6801	12	0488	8	23	0	49	5	06306	2790
	40	6789	12	0496	8	22	1	55	6	03516	2619
	50	6777	13	0504	9	22	0	61	6	00897	2468
3	0	− 3 9966764	14	− 1 9970513	9	− 8 38122	0	0 29868	7	0 98429	2333
	10	6750	15	0522	9	22	0	75	7	96096	2211
	20	6735	15	0532	10	22	0	82	7	93885	2102
	30	6720	16	0542	10	22	0	89	7	91783	2002
	40	6704	17	0552	10	22	0	98	9	89781	1912
	50	6687	17	0564	12	21	1	0 29906	8	87869	1828
4	0	− 3 9966670	19	− 1 9970575	11	− 8 38121	0	0 29915	9	0 86041	1752
	10	6651	19	0588	13	21	0	24	9	84289	1683
	20	6632	19	0600	12	21	0	33	9	82606	1617
	30	6613	21	0613	13	21	0	43	10	80989	1556
	40	6592	21	0627	14	20	1	53	10	79433	1500
	50	6571	22	0641	14	20	0	64	11	77933	1448
5	0	− 3 9966549	23	− 1 9970656	15	− 8 38120	0	0 29975	11	0 76485	1399
	10	6526	23	0671	15	20	0	87	12	75086	1352
	20	6503	24	0687	16	20	0	98	11	73734	1309
	30	6479	25	0703	16	19	1	0·30010	12	72425	1269
	40	6454	26	0719	16	19	0	23	13	71156	1230
	50	6428	26	0736	17	19	0	36	13	69926	1194
6	0	− 3 9966402	27	− 1 9970754	18	− 8·38119	0	0 30049	13	0 68732	1160
	10	6375	28	0772	18	18	1	63	14	67572	1127
	20	6347	29	0791	19	18	0	77	14	66445	1096
	30	6318	29	0810	19	18	0	91	14	65349	1067
	40	6289	29	0829	19	17	1	0 30106	15	64282	1039
	50	6259	30	0849	20	17	0	21	15	63243	1013
			31		21		0		16		

Terrestrial Latitudes, Longitudes, and Reverse Azimuths

Lati tude	P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
7 0	− 3 [illegible]	31	− 1 [illegible]	21	− 8 38117	1	0 30137	16	0 6°230	986
10	[illegible]	31	[illegible]	21	16	0	53	16	61244	963
20	[illegible]	32	[illegible]	22	16	0	69	16	60281	939
30	[illegible]	33	[illegible]	23	16	1	85	18	59342	917
40	[illegible]	34	[illegible]	22	15	0	30103	17	58425	896
50	[illegible]	34	[illegible]	24	15	0	20	18	57529	875
8 0	− 3 [illegible]	36	− 1 [illegible]	24	− 8 38115	1	0 30138	18	0 56654	856
10	[illegible]	36	[illegible]	24	14	0	56	18	55798	837
20	[illegible]	37	[illegible]	24	14	0	74	19	54961	819
30	[illegible]	37	[illegible]	25	14	0	93	19	54142	801
40	[illegible]	38	[illegible]	25	13	1	30313	20	53341	784
50	[illegible]	39	[illegible]	26	13	0	32	19	52557	769
9 0	− 3 [illegible]	39	− 1 [illegible]	26	− 8 38113	0	0 30351	21	0 51788	752
10	[illegible]	40	[illegible]	27	12	1	373	20	51036	737
20	[illegible]	41	[illegible]	27	12	0	394	21	50299	723
30	[illegible]	41	[illegible]	28	11	1	415	21	49576	709
40	[illegible]	43	[illegible]	28	11	0	437	22	48867	695
50	[illegible]	43	[illegible]	29	10	1	459	22	48172	682
10 0	− 3 [illegible]	43	− 1 [illegible]	29	− 8 38110	0	0 30481	22	0 47490	669
10	[illegible]	45	[illegible]	29	10	0	504	23	46821	656
20	[illegible]	45	[illegible]	31	09	1	527	23	46165	645
30	[illegible]	45	[illegible]	31	09	0	550	24	45520	633
40	[illegible]	47	[illegible]	31	08	1	574	23	44887	621
50	[illegible]	47	[illegible]	31	08	0	599	24	44266	611
11 0	− 3 [illegible]	48	− 1 [illegible]	32	− 8 38107	0	0 30623	24	0 43655	600
10	[illegible]	48	[illegible]	32	07	1	648	26	43055	589
20	[illegible]	49	[illegible]	33	06	0	674	26	42466	579
30	[illegible]	50	[illegible]	33	06	1	700	26	41887	570
40	[illegible]	51	[illegible]	34	05	0	726	27	41317	560
50	[illegible]	51	[illegible]	34	05	1	753	27	40757	550

(5455)

TABLE I.—Logarithms for facilitating the Computation of

Latitude		P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
°	′										
		−		−		−					
12	0	3 9964974		1 9971706		8·38104		0 30780		0 40207	
			53		35		0		27		542
	10	4921		1741		04		807		39665	
			53		36		1		28		532
	20	4868		1777		03		835		39133	
			54		36		0		28		524
	30	4814		1813		03		863		38609	
			55		36		1		29		516
	40	4759		1849		02		892		38093	
			55		37		0		28		507
	50	4704		1886		02		920		37586	
			56		37		1		30		500
		−		−		−					
13	0	3 9964648		1 9971923		8 38101		0 30950		0 37086	
			57		38		1		30		492
	10	4591		1961		00		980		36594	
			57		39		0		30		484
	20	4534		2000		00		0 31010		36110	
			58		38		1		30		477
	30	4476		2038		8 38099		040		35633	
			59		39		0		31		469
	40	4417		2077		99		071		35164	
			60		40		1		31		462
	50	4357		2117		98		102		34702	
			60		40		1		32		455
		−		−		−					
14	0	3·9964297		1·9972157		8 38097		0 31134		0 34247	
			60		40		0		32		448
	10	4237		2197		97		166		33799	
			62		41		1		33		442
	20	4175		2238		96		199		33357	
			62		42		0		33		435
	30	4113		2280		96		232		32922	
			62		41		1		33		429
	40	4051		2321		95		265		32493	
			64		43		1		34		422
	50	3987		2364		94		299		32071	
			64		42		0		34		416
		−		−		−					
15	0	3 9963923		1·9972406		8 38094		0 31333		0 31655	
			64		44		1		34		410
	10	3859		2450		93		367		31245	
			66		43		1		35		404
	20	3793		2493		92		402		30841	
			66		44		0		35		399
	30	3727		2537		92		437		30442	
			66		44		1		36		393
	40	3661		2581		91		473		30049	
			67		45		1		36		388
	50	3594		2626		90		509		29661	
			68		45		0		37		383
		−		−		−					
16	0	3·9963526		1·9972671		8 38090		0 31546		0 29278	
			69		46		1		37		377
	10	3457		2717		89		582		28901	
			69		46		1		38		371
	20	3388		2763		88		620		28530	
			70		47		0		37		367
	30	3318		2810		88		657		28163	
			70		46		1		38		361
	40	3248		2856		87		695		27802	
			71		48		1		39		357
	50	3177		2904		86		734		27445	
			72		48		0		39		351

Terrestrial Latitudes, Longitudes, and Reverse Azimuths

Latitude		P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
		−		−		−					
17	0	3 [illegible]		1 [illegible]		8 38086		0 31773		0 27094	
			72		48		1		39		347
	10	[illegible]		[illegible]		85		812		26747	
			73		48		1		40		342
	20	[illegible]		[illegible]		84		852		26405	
			73		49		1		40		338
	30	2887		3097		83		892	41	26067	333
			74		50		0				
	40	2813		3147		83		933	40	25734	
			75		50		1				329
	50	2738		3197		82		973		25405	
		−	76	−	50	−	1		42		324
18	0	3 [illegible] 2663		1 [illegible] 3247		8 38081		0 32015		0 25081	
			76		50		1		42		320
	10	2 [illegible] 87		3297		80		057		24761	
			77		51		0		42		316
	20	2510		3348		80		099		24445	
			77		52		1		42		312
	30	2433		3400		79		141	43	24133	
			78		52		1				307
	40	[illegible]355		34 2		78		184		23826	
			78		52		1		44		304
	50	2277		3504		77		228		23522	
			79	−	52	−	1		44		300
19	0	3 [illegible]2198		1 9973556		8 38076		0 32272		0 23222	
			80		54		0		44		295
	10	2118		3610		76		316		22927	
			80		53		1		44		292
	20	2038		3663		75		360		22635	
			80		54		1		45		289
	30	1958		3717		74		405		22346	
			82		54		1		46		284
	40	1876		3771		73		451		22062	
			81		55		1		46		281
	50	1795		3826		72		497		21781	
		−	83	−	54	−	0		46		278
20	0	3 9961712		1 9973880		8 38072		0 32543		0 21503	
			83		56		1		47		273
	10	1629		3936		71		590		21230	
			83		56		1		47		271
	20	1546		3992		70		637		20959	
			85		56		1		48		267
	30	1461		4048		69		685		20692	
			84		56		1		48		263
	40	1377		4104		68		733		20429	
			80		57		1		48		261
	50	1291		4161		67		781		20168	
		−	85	−	57	−	0		49		257
21	0	3 9961206		1 9974218		8 38067		0 32830		0 19911	
			87		58		1		49		253
	10	1119		4276		66		879		19658	
			87		58		1		50		251
	20	1032		4334		65		929		19407	
			87		58		1		50		248
	30	0945		4392		64		979		19159	
			88		59		1		51		244
	40	0857		4451		65		0 33030		18915	
			89		59		1		51		242
	50	0768		4510		62		081		18673	
			89		59		1		51		239

TABLE I.—Logarithms for facilitating the Computation of

Latitude	P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
° ′										
22 0	− 3 9930679		− 1 9974569		− 8 38061		0 33132		0 18434	
		90		60		1		52		235
10	0589		4629		60		184		18199	
		90		60		0		52		233
20	0499		4689		60		236		17966	
		91		61		1		53		230
30	0408		4750		59		289		17736	
		91		60		1		53		226
40	0317		4810		58		342		17510	
		92		62		1		54		225
50	0225		4872		57		396		17285	
		92		61		1		54		221
23 0	− 3 9960133		− 1 9974933		− 8 38056		0 33450		0 17064	
		93		62		1		54		219
10	0040		4995		55		504		16845	
		93		62		1		55		216
20	− 3 9959947		5057		54		559		16629	
		94		63		1		55		213
30	9853		5120		53		614		16416	
		94		63		1		56		211
40	9759		5183		52		670		16205	
		95		63		1		56		208
50	9664		5246		51		726		15997	
		96		64		1		57		205
24 0	− 3 9959568		− 1 9975310		− 8 38050		0 33783		0 15792	
		96		64		1		57		204
10	9472		5374		49		840		15588	
		96		64		1		58		200
20	9376		5438		48		898		15388	
		97		64		1		58		199
30	9279		5502		47		956		15189	
		97		65		1		58		195
40	9182		5567		46		0 34014		14994	
		98		66		1		59		194
50	9084		5633		45		073		14800	
		99		65		1		59		191
25 0	− 3 9958985		− 1 9975698		− 8 38044		0 34132		0 14609	
		98		66		1		60		189
10	8887		5764		43		192		14420	
		100		66		1		61		187
20	8787		5830		42		252		14233	
		100		67		1		61		184
30	8687		5897		41		313		14049	
		100		67		1		61		182
40	8587		5964		40		374		13867	
		101		67		1		62		180
50	8486		6031		39		436		13687	
		101		67		1		62		178
26 0	− 3 9958385		− 1 9976098		− 8 38038		0 34498		0 13509	
		102		68		1		62		175
10	8283		6166		37		560		13334	
		102		68		1		63		174
20	8181		6234		36		623		13160	
		102		69		1		64		172
30	8079		6303		35		687		12988	
		103		68		1		64		169
40	7976		6371		34		751		12819	
		104		69		1		64		167
50	7872		6440		33		815		12652	
		104		70		1		65		166

Terrestrial Latitudes, Longitudes, and Reverse Azimuths.

Latitude		P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
	′										
27	0	− 3 2957768		− 1 9976510		− 8 38032		0 31880		0 12486	
			104		69		1		65		163
	10	7664		6579		31		945		12323	
			105		70		1		66		162
	20	7559		6648		30		0 31011		12161	
			105		70		1		66		160
	30	7454		6719		29		077		12001	
			106		71		1		67		158
	40	7348		6790		28		144		11843	
			105		71		1		67		155
	50	7242		6861		27		211		11688	
			107		71		1		68		154
28	0	− 3 9357135		− 1 9976932		− 8 38026		0 31279		0 11534	
			107		71		1		68		152
	10	7028		7003		25		317		11382	
			107		71		1		69		151
	20	6921		7074		24		416		11231	
			108		72		1		69		148
	30	6813		7146		23		485		11083	
			108		72		1		69		147
	40	6705		7218		22		554		10936	
			109		73		2		70		145
	50	6596		7291		20		624		10791	
			109		73		1		71		143
29	0	− 3 9356487		− 1 9977364		− 8 38019		0 35695		0 10648	
			109		72		1		71		141
	10	6378		7436		18		766		10507	
			110		74		1		71		140
	20	6268		7510		17		837		10367	
			110		73		1		72		138
	30	6158		7583		16		909		10229	
			111		74		1		73		137
	40	6047		7657		15		982		10092	
			111		74		1		73		134
	50	5936		7731		14		0 36055		09958	
			111		74		1		73		134
30	0	− 3 9355825		− 1 9977805		− 8 38013		0 36128		0 09824	
			112		75		1		74		131
	10	5713		7889		12		202		09693	
			112		74		1		74		130
	20	5601		7964		11		276		09563	
			112		75		2		75		129
	30	5489		8039		09		351		09434	
			113		76		1		76		127
	40	5376		8115		08		427		09307	
			113		75		1		76		125
	50	5263		8189		07		503		09182	
			114		76		1		76		124
31	0	− 3 9355149		− 1 9978256		− 8 38006		0 36579		0 09058	
			114		76		1		77		123
	10	5035		8332		05		656		08935	
			114		76		1		77		121
	20	4921		8408		04		733		08814	
			115		76		1		78		119
	30	4808		8484		03		811		08695	
			115		77		2		79		118
	40	4694		8561		01		890		08577	
			115		77		1		79		117
	50	4579		8638		00		969		08460	
			115		77		1		79		116

TABLE I.—Logarithms for facilitating the Computation of

Latitude	P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
° ′										
	−		−		−					
32 0	3 9954461		1 9978715		8 37999		0·37048		0 08344	
		116		77		1		80		114
10	4345		8792		98		128		08230	
		117		78		1		81		113
20	4228		8870		97		209		08117	
		116		77		1		81		111
30	4112		8947		96		290		08006	
		117		78		2		81		110
40	3995		9025		94		371		07896	
		117		78		1		82		108
50	3878		9103		93		453		07788	
		118		79		1		83		107
33 0	3 9953760		1 9979182		8 37992		0·37536		0·07681	
		118		78		1		83		106
10	3642		9260		91		619		07575	
		118		79		1		83		105
20	3524		9339		90		702		07470	
		118		79		1		85		104
30	3406		9418		89		787		07366	
		119		79		2		84		102
40	3287		9497		87		871		07264	
		119		80		1		85		101
50	3168		9577		86		956		07163	
	−	119	−	79	−	1		86		99
34 0	3 9953049		1 9979656		8 37985		0 38042		0 07064	
		120		80		1		86		99
10	2929		9736		84		128		06965	
		120		80		1		87		97
20	2809		9816		83		215		06868	
		120		80		2		88		96
30	2689		9896		81		303		06772	
		121		80		1		87		95
40	2568		9976		80		390		06677	
	−	120	−	81	−	1		89		94
50	2448		1 9980057		79		479		06583	
	−	121	−	80	−	1		89		93
35 0	3 9952327		1 9980137		8 37978		0 38568		0 06490	
		121		81		1		89		91
10	2206		0218		77		657		06399	
		122		81		2		91		91
20	2084		0299		75		748		06308	
		122		81		1		90		89
30	1962		0380		74		838		06219	
		122		82		1		91		88
40	1840		0462		73		929		06131	
		122		81		1		92		87
50	1718		0543		72		0 39021		06044	
	−	122	−	82	−	2		92		86
36 0	3 9951596		1 9980625		8 37970		0 39113		0·05958	
		123		82		1		93		85
10	1473		0707		69		205		05873	
		123		82		1		94		84
20	1350		0789		68		301		05789	
		123		82		1		94		83
30	1227		0871		67		394		05706	
		123		82		1		94		82
40	1104		0953		66		488		05624	
		124		82		2		99		81
50	0980		1035		64		584		05543	
		124		83		1		95		80

Terrestrial Latitudes, Longitudes, and Reverse Azimuths.

Latitude.	P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff. −
° ′										
37 0	− 3·9958[illegible]		− 1·9981118		− 8·37983		0·39679		0·03463	
		124		82		1		97		79
10	0732		1200		62		776		03384	
		124		84		1		96		78
20	0608		1283		61		872		03306	
		124		83		2		98		77
30	0484		1366		59		970		03229	
		125		83		1		98		76
40	0359		1449		58		0·40068		03153	
		125		83		1		99		75
50	0234		1532		57		167		03078	
		125		84		1		99		75
38 0	− 3·9950109		− 1·9981616		− 8·37956		0·40266		0·03003	
		125		83		2		100		74
10	− 3·9949984		1699		54		366		04929	
		125		84		1		100		72
20	9859		1783		53		466		04857	
		126		83		1		101		71
30	9733		1866		52		567		04786	
		126		84		1		102		71
40	9607		1950		51		669		04715	
		126		84		2		102		70
50	9482		2034		49		771		04645	
		126		84		1		103		68
39 0	− 3·9949356		− 1·9982118		− 8 37948		0·40874		0·04577	
		127		84		1		103		68
10	9229		2202		47		977		04509	
		126		85		1		104		67
20	9103		2287		46		0·41081		04442	
		126		84		2		105		67
30	8977		2371		44		186		04375	
		127		84		1		105		65
40	8850		2455		43		291		04310	
		127		85		1		106		65
50	8723		2540		42		397		04245	
		127		84		2		107		63
40 0	− 3·9948596		− 1·9982624		− 8 37940		0·41504		0·04182	
		127		85		1		107		63
10	8469		2709		39		611		04119	
		127		85		1		108		62
20	8342		2794		38		719		04057	
		127		85		1		108		61
30	8215		2879		37		827		03996	
		126		85		2		109		61
40	8087		2964		35		936		03935	
		127		85		1		110		60
50	7960		3049		34		0 42046		03875	
		128		85		1		110		59
41 0	− 3·9947832		− 1 9983134		− 8 37933		0 12156		0·03816	
		128		85		1		111		59
10	7704		3219		32		267		03757	
		127		85		2		112		58
20	7577		3304		30		379		03699	
		128		86		1		112		57
30	7449		3390		29		491		03642	
		128		85		1		113		56
40	7321		3475		28		604		03586	
		129		85		2		114		55
50	7192		3560		26		718		03531	
		128		86		1		114		54

TABLE I.—Logarithms for facilitating the Computation of

Latitude	P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
° ′										
	−		−		−					
42 0	3 9947064		1 9983646		8 37925		0 42832		0 03477	
		128		85		1		116		54
10	6936		3731		24		917		03423	
		129		86		2		116		53
20	6807		3817		22		0 43063		03370	
		128		85		1		116		53
30	6679		3902		21		179		03317	
		128		86		1		117		52
40	6551		3988		20		296		03265	
		129		86		1		118		51
50	6422		4074		19		414		03214	
		129		86		2		118		50
43 0	− 3 9946293		− 1 9984160		− 8 37917		0 43532		0 03164	
		128		85		1		119		50
10	6165		4245		16		651		03114	
		129		86		1		120		49
20	6036		4331		15		771		03065	
		129		86		1		120		49
30	5907		4417		14		891		03016	
		129		86		2		121		48
40	5778		4503		12		0 44012		02968	
		129		86		1		122		47
50	5649		4589		11		134		02921	
		129		86		1		122		47
44 0	− 3 9945520		− 1 9984675		− 8 37910		0 44256		0 02874	
		128		86		2		124		46
10	5392		4761		08		380		02828	
		129		86		1		123		45
20	5263		4847		07		503		02783	
		129		86		1		125		45
30	5134		4933		06		628		02738	
		129		86		1		125		44
40	5005		5019		05		753		02694	
		129		86		2		126		44
50	4876		5105		03		879		02650	
		129		86		1		127		44
45 0	− 3 9944747		− 1 9985191		− 8 37902		0 45006		0 02606	
		129		86		1		128		43
10	4618		5277		01		134		02563	
		129		86		2		128		42
20	4489		5363		− 8 37899		262		02521	
		129		86		1		129		41
30	4360		5449		98		391		02480	
		129		86		1		130		40
40	4231		5535		97		521		02440	
		129		86		2		131		40
50	4102		5621		95		652		02400	
		129		86		1		131		39
46 0	− 3 9943973		− 1 9985707		− 8 37894		0 45783		0 02361	
		129		86		1		132		39
10	3844		5793		93		915		02322	
		129		86		1		133		39
20	3715		5879		92		0 46048		02283	
		129		86		2		133		38
30	3586		5965		90		181		02245	
		129		86		1		135		38
40	3457		6050		89		316		02207	
		129		86		1		135		37
50	3328		6136		88		451		02170	
		129		86		2		136		37

Terrestrial Latitudes, Longitudes, and Reverse Azimuths.

Latitude		P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
°	′										
		−		−		−					
47	0	3 9913189		1 0086222		8 37886		0 46387		0 02133	
			128		81		1		137		36
	10	3171		6348		85		724		02097	
			129		80		1		137		36
	20	2842		6344		84		861		02061	
			128		83		1		138		35
	30	2514		6479		83		999		02026	
			129		86		2		140		34
	40	2185		6565		81		0 47139		01992	
			128		86		1		140		34
	50	2557		6651		80		279		01958	
			129		83		1		140		33
		−		−		−					
48	0	3 9912428		1 0086736		8 37879		0 47419		0 01925	
			128		80		2		142		33
	10	2301		6822		77		561		01892	
			128		83		1		142		33
	20	2172		6907		76		703		01859	
			129		86		1		143		32
	30	2043		6993		75		846		01827	
			128		85		1		145		31
	40	1915		7078		74		991		01796	
			128		86		2		144		31
	50	1787		7164		72		0 48135		01765	
			127		85		1		146		30
		−		−		−					
49	0	3 9911660		1 0087249		8 37871		0 48281		0 01735	
			128		85		1		147		31
	10	1532		7334		70		428		704	
			128		85		1		147		31
	20	1404		7419		69		575		673	
			127		85		2		149		30
	30	1277		7504		67		724		643	
			128		85		1		149		29
	40	1149		7589		66		873		614	
			127		87		1		150		29
	50	1022		7674		65		0 49023		585	
			127		85		2		151		29
		−		−		−					
50	0	3 9910895		1 0087759		8 37863		0 49174		0 01556	
			127		85		1		152		28
	10	0768		7844		62		326		528	
			127		84		1		152		27
	20	0641		7928		61		478		501	
			127		85		1		154		27
	30	0514		8013		60		632		474	
			127		84		2		155		27
	40	0387		8097		58		787		447	
			126		84		1		155		26
	50	0261		8181		57		942		421	
			127		84		1		156		26
		−		−		−					
51	0	3 9910134		1 0088266		8 37856		0 50098		0 01395	
			126		84		1		158		26
	10	0008		8350		55		256		369	
		−	126		84		2		158		25
	20	3 9909882		8434		53		414		344	
			126		84		1		159		25
	30	9756		8518		52		573		319	
			126		84		1		160		24
	40	9630		8602		51		733		295	
			125		83		2		161		24
	50	9505		8685		49		894		271	
			125		84		1		162		24

TABLE I.—Logarithms for facilitating the Computation of

Latitude		P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
°	′										
		−		−		−					
52	0	3 9939380		1 9989769		8 37848		0 51056		0 01247	
			126		83		1		163		24
	10	9254		8852		47		219		223	
			125		84		1		164		23
	20	9129		8936		46		383		200	
			124		83		1		165		23
	30	9005		9019		45		548		177	
			125		83		2		166		22
	40	8880		9102		43		714		155	
			125		83		1		167		22
	50	8755		9185		42		881		133	
			124		83		1		168		21
		−		−		−					
53	0	3 9938631		1 9989268		8 37841		0 52049		0 01112	
			124		82		1		169		22
	10	8507		9350		40		218		090	
			124		83		2		170		21
	20	8383		9433		38		388		069	
			123		82		1		171		21
	30	8260		9515		37		559		048	
			124		83		1		172		20
	40	8136		9598		36		731		028	
			123		82		1		174		20
	50	8013		9680		35		905		008	
			122		82		2		174		19
		−		−		−					
54	0	3 9937890		1 9989762		8 37833		0 53079		0 00989	
			122		82		1		175		20
	10	7768		9844		32		254		969	
			123		81		1		176		19
	20	7645		9925		31		430		950	
			122		82		1		178		19
	30	7523		0007		30		608		931	
			122		81		1		178		18
	40	7401		0088		29		786		913	
			122		81		2		180		18
	0	7279		0169		27		966		895	
			121		81		1		180		17
		−		−		−					
55	0	3 9937159		1 9990250		8 37826		0 54146		0 00878	
			122		81		1		182		18
	10	7036		0331		25		328		860	
			121		81		1		183		18
	20	6915		0412		24		511		842	
			120		80		2		184		17
	30	6795		0492		22		695		825	
			121		80		1		185		17
	40	6674		0572		21		880		808	
			120		81		1		187		16
	50	6554		0653		20		0 55067		792	
			120		80		1		187		16
		−		−		−					
56		3 9936434		1 9990733		8 37819		0 55254		0 00776	
			120		79		1		189		16
	10	6314		0812		18		443		760	
			119		80		2		190		16
	20	6195		0892		16		633		744	
			119		79		1		191		16
	30	6076		0971		15		824		728	
			119		79		1		192		15
	40	5957		1050		14		0 56016		713	
			118		79		1		193		15
	50	5839		1129		13		209		698	
			118		79		1		195		14

Terrestrial Latitudes, Longitudes and Reverse Azimuths

Latitude	P	Diff −	Q	Diff +	R	Diff −	S	Diff +	T	Diff −
57 0	− 3 4935721	118	− 1 4991208	79	− 8 37812	1	0 56104	199	0 00684	15
10	7603	118	1287	78	11	2	603	197	669	14
20	5485	117	1365	78	09	1	797	199	655	14
30	5368	117	1443	78	08	1	996	199	641	14
40	5251	117	1521	78	07	1	0 57195	201	627	13
50	5134	116	1599	78	06	1	396	203	614	13
58 0	− 3 4935018	116	− 1 4991677	77	− 8 37805	1	0 57599	203	0 00601	13
10	4902	116	1754	77	04	2	802	205	588	13
20	478	115	1831	77	02	1	0 58007	207	575	13
30	4671	115	1908	76	01	1	214	207	562	12
40	4556	114	1984	77	00	1	421	209	550	12
50	4442	115	2061	76	− 8 37799	1	630	210	538	12
59 0	− 3 4934327	114	− 1 4992137	76	− 8 37798	1	0 58840	212	0 00526	12
10	4213	113	2213	76	97	1	0 59052	213	514	12
20	4100	113	2289	75	96	2	263	215	502	12
30	3987	113	2364	75	94	1	450	216	490	11
40	3874	113	2439	75	93	1	696	217	479	11
50	3761	112	2514	75	92	1	913	219	468	10
60 0	− 3 4933649		− 1 4992589		− 8 37791		0 60132		0 00458	

TABLE II (A)

Directions for applying the signs to the terms of the Latitude, Longitude, and Azimuth formulæ, when the fixed station A lies North of the Equator

The Azimuth is reckoned from South by West The Latitude North, and Longitude East, should always be considered *positive*

Terms of the Formulæ	Magnitude of the given Azimuth A			
	0 to 90°	90 to 180°	180 to 270	270° to 360°
$\delta_1\lambda$	−	+	+	−
$\delta_1 L$	−	−	+	+
$\delta_1 A$	−	−	+	+
$\delta\lambda$	−	−	−	−
$\delta_2 L$	+	−	+	−
δA	+	−	+	−

For use in Distance and Azimuth Computation —

$A + \frac{\Delta A}{2}$ is in	1st	2nd	3rd	4th Quadrant
when $\frac{\Delta\lambda}{\Delta L}$ are	$\frac{-}{-}$	$\frac{+}{-}$	$\frac{+}{+}$	$\frac{-}{+}$

TABLE II (I)

Directions for applying the signs to the terms of the Latitude, Longitude, and Azimuth formulæ, when the fixed station A lies to the South of the Equator.

The Latitude South, and the Longitude East, should be considered *positive*

Terms of the Formulæ	Magnitude of the given Azimuth A			
	0 to 90	90 to 180	180° to 270	270 to 360
$\delta_1\lambda$	+	−	−	+
δL	−	−	+	+
$\delta_1 A$	+	+	−	−
$\delta\lambda$	−	−	−	−
δL	−	+	−	+
δA	+	−	+	−

For use in Distance and Azimuth Computation —

$A + \frac{\Delta A}{2}$ is in	1st	2nd	3rd	4th Quadrant
when $\frac{\Delta\lambda}{\Delta L}$ are	$\frac{+}{-}$	$\frac{-}{-}$	$\frac{-}{+}$	$\frac{+}{+}$

TABLE III

Computation of Heights from Vertical Angles

Initial K, to be Used in Computing Heights when only One Angle has been Observed

Distance between Stations in feet	K
1 000	0 4
2 000	0 9
3 000	0 13
4 000	0 17
5 000	0 21
6 000	0 26
7 000	0 30
8 000	0 34
9 000	0 38
10 000	0 43
20 000	1 25
30 000	2 8
40 000	2 50
50 000	3 33
60 000	4 15
70 000	4 58
80 000	5 40
90 000	6 23
100 000	7 5

The value of the coefficient of refraction has been found on the average to be about 07 It is with this value that the above table has been computed

TABLE IV

Computation of Heights

To facilitate finding the Subtended Angle when only one Angle has been observed

Latitude	Adopted Refraction Expressed in Decimals of Contained Arc								
	0 10	0 09	0 08	0 07	0 06	0 05	0 04	0 03
°								
0	2 5276	2 4027	2 3020	2 3815	2 3713	2 3613	2 3515	2 3420	2 3327
5	5277	4027	3920	3815	3713	3613	3516	3420	3327
10	5277	4028	3921	3816	3714	3614	3516	3421	3327
15	5278	4029	3922	3817	3715	3615	3517	3422	3328
20	5280	4030	3923	3818	3716	3616	3519	3423	3330
25	5281	4032	3925	3820	3718	3618	3521	3425	3332
30	5284	4034	3927	3822	3720	3620	3523	3427	3334
35	5286	4036	3929	3825	3722	3623	3525	3429	3336
40	5288	4039	3932	3827	3725	3625	3527	3432	3338
45	5291	4042	3935	3830	3728	3628	3530	3435	3342
50	5294	4045	3937	3833	3731	3631	3533	3438	3344
55	5297	4047	3940	3835	3733	3633	3536	3440	3347
60	5299	4049	3942	3838	3736	3636	3538	3442	3349

Note —If nothing is known of the Refraction, adopt 0 07 as the value of it

TABLES V. and VI.

For Determining Differences of Height with the Barometer.

(Baily.)

TABLE V.—Part I. Thermometers in the Open Air in Degrees Fahrenheit

$t + t'$	A	$t + t'$	A	$t + t'$	A
1	4·74[illegible]13	6	4·7[illegible]113	130	4·[illegible]113
5	4·73[illegible]91	70	[illegible]53	135	[illegible]32
10	[illegible]37	75	[illegible]02	140	[illegible]12
15	[illegible]83	80	[illegible]51	145	[illegible]97
20	[illegible]26	85	4·74[illegible]0	150	4·[illegible]87
25	4·70141	90	[illegible]01	155	[illegible]45
30	[illegible]82	95	[illegible]35	160	[illegible]56
35	[illegible]42	100	[illegible]72	165	[illegible]64
40	[illegible]01	105	[illegible]08	170	[illegible]90
45	4·77138	110	4·[illegible]39	175	4·[illegible]115
50	[illegible]74	115	[illegible]65	180	[illegible]39
55	[illegible]09	120	[illegible]86		
60	[illegible]71	125	913		

Part II. Attached Thermometers (not required with aneroid)

$t - t'$	B	$t - t'$	B	$t - t'$	B
0	0·0000	25	0·0109	50	0·0217
5	[illegible]12	30	130	55	[illegible]39
10	[illegible]43	35	152	60	239
15	[illegible]65	40	174		
20	[illegible]87	45	196		

TABLE VI.—Latitude of the place.

Lat	C	Lat	C	Lat	C
0	0·00117	35	0·00140	70	1·00010
5	115	40	29	75	01
10	119	45	0·00000	80	1·00009
15	101	50	1·00060	85	05
20	90	55	60	90	03
25	75	60	42		
30	56	65	25		

Tables V and VI (*continued*)

If β be the reading of barometer at lower station

β' " " " upper "

t " detached thermometer in air at lower station

t' " " " " upper "

τ " attached " " lower "

τ' " " " " upper "

A, the number in the table corresponding to $t + t'$

B, " " " $t - t'$

Make $D = \log \beta - (\log \beta' + B)$

then

$\log D + A + C = \log$ of the difference in altitude

Example.—In lat 51° 30 the barometer at upper station read 25 55 in and 29 81 at lower station The readings of the detached thermometers were 50° 5 and 63 , and those of the attached thermometers 52 and 62° at the upper and lower stations respectively What was the difference of altitude?

Log 29 81	−	1 47436
− Log 25 55	−	1 40739
B	−	0 00013
D		0 06684
Log D		2 82308
A		1 80389
C		1 99973
Log l	−	3 62670

l − 4234 feet the required difference

NOTE.—In the case of metals the term B is 0 as they are compensated for change of temperature of the *instrument* The term A, however, which depends on the *air* temperatures, must always be included in the computation

TABLES VII and VIII

For Determining Heights with the Boiling Point Thermometer

TABLE VII

Approximate Height* in feet Corresponding to the Observed Boiling Point in Degrees Fahrenheit and Corresponding Barometer Readings

Boiling Point	Barometer Reading	Approximate Height	Boiling Point	Barometer Reading	Approximate Height
°			°		
212	29 021	—	195	21 133	9 084
211	29 329	522	194	20 690	9 638
210	28 746	1 046	193	20 2o5	10 193
209	28 174	1 571	192	19 828	10 750
208	27 613	2 097	191	19 409	11 307
207	27 062	2 624	190	18 998	11 867
206	26 521	3 151	189	18 59o	12 42C
205	2o 989	3 680	188	18 199	12 988
204	25 466	4 210	187	17 809	13 5o6
203	24 9C2	4 741	186	17 426	14 124
202	24 447	5 278	185	17 050	14 694
201	23 9o0	5 815	184	16 681	15 266
200	23 461	6 3o4	183	16 319	15 839
199	2_ 980	6 89o	182	15 964	16 412
198	22 507	7 439	181	15 616	16 987
197	22 042	7 984	180	15 275	17 5C4
196	21 584	8 533			

* Accurately—this table gives the altitude above level at which water boils at 212° temperature of intermediate air being 32° F

TABLE VIII

Correction for Temperature of Intermediate Air			
Mean Temperature	Multiplier	Mean Temperature	Multiplier
°		°	
20	0 97o	55	1 048
2o	0 98o	60	1 o58
30	0 996	6o	1 069
3o	1 00C	70	1 079
40	1 017	7o	1 090
45	1 027	80	1 100
50	1 038	8o	1 110

Example.—The boiling point at upper station was 204° 2 and at lower station 208° 7, and the respective air temperatures were 75 and 83°

Tabular number for 204 2 = 4107
208 7 = 1726

2381

Temperature at upper station, 75
lower " 83

Mean temperature 79, multiplier, 1 1044

And difference of height = 2381 × 1 044 = 2628 feet

BLE IX.—Graticules of Maps. Sides and Diagonals of Squares of a quarter of a degree of Lat. and Long. on the scale of 1 inch to 2 miles

Latitude	Length in Inches			
	m on meridian	n on lower parallel	p on upper parallel	q on diagonal
	$\frac{\pi}{180} \times \frac{\rho}{\nu \cdot 80}$	$\frac{1}{4} \times \frac{\pi}{180} \times 4 \times \frac{\rho \cos \lambda}{\nu \cdot 80}$		$\sqrt{m^2 + p^2}$
From 0 0 to 0 1	8 58	8 617	8 617	12 187
0 1 0 30	858	617	616	187
0 30 0 4	858	615	613	18
0 4 1 0	858	614	612	18
1 0 1 1	858	614	610	186
1 1 1 30	858	614	607	18
1 30 1 4	858	614	603	184
1 4 2 0	858	613	601	183
2 0 2 1	8 58	8 611	8 600	12 18
2 1 2 30	858	611	598	181
2 30 2 4	858	608	597	180
2 4 3 0	858	605	593	179
3 0 3 1	858	603	593	178
3 1 3 30	858	600	591	176
3 30 3 4	858	598	588	174
3 4 4 0	858	595	586	173
4 0 4 1	8 58	8 592	8 583	12 171
4 1 4 30	858	589	580	169
4 30 4 4	857	586	577	167
4 4 5 0	857	583	574	166
5 0 5 1	857	580	571	165
5 1 5 30	857	577	567	163
5 30 5 4	857	573	563	162
5 4 6 0	856	570	560	160
6 0 6 1	8 856	8 566	8 553	12 158
6 1 6 30	856	563	551	156
6 30 6 4	856	559	547	154
6 4 7 0	856	556	543	153
7 0 7 1	855	552	538	151
7 1 7 30	855	548	534	150
7 30 7 4	854	544	530	148
7 4 8 0	854	540	526	147
8 0 8 1	8 853	8 536	8 522	12 145
8 1 8 30	853	532	518	144
8 30 8 4	852	528	514	142
8 4 9 0	852	524	510	141
9 0 9 1	851	520	506	139
9 1 9 30	851	516	502	138
9 30 9 4	850	512	498	137
9 4 10 0	850	508	494	135
10 0 10 1	8 849	8 504	8 490	12 134
10 1 10 30	849	500	486	133
10 30 10 4	848	496	482	131
10 4 11 0	848	492	478	130
11 0 11 1	847	488	474	129
11 1 11 30	847	484	470	128
11 30 11 4	846	480	466	127
11 4 12 0	846	476	462	126

TABLE IX.—Graticules of Maps. Sides and Diagonals of Squares of

Latitude.	Length in Inches.			
	m on meridian	n on lower parallel.	p on upper parallel	q on diagonal
° ′ ° ′				
From 12 0 to 12 15	8·592	8·459	8·451	12·054
12 15 „ 12 30	592	451	443	049
12 30 „ 12 45	592	443	435	043
12 45 „ 13 0	592	435	426	037
13 0 „ 13 15	592	426	418	031
13 15 „ 13 30	593	418	409	026
13 30 „ 13 45	593	409	400	020
13 45 „ 14 0	593	400	391	014
14 0 „ 14 15	8 593	8 391	8 382	12·007
14 15 „ 14 30	593	382	373	001
14 30 „ 14 45	594	373	364	11·995
14 45 „ 15 0	594	364	354	989
15 0 „ 15 15	594	354	344	982
15 15 „ 15 30	594	344	334	974
15 30 „ 15 45	594	334	324	968
15 45 „ 16 0	595	324	314	962
16 0 „ 16 15	8·595	8·314	8 303	11·954
15 15 „ 16 30	595	303	293	947
16 30 „ 16 45	595	293	282	940
16 45 „ 17 0	595	282	271	932
17 0 „ 17 15	596	271	260	925
17 15 „ 17 30	596	260	249	918
17 30 „ 17 45	596	249	238	910
17 45 „ 18 0	596	238	226	902
18 0 „ 18 15	8 596	8·226	8·214	11·894
18 15 „ 18 30	597	214	203	886
18 30 „ 18 45	597	203	191	878
18 45 „ 19 0	597	191	179	870
19 0 „ 19 15	597	178	166	861
19 15 „ 19 30	598	166	154	853
19 30 „ 19 45	598	154	141	845
19 45 „ 20 0	598	141	128	836
20 0 „ 20 15	8 598	8·128	8 115	11 827
20 15 „ 20 30	599	115	102	819
20 30 „ 20 45	599	102	089	810
20 45 „ 21 0	599	089	076	801
21 0 „ 21 15	599	076	062	792
21 15 „ 21 30	600	062	049	783
21 30 „ 21 45	600	049	035	774
21 45 „ 22 0	600	035	021	765
22 0 „ 22 15	8·600	8·021	8 007	11·755
22 15 „ 22 30	601	007	7 992	746
22 30 „ 22 45	601	7 992	978	736
22 45 „ 23 0	601	978	963	726
23 0 „ 23 15	601	963	949	716
23 15 „ 23 30	602	949	934	707
23 30 „ 23 45	602	934	919	697
23 45 „ 24 0	602	919	904	687

a quarter of a degree of Lat and Long on the scale of 1 inch to 2 miles

Latitude	Length in Inches			
	m on meridian	n on lower parallel	p on upper parallel	q on diagonal
° °				
From 24 0 to 24 15	8·603	7·904	7·885	11·677
24 15 , 24 30	603	889	873	667
24 30 , 24 45	603	873	857	656
24 45 , 25 0	604	857	841	646
25 0 , 25 15	604	841	825	636
25 15 , 25 30	604	825	809	626
25 30 , 25 45	604	809	793	615
25 45 , 26 0	605	793	777	604
26 0 , 26 15	8·605	7·777	7·760	11·593
26 15 , 26 30	606	760	743	582
26 30 , 26 45	606	743	727	571
26 45 , 27 0	606	727	709	559
27 0 , 27 15	606	709	692	548
27 15 , 27 30	606	692	675	537
27 30 , 27 45	607	675	658	526
27 45 , 28 0	607	658	640	515
28 0 , 28 15	8·607	7·640	7·623	11·503
28 15 , 28 30	608	623	605	492
28 30 , 28 45	608	605	587	480
28 45 , 29 0	608	587	569	468
29 0 , 29 15	609	569	550	457
29 15 , 29 30	609	551	532	445
29 30 , 29 45	609	532	513	433
29 45 , 30 0	610	513	495	421
30 0 , 30 15	8·610	7·495	7·476	11·409
30 15 , 30 30	610	476	457	397
30 30 , 30 45	611	457	438	385
30 45 , 31 0	611	438	419	372
31 0 , 31 15	611	419	399	360
31 15 , 31 30	612	399	379	347
31 30 , 31 45	612	379	360	335
31 45 , 32 0	612	360	340	323
32 0 , 32 15	8·613	7·340	7·320	11·310
32 15 , 32 30	613	320	300	297
32 30 , 32 45	613	300	279	284
32 45 , 33 0	614	279	259	271
33 0 , 33 15	614	259	238	258
33 15 , 33 30	614	238	218	244
33 30 , 33 45	615	218	197	232
33 45 , 34 0	615	197	176	219
34 0 , 34 15	8·616	7·176	7·155	11·206
34 15 , 34 30	616	155	134	193
34 30 , 34 45	616	134	112	179
34 45 , 35 0	617	112	091	166
35 0 , 35 15	617	091	069	153
35 15 , 35 30	617	069	047	139
35 30 , 35 45	618	047	025	126
35 45 , 36 0	618	026	003	113

TABLE IX.—Graticules of Maps. Sides and Diagonals of Squares of

Latitude	Length in Inches			
	m on meridian	n on lower parallel	p on upper parallel	q on diagonal
° ′ ° ′				
From 36 0 to 36 15	8 618	7 003	6 981	11·098
36 15 „ 36 30	619	6 981	959	085
36 30 „ 36 45	619	959	937	071
36 45 „ 37 0	620	937	914	057
37 0 „ 37 15	620	914	891	043
37 15 „ 37 30	620	891	868	029
37 30 „ 37 45	621	868	846	015
37 45 „ 38 0	621	846	822	001
38 0 „ 38 15	8 621	6 822	6 799	10 987
38 15 „ 38 30	622	799	776	973
38 30 „ 38 45	622	776	752	959
38 45 „ 39 0	623	752	729	945
39 0 „ 39 15	623	729	705	930
39 15 „ 39 30	623	705	681	916
39 30 „ 39 45	624	681	657	902
39 45 „ 40 0	624	657	633	887
40 0 „ 40 15	8 625	6 633	6·309	10 873
40 15 „ 40 30	625	609	584	858
40 30 „ 40 45	625	584	560	843
40 45 „ 41 0	626	560	535	829
41 0 „ 41 15	626	535	510	814
41 15 „ 41 30	626	510	486	800
41 30 „ 41 45	627	486	461	785
41 45 „ 42 0	627	461	435	770
42 0 „ 42 15	8 627	6 435	6·410	10 755
42 15 „ 42 30	628	410	385	741
42 30 „ 42 45	628	385	359	726
42 45 „ 43 0	629	359	334	712
43 0 „ 43 15	629	334	308	696
43 15 „ 43 30	629	308	282	681
43 30 „ 43 45	630	282	256	667
43 45 „ 44 0	630	256	230	651
44 0 „ 44 15	8 631	6 230	6 204	10 637
44 15 „ 44 30	631	204	177	621
44 30 „ 44 45	631	177	151	606
44 45 „ 45 0	632	151	124	591
45 0 „ 45 15	632	124	098	576
45 15 „ 45 30	632	098	071	561
45 30 „ 45 45	633	071	044	546
45 45 „ 46 0	633	044	017	531
46 0 „ 46 15	8 634	6 017	5 990	10 516
46 15 „ 46 30	634	5 990	963	501
46 30 „ 46 45	634	963	935	485
46 45 „ 47 0	635	935	908	470
47 0 „ 47 15	635	908	880	455
47 15 „ 47 30	635	880	852	439
47 30 „ 47 45	636	852	824	424
47 45 „ 48 0	636	824	797	409

a quarter of a degree of Lat. and Long on the scale of 1 inch to 2 miles

Latitude				Length in Inches			
				m	n	p	q
				on meridian	on lower parallel	on upper parallel	on diagonal
From	48 0	to	48 15	8·637	5 797	5 769	10 394
	48 15	„	48 30	637	769	743	378
	48 30		48 45	637	743	712	363
	48 45		49 0	638	712	684	348
	49 0	„	49 15	638	684	655	333
	49 15		49 30	639	655	627	318
	49 30		49 45	639	627	598	302
	49 45		50 0	639	598	569	286
	50 0		50 15	8 640	5 569	5 540	10 271
	50 15		50 30	640	540	511	256
	50 30		50 45	640	511	482	240
	50 45		51 0	641	482	453	225
	51 0		51 15	641	453	423	210
	51 15		51 30	642	423	394	195
	51 30		51 45	643	394	364	179
	51 45	„	52 0	643	364	335	164
	52 0		52 15	8 643	5 335	5·305	10 149
	52 15	„	52 30	643	305	275	133
	52 30	„	52 45	644	275	245	118
	52 45		53 0	644	245	215	103
	53 0		53 15	644	215	185	088
	53 15		53 30	645	185	155	073
	53 30		53 45	645	155	124	057
	53 45		54 0	645	124	094	042
	54 0		54 15	8 646	5 094	5 063	10 027
	54 15		54 30	646	063	032	012
	54 30		54 45	646	032	002	9 996
	54 45		55 0	647	002	4 971	981
	55 0		55 15	647	4 971	940	966
	55 15		55 30	647	940	909	951
	55 30		55 45	648	909	878	936
	55 45		56 0	648	878	846	921
	56 0		56 15	8 649	4 846	4 815	9 906
	56 15		56 30	649	815	784	891
	56 30	„	56 45	650	784	752	876
	56 45		57 0	650	752	721	861
	57 0		57 15	650	721	689	847
	57 15		57 30	651	689	657	832
	57 30		57 45	651	657	625	817
	57 45		58 0	651	625	593	802
	58 0		58 15	8 651	4 593	4 561	9 787
	58 15		58 30	652	561	529	773
	58 30		58 45	652	529	497	758
	58 45		59 0	652	497	464	743
	59 0		59 15	653	464	432	729
	59 15	„	59 30	653	432	400	715
	59 30		59 45	653	400	367	700
	59 45		60 0	654	367	334	686

TABLE X.—Length in Miles of

Latitude	Length of 15 of Latitude	Length of 15 of Longitude	Latitude	Length of 15 of Latitude	Length of 15′ of Longitude
° ′			° ′		
0 0 to 0 15	17 176	17 294	16 0 to 16 15	17 190	16 628
1 0 to 1 15	176	·290	17 0 to 17 15	·191	542
2 0 to 2 15	176	·282	18 0 to 18 15	192	452
3 0 to 3 15	176	270	19 0 to 19 15	194	356
4 0 to 4 15	176	252	20 0 to 20 15	196	256
5 0 to 5 15	178	228	21 0 to 21 15	198	·152
6 0 to 6 15	178	200	22 0 to 22 15	200	·042
7 0 to 7 15	178	·166	23 0 to 23 15	·202	15 926
8 0 to 8 15	180	126	24 0 to 24 15	206	808
9 0 to 9 15	180	082	25 0 to 25 15	208	·682
10 0 to 10 15	182	032	26 0 to 26 15	210	·554
11 0 to 11 15	182	16·978	27 0 to 27 15	212	·418
12 0 to 12 15	183	918	28 0 to 28 15	214	·280
13 0 to 13 15	184	852	29 0 to 29 15	218	·138
14 0 to 14 15	186	782	30 0 to 30 15	220	14 990
15 0 to 15 15	188	708	31 0 to 31 15	222	838

a quarter of a degree (15′) of Latitude and Longitude.

Latitude	Length of 15′ of Latitude	Length of 15′ of Longitude	Latitude	Length of 15′ of Latitude	Length of 15′ of Longitude.
° ′			° ′		
32 0 to 32 15	.. 17 226	14 680	47 0 to 47 15	. 17 270	11 816
33 0 to 33 15	.. 228	518	48 0 to 48 15	. 274	·594
34 0 to 34 15	. 232	·350	49 0 to 49 15	.. 276	368
35 0 to 35 15	234	182	50 0 to 50 15	.. 280	138
36 0 to 36 15	·236	006	51 0 to 51 15	.. 282	10·906
37 0 to 37 15	240	13 828	52 0 to 52 15	285	·670
38 0 to 38 15	.. 242	·644	53 0 to 53 15	.. 288	·430
39 0 to 39 15	.. 246	458	54 0 to 54 15	. 292	·188
40 0 to 40 15	.. 250	266	55 0 to 55 15	294	9 942
41 0 to 41 15	.. 252	·070	56 0 to 56 15	.. 298	692
42 0 to 42 15	.. 254	12 870	57 0 to 57 15	.. 300	442
43 0 to 43 15	.. 258	668	58 0 to 58 15	.. 303	·186
44 0 to 44 15	262	·460	59 0 to 59 15	.. ·306	8 928
45 0 to 45 15	264	248	60 0 to 60 15	308	669
46 0 to 46 15	268	034			

The length of the diagonal, q, of a space bounded by meridians and parallels m, n, p,

$$= \sqrt{m^2 + np}$$

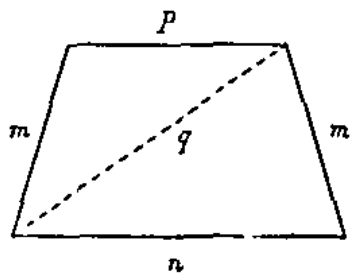


TABLE XI.—Linear value in feet of one second of Arc

Formula: Length in feet $= \rho \sin 1''$

Latitude	Length in feet	Logarithm	Diff.	Latitude	Length in feet	Logarithm	Diff
° ′			+	° ′			+
0 0	100 7654	2 0033115	0	2 30	100 7674	2 0033199	6
5	7654	115	1	35	7675	205	6
10	7654	116	0	40	7676	211	6
15	7654	116	1	45	7678	217	6
20	7654	117	1	50	7679	223	6
25	7654	118	1	55	7681	229	7
30	7655	119	1	3 0	100 7682	2 0033236	7
35	7655	120	1	5	7684	243	7
40	7656	121	1	10	7685	250	7
45	7656	122	2	15	7687	257	8
50	7656	124	2	20	7689	265	7
55	7657	126	3	25	7690	272	8
1 0	100·7657	2 0033129	2	30	7692	280	8
5	7658	131	3	35	7694	288	8
10	7658	134	2	40	7696	296	8
15	7659	136	3	45	7698	304	9
20	7660	139	3	50	7700	313	8
25	7660	142	3	55	7702	321	9
30	7661	145	4	4 0	100 7704	2 0033330	9
35	7662	149	4	5	7706	339	9
40	7663	153	3	10	7708	348	9
45	7664	156	4	15	7710	357	10
50	7665	160	4	20	7713	367	10
55	7666	164	5	25	7715	377	10
2 0	100 7667	2 0033169	4	30	7717	387	10
5	7668	173	5	35	7719	397	11
10	7669	178	5	40	7722	408	10
15	7670	183	5	45	7724	418	11
20	7671	188	5	50	7727	429	11
25	7672	193	6	55	7729	440	11

and its Logarithm, measured along the Meridian.

Latitude	Length in feet.	Logarithm	Diff
° ′			
5 0	100 7732	2·0033451	
			11
5	7735	462	
			12
10	7737	474	
			11
15	7740	485	
			12
20	7743	497	
			12
25	7745	509	
			12
30	7748	521	
			12
35	7751	533	
			13
40	7754	546	
			13
45	7757	559	
			13
50	7760	572	
			13
55	7763	585	
			13
6 0	100 7766	2 0033598	
			13
5	7769	611	
			14
10	7772	625	
			14
15	7776	639	
			14
20	7779	653	
			14
25	7782	667	
			15
30	7786	682	
			14
35	7789	696	
			15
40	7792	711	
			15
45	7796	726	
			15
50	7799	741	
			15
55	7803	756	
			16
7 0	100 7806	2 0033772	
			15
5	7810	787	
			16
10	7814	803	
			16
15	7817	819	
			16
20	7821	835	
			16
25	7825	851	
			17

Latitude	Length in feet.	Log[illegible]	Diff
° ′			
7 30	100 7829	2 0033[illegible]	
			17
35	7833	[illegible]	
			17
40	7837	902	
			17
45	7841	919	
			17
50	7845	936	
			17
55	7849	953	
			18
8 0	100 7853	2 0033971	
			18
5	7857	[illegible]	
			18
10	7861	2 0034007	
			18
15	7865	025	
			19
20	7870	044	
			18
25	7874	062	
			19
30	7878	081	
			19
35	7883	100	
			19
40	7887	119	
			19
45	7892	138	
			19
50	7896	157	
			20
55	7901	177	
			20
9 0	100 7905	2 0034197	
			20
5	7910	217	
			20
10	7914	237	
			21
15	7919	257	
			21
20	7924	278	
			20
25	7929	298	
			21
30	7934	319	
			21
35	7939	340	
			22
40	7944	362	
			21
45	7949	383	
			22
50	7953	405	
			21
55	7959	426	
			22

TABLE XI—Linear value in feet of one second of Arc

Latitude	Length in feet	Logarithm	Diff	Latitude	Length in feet	Logarithm	Diff.
° ′			+	° ′			+
10 0	100 7964	2 0034448	22	12 30	100 8135	2 0035186	27
5	7969	470	22	35	8141	213	28
10	7974	492	22	40	8148	241	27
15	7979	514	33	45	8154	268	28
20	7984	537	23	50	8160	296	28
25	7990	560	23	55	8167	324	28
30	7996	583	23	13 0	100 8173	2 0035352	28
35	8000	606	24	5	8180	380	29
40	8006	630	23	10	8187	409	28
45	8011	653	24	15	8193	437	29
50	8017	677	24	20	8200	466	29
55	8022	701	24	25	8206	495	29
11 0	100 8028	2 0034725	24	30	8213	524	29
5	8034	749	24	35	8220	553	30
10	8039	773	24	40	8227	583	30
15	8045	797	25	45	8234	613	30
20	8050	822	25	50	8241	643	30
25	8056	847	25	55	8248	673	30
30	8062	872	25	14 0	100 8255	2 0035703	30
35	8068	897	26	5	8262	733	30
40	8074	923	25	10	8269	763	31
45	8080	948	26	15	8276	794	31
50	8086	974	26	20	8283	825	31
55	8092	2 0035000	26	25	8290	856	31
12 0	100 8098	2 0035026	26	30	8297	887	31
5	8104	052	27	35	8305	918	31
10	8110	079	26	40	8312	949	32
15	8116	105	27	45	8319	981	32
20	8122	132	27	50	8327	2 0036013	32
25	8129	159	27	55	8334	045	32

and its Logarithm, measured along the Meridian.

Latitude		Length in feet.	Logarithm	Diff	Latitude		Length in feet	Logarithm	Diff
°	′				°	′			
15	0	100·8312	2·0036077	32	17	30	100·8582	2·0037113	37
	5	8319	109	32		35	8591	150	37
	10	8327	141	33		40	8599	187	37
	15	8334	174	33		45	8608	224	38
	20	8342	207	33		50	8617	262	38
	25	8350	240	33		55	8626	300	38
	30	8357	273	33	18	0	100·8634	2·0037337	37
	35	8365	306	33		5	8643	375	38
	40	8373	339	33		10	8652	413	38
	45	8410	372	34		15	8661	451	38
	50	8418	406	34		20	8670	491	39
	55	8426	440	34		25	8679	528	38
16	0	100·8434	2·0036474	34		30	8688	567	39
	5	8442	508	35		35	8697	606	39
	10	8450	543	34		40	8706	645	39
	15	8458	577	35		45	8715	684	39
	20	8466	612	35		50	8724	721	37
	25	8474	647	35		55	8734	762	41
	30	8482	682	35	19	0	100·8743	2·0037802	40
	35	8490	717	35		5	8752	842	40
	40	8498	752	35		10	8761	883	41
	45	8506	787	36		15	8770	922	39
	50	8515	823	36		20	8779	962	40
	55	8523	859	36		25	8789	2·0038002	40
17	0	100·8531	2·0036895	36		30	8798	042	40
	5	8540	931	36		35	8807	083	41
	10	8548	967	36		40	8817	123	40
	15	8557	2·0037003	37		45	8826	164	41
	20	8565	040	36		50	8836	205	41
	25	8574	076	37		55	8845	246	41
									42

TABLE XI—Linear value in feet of one second of Arc

Latitude		Length in feet	Logarithm	Diff
°	′			+
20	0	100 8855	2 0038288	41
	5	8865	329	42
	10	8874	371	41
	15	8884	412	42
	20	8894	454	42
	25	8903	496	42
	30	8913	538	42
	35	8923	580	43
	40	8933	623	42
	45	8943	665	43
	50	8953	708	43
	55	8963	751	43
21	0	100 8973	2 0038794	43
	5	8983	837	44
	10	8993	881	43
	15	9003	924	44
	20	9013	968	43
	25	9023	2 0039011	44
	30	9033	055	44
	35	9043	099	44
	40	9054	143	44
	45	9064	187	45
	50	9074	232	44
	55	9085	276	45
22	0	100 9095	2 0039321	45
	5	9105	366	45
	10	9116	411	45
	15	9127	456	45
	20	9137	501	45
	25	9147	546	46
	30	9158	592	45
	35	9169	637	46
	40	9179	683	46
	45	9190	729	46
	50	9200	775	46
	55	9211	821	46
23	0	100 9222	2 0039867	46
	5	9233	913	47
	10	9244	960	46
	15	9254	2 0040006	47
	20	9265	053	47
	25	9276	100	47
	30	9287	147	47
	35	9298	194	47
	40	9309	241	47
	45	9320	288	48
	50	9331	336	48
	55	9342	384	48
24	0	100 9353	2 0040432	48
	5	9364	480	48
	10	9375	528	48
	15	9387	576	48
	20	9398	624	48
	25	9409	672	49
	30	9420	721	48
	35	9432	769	49
	40	9443	818	49
	45	9454	867	49
	50	9466	916	49
	55	9477	965	50

and its Logarithm, measured along the Meridian.

Latitude	Length in feet.	Logarithm	Diff	Latitude	Length in feet	Logarithm	Diff
° ′			+	° ′			+
25 0	100 9789	2 0041015	49	27 30	100 9845	2 0042516	53
5	9799	064	49	35	9857	569	53
10	9812	113	50	40	9869	622	53
15	9823	163	50	45	9882	706	53
20	9835	213	50	50	9894	758	53
25	9847	263	50	55	9906	811	54
30	9858	313	50	28 0	100 9919	2 0042865	53
35	9870	363	50	5	9931	918	54
40	9881	413	50	10	9944	972	53
45	9893	463	50	15	9956	2 0043025	54
50	9905	514	51	20	9969	079	54
55	9916	564	50	25	9981	133	54
26 0	100 9928	2 0041615	51	30	9994	187	54
5	9940	666	51	35	101 0006	241	54
10	9952	717	51	40	0019	295	54
15	9964	768	51	45	0031	349	54
20	9976	819	51	50	0044	403	54
25	9987	870	51	55	0056	457	55
30	9999	921	51	29 0	101 0069	2 0043512	55
35	9711	972	52	5	0082	567	55
40	9723	2 0042024	52	10	0095	622	55
45	9735	076	52	15	0107	677	55
50	9747	128	52	20	0120	732	55
55	9760	180	52	25	0133	787	55
27 0	100 9772	2 0042232	52	30	0146	842	55
5	9784	284	52	35	0159	897	55
10	9796	336	52	40	0172	952	55
15	9808	388	53	45	0185	2 0044007	56
20	9820	441	52	50	0 98	063	56
25	9832	493	53	55	0210	119	56

TABLE XI—Linear value in feet of one second of Arc

Latitude	Length in feet	Logarithm	Diff	Latitude	Length in feet	Logarithm	Diff
° ′			+	° ′			+
30 0	101 0223	2 0044175	56	32 30	101 0622	2 0045888	58
5	0236	231	56	35	0635	946	59
10	0249	287	56	40	0649	2 0046005	58
15	0262	343	56	45	0663	063	59
20	0275	399	56	50	0677	122	59
25	0289	455	56	55	0690	181	59
30	0302	511	56	33 0	101 0704	2 0046240	59
35	0315	567	57	5	0718	299	59
40	0328	624	56	10	0731	358	59
45	0341	680	57	15	0745	417	59
50	0354	737	57	20	0759	476	59
55	0367	794	57	25	0773	535	59
31 0	101 0381	2 0044851	57	30	0787	594	59
5	0394	908	57	35	0800	653	60
10	0407	965	57	40	0814	713	59
15	0421	2 0045022	57	45	0828	772	60
20	0434	079	57	50	0842	832	59
25	0447	136	57	55	0856	891	60
30	0461	193	57	34 0	101 0870	2 0046951	60
35	0474	250	58	5	0883	2 0047011	60
0	0487	308	58	10	0897	071	60
45	0501	366	58	15	0911	131	60
50	0514	424	57	20	0925	191	60
55	0527	481	58	25	0939	251	60
32 0	101 0541	2 0045539	58	30	0953	311	60
5	0554	597	58	35	0967	371	60
10	0568	655	58	40	0981	431	60
15	0581	713	59	45	0995	491	61
20	0595	772	58	50	1009	552	60
25	0608	830	58	55	1023	612	61

and its Logarithm, measured along the Meridian.

Latitude	Length in feet	Logarithm	Diff	Latitude	Length in feet	Logarithm	Diff
° ′			+	° ′			+
35 0	101 1038	2·0047673	60	37 30	101 1467	2 0049516	62
5	1052	733	61	35	1481	578	63
10	1066	794	61	40	1496	641	62
15	1080	855	61	45	1510	703	63
20	1094	916	61	50	1525	766	62
25	1108	977	61	55	1539	828	63
30	1122	2·0038038	61	38 0	101 1554	2 0049891	62
35	1137	099	61	5	1569	953	63
40	1151	160	61	10	1583	2·0050016	62
45	1165	221	61	15	1598	078	63
50	1179	282	61	20	1612	141	63
55	1193	343	61	25	1627	204	63
36 0	101 1208	2·0038404	61	30	1642	267	62
5	1222	465	62	35	1656	329	63
10	1236	527	61	40	1671	392	63
15	1250	588	62	45	1686	455	63
20	1265	650	61	50	1700	518	63
25	1279	711	62	55	1715	581	63
30	1294	773	61	39 0	101 1730	2 0050644	63
35	1308	834	62	5	1744	707	64
40	1322	896	62	10	1759	771	63
45	1337	958	62	15	1774	834	63
50	1351	2 0049020	62	20	1788	897	63
55	1366	082	62	25	1803	960	63
37 0	101 1380	2 0049144	62	30	1818	2 0051023	63
5	1395	206	62	35	1832	086	64
10	1409	268	62	40	1847	150	63
15	1423	330	62	45	1862	213	64
20	1438	392	62	50	1877	277	63
25	1452	454	62	55	1891	340	64

TABLE XI.—Linear value in feet of one second of Arc

Latitude	Length in feet	Logarithm	Diff	Latitude	Length in feet	Logarithm	Diff
° ′			+	° ′			+
40 0	101 1905	2 0051404	63	42 30	101 2353	2 0053321	64
5	1921	467	64	35	2368	385	64
10	1936	531	63	40	2383	449	64
15	1951	594	64	45	2398	513	65
20	1966	658	63	50	2413	578	64
25	1980	721	64	55	2428	642	65
30	1995	785	64	43 0	101 2443	2 0053707	64
35	2010	849	64	5	2458	771	64
40	2025	913	63	10	2473	835	64
45	2040	976	64	15	2488	899	65
50	2055	2 0052040	64	20	2503	964	64
55	2070	104	64	25	2518	2 0054028	65
41 0	101 2085	2 0052168	64	30	2533	093	64
5	2100	232	64	35	2548	157	65
10	2114	296	63	40	2563	222	64
15	2129	359	64	45	2578	286	65
20	2144	423	64	50	2593	351	64
25	2159	487	64	55	2608	415	64
30	2174	551	64	44 0	101 2623	2 0054479	64
35	2189	615	64	5	2638	543	65
40	2204	679	64	10	2653	608	64
45	2219	743	65	15	2668	672	65
50	2234	808	64	20	2684	737	64
55	2249	872	64	25	2699	801	65
42 0	101 2264	2 0052936	64	30	2714	866	64
5	2279	2 0053000	64	35	2729	930	65
10	2294	064	64	40	2744	995	64
15	2308	128	64	45	2759	2 0055059	65
20	2323	192	64	50	2774	124	64
25	2338	256	65	55	2789	189	65

and its Logarithm, measured along the Meridian.

Latitude		Length in feet.	Logarithm	Diff.
°	′			+
45	0	101 2851	2 0055253	
	5	2819	317	64
	10	2854	382	65
	15	2849	446	64
	20	2884	511	65
	25	2879	575	64
				63
	30	2894	643	
	35	2910	708	64
	40	2924	769	65
	45	2940	833	64
	50	2954	898	65
	55	2969	962	64
				65
46	0	101 2984	2 0056027	
	5	2999	091	64
	10	3015	156	65
	15	3030	220	64
	20	3045	285	65
	25	3060	349	64
				65
	30	3075	414	
	35	3090	478	64
	40	3105	543	65
	45	3120	607	64
	50	3135	672	65
	55	3150	736	64
				64
47	0	101 3165	2 0056800	
	5	3180	864	64
	10	3195	929	65
	15	3210	993	64
	20	3225	2 0057058	65
	25	3240	122	64
				64

Latitude		Length in feet.	Logarithm	Diff.
°	′			+
47	30	101 3255	2 0057186	
	35	3270	250	64
	40	3285	315	65
	45	3300	379	64
	50	3315	443	64
	55	3330	507	64
				64
48	0	101 3345	2 0057572	
	5	3360	636	64
	10	3375	700	64
	15	3390	764	64
	20	3405	829	64
	25	3419	892	64
				64
	30	3434	956	
	35	3449	2 0058020	64
	40	3464	085	65
	45	3479	149	64
	50	3494	213	64
	55	3509	276	63
				64
49	0	101 3524	2 0058340	
	5	3539	404	64
	10	3554	468	64
	15	3569	532	64
	20	3584	596	64
	25	3598	659	63
				64
	30	3613	723	
	35	3628	787	64
	40	3643	851	64
	45	3658	914	63
	50	3673	978	64
	55	3688	2 0059041	63
				61

TABLE XI—Linear value in feet of one second of Arc

Latitude	Length in feet	Logarithm	Diff	Latitude	Length in feet	Logarithm	Diff
° ′			+	° ′			+
50 0	101 3703	2 0059105	63	52 30	101 4144	2 ·0060995	62
5	3717	168	64	35	4158	2 ·0061057	63
10	3732	232	63	40	4173	120	62
15	3747	295	64	45	4187	182	63
20	3762	359	63	50	4202	245	62
25	3776	422	64	55	4217	307	62
30	3791	486	63	53 0	101 4231	2 ·0061369	62
35	3806	549	64	5	4246	431	62
40	3821	613	63	10	4260	493	62
45	3836	676	63	15	4275	555	62
50	3851	739	63	20	4289	617	61
55	3865	802	64	25	4303	678	62
51 0	101 3880	2 0059866	63	30	4318	740	62
5	3895	929	63	35	4332	802	62
10	3909	992	63	40	4347	864	61
15	3924	2 0060055	63	45	4361	925	62
20	3939	118	63	50	4375	987	61
25	3954	181	63	55	4390	2 0062048	62
30	3968	244	62	54 0	101 4404	2 0062110	61
35	3983	306	63	5	4418	171	61
40	3998	369	63	10	4433	232	61
45	4012	432	63	15	4447	293	62
50	4027	495	62	20	4461	355	61
55	4041	557	63	25	4476	416	61
52 0	101 4056	2 ·0060620	63	30	4490	477	61
5	4071	683	63	35	4504	538	61
10	4085	746	62	40	4518	599	61
15	4100	808	63	45	4532	660	61
20	4115	871	62	50	4547	721	60
25	4129	933	62	55	4561	781	61

and its Logarithm, measured along the Meridian.

Latitude		Length in feet.	Logarithm	Diff	Latitude		Length in feet	Logarithm	Diff
°	′			+	°	′			+
55	0	101 4573	2 [illegible]	61	57	30	101 4993	2 0061632	58
	5	4589	903	61		35	5007	690	59
	10	4603	964	60		40	5021	749	58
	15	4618	2 [illegible]	61		45	5034	807	59
	20	4632	085	60		50	5048	866	58
	25	4646	145	60		55	5062	924	58
	30	4660	205	60	58	0	101 5075	2 0064982	58
	35	4674	265	61		5	5089	2 0065040	58
	40	4688	326	60		10	5102	098	58
	45	4702	386	60		15	5116	156	58
	50	4716	446	60		20	5129	214	57
	55	4730	506	60		25	5143	271	58
56	0	101 4744	2 0063566			30	5156	329	57
	5	4758	626	60		35	5170	386	58
	10	4772	686	60		40	5183	444	57
	15	4786	745	59		45	5197	501	57
	20	4800	805	60		50	5201	558	57
	25	4814	864	59		55	5223	615	58
	30	4828	924	60	59	0	101 5237	2 0065673	57
	35	4842	983	59		,	5250	730	57
	40	4856	2 0064043	60		10	5263	787	56
	45	4869	102	59		15	5276	843	57
	50	4883	161	59		20	5289	900	56
	55	4897	220	59		25	5303	956	57
57	0	101 4911	2 0064279			30	5316	2 0066013	56
	5	4925	338	59		35	5329	069	57
	10	4938	397	59		40	5343	126	56
	15	4952	456	59		45	5356	182	57
	20	4966	515	59		50	5369	239	56
	25	4980	573	58		55	5382	295	58
				59	60	0	101 5395	2 0066351	

TABLE XII.—Linear value in feet of one second of Arc

Formula: Length in feet $= \frac{\pi}{180 \times 3600} \nu \cos \lambda$.

Latitude.	Length in feet	Diff.	Logarithm.	Diff	Latitude.	Length in feet.	Diff	Logarithm.	Diff.
° ′		—		—	° ′		—		—
0 0	101·4538		2 0062683		2 30	101·3579		2 0038576	
		1		5			65		279
5	4537		2678		35	3514		8297	
		4		13			67		287
10	4533		2665		40	3447		8010	
		5		23			69		297
15	4528		2642		45	3378		7713	
		7		31			72		306
20	4521		2611		50	3306		7407	
		10		42			74		316
25	4511		2569		55	3232		7091	
		11		50			75		324
30	4500		2519		3 0	101·3157		2·0056767	
		14		59			78		333
35	4486		2460		5	3079		6434	
		16		69			79		342
40	4470		2391		10	3000		6092	
		18		77			83		353
45	4452		2314		15	2917		5739	
		21		87			84		360
50	4431		2227		20	2833		5379	
		22		96			86		370
55	4409		2131		25	2747		5009	
		24		105			88		379
1 0	101·4385		2 0062026		30	2659		4630	
		27		114			91		388
5	4358		1912		35	2568		4242	
		29		123			93		398
10	4329		1789		40	2475		3844	
		31		133			95		407
15	4298		1656		45	2380		3437	
		33		141			96		415
20	4265		1515		50	2284		3022	
		35		151			99		425
25	4230		1364		55	2185		2597	
		37		159			102		434
30	4193		1205		4 0	101·2083		2 0052163	
		40		169			103		443
35	4153		1036		5	1980		1720	
		41		178			105		453
40	4112		0858		10	1875		1267	
		44		187			108		462
45	4068		0671		15	1767		0805	
		46		197			110		471
50	4022		0474		20	1657		0334	
		48		204			112		480
55	3974		0270		25	1545		2 0049854	
		50		215			113		489
2 0	101·3924		2·0060055		30	1432		9365	
		52		224			116		498
5	3872		2 0059831		35	1316		8867	
		54		233			119		507
10	3818		9598		40	1197		8360	
		57		242			120		518
15	3761		9356		45	1077		7842	
		58		251			122		525
20	3703		9105		50	0955		7317	
		61		260			125		536
25	3642		8845		55	0830		6781	
		63		269			127		544

and its Logarithm, measured along Parallels of Latitude.

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
° ′					° ′				
5 0	101 0703		2 0041237		7 30	100 5917		2 0025231	
		128		544			193		1
5	0575		5684		35	5724		4780	
		131		563			194		1
10	0444		5121		40	5530		2941	
		134		572			197		1
15	0310		4549		45	5333		3100	
		135		581			199		1
20	0175		3968		50	5134		2241	
		137		591			200		1
25	0038		3377		55	4934		1374	
		139		599			201		1
30	100 9899		2778		8 0	100 4731		2 0010498	
		142		608			206		1
35	9757		2170		5	4525		2 0001690	
		143		618			207		1
40	9614		1552		10	4318		8714	
		146		628			209		1
45	9468		0924		15	4109		7898	
		148		636			211		1
50	9320		0288		20	3898		6982	
		150		645			214		1
55	9170		2 0039643		25	3684		6071	
		153		656			215		1
6 0	100 9017		2 0039087		30	3469		5038	
		154		663			218		1
5	8863		8324		35	3251		4095	
		156		674			221		1
10	8707		7650		40	3031		3143	
		159		682			222		1
15	8548		6968		45	2809		2182	
		161		692			224		1
20	8388		6276		50	2585		1212	
		163		701			226		1
25	8225		5575		55	2359		0232	
		165		710			229		1
30	8060		4865		9 0	100 2130		2 0009243	
		167		721			230		1
35	7893		4145		5	1900		8244	
		169		728			232		1
40	7724		3417		10	1668		7237	
		171		738			235		1
45	7553		2679		15	1433		6220	
		173		747			237		1
50	7380		1932		20	1196		5193	
		176		757			238		1
55	7204		1175		25	0958		4157	
		178		766			241		1
7 0	100 7026		2 0030409		30	0717		3111	
		179		775			243		1
5	6847		2 0029634		35	0474		2056	
		182		785			245		1
10	6665		8849		40	0229		0993	
		184		793			248		1
15	6481		8056		45	99 9981		1 9999919	
		186		803			249		1
20	6295		7253		50	9732		8836	
		188		811			251		1
25	6107		6442		55	9481		7744	
		190		822			254		1

TABLE XII.—Linear value in feet of one second of Arc

Latitude	Length in feet	Diff	Logarithm	Diff.	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
10 0	99 9227		1 9996642		12 30	99 0647		1 9959118	
		255		1111			319		1396
5	8972		5531		35	0328		57792	
		258		1121			320		1405
10	8714		4410		40	0008		56387	
		260		1129			323		1415
15	8454		3281		45	98 9685		54972	
		262		1140			324		1425
20	8192		2141		50	9361		53547	
		264		1149			327		1435
25	7928		0992		55	9034		52123	
		266		1159			329		1444
30	7662		1 9989833		13 0	98 8705		1 9950668	
		268		1167			331		1454
35	7394		8666		5	8374		49214	
		271		1177			333		1463
40	7123		7489		10	8041		47751	
		272		1187			335		1473
45	6851		6302		15	7706		46278	
		275		1196			337		1482
50	6576		5106		20	7369		44796	
		276		2205			339		1493
55	6300		3901		25	7030		43303	
		279		1215			341		1502
11 0	99 6021		1 9982686		30	6689		41801	
		281		1225			344		1511
5	5740		81461		35	6345		40290	
		283		1234			345		1521
10	5457		80227		40	6000		38769	
		285		1244			347		1531
15	5172		78983		45	5653		37238	
		287		1253			350		1541
20	4885		77730		50	5303		35697	
		289		1263			352		1550
25	4596		76467		55	4951		34147	
		291		1271			354		1560
30	4305		75196		14 0	98 4597		1 9932587	
		294		1282			355		1570
35	4011		73914		5	4212		31017	
		295		1290			358		1579
40	3716		72624		10	3884		29438	
		297		1301			360		1589
45	3419		71323		15	3524		27849	
		300		1310			362		1600
50	3119		70013		20	3162		26249	
		302		1320			364		1607
55	2817		68693		25	2798		24642	
		304		1329			366		1619
12 0	99 2513		1·9967364		30	2432		23023	
		305		1338			369		1629
5	2208		66026		35	2063		21394	
		308		1349			370		1637
10	1900		64677		40	1693		19757	
		311		1358			373		1648
15	1589		63319		45	1320		18109	
		312		1367			374		1657
20	1277		61952		50	0946		16452	
		314		1377			376		1667
25	0963		60575		55	0570		14785	
		316		1387			379		1677

and its Logarithm, measured along Parallels of Latitude.

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
15 0	98·0191		1·9913103		17 30	96·7879		1·9858211	
		281		1687			442		1985
5	97·7910		11421		35	7437		56226	
		282		1698			444		1994
10	9128		09723		40	6993		54232	
		285		1709			446		2004
15	9443		08013		45	6547		52228	
		287		1716			449		2015
20	8656		06303		50	6098		50213	
		288		1729			450		2024
25	8368		04577		55	5648		48189	
		291		1736			452		2036
30	7877		02841		18 0	96·5196		1·9846153	
		293		1748			455		2044
35	7584		01093		5	4741		44109	
		295		1755			456		2055
40	7289		1·9899340		10	4285		42054	
		297		1766			459		2066
45	6992		97574		15	3826		39988	
		299		1775			460		2075
50	6692		95790		20	3366		37913	
		301		1785			462		2086
55	5891		94014		25	2904		35828	
		303		1795			465		2095
16 0	97·5588		1·9892219		30	2439		33733	
		305		1805			466		2106
5	5283		90414		35	1973		31627	
		308		1814			469		2116
10	4975		88609		40	1504		29511	
		309		1825			471		2126
15	4666		86775		45	1033		27385	
		312		1834			472		2136
20	3354		84941		50	0561		25249	
		313		1845			475		2147
25	3441		83096		55	0086		23102	
		316		1854			476		2156
30	3025		81242		19 0	95·9610		1·9820946	
		317		1864			479		2166
35	2608		79378		5	9131		18780	
		320		1875			481		2178
40	2188		77503		10	8650		16602	
		322		1885			483		2188
45	1766		75618		15	8167		14414	
		323		1894			484		2197
50	1343		73724		20	7683		12217	
		326		1904			487		2208
55	0917		71820		25	7196		10009	
		328		1914			489		2218
17 0	97·0489		1·9869906		30	6707		07791	
		330		1924			490		2228
5	0059		67982		35	6217		05563	
		332		1934			493		2239
10	96·9627		66048		40	5724		03324	
		334		1945			495		2249
15	9191		64103		45	5229		01075	
		336		1954			497		2260
20	8757		62149		50	4732		1·9798815	
		338		1964			499		2270
25	8319		60185		55	4233		96545	
		340		1974			501		2280

TABLE XII.—Linear value in feet of one second of Arc

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
20 0	93 3732		1 9704265		22 30	93 7777		1 9720995	
		502		2290			563		2606
5	3230		91975		35	7214		18389	
		505		2301			564		2618
10	2725		89674		40	6650		15771	
		507		2311			567		2627
15	2218		87363		45	6083		13144	
		509		2321			569		2639
20	1709		85042		50	5514		10505	
		511		2332			570		2650
25	1198		82710		55	4944		07855	
		513		2343			573		2660
30	0685		80367		23 0	93 4371		1 9705195	
		515		2353			574		2672
35	0170		78014		5	3797		02523	
		517		2363			577		2681
40	94 9653		75651		10	3220		1 9699842	
		519		2374			578		2694
45	9134		73277		15	2642		97148	
		520		2384			581		2703
50	8614		70893		20	2061		94445	
		523		2394			582		2715
55	8091		68499		25	1479		91730	
		525		2406			584		2725
21 0	94 7566		1 9766093		30	0895		89005	
		527		2416			587		2736
5	7039		63677		35	0308		86269	
		529		2125			588		2748
10	6510		61252		40	92 9720		83521	
		531		2437			590		2758
15	5979		58815		45	9130		80763	
		533		2447			593		2769
20	5446		56368		50	8537		77994	
		535		2458			594		2780
25	4911		53910		55	7943		75214	
		537		2468			596		2790
30	4374		51442		24 0	92 7347		1 9672424	
		538		2478			598		2802
35	3836		48964		5	6749		69622	
		541		2491			600		2813
40	3295		46473		10	6149		66809	
		543		2499			602		2824
45	2752		43974		15	5547		63985	
		545		2511			604		2835
50	2207		41463		20	4943		61150	
		547		2521			606		2846
55	1660		38942		25	4337		58304	
		548		2531			608		2857
22 0	94 1112		1 9736411		30	3729		55447	
		551		2543			609		2867
5	0561		33868		35	3120		52580	
		553		2553			612		2879
10	0008		31315		40	2508		49701	
		555		2564			614		2891
15	93 9453		28751		45	1894		46810	
		556		2574			615		2901
21	8897		26177		50	1279		43909	
		559		2586			618		2913
25	8338		23591		55	0661		40997	
		561		2596			620		2924

and its Logarithm, measured along Parallels of Latitude.

Latitude	Length in feet.	Diff	Logarithm.	Diff.	Latitude.	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
25 0	92·0041		1·9638073		27 30	90·0558		1·9545116	
		621		2934			679		3277
5	91·9420		35139		35	89 9879		41839	
		624		2946			681		3288
10	8796		32193		40	9198		38551	
		625		2957			683		3299
15	8171		29236		45	8515		35252	
		627		2968			685		3312
20	7544		26268		50	7830		31940	
		629		2979			687		3324
25	6915		23289		55	7143		28617	
		632		2991			689		3335
30	6283		20298		28 0	89 6454		1·9525282	
		633		3002			690		3346
35	5650		17296		5	5764		21936	
		635		3013			692		3358
40	5015		14283		10	5072		18578	
		637		3024			695		3372
45	4378		11259		15	4377		15206	
		638		3035			696		3381
50	3740		08224		20	3681		11825	
		641		3048			698		3394
55	3099		05176		25	2983		08431	
		643		3058			700		3406
26 0	91 2456		1·9602118		30	2283		05025	
		645		3070			702		3418
5	1811		1·9599048		35	1581		01607	
		646		3080			704		3429
10	1165		95968		40	0877		1·9498178	
		649		3093			706		3441
15	0516		92875		45	0171		94737	
		650		3103			707		3453
20	90 9866		89772		50	88 9464		91284	
		653		3116			709		3465
25	9213		86656		55	8755		87819	
		654		3126			712		3477
30	8559		83530		29 0	88 8043		1·9484342	
		656		3137			713		3490
35	7903		80393		5	7330		80852	
		659		3150			715		3501
40	7244		77243		10	6615		77351	
		660		3161			717		3513
45	6584		74082		15	5898		73838	
		662		3172			719		3525
50	5922		70910		20	5179		70313	
		663		3183			720		3538
55	5259		67727		25	4459		66775	
		666		3196			723		3548
27 0	90 4593		1·9564531		30	3736		63227	
		668		3207			724		3562
5	3925		61324		35	3012		59665	
		670		3218			726		3573
10	3255		58106		40	2286		56092	
		671		3231			728		3585
15	2584		54875		45	1558		52507	
		674		3241			730		3598
20	1910		51634		50	0828		48909	
		675		3253			732		3611
25	1235		48381		55	0096		45298	
		677		3265			734		3622

TABLE XII —Linear value in feet of one second of Arc

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
30 0	87 9362	736	1 9441676	3635	32 30	85 6192	791	1 9327233	4012
5	8626	737	38041	3646	35	5701	792	23221	4023
10	7889	739	34395	3658	40	4909	795	19198	4038
15	7150	742	30737	3672	45	4114	796	15160	4049
20	6408	743	27065	3684	50	3318	798	11111	4063
25	5665	744	23381	3695	55	2520	799	07048	4076
30	4921	747	19686	3708	33 0	85 1721	802	1 9302972	4089
35	4174	749	15978	3721	5	0919	803	1 9298883	4102
40	3425	750	12257	3733	10	0116	805	94781	4115
45	2675	752	08524	3745	15	84 9311	807	90666	4128
50	1923	755	04779	3758	20	8504	809	86538	4142
55	1168	756	01021	3770	25	7695	811	82396	4154
31 0	87 0412	757	1 9397251	3783	30	6884	812	78242	4168
5	86 9655	760	93468	3795	35	6072	814	74074	4180
10	8896	762	89673	3808	40	5258	816	69894	4195
15	8137	763	85865	3820	45	4442	817	65699	4207
20	7370	765	82045	3833	50	3625	820	61492	4221
25	6605	767	78212	3845	55	2805	821	57271	4234
30	5838	769	74367	3858	34 0	84 1984	823	1 9253037	4247
35	5069	770	70509	3871	5	1161	825	48790	4261
40	4299	773	66638	3882	10	0336	827	44529	4274
45	3526	774	62756	3897	15	83 9509	828	40255	4287
50	2752	776	58859	3909	20	8681	830	35968	4301
55	1976	778	54950	3921	25	7851	832	31667	4315
32 0	86 1198	781	1 9351029	3934	30	7019	834	27352	4329
5	0418	782	47095	3947	35	6185	836	23024	4341
10	85 9636	783	43148	3960	40	5350	838	18683	4356
15	8853	785	39188	3972	45	4512	839	14327	4368
20	8068	787	35216	3985	50	3673	841	09959	4382
25	7281	789	31231	3998	55	2832	842	05577	4396

and its Logarithm, measured along Parallels of Latitude

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
35 0	83 1990		1·9201181		37 30	80 3901		1·9042817	
		844		4110			897		4834
5	1146		1·9196771		35	5004		37983	
		846		4123			898		4847
10	0300		92118		40	4106		33136	
		848		4137			900		4863
15	82 9452		87011		45	3206		28272	
		850		4150			901		4877
20	8602		83461		50	2305		23395	
		851		4165			903		4892
25	7751		78996		55	1402		18503	
		853		4179			905		4907
30	6898		74517		38 0	80 0497		1·9033596	
		855		4191			907		4921
35	6043		70026		5	79 9590		28675	
		857		4507			908		4936
40	5186		65519		10	8682		23739	
		858		4520			910		4951
45	4328		60999		15	7772		18788	
		860		1533			912		1966
50	3468		56466		20	6860		13822	
		862		1548			913		1982
55	2606		51918		25	5947		08840	
		864		1562			915		1996
36 0	82 1742		1·9147356		30	5032		03844	
		865		4576			917		5011
5	0877		42780		35	4115		1·8998833	
		867		4590			919		5026
10	0010		38190		40	3196		93807	
		869		4604			920		5041
15	81 9141		33586		45	2276		88766	
		871		1618			922		5056
20	8270		28968		50	1354		83710	
		872		1632			923		5072
25	7398		24336		55	0431		78638	
		874		1647			925		5086
30	6524		19689		39 0	79 9506		1·8973552	
		876		1660			927		5102
35	5648		15029		5	8579		68450	
		878		4675			929		5117
40	4770		10354		10	7650		63333	
		879		4689			930		5132
45	3891		05665		15	6720		58201	
		880		4703			932		5147
50	3011		00962		20	5788		53054	
		883		4718			934		5163
55	2128		1·9096244		25	4854		47891	
		885		4732			936		5178
37 0	81 1243		1·9091512		30	3919		42713	
		886		1746			937		5193
5	0357		86770		35	2982		37520	
		888		1761			938		5209
10	80 9469		82005		40	2044		32311	
		889		4775			940		5225
15	8580		77230		45	1104		27086	
		891		1790			942		5240
20	7689		72440		50	0162		21846	
		893		4805			944		5256
25	6796		67635		55	77 9218		16590	
		895		4818			945		5271

TABLE XII—Linear value in feet of one second of Arc

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
°		—		—			—		—
40 0	7 8 73	947	1 8911319	5°87	42 30	74 91o7	996	1 874 7°7	o o
5	3°6	948	0603°	530	3o	8161	997	399	o79°
10	63 8	9 1	00730	o319	40	°161	999	34160	5809
15	54 7	9 °	1 889 411	5334	4	616o	1000	283o1	o8°6
20	44 o	9 3	90077	53 0	50	o1°o	100°	2°o°o	5841
°o	3o°	9	847 7	o366	5	4163	1003	1°681	o8o9
30	2o67	9o7	79361	o381	43 0	°4 3160	100o	1 8 1082°	58 8
3o	1610	9 8	73980	5307	5	21oo	1007	04944	f894
40	06 °	960	68o83	5414	10	1148	1008	1 86990o0	o913
4o	76 369°	96°	63169	5430	15	0110	1010	93137	59°8
50	8730	963	5 39	544o	°0	o 9130	1011	8 °09	o947
5o	7767	965	5 294	5461	25	8119	1013	8126°	5964
41 0	°6 680°	966	1 8846833	478	30	7106	1015	75208	598_
5	5836	968	413oo	5493	3o	6091	1016	69316	5898
10	4868	9 0	3 86°	o011	40	507o	1018	63318	6017
1o	3898	9 °	303o1	5o°6	4.	4o57	1019	5 301	6034
20	J 6	9 3	248°o	o043	50	3038	10°0	51°67	60o
°o	19o3	97o	19 8°	5oo9	5o	2018	10°3	4o°1o	60 0
30	09 8	9 6	137°3	5o o	44 0	°3 399o	10°4	1 863914o	6087
3o	000°	9 8	08148	5o9°	o	7 39 1	10 o	330o8	610o
40	° 90 1	9 9	0 o 6	5608	10	8946	10 7	269o3	6123
4	801o	1 8 96948	°81	o6 o	15	919	10 9	°0830	6141
50	°0°1	983	913 3	5640	°0	6890	1030	14689	61 8
o5	6091	984	8 683	o°o8	°	5860	1031	08o31	61 7
42 (	o o07	986	1 8 800 o	o° o	30	48°9	1033	0 3o4	619o
	4111	988	13 0	5°31	3o	3 96	103	1 85961o9	6 13
1	31°3	989	°8 9	o 08	40	2761	1036	89946	6 31
1o	°134	991	6 o1	5 o	4o	1 o	1038	83715	6 o0
°)	1143	99	5 °6	5 11	o0	0687	1039	°716o	6_67
°o	(1o1	994	5119o	5 o8	5o	71 3648	1041	71198	6_86

and its Logarithm, measured along Parallels of Latitude.

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff.
° ′		—		—	° ′		—		—
45 0	71 8007		1 8561912		47 30	68 6679		1 8367349	
		1043		6304			1087		6882
5	7764		58608		35	5592		60658	
		1044		6323			1089		6902
10	6520		52285		40	4503		53756	
		1045		6341			1090		6922
15	5175		45944		45	3413		46834	
		1047		6360			1091		6943
20	4128		39584		50	2322		39891	
		1048		6378			1093		6962
25	3081		33206		55	1229		32929	
		1050		6397			1095		6985
30	2030		26809		48 0	68 0134		1 8325944	
		1052		6415			1096		7004
35	1278		20394		5	67 9038		18940	
		1053		6435			1098		7025
40	0225		13959		10	7940		11915	
		1055		6453			1099		7046
45	70 9170		07506		15	6841		04869	
		1056		6472			1100		7065
50	8114		01034		20	6741		1 8297804	
		1057		6491			1102		7087
55	7057		1 8494543		25	4639		90717	
		1059		6510			1103		7108
46 0	70 5998		1 8458033		30	3536		83609	
		1061		6529			1105		7129
5	4937		81504		35	2431		76480	
		1062		6548			1106		7149
10	3875		74956		40	1325		69331	
		1064		6568			1107		7171
15	2811		68388		45	0218		62160	
		1065		6586			1109		7192
20	1746		61802		50	66 9109		54968	
		1066		6605			1110		7212
25	0680		55197		55	7999		47756	
		1068		6626			1112		7236
30	69 9612		48571		49 0	66 6887		1 8240520	
		1070		6644			1113		7255
35	8542		41927		5	5774		33265	
		1071		6664			1115		7277
40	7471		35263		10	4659		25988	
		1072		6683			1116		7299
45	6399		28580		15	3543		18689	
		1074		6704			1118		7320
50	5325		21876		20	2425		11369	
		1076		6722			1119		7342
55	4249		15154		25	1306		04027	
		1077		6743			1120		7364
47 0	69 3172		1 8408411		30	0186		1 8196663	
		1078		6761			1122		7385
5	2094		01650		35	65 9064		89278	
		1080		6783			1123		7407
10	1014		1 8394867		40	7941		81871	
		1081		6801			1124		7429
15	68 9933		88066		45	6817		74442	
		1083		6822			1126		7452
20	8850		81244		50	5691		66990	
		1085		6842			1127		7472
25	7765		74402		55	4564		59518	
		1086		6862			1129		7496

TABLE XII.—Linear value in feet of one second of Arc

Latitude	Length in feet	Diff	Logarithm.	Diff.	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
40 0	77 8273	947	1 8911319	5287	42 30	74 9157	996	1 8745727	5775
5	7326	948	06032	5302	35	8161	997	39952	5792
10	6378	951	00730	5319	40	7164	999	34160	5809
15	5427	952	1 8895411	5334	45	6165	1000	28351	5826
20	4475	953	90077	5350	50	5165	1002	22525	5844
25	3522	955	84727	5366	55	4163	1003	16681	5859
30	2567	957	79361	5381	43 0	74 3160	1005	1 8710822	5878
35	1610	958	73980	5397	5	2155	1007	04944	5894
40	0652	960	68583	5414	10	1148	1008	1 8699050	5913
45	76 9692	962	63169	5430	15	0140	1010	93137	5928
50	8730	963	57739	5445	20	73 9130	1011	87209	5947
55	7767	965	52294	5461	25	8119	1013	81262	5964
41 0	76 6802	966	1 8846833	5478	30	7106	1015	75298	5982
5	5836	968	41355	5493	35	6091	1016	69316	5998
10	4868	970	35862	5511	40	5075	1018	63318	6017
15	3898	972	30351	5526	45	4057	1019	57301	6034
20	2926	973	24825	5543	50	3038	1020	51267	6052
25	1953	975	19282	5559	55	2018	1023	45215	6070
30	0978	976	13723	5575	44 0	73 0995	1024	1 8639145	6087
35	0002	978	08148	5592	5	72 9971	1025	33058	6105
40	75 9024	979	02556	5608	10	8946	1027	26953	6123
45	8045	981	1 8796948	5625	15	7919	1029	20830	6141
50	7064	983	01323	5640	20	6890	1030	14689	6158
55	6081	984	85683	5658	25	5860	1031	08531	6177
42 0	75 5097	986	1 8780025	5675	30	4829	1033	02354	6195
5	4111	988	74350	5691	35	3796	1035	1 8596159	6213
10	3123	989	68659	5708	40	2761	1036	89946	6231
15	2134	991	62951	5725	45	1725	1038	83715	6250
20	1143	992	57226	5741	50	0687	1039	77465	6267
25	0151	994	51485	5758	55	71 9648	1041	71198	6286

and its Logarithm, measured along Parallels of Latitude.

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
45 0	71 8697		1 8561912		47 30	68 6679		1 8367549	
		1043		6304			1057		6882
5	7564		58608		35	5592		60658	
		1044		6321			1089		6902
10	6520		52287		40	4503		53756	
		1045		6341			1090		6922
15	5475		45944		45	3413		46834	
		1047		6360			1091		6943
20	4428		39584		50	2322		39891	
		1048		6378			1093		6962
25	3381		33206		55	1229		32929	
		1051		6397			1095		6985
30	2331		26809		48 0	68 0134		1 8325944	
		1052		6415			1096		7004
35	1278		20394		5	67 9038		18940	
		1053		6435			1098		7025
40	0225		13959		10	7940		11915	
		1055		6453			1099		7046
45	70 9170		07506		15	6841		04869	
		1056		6472			1100		7065
50	8114		01034		20	5741		1 8297804	
		1057		6491			1102		7087
55	7057		1 8494543		25	4639		00717	
		1059		6510			1103		7108
46 0	70 5998		1 8488033		30	3536		83609	
		1061		6529			1105		7129
5	4937		81504		35	2431		76480	
		1062		6548			1106		7149
10	3875		74956		40	1325		69331	
		1064		6568			1107		7171
15	2811		68388		45	0218		62160	
		1065		6586			1109		7192
20	1746		61802		50	66 9109		54968	
		1066		6605			1110		7212
25	0680		55197		55	7999		47756	
		1068		6626			1112		7236
30	69 9612		48571		49 0	66 6887		1 8240520	
		1070		6644			1113		7255
35	8542		41927		5	5774		33265	
		1071		6664			1115		7277
40	7471		35263		10	4659		25988	
		1072		6683			1116		7299
45	6399		28580		15	3543		18689	
		1074		6704			1118		7320
50	5325		21876		20	2425		11369	
		1076		6722			1119		7342
55	4249		15154		25	1306		04027	
		1077		6743			1120		7364
47 0	69 3172		1 8408411		30	0186		1 8196663	
		1078		6761			1122		7385
5	2094		01650		35	65 9064		89278	
		1080		6783			1123		7407
10	1014		1 8394867		40	7941		81871	
		1081		6801			1124		7429
15	68 9933		88066		45	6817		74442	
		1083		6822			1126		7452
20	8850		81244		50	5691		66990	
		1085		6842			1127		7472
25	7765		74402		55	4564		59518	
		1086		6862			1129		7496

TABLE XII.—Linear value in feet of one second of Arc

Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—
50 0	65 3435		1 8152022	
		1130		7518
5	2305		14504	
		1132		7540
10	1173		36964	
		1133		7563
15	0040		29401	
		1134		7585
20	64 8906		21816	
		1136		7607
25	7770		14209	
		1137		7631
30	6633		06578	
		1138		7652
35	5495		1 8098926	
		1140		7675
40	4355		91251	
		1141		7699
45	3214		83552	
		1143		7722
50	2071		75830	
		1144		7744
55	0927		68086	
		1145		7768
51 0	63 9782		1 8060318	
		1147		7791
5	8635		52527	
		1148		7814
10	7487		44713	
		1149		7838
15	6338		36875	
		1151		7861
20	5187		29014	
		1152		7884
25	4035		21130	
		1154		7908
30	2881		13222	
		1155		7932
35	1726		05290	
		1156		7956
40	0570		1 7997334	
		1157		7979
45	62 9413		89355	
		1159		8004
50	8254		81351	
		1160		8027
55	7094		73324	
		1162		8053
52 0	62 5932		1 7965271	
		1163		8076
5	4769		57195	
		1164		8100
10	3605		49095	
		1166		8125
15	2439		40970	
		1167		8149
20	1272		32821	
		1168		8174
25	0104		24647	
		1169		8200

Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—
52 30	61 8935		1 7916447	
		1171		8223
35	7764		08224	
		1172		8248
40	6592		1 7899976	
		1174		8273
45	5418		91703	
		1175		8299
50	4243		83404	
		1176		8324
55	3067		75080	
		1177		8349
53 0	61 1890		1 7866731	
		1179		8374
5	0711		58357	
		1180		8400
10	60 9531		49957	
		1181		8425
15	8350		41532	
		1183		8451
20	7167		33081	
		1184		8478
25	5983		24603	
		1185		8502
30	4798		16101	
		1187		8529
35	3611		07572	
		1188		8555
40	2423		1 7799017	
		1189		8581
45	1234		90436	
		1190		8607
50	0044		81829	
		1192		8634
55	59 8852		73195	
		1193		8660
54 0	59 7659		1 7764535	
		1194		8687
5	6465		55848	
		1196		8713
10	5269		47135	
		1197		8741
15	4072		38394	
		1198		8767
20	2874		29627	
		1199		8795
25	1675		20832	
		1201		8822
30	0474		12010	
		1202		8849
35	58 9272		03161	
		1203		8875
40	8069		1 7694286	
		1204		8904
45	6865		85382	
		1206		8931
50	5659		76451	
		1207		8959
55	4452		67492	
		1208		8987

and its Logarithm, measured along Parallels of Latitude.

Latitude	Length in feet	Diff	Logarithm	Diff.	Latitude	Length in feet	Diff	Logarithm	Diff.
° ′		—		—	° ′		—		—
55 0	58 3244		1 7628535		57 30	54 6431		1 7375334	
		1209		9015			1216		9912
5	2035		19520		35	5215		65442	
		1211		9042			1216		9943
10	0824		11478		40	3999		55199	
		1212		9071			1218		9976
15	57 9612		01407		45	2681		45523	
		1213		9103			1219		10007
20	8399		52277		50	1362		35516	
		1214		9137			1251		10041
25	7185		13139		55	0111		25475	
		1216		9167			1251		10073
30	5969		03972		58 0	53 8813		1 7315402	
		1217		9195			1253		10105
35	4752		1 7594858		5	7687		05297	
		1218		9224			1254		10139
40	3534		85595		10	6433		1 7295158	
		1219		9253			1255		10172
45	2315		76352		15	5178		84986	
		1220		9282			1256		10205
50	1095		67080		20	3922		74781	
		1222		9310			1257		10237
55	56 9873		57781		25	2665		64544	
		1223		9339			1258		10272
56 0	56 8650		1 7548450		30	1407		54272	
		1224		9369			1259		10305
5	7426		39081		35	0148		43967	
		1226		9389			1261		10349
10	6200		29701		40	52 8887		33627	
		1226		9418			1262		10373
15	4974		20283		45	7625		23254	
		1228		9449			1263		10408
20	3746		10834		50	6362		12846	
		1229		9478			1264		10440
25	2517		01356		55	5098		02406	
		1230		9508			1265		10477
30	1287		1 7491848		59 0	52 3833		1 7191929	
		1231		9538			1266		10511
35	0056		82310		5	2567		81418	
		1233		9570			1267		10545
40	55 8823		72740		10	1300		70873	
		1234		9599			1269		10581
45	7589		63141		15	0031		60292	
		1235		9630			1270		10617
50	6354		53511		20	51 8761		49675	
		1236		9661			1271		10651
55	5118		43850		25	7490		39024	
		1238		9691			1271		10686
57 0	53883		1 7434159		30	6219		1 7128338	
		1238		9723			1273		10723
5	2642		24436		35	4946		17615	
		1240		9754			1274		10758
10	1402		14682		40	3672		06857	
		1241		9784			1275		10794
15	0161		04898		45	2397		1 7096063	
		1242		9816			1277		10831
20	54 8919		1 7395082		50	1120		85232	
		1243		9848			1277		10867
25	7676		85234		55	50 9843		74365	
		1245		9880			1278		10903
					60 0	50 8565		1 7063462	

TABLE XII—Linear value in feet of one second of Arc

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	°		—		—
50 0	65 3135		1 8152022		52 30	61 8935		1 7916447	
		1130		7518			1171		8223
5	2305		14504		35	7764		08224	
		1132		7540			1172		8248
10	1173		30964		40	6592		1 7899976	
		1133		7563			1174		8273
15	0040		29401		45	5418		91705	
		1134		7585			1175		8299
20	64 8906		21816		50	4243		83404	
		1136		7607			1176		8324
25	7770		14209		55	3067		76080	
		1137		7631			1177		8349
30	6633		06578		53 0	61 1890		1 7866731	
		1138		7652			1179		8374
35	5495		1 8098926		5	0711		58357	
		1140		7675			1180		8400
40	4355		91251		10	60 9531		49957	
		1141		7699			1181		8425
45	3214		83552		15	8350		41532	
		1143		7722			1183		8451
50	2071		75830		20	7167		33081	
		1144		7744			1184		8478
55	0927		68086		25	5983		24603	
		1145		7768			1185		8503
51 0	63 9782		1 8060318		30	4798		16101	
		1147		7791			1187		8529
5	8635		52527		35	3611		07572	
		1148		7814			1188		8555
10	7487		44713		40	2423		1 7799017	
		1149		7838			1189		8581
15	6338		36875		45	1234		90436	
		1151		7861			1190		8607
20	5187		29014		50	0044		81829	
		1152		7884			1192		8634
25	4035		21130		55	59 8852		73195	
		1154		7908			1193		8660
30	2881		13222		54 0	59 7659		1 7764535	
		1155		7932			1194		8687
35	1726		05290		5	6465		55848	
		1156		7956			1196		8713
40	0570		1 7997334		10	5269		47135	
		1157		7979			1197		8741
45	62 9413		89355		15	4072		38394	
		1159		8004			1198		8767
50	8254		81351		20	2874		29627	
		1160		8027			1199		8795
55	7094		73324		25	1675		20832	
		1162		8053			1201		8822
52 0	62 5932		1 7965271		30	0474		12010	
		1163		8076			1202		8849
5	4769		57195		35	58 9272		03161	
		1164		8100			1203		8875
10	3605		49095		40	8069		1 7894286	
		1166		8125			1204		8904
15	2439		40970		45	6865		85382	
		1167		8149			1206		8931
20	1272		32821		50	5659		76451	
		1168		8174			1207		8959
25	0104		24647		55	4452		67492	
		1169		8200			1208		8987

and its Logarithm, measured along Parallels of Latitude.

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
° ′		—		—	° ′		—		—
55 0	[illegible] 3214		1 76[illegible]095		57 30	54 6431		1 7375354	
		1209		9015			1246		9912
5	2335		49119		35	5185		65442	
		1211		9012			1246		9943
10	0821		13448		40	3939		55499	
		1212		9071			1248		9976
15	57[illegible]9 12		71477		45	2691		45523	
		1213		9103			1249		10007
20	[illegible]799		22277		50	1442		35516	
		1214		9127			1251		10041
25	7185		13150		55	0191		25475	
		1216		9157			1251		10073
30	5969		03993		58 0	53 8943		1 7315402	
		1217		9185			1253		10105
35	4752		1 7894808		5	7687		05297	
		1218		9213			1254		10139
40	3534		85595		10	6433		1 7295158	
		1219		9243			1255		10172
45	2315		76352		15	5178		84986	
		1220		9272			1256		10206
50	1095		67080		20	3922		74781	
		1222		9300			1257		10237
55	56 9873		57780		25	2663		64544	
		1223		9333			1258		10272
56 0	56 8653		1 7848450		30	1407		54272	
		1224		9360			1259		10305
5	7436		39090		35	0148		43967	
		1225		9389			1261		10340
10	6211		29701		40	52 8887		33627	
		1226		9418			1262		10373
15	4974		20283		45	7626		23254	
		1228		9449			1263		10408
20	3746		10834		50	6362		12846	
		1229		9478			1264		10440
25	2517		01356		55	5098		02406	
		1230		9508			1266		10477
30	1287		1 7491848		59 0	52 3833		1 7191929	
		1231		9538			1266		10511
35	0056		82310		5	2567		81418	
		1233		9570			1267		10545
40	55 8823		72740		10	1300		70873	
		1234		9599			1269		10581
45	7583		63141		15	0031		60292	
		1235		9630			1270		10617
50	6344		53511		20	51 8761		49675	
		1236		9661			1271		10651
55	5118		43851		25	7491		39024	
		1238		9691			1271		10686
57 0	53 3883		1 7434159		30	6219		1 7128338	
		1238		9723			1273		10723
5	2642		24436		35	4946		17615	
		1240		9754			1274		10758
10	1402		14682		40	3672		06857	
		1241		9784			1276		10794
15	0161		04898		45	2397		1 7096063	
		1242		9816			1277		10831
20	54 8919		1 7395092		50	1120		85232	
		1243		9848			1277		10867
25	7676		85234		55	50 9843		74365	
		1245		9880			1278		10903
					60 0	50 8565		1 7063462	

TABLE XII—Linear value in feet of one second of Arc

Latitude	Length in feet	Diff	Logarithm	Diff	Latitude	Length in feet	Diff	Logarithm	Diff
°		—		—	°		—		—
50 0	6o 313	1130	1 81 2022	7o18	52 30	61 893o	1171	1 7916447	8° 3
5	2306	1132	14o04	7o40	35	7764	1172	08924	8°48
10	1173	1133	36964	7o63	40	6o9o	1174	1 78999/6	82°3
15	0040	1134	29401	7585	45	5418	1175	9170o	8°99
20	64 8906	1136	21816	7607	50	4243	1176	83404	8324
25	77 0	1137	14°09	7631	55	3067	1177	75080	8349
30	6633	1138	06o78	7602	53 0	61 1890	1179	1 7866731	8374
35	5495	1140	1 80989 6	767o	5	0711	1180	583o7	8400
40	4355	1141	912o1	7699	10	60 9531	1181	499o7	842o
45	3214	1143	83o52	7722	15	83 0	1183	41532	8451
50	2071	1144	75830	7744	20	7167	1184	33081	8478
55	0927	114o	68086	7768	25	5983	118o	24603	850-
51 0	63 9 8°	1147	1 8060318	7791	30	4798	1187	16101	85°9
5	8635	1148	52527	7814	35	3611	1188	07o72	8o55
10	7487	1149	44713	7838	40	2423	1189	1 7799017	8o81
15	6338	1151	36875	7861	45	1°34	1190	90436	8607
20	5187	1152	29014	7884	50	0044	1192	81829	8634
25	4036	11o4	21130	7908	55	59 8852	1193	7319o	8660
30	2881	115o	13°°2	7932	54 0	59 7659	1194	1 7764535	8687
35	1726	1156	05°90	79o6	5	6465	1196	5o848	8713
40	0570	1157	1 7990 334	7979	10	5°69	1197	4 135	8741
45	62 9413	1159	893o6	8004	15	4072	1198	38394	8767
50	8254	1160	81301	8027	20	2874	1199	29627	8 9o
55	7094	116-	733 4	8053	25	1675	1°01	20832	8822
52 0	62 5933	1163	1 7°96 271	80°6	30	0474	120-	1°010	8849
5	4 69	1164	5°19o	8100	35	58 9272	1°03	03101	88 5
10	3605	1166	4999o	812o	40	8069	1204	1 7694°86	8904
15	2439	1167	409 0	8149	45	7865	1°06	85382	8931
20	1272	116°	3°°_1	8174	50	6659	1°07	76o1	89o9
25	0104	1169	24647	8200	55	4452	1208	67492	8987

TABLE XIV.—Astronomical Refraction

The Mean Refraction is for Barometer 30 inches and Temperature 50° Fahr

Apparent Altitude	Mean Refraction	Diff for 1′ Alt	Diff for +1 in Baro	Diff for 1° Temp	Apparent Altitude	Mean Refraction	Diff for 1′ Alt	Diff for +1 in Baro	Diff for −1° Temp
° ′	′ ″	′	″	′	° ′	′ ″	′	″	″
0 0	33 51	11 7	74	8 1	4 0	11 52	2 2	24 1	1·70
5	32 53	11·3	71	7 6	10	11 30	2 1	23 4	1 64
10	31 58	10·9	69	7 3	20	11 10	2 0	22 7	1 58
15	31 5	10 5	67	7·0	30	10 50	1 9	22 0	1 53
20	30 13	10 1	65	6 7	40	10 32	1 8	21 3	1 48
25	29 24	9 7	63	6 4	50	10 15	1 7	20 7	1 43
30	28 37	9 4	61	6 1	5 0	9 58	1 6	20 1	1·38
35	27 51	9·0	59	5·9	10	9 42	1 5	19 6	1 34
40	27 6	8 7	58	5 6	20	9 27	1 5	19 1	1 30
45	26 24	8 4	56	5 4	30	9 11	1 4	18 6	1 26
50	25 43	8 0	55	5 1	40	8 58	1 3	18 1	1 22
55	25 3	7 7	53	4·9	50	8 45	1 3	17 6	1 19
1 0	24 25	7 4	52	4 7	6 0	8 32	1 2	17 2	1 15
5	23 48	7 1	50	4 6	10	8 20	1 2	16 8	1 11
10	23 13	6·9	49	4 5	20	8 9	1 1	16 4	1 09
15	22 40	6 6	48	4 4	30	7 58	1 1	16 0	1 06
20	22 8	6 3	46	4 2	40	7 47	1 0	15 7	1 03
25	21 37	6 1	45	4 0	50	7 37	1 0	15 3	1 00
30	21 7	5·9	44	3 9	7 0	7 27	1 0	15 0	0 98
35	20 38	5 7	43	3 8	10	7 17	0 9	14 6	95
40	20 10	5 5	42	3 6	20	7 8	9	14 3	93
45	19 43	5 3	40	3 5	30	6 59	8	14 1	91
50	19 17	5 1	39	3 4	40	6 51	8	13 8	89
55	18 52	4 9	39	3 3	50	6 43	8	13 5	87
2 0	18 29	4 8	38	3 2	8 0	6 35	0 7	13 3	0 85
5	18 5	4 6	37	3 1	10	6 28	7	13 1	83
10	17 43	4 4	36	3 0	20	6 21	7	12 8	82
15	17 21	4 3	36	2 9	30	6 14	7	12 6	80
20	17 0	4 1	35	2 8	40	6 7	7	12 3	79
25	16 40	4 0	34	2 8	50	6 0	6	12 1	77
30	16 21	3 9	33	2 7	9 0	5 54	0 6	11 9	0 76
35	16 2	3 7	33	2 7	10	5 47	6	11 7	74
40	15 43	3 6	32	2 6	20	5 41	6	11 5	73
45	15 25	3 5	32	2 6	30	5 36	6	11 3	71
50	15 8	3 4	31	2 4	40	5 30	5	11 1	71
55	14 51	3 3	30	2 3	50	5 25	5	11 0	70
3 0	14 35	3 2	30	2 3	10 0	5 20	0 5	10 8	0 69
5	14 19	3 1	29	2 2	10	5 15	5	10 6	67
10	14 4	3 0	29	2 2	20	5 10	5	10 4	65
15	13 50	2 9	28	2 1	30	5 5	5	10 2	64
20	13 35	2 8	28	2 1	40	5 0	5	10 1	63
25	13 21	2 7	27	2 0	50	4 56	4	9 9	62
30	13 7	2 7	27	2 0	11 0	4 51	0 4	9 8	0 60
35	12 53	2 6	26	2 0	10	4 47	4	9 6	59
40	12 41	2 5	26	1 9	20	4 43	4	9 5	58
45	12 28	2 4	25	1 9	30	4 39	4	9 4	57
50	12 16	2 4	25	1 9	40	4 35	4	9 2	56
55	12 3	2 3	25	1 8	50	4 31	4	9 1	55

NOTE.—If the Barometer is over 30 inches the Barometer correction is *additive* to the Mean Refraction
If the Thermometer is less than 50° the Thermometer correction is *additive* to the Mean Refraction
And *vice versa*

TABLE XIII

Spherical Excess

Area of Triangle in Square Miles	*Spherical* Excess	Area of Triangle in Square Miles	*Spherical* Excess	Area of Triangle in Square Miles	*Spherical* Excess
					"
5	0 07	60	0 79	400	5 27
10	13	70	92	500	6 59
15	20	80	1 05	600	7 91
20	26	90	1 19	700	9 23
30	40	100	1 32	800	10 54
40	53	200	2 64	900	11 86
50	66	300	3 95	1000	13 18

Computed from formula, spherical excess $= \frac{A}{r^2 \sin 1}$ where A = area of triangle, r = mean radius of curvature

The table has been made out for latitude 30°, but may be used for all latitudes for topographical, tertiary, and secondary work

TABLE XIV.—Astronomical Refraction

The Mean Refraction is for Barometer 30 inches and Temperature 50° Fahr

Apparent Altitude	Mean Refraction	Diff for 1 Alt	Diff for +1 in Baro	Diff for 1° Temp
° ′	′ ″	′	″	″
0 0	33 51	11 7	74	8 1
5	32 53	11 3	71	7 6
10	31 58	10 9	69	7 3
15	31 5	10 5	67	7 0
20	30 13	10 1	65	6 7
25	29 24	9 7	63	6 4
30	28 37	9 4	61	6 1
35	27 51	9 0	59	5 9
40	27 6	8 7	58	5 6
45	26 24	8 4	56	5 4
50	25 43	8 0	55	5 1
55	25 3	7 7	53	4 9
1 0	24 25	7 4	52	4 7
5	23 48	7 1	50	4 6
10	23 13	6 9	49	4 5
15	22 40	6 6	48	4 4
20	22 8	6 3	46	4 2
25	21 37	6 1	45	4 0
30	21 7	5 9	44	3 9
35	20 38	5 7	43	3 8
40	20 10	5 5	42	3 6
45	19 43	5 3	40	3 5
50	19 17	5 1	39	3 4
55	18 52	4 9	39	3 3
2 0	18 29	4 8	38	3 2
5	18 5	4 6	37	3 1
10	17 43	4 4	36	3 0
15	17 21	4 3	36	2 9
20	17 0	4 1	35	2 8
25	16 40	4 0	34	2 8
30	16 21	3 9	33	2 7
35	16 2	3 7	33	2 7
40	15 43	3 6	32	2 6
45	15 25	3 5	32	2 5
50	15 8	3 4	31	2 4
55	14 51	3 3	30	2 3
3 0	14 35	3 2	30	2 3
5	14 19	3 1	29	2 2
10	14 4	3 0	29	2 2
15	13 50	2 9	28	2 1
20	13 35	2 8	28	2 1
25	13 21	2 7	27	2 0
30	13 7	2 7	27	2 0
35	12 53	2 6	26	2 0
40	12 41	2 5	26	1 9
45	12 28	2 4	25	1 9
50	12 16	2 4	25	1 9
55	12 3	2 3	25	1 8

Apparent Altitude	Mean Refraction	Diff for 1 Alt	Diff for +1 in Baro	Diff for −1° Temp
° ′	″		′	″
4 0	11 52	2 2	24 1	1 70
10	11 30	2 1	23 4	1 64
20	11 10	2 0	22 7	1 58
30	10 50	1 9	22 0	1 53
40	10 32	1 8	21 3	1 48
50	10 15	1 7	20 7	1 43
5 0	9 58	1 6	20 1	1 38
10	9 42	1 5	19 6	1 34
20	9 27	1 5	19 1	1 30
30	9 11	1 4	18 6	1 26
40	8 58	1 3	18 1	1 22
50	8 45	1 3	17 6	1 19
6 0	8 32	1 2	17 2	1 15
10	8 20	1 2	16 8	1 11
20	8 9	1 1	16 4	1 09
30	7 58	1 1	16 0	1 06
40	7 47	1 0	15 7	1 03
50	7 37	1 0	15 3	1 00
7 0	7 27	1 0	15 0	0 98
10	7 17	0 9	14 6	95
20	7 8	9	14 3	93
30	6 59	8	14 1	91
40	6 51	8	13 8	89
50	6 43	8	13 5	87
8 0	6 35	0 7	13 3	0 85
10	6 28	7	13 1	83
20	6 21	7	12 8	82
30	6 14	7	12 6	80
40	6 7	7	12 3	79
50	6 0	6	12 1	77
9 0	5 51	0 6	11 9	0 76
10	5 47	6	11 7	74
20	5 41	6	11 5	73
30	5 36	6	11 3	71
40	5 30	5	11 1	71
50	5 25	5	11 0	70
10 0	5 20	0 5	10 8	0 69
10	5 15	5	10 6	67
20	5 10	5	10 4	65
30	5 5	5	10 2	64
40	5 0	5	10 1	63
50	4 56	4	9 9	62
11 0	4 51	0 4	9 8	0 60
10	4 47	4	9 6	59
20	4 43	4	9 5	58
30	4 39	4	9 4	57
40	4 35	4	9 2	56
50	4 31	4	9 1	55

NOTE.—If the Barometer is over 30 inches the Barometer correction is *additive* to the Mean Refraction
If the Thermometer is less than 50° the Thermometer correction is *additive* to the Mean Refraction
And *vice versa*

TABLE XIII

Spherical Excess

Area of Triangle in Square Miles	Spherical Excess	Area of Triangle in Square Miles	Spherical Excess	Area of Triangle in Square Miles	Spherical Excess
	′		′		′
5	0 07	60	0 79	400	5 27
10	13	70	92	500	6 59
15	20	80	1 05	600	7 91
20	26	90	1 19	700	9 23
30	40	100	1 32	800	10 54
40	53	200	2 64	900	11 86
50	66	300	3 95	1000	13 18

Computed from formula spherical excess $= \frac{A}{r \sin 1}$ where A = area of triangle, r = mean radius of curvature

The table has been made out for latitude 30°, but may be used for all latitudes for topographical, tertiary, and secondary work

TABLE XV

Parallax of the Sun

Altitude	Parallax	Altitude	Parallax
°		°	
0	8 8	50	5 7
5	8 8	55	5 1
10	8 7	60	4 4
15	8 5	65	3 7
20	8 3	70	3 0
25	8 0	75	2 3
30	7 7	80	1 5
35	7 2	85	0 8
40	6 8	90	0 0
45	6 2		

Computed from the formula

Parallax in altitude = horizontal parallax × cos altitude

The sun's horizontal parallax varies during the year from 8″ 95 to 8″ 65
The above is a mean value, sufficiently exact for all topographical purposes

TABLE XIV.—Astronomical Refraction.

The Mean Refraction is for Barometer 30 inches and Temperature 50° Fahr

Apparent Altitude	Mean Refraction	Diff for 1 Alt	Diff for + 1 in Baro	Diff for − 1° Temp	Apparent Altitude	Mean Refraction	Diff for 1′ Alt	Diff for + 1 in Baro	Diff for − 1° Temp
° ′	′ ″	′	′	′	° ′	′ ″	′	′	′
12 0	4 28 1	0 38	9 00	0 556	42 0	1 4 6	0 038	2 16	0 130
10	4 24 4	37	8 86	548	43 0	1 2 4	036	2 09	125
20	4 20 8	36	8 74	541	44 0	1 0 3	034	2 02	120
30	4 17 3	35	8 63	533	45 0	0 58 1	034	1 94	117
40	4 13 9	33	8 51	524	46 0	56 1	033	1 88	112
50	4 10 7	32	8 41	517	47 0	54 2	032	1 81	108
13 0	4 7 5	0 31	8 30	0 509	48 0	0 52 3	0·031	1·75	0 104
10	4 4 4	31	8 20	503	49 0	50 5	030	1 69	101
20	4 1 4	30	8 10	496	50 0	48 8	029	1 63	097
30	3 58 4	30	8 00	490	51 0	47 1	028	1 58	094
40	3 55 5	29	7 89	482	52 0	45 4	027	1 52	090
50	3 52 6	29	7 79	476	53 0	43 8	026	1 47	088
14 0	3 49·9	0 28	7 70	0 469	54 0	0 42 2	0·026	1 41	0 085
10	3 47 1	28	7 61	464	55 0	40 8	025	1 36	082
20	3 44 4	27	7 52	458	56 0	39 3	025	1 31	079
30	3 41 8	26	7 43	453	57 0	37 8	025	1 26	076
40	3 39 2	26	7 34	448	58 0	36 4	024	1 22	073
50	3 36 7	25	7 26	444	59 0	35 0	024	1 17	070
15 0	3 34 3	0 24	7 18	0 439	60 0	33 6	0 023	1 12	0 067
30	3 27 3	22	6 95	424	61 0	32 3	022	1·08	065
16 0	3 20 6	21	6 73	411	62 0	31 0	022	1·04	062
30	3 14 4	20	6 51	399	63 0	29·7	021	0 99	060
17 0	3 8 5	19	6 31	386	64 0	28 4	021	95	057
30	3 2 9	18	6 12	374	65 0	27 2	020	91	055
18 0	2 57 6	0 17	5 98	0 362	66 0	25·9	0 020	0 87	0 052
19 0	2 47 7	16	5 61	340	67 0	24 7	020	83	050
20 0	2 38 7	15	5 31	322	68 0	23 5	020	79	047
21 0	2 30 5	13	5·04	305	69 0	22 4	020	75	045
22 0	2 23 2	12	4 79	290	70 0	21 2	020	71	043
23 0	2 16 5	11	4 57	276	71 0	19 9	020	67	040
24 0	2 10 1	0 10	4 36	0 264	72 0	18 8	0·019	0 63	0·038
25 0	2 4 2	09	4 16	252	73 0	17 7	018	59	036
26 0	1 58 8	09	3·97	241	74 0	16 6	018	56	033
27 0	1 53 8	08	3 81	230	75 0	15 5	018	52	031
28 0	1 49 1	08	3 65	219	76 0	14 4	018	48	029
29 0	1 44·7	07	3 50	209	77 0	13 4	017	45	027
30 0	1 40 5	0·07	3 36	0 201	78 0	12 3	0·017	0 41	0 025
31 0	1 36 6	06	3 23	193	79 0	11 2	017	38	023
32 0	1 33·0	06	3 11	186	80 0	10 2	017	34	021
33 0	1 29 5	06	2·99	179	81 0	9 2	017	31	018
34 0	1 26 1	05	2 88	173	82 0	8 2	017	27	016
35 0	1 23·0	05	2·78	167	83 0	7 1	017	24	014
36 0	1 20·0	0·05	2 68	0 161	84 0	6 1	0 017	0 20	0·012
37 0	1 17 1	05	2 58	155	85 0	5 1	017	17	010
38 0	1 14 4	05	2 49	149	86 0	4 1	017	14	008
39 0	1 11 8	04	2 40	144	87 0	3 1	017	10	006
40 0	1 9 3	04	2 32	139	88 0	2·0	017	07	004
41 0	1 6·9	04	2 24	134	89 0	1·0	017	03	002

NOTE.—If the Barometer is over 30 inches the Barometer correction is *additive* to the Mean Refraction
If the Thermometer is less than 50° the Thermometer correction is *additive* to the Mean Refraction
And vice versa

25	0 3	3 9	11 5	22 9	38 3	57 6	80 8	108 0	139 1	174 1	214 0	257 9	306 6	360 3	418 0	480 5	547 9	620 1	696 6	777 9
26	0 4	4 0	11 6	23 1	38 6	58 0	81 3	108 9	139 6	174 7	214 7	258 6	307 3	361 2	419 0	481 5	548 9	621 1	697 6	778 4
27	0 4	4 1	11 8	23 4	38 9	58 1	81 7	109 0	140 2	175 1	214 4	258 4	307 1	361 1	419 8	482 3	549 8	622 1	698 6	779 4
28	0 4	4 2	11 9	23 6	39 2	58 7	82 1	109 5	140 7	175 9	215 1	258 1	307 8	361 9	420 6	483 2	550 8	623 2	699 7	780 5	868 2
29	0 5	4 3	12 1	23 8	39 5	59 0	82 5	110 0	141 3	176 6	215 8	259 9	308 9	363 0	421 7	484 3	551 8	624 3	700 9	781 8	869 6
30	0 5	4 4	12 3	24 0	39 8	59 4	83 0	110 4	141 8	177 2	216 4	260 4	309 7	363 7	422 7	485 4	553 1	625 4	701 9	782 9	870 8
31	0 5	4 5	12 4	24 3	40 1	59 8	83 4	110 9	142 4	177 8	217 1	260 9	310 5	364 6	423 6	486 4	553 9	626 5	703 2	783 9	871 9
32	0 6	4 6	12 6	24 5	40 3	60 1	83 8	111 4	143 0	178 4	217 8	261 4	311 4	365 5	424 6	487 5	555 0	627 5	703 3	784 1	872 7
33	0 6	4 7	12 8	24 7	40 6	60 5	84 2	111 9	143 5	179 0	218 5	262 0	312 0	366 4	425 5	488 5	556 0	628 5	704 5	785 3	873 6
34	0 6	4 8	12 9	25 0	40 9	60 8	84 7	112 4	144 1	179 7	219 2	262 6	312 6	367 1	426 4	489 5	557 0	629 7	705 8	786 5	874 5
35	0 7	4 9	13 1	25 2	41 2	61 2	85 1	112 9	144 6	180 3	219 9	263 4	313 3	367 8	427 4	490 5	558 0	630 8	707 0	787 7	875 6
36	0 7	5 0	13 3	25 4	41 5	61 6	85 5	113 4	145 2	180 9	220 6	264 1	314 0	368 4	428 1	491 4	559 0	631 8	707 9	788 8	876 8
37	0 7	5 1	13 4	25 7	41 8	61 9	86 0	113 9	145 8	181 6	221 3	264 9	314 8	369 2	428 9	492 4	560 0	632 8	708 9	789 8	877 8
38	0 8	5 2	13 6	25 9	42 1	62 3	86 4	114 4	146 3	182 2	222 0	265 7	315 7	369 8	429 8	493 4	561 0	633 8	709 9	790 8	878 8
39	0 8	5 3	13 8	26 2	42 5	62 7	86 8	114 9	146 9	182 8	222 7	266 4	316 4	370 7	430 7	494 4	562 1	634 8	710 9	791 8	879 8
40	0 9	5 4	14 0	26 4	42 8	63 0	87 3	115 4	147 5	183 5	223 4	267 2	317 0	371 6	431 6	495 4	563 2	635 8	711 9	792 8	880 8
41	0 9	5 6	14 1	26 6	43 1	63 4	87 7	115 9	148 0	184 1	224 1	267 8	317 8	372 5	432 5	496 4	564 2	636 8	712 9	793 8	881 8
42	1 0	5 7	14 3	26 9	43 4	63 8	88 1	116 4	148 6	184 7	224 8	268 4	318 6	373 3	433 4	497 4	565 2	637 8	713 9	794 8	882 8
43	1 0	5 8	14 5	27 1	43 7	64 2	88 6	116 9	149 2	185 1	225 5	269 1	319 4	374 1	434 3	498 4	566 2	638 8	714 9	795 8	883 8
44	1 1	5 9	14 7	27 4	44 0	64 5	89 0	117 4	149 7	186 0	226 2	270 3	319 3	375 0	435 2	499 4	567 3	639 8	715 9	796 8	884 8
45	1 1	6 0	14 8	27 6	44 3	64 9	89 5	117 9	150 3	186 8	226 9	271 0	319 1	375 1	435 1	500 4	568 3	640 8	716 9	797 8	885 8
46	1 2	6 1	15 0	27 9	44 6	65 3	89 9	118 4	150 9	187 3	227 6	271 8	319 9	376 0	436 0	501 4	569 3	641 8	717 9	798 8	886 8
47	1 2	6 2	15 2	28 1	44 9	65 7	90 3	118 9	151 5	187 9	228 3	272 0	320 8	376 9	436 9	502 4	570 3	642 8	718 9	799 8	887 8
48	1 3	6 4	15 4	28 3	45 2	66 0	90 8	119 5	152 0	188 5	229 0	273 3	321 6	377 8	437 9	503 4	571 3	643 8	719 9	800 8	888 8
49	1 3	6 5	15 6	28 6	45 5	66 4	91 2	120 0	152 6	189 2	229 7	274 1	322 4	378 7	438 9	504 4	572 3	644 8	720 9	801 8	889 8
50	1 4	6 6	15 8	28 8	45 9	66 8	91 7	120 5	153 2	189 8	230 4	274 9	323 3	379 6	439 8	505 4	573 3	645 8	721 9	802 8	890 8
51	1 4	6 7	15 9	29 1	46 2	67 2	92 1	121 0	153 8	190 5	231 1	275 6	324 1	380 5	440 8	506 4	574 3	646 8	722 9	803 8	891 8
52	1 5	6 8	16 1	29 4	46 5	67 6	92 6	121 5	154 3	191 1	231 8	276 4	325 0	381 4	441 8	507 4	575 3	647 8	723 9	804 8	892 8
53	1 5	7 0	16 3	29 6	46 8	68 0	93 0	122 0	154 9	191 8	232 5	277 2	325 8	382 3	442 8	508 4	576 3	648 8	724 9	805 8	893 8
54	1 6	7 1	16 5	29 9	47 1	68 3	93 5	122 5	155 5	192 4	233 2	278 0	326 7	383 3	443 8	509 4	577 3	649 8	725 9	806 8	894 8
55	1 6	7 2	16 7	30 1	47 5	68 7	93 9	123 1	156 1	193 1	234 0	278 8	327 5	384 0	444 8	510 4	578 3	650 8	726 9	807 8	895 8
56	1 7	7 3	16 9	30 4	47 8	69 1	94 4	123 6	156 7	193 7	234 7	279 5	328 4	384 1	445 8	511 4	579 3	651 8	727 9	808 8	896 8
57	1 8	7 5	17 1	30 6	48 1	69 5	94 8	124 1	157 3	194 4	235 4	280 3	329 2	385 2	446 8	512 4	580 3	652 8	728 9	809 8	897 8
58	1 8	7 6	17 3	30 9	48 4	69 9	95 3	124 6	157 8	195 0	236 1	281 1	330 0	386 2	447 8	513 4	581 3	653 8	729 9	810 8	898 8
59	1 9	7 7	17 5	31 2	48 8	70 3	95 7	125 1	158 4	196 7	236 8	281 9	330 9	386 8	448 8	514 4	582 3	654 8	730 9	811 8	899 8

TABLE XVI

Latitude by Circum Meridian Observations

Reduction to Meridian

$$m = \frac{2 \sin^2 \frac{1}{2}}{\sin 1''}$$

t	m	1m	2m	3m	4m	5m	6m	7m	8m	9m	10m	11m	12m	13m	14m	15m	16m	17m	18m	19m
s	′	″																	′	″
0	0 0	2 0	7 8	17 7	31 4	49 1	70 7	96 2	125 7	159 0	196 3	237 5	282 7	331 7	384 7	441 6	502 5	567 2	635 9	708 4
1	0 0	2 0	8 0	17 9	31 7	49 4	71 1	96 7	126 2	159 6	197 0	238 1	284 3	332 6	385 6	442 6	503 5	568 3	637 0	709 7
2	0 0	2 1	8 1	18 1	31 9	49 7	71 5	97 1	126 7	160 2	197 6	239 0	284 3	333 4	386 6	443 6	504 6	569 4	638 2	710 9
3	0 0	2 2	8 2	18 3	32 2	50 1	71 9	97 6	127 2	160 8	198 3	239 7	285 0	334 3	387 5	444 6	505 6	570 5	639 4	712 1
4	0 0	2 2	8 4	18 5	32 5	50 4	72 3	98 0	127 8	161 4	198 9	240 4	285 8	335 2	388 4	445 6	506 7	571 6	640 6	713 4
5	0 0	2 3	8 5	18 7	32 7	50 7	72 7	98 5	128 3	162 0	199 6	241 1	286 6	336 0	389 3	446 6	507 7	572 8	641 7	714 6
6	0 0	2 4	8 7	18 9	33 0	51 1	73 1	99 0	128 8	162 6	200 3	241 9	287 4	336 8	390 2	447 5	508 8	573 9	642 9	715 9
7	0 0	2 4	8 8	19 1	33 3	51 4	73 5	99 4	129 3	163 2	200 9	242 6	288 2	337 7	391 2	448 5	509 8	574 9	644 1	717 1
8	0 0	2 5	8 9	19 3	33 5	51 7	73 9	99 9	129 9	163 8	201 6	243 3	289 0	338 6	392 1	449 5	510 9	576 1	645 3	718 4
9	0 0	2 6	9 1	19 5	33 8	52 1	74 3	100 4	130 4	164 4	202 2	244 1	289 8	339 4	393 0	450 5	511 9	577 2	646 5	719 6
10	0 1	2 7	9 2	19 7	34 1	52 4	74 7	100 8	130 9	165 0	202 9	244 8	290 6	340 3	393 9	451 5	513 0	578 4	647 7	720 9
11	0 1	2 7	9 4	19 9	34 4	52 7	75 1	101 3	131 5	165 6	203 6	245 5	291 4	341 2	394 9	452 5	514 0	579 5	648 9	722 1
12	0 1	2 8	9 5	20 1	34 6	53 1	75 5	101 8	132 0	166 2	204 2	246 3	292 2	342 0	395 8	453 5	515 1	580 6	650 0	723 4
13	0 1	2 9	9 6	20 3	34 9	53 4	75 9	102 3	132 6	166 8	204 9	247 0	293 0	342 9	396 7	454 5	516 1	581 7	651 2	724 6
14	0 1	3 0	9 8	20 5	35 2	53 8	76 3	102 7	133 1	167 4	205 6	247 7	293 8	343 7	397 6	455 5	517 2	582 9	652 4	725 9
15	0 1	3 1	9 9	20 7	35 5	54 1	76 7	103 2	133 6	168 0	206 3	248 5	294 6	344 6	398 6	456 5	518 3	584 0	653 3	727 2
16	0 1	3 1	10 1	20 9	35 7	54 4	77 1	103 7	134 2	168 6	206 9	249 2	295 4	345 5	399 5	457 5	519 3	585 1	654 8	728 4
17	0 2	3 2	10 2	21 2	36 0	54 8	77 5	104 2	134 7	169 2	207 6	249 9	296 2	346 4	400 5	458 5	520 4	586 2	656 0	729 7
18	0 2	3 3	10 4	21 4	36 3	55 1	77 9	104 6	135 3	169 8	208 3	250 7	297 0	347 2	401 4	459 5	521 5	587 4	657 2	730 9
19	0 2	3 4	10 5	21 6	36 6	55 5	78 3	105 1	135 8	170 4	208 9	251 4	297 8	348 1	402 3	460 5	522 5	588 5	658 4	732 2
20	0 2	3 5	10 7	21 8	36 9	55 8	78 8	105 6	136 3	171 0	209 6	252 2	298 6	349 0	403 3	461 5	523 6	589 6	659 6	733 5
21	0 2	3 6	10 8	22 0	37 2	56 2	79 2	106 1	136 9	171 6	210 3	252 9	299 4	349 8	404 2	462 5	524 7	590 8	660 8	734 7
22	0 3	3 7	11 0	22 3	37 4	56 5	79 6	106 6	137 4	172 2	211 0	253 6	300 2	350 7	405 1	463 5	525 7	591 9	662 0	736 0
23	0 3	3 8	11 2	22 5	37 7	56 9	80 0	107 0	138 0	172 9	211 7	254 4	301 0	351 6	406 1	464 5	526 8	593 0	663 2	737 3
24	0 3	3 8	11 3	22 7	38 0	57 3	80 4	107 5	138 5	173 5	212 3	255 1	301 8	352 5	407 0	465 5	527 9	594 2	664 4	738 5

TABLE XVIII

Longitude by Occultations

Reduction of Latitude

Compression $\frac{1}{294}$

Lat	Red	Lat	Red	Lat	Red
°	′			°	
0	0 0	30	10 7	60	10 9
1	0 24	31	10 19	61	9 56
2	0 49	32	10 30	62	9 43
3	1 13	33	10 40	63	9 29
4	1 37	34	10 50	64	9 14
5	2 1	35	10 59	65	8 59
6	2 25	36	11 7	66	8 43
7	2 49	37	11 14	67	8 26
8	3 13	38	11 21	68	8 9
9	3 37	39	11 27	69	7 51
10	3 59	40	11 31	70	7 32
11	4 22	41	11 35	71	7 13
12	4 45	42	11 38	72	6 54
13	5 7	43	11 40	73	6 34
14	5 28	44	11 41	74	6 13
15	5 50	45	11 42	75	5 52
16	6 11	46	11 42	76	5 31
17	6 31	47	11 41	77	5 9
18	6 51	48	11 38	78	4 46
19	7 11	49	11 36	79	4 24
20	7 30	50	11 32	80	4 1
21	7 49	51	11 27	81	3 38
22	8 8	52	11 22	82	3 14
23	8 24	53	11 15	83	2 50
24	8 41	54	11 8	84	2 26
25	8 57	55	11 0	85	2 2
26	9 12	56	10 52	86	1 38
27	9 27	57	10 42	87	1 14
28	9 41	58	10 32	88	0 49
29	9 54	59	10 21	89	0 24

Formula

$$q = l - (2 - e^2)\frac{e^2}{\sin 1}\sin 2\phi \left\{\frac{1}{2} + \frac{e}{2}\right\}\frac{\sin 4\phi}{2\sin 1},$$

$$e = \sqrt{2e - e^2}$$

$$e = \frac{1}{294}$$

TABLE XVII

Longitude by Occultations

Correction of the Moon's Equatorial Parallax for the figure of the Earth
(Compression $\frac{1}{294\cdot6}$)

Lat	Horizontal Parallax				
	54	56	58	60	62′
°				′	″
0	0	0	0	0	0
8	2	2	2	2	2
16	8	9	9	9	9
20	1 3	1 3	1 4	1 4	1 5
24	1 8	1 9	2 0	2 0	2 0
28	2 5	2 5	2 6	2 7	2 8
32	3 1	3 2	3 3	3 4	3 5
36	3 8	4 0	4 1	4 3	4 4
40	4 6	4 7	4 9	5 1	5 2
44	5 3	5 5	5 7	5 9	6 1
48	6 1	6 7	7 0	7 2	7 4
52	6 9	7 1	7 4	7 6	7 9
56	7 6	7 9	8 2	8 5	8 7
60	8 3	8 6	8 9	9 2	9 6
64	9 0	9 3	9 6	10 0	10 3
68	9 5	9 9	10 3	10 6	11 0
72	10 0	10 4	10 8	11 2	11 6
76	10 5	10 9	11 2	11 6	12 0
80	10 8	11 2	11 6	12 0	12 4

APPENDIX I

TABLE I.—LATITUDES, LONGITUDES AND REVERSE AZIMUTHS

This Table gives the logarithms of the quantities P, Q, R, S, T used in the forms employed for the computation of Terrestrial Latitudes, Longitudes, and Reverse Azimuths (*vide* Form 3)

Suppose that **A** and **B** are two stations and that we have given—

λ = Latitude of **A**

L = Longitude of **A**,

A = Azimuth of **B** from **A** (measured from S. to W.)

s = Distance in feet at mean sea level between **A** and **B**,

and we require

λ_b = Latitude of **B**

L_b = Longitude of **B**

B = Azimuth of **A** from **B**

If we put

$$\lambda \quad \lambda + \Delta\lambda \qquad L_b \quad L + \Delta L, \quad \text{and} \quad B = s + A + \Delta A$$

it will be seen that we require the differences

$$\Delta\lambda \quad \Delta L \quad \text{and} \quad \Delta A$$

The values of these quantities are found as follows —

Putting

$$\Delta\lambda = \delta_1\lambda + \delta\lambda$$

$$\Delta L \quad \delta_1 L + \delta L$$

$$\Delta A \quad \delta_1 A + \delta A$$

then

$\delta_1\lambda$	$P \cos A\ s$	$\delta\lambda$	$\delta_1 A I \sin A\ s$
$\delta_1 L$	$\delta_1\lambda Q \sec\lambda \tan A$	δL	$\delta\lambda S \cot A$
$\delta_1 A$	$s_1 I \sin\lambda$	δA	δLT

which are the expressions used in the form for computation

It will be noticed that each term is found consecutively from the preceding one

The proper signs to be given to the quantities will be found in Tables II (A) and II (B)

For Latitudes other than those given in the Table the quantities must be found by interpolation

APPENDIX I

TABLE I—LATITUDES, LONGITUDES AND REVERSE AZIMUTHS

This Table gives the logarithms of the quantities P, Q R, S T used in the forms employed for the computation of Terrestrial Latitudes Longitudes, and Reverse Azimuths (*vide* Form 2)

Suppose that **A** and **B** are two stations and that we have given—

λ – Latitude of **A**

L = Longitude of **A**

A = Azimuth of **B** from **A** (measured from S to W)

s = Distance in feet at mean sea level between **A** and **B**,

and we require

λ_b – Latitude of **B**

L_b – Longitude of **B**

B – Azimuth of **A** from **B**

If we put

$$\lambda_b = \lambda + \Delta\lambda \qquad L_b = L + \Delta L, \quad \text{and} \quad B = \sim + A + \Delta A$$

it will be seen that we require the differences

$$\Delta\lambda, \quad \Delta L \quad \text{and} \quad \Delta A$$

The values of the quantities are found as follows —

Putting

$$\Delta\lambda = \delta_1\lambda + \delta\lambda$$

$$\Delta L = \delta_1 L + \delta L$$

$$\Delta A = \delta_1 A + \delta A$$

then

$\delta_1\lambda$	$P\cos A \cdot s$	$\delta\lambda$	$\delta_1 A L_1 \sin A \cdot s$
$\delta_1 L$	$\delta_1\lambda Q \sec\lambda \tan A$	δL	$\delta\lambda S \cot A$
$\delta_1 A$	$\delta_1 L \sin\lambda$	δA	δLT

which are the expressions used in the form for computation

It will be noticed that each term is found consecutively from the preceding one

The proper signs to be given to the quantities will be found in Tables II (A) and II (B)

For latitudes other than those given in the Table the quantities must be found by interpolation

APPENDIX I

TABLE I.—LATITUDES, LONGITUDES AND REVERSE AZIMUTHS

This Table gives the logarithms of the quantities P, Q, R, S, T used in the forms employed for the computation of Terrestrial Latitudes, Longitudes, and Reverse Azimuths (*vide* Form 2)

Suppose that **A** and **B** are two stations and that we have given—

λ = Latitude of **A**

L = Longitude of **A**,

$\backslash$ = Azimuth of **B** from **A** (measured from S to W)

s = Distance in feet at mean sea level between **A** and **B**,

and we require

λ_b = Latitude of **B**

L_b = Longitude of **B**

B = Azimuth of **A** from **B**

If we put

$$\lambda_b = \lambda + \Delta\lambda \qquad L_b = L + \Delta L, \quad \text{and} \quad B = \pi + A + \Delta A,$$

it will be seen that we require the differences

$$\Delta\lambda, \quad \Delta L \quad \text{and} \quad \Delta A$$

The values of these quantities are found as follows —

Putting

$$\Delta\lambda = \delta_1\lambda + \delta\lambda$$

$$\Delta L = \delta_1 L + \delta L$$

$$\Delta A = \delta_1 A + \delta A$$

then

$$\delta_1\lambda = P\cos A \, s \qquad \delta\lambda = \delta_1 A I \nu \sin A$$

$$\delta_1 L = \delta_1\lambda Q \sec\lambda \tan\backslash \qquad \delta L = \delta\lambda S \cot\backslash$$

$$\delta_1 A = s_1 L \sin\lambda \qquad \delta\backslash = \delta LT,$$

which are the expressions used in the form for computation

It will be noticed that each term is found consecutively from the preceding one

The proper signs to be given to the quantities will be found in Tables II (A) and II (B)

For latitudes other than those given in the Table the quantities must be found by interpolation

APPENDIX II

COMPUTATION OF DISTANCES AND AZIMUTHS

Given the latitudes and longitudes of two points A and B

REQUIRED	Azimuths B from A (A) and A from B (π + A + ΔA) and length in feet between Station A and Station B (c)	
Data	Latitude	Longitude
Station A	λ_a −	L_a −
Station B	λ_b	L_b −
	$\Delta\lambda$ ±	ΔL − ±
	$\frac{\Delta\lambda}{2}$ ±	$\frac{\Delta L}{2}$ − ±
λ_n − Middle Latitude $\left(\lambda_a + \frac{\Delta\lambda}{2}\right)$		

$\Delta\lambda$ When A and B are both N or S of the Equator

$$\Delta\lambda \text{ is } \begin{matrix}+\\-\end{matrix} \text{ when } \lambda_b \text{ is } \begin{matrix}\text{greater}\\\text{less}\end{matrix} \text{ than } \lambda_a \text{ and } \lambda_n = \tfrac{1}{2}(\lambda_a + \lambda_b)$$

If the ray crosses the Equator

$\Delta\lambda$ is always negative and $= \lambda_a + \lambda_b$, and $\lambda_n = \frac{1}{2}$ diff between λ_a and λ_b

ΔL When A and B are both W of Greenwich

$$\Delta L \text{ is } \begin{matrix}+\\-\end{matrix} \text{ when } L_b \text{ is } \begin{matrix}\text{less}\\\text{greater}\end{matrix} \text{ than } L_a$$

When A and B are both E of Greenwich

$$\Delta L \text{ is } \begin{matrix}+\\-\end{matrix} \text{ when } L_b \text{ is } \begin{matrix}\text{greater}\\\text{less}\end{matrix} \text{ than } L_a$$

If the ray crosses the meridian of Greenwich —

$$\Delta L = L_a + L_b \text{ and is } \begin{matrix}+\\-\end{matrix} \text{ if } L_b \text{ is } \begin{matrix}E\\W\end{matrix} \text{ of Greenwich}$$

Formulæ	Logarithms		Results
	To 5 places of Decimals		
	$\log \frac{\Delta L}{2}$ (in secs)	–	$\frac{\Delta\lambda}{2}$ –
$\frac{\Delta\lambda}{2} = \frac{\Delta L}{2} \sin \lambda_m$	$\log \sin \lambda_m$	–	[When λ_m is $\frac{N}{S}$ of equator ΔA has the $\frac{\text{same}}{\text{opposite}}$ sign as ΔL]
	$\log \frac{\Delta\lambda}{2}$	–	
	Log Table XII		
$\log \tan\left(\lambda + \frac{\Delta\lambda}{2}\right) =$	Colog Table XI		$\lambda + \frac{\Delta\lambda}{2}$
Log Table XII † log Table XI † + log ΔL log $\Delta\lambda$	log ΔL (in secs)		[Quadrant obtained from Table II (A) or II (B) with given signs of $\Delta\lambda$ and ΔL as above]
	Col $\Delta\lambda$		
	$\log \tan\left(\lambda + \frac{\Delta\lambda}{2}\right)$		
	$\log \sec\left(\lambda + \frac{\Delta\lambda}{2}\right)$		
$\log c = \log \sec\left(\lambda + \frac{\Delta\lambda}{2}\right) +$ log Table XI † + log $\Delta\lambda$	log Table XI	=	
	log $\Delta\lambda$ (in secs)		
	$\log c$		c
Required Azimuths			
	$\lambda + \frac{\Delta\lambda}{2}$		
λ	$\frac{\Delta\lambda}{2}$	+ or	
	Diff		Azimuth of **B** from **A**
$\pi + \lambda + \Delta\lambda$	π + Sum		Azimuth of **A** from **B**

† Values for middle latitude, i.e. for $\lambda + \frac{\Delta\lambda}{2}$

APPENDIX III

ALTERNATIVE FORMULÆ FOR DETERMINING LATITUDE, LONGITUDE, AND REVERSE AZIMUTH IN TRIANGULATION, ALSO THOSE FOR THE REVERSE PROCESS

Direct Process —

$$\frac{\Delta A}{2} = \frac{\Delta L}{2}\left(\sin \lambda + \frac{\Delta \lambda}{2}\right) \tag{1}$$

$$\Delta \lambda = - \frac{e}{\rho} \cos\left(A + \frac{\Delta A}{2}\right) \operatorname{cosec} 1 \tag{2}$$

$$\Delta L = - \frac{e}{\nu} \frac{\sin\left(A + \frac{\Delta A}{2}\right)}{\cos\left(\lambda + \frac{\Delta \lambda}{2}\right)} \operatorname{cosec} 1 \tag{3}$$

where A, λ L are the initial azimuth latitude and longitude and ΔA $\Delta \lambda$ ΔL, are the increments to be added to the initial values to obtain those of the distant station at the end of the line of which e is the length in feet

Now

$$\log \frac{\operatorname{cosec} 1}{\rho} = P \text{ (Table I)}$$

and

$$\log \frac{\operatorname{cosec} 1}{\nu} = P + Q \text{ (Table I)}$$

To obtain a value for $\frac{\Delta A}{2}$ the approximate position of the end of the line must be known by measurement from a plane-table or approximate computation, and the rough values for ΔL and $\Delta \lambda$ thus obtained are substituted in (1) The rest is obvious

The Reverse Process, *i.e.* the latitudes and longitudes of the two stations being known, to compute the azimuths and distance —

Here we know ΔL λ, and $\Delta \lambda$ and can therefore compute the value of ΔA from (1)

Dividing (3) by (2)

$$\frac{\Delta L}{\Delta \lambda} = \frac{\rho}{\nu} \tan\left(A + \frac{\Delta A}{2}\right) \sec\left(\lambda + \frac{\Delta \lambda}{2}\right) \tag{4},$$

where

$$\log \frac{\rho}{\nu} = Q \text{ (Table I)}$$

From this $\left(A + \frac{\Delta A}{2}\right)$ can be computed and then from (2) e can be found

NOTE —Both in the Direct Process and in the Reverse Process the values of P and Q to be used are those for the *mean latitude* $\left(\lambda + \frac{\Delta \lambda}{2}\right)$

APPENDIX IV

TABLE IV—COMPUTATION OF HEIGHTS

This table is to facilitate finding the subtended angle when only one angle has been observed

D_a / I_a } angle of { Depression / Elevation } at **A**

D_b / I_b } to do at **B**

c = distance in feet between **A** and **B**

Case 1.—When reciprocal angles have been observed—

(*a*) If both angles are depressions take half the difference
(*b*) If one angle only is in elevation take half the sum

The result is an auxiliary angle called the subtended angle (S)—

$$\text{i.e. } S = \frac{D_b - D_a}{2} \text{ or } \frac{I_a + D_b}{2}$$

Case 2.—*When one angle only* (D_a *or* I_a) *has been observed we must first find the subtended angle*

Rule.—Subtract the quantity in Table IV from log c. The natural number corresponding to the resulting logarithm is an angle K in seconds of arc, then—

$$S = K - D, \text{ or } K + I$$

Having now found S in either case the difference in height in feet (h) between **A** and **B** is obtained from the formula—

$$h = c \tan S$$

EXAMPLE OF 2ND CASE—

Given $\log c = 4.8907$
and $D = 0^\circ\ 14'\ 25''$,

to find S in lat 20° with coefficient of refraction .07—

$\log c = 4.8907$

Number in Table IV under .07 for lat 20 } $= 2.3716$

$\log K = 2.5191$

$K = 330'' = 0^\circ\ 5'\ 30''$
$D = 0\ 14\ 35$

Hence $S = K - D = 0\ 9\ 5$

See Form II, p. 31

APPENDIX III

ALTERNATIVE FORMULÆ FOR DETERMINING LATITUDE, LONGITUDE, AND REVERSE AZIMUTH IN TRIANGULATION, ALSO THOSE FOR THE REVERSE PROCESS

Direct Process —

$$\frac{\Delta A}{2} = \frac{\Delta L}{2}\left(\sin \lambda + \frac{\Delta\lambda}{2}\right) \quad . \quad (1),$$

$$\Delta\lambda = \frac{c}{\rho} \cos\left(A + \frac{\Delta A}{2}\right) \operatorname{cosec} 1 \quad . \quad (2),$$

$$\Delta L = \frac{c}{\nu} \frac{\sin\left(A + \frac{\Delta A}{2}\right)}{\cos\left(\lambda + \frac{\Delta\lambda}{2}\right)} \frac{\Delta\lambda}{2} \operatorname{cosec} 1' \quad . \quad . \quad (3),$$

where A, λ, L are the initial azimuth latitude, and longitude, and ΔA, $\Delta\lambda$, ΔL, are the increments to be added to the initial values to obtain those of the distant station at the end of the line, of which c is the length in feet

Now

$$\log \frac{\operatorname{cosec} 1}{\rho} - P \text{ (Table I)}$$

and

$$\log \frac{\operatorname{cosec} 1}{\nu} - P + Q \text{ (Table I)}$$

To obtain a value for $\frac{\Delta A}{2}$ the approximate position of the end of the line must be known by measurement from a plane table or approximate computation, and the rough values for ΔL and $\Delta\lambda$ thus obtained are substituted in (1) The rest is obvious

The Reverse Process, *i e* the latitudes and longitudes of the two stations being known, to compute the azimuths and distance —

Here we know ΔL, λ, and $\Delta\lambda$, and can therefore compute the value of ΔA from (1)

Dividing (3) by (2),

$$\frac{\Delta L}{\Delta\lambda} = \frac{\rho}{\nu} \tan\left(A + \frac{\Delta A}{2}\right) \sec\left(\lambda + \frac{\Delta\lambda}{2}\right) \quad (4),$$

where

$$\log \frac{\rho}{\nu} = Q \text{ (Table I)}$$

From this, $\left(A + \frac{\Delta A}{2}\right)$ can be computed, and then from (2) c can be found

NOTE —Both in the Direct Process and in the Reverse Process the values of P and Q to be used are those for the *mean latitude* $\left(\lambda + \frac{\Delta\lambda}{2}\right)$

APPENDIX IV

TABLE IV—COMPUTATION OF HEIGHTS

This table is to facilitate finding the subtended angle when only one angle has been observed—

D_a or E_a } angle of { Depression / Elevation } at **A**

D_b or E_b } to at **B**

c distance in feet between **A** and **B**

Case — When reciprocal angles have been observed—

(*a*) If both angles are depressions take half the difference

(*b*) If one angle only is an elevation take half the sum

The result is an auxiliary angle called the subtended angle (S)—

$$\text{or } S = \frac{D_b - D_a}{2} \quad \text{or} \quad \frac{E_a + D_b}{2}$$

2nd Case — When no angle only (D_a or E_a) has been observed, we must first find the subtended angle

Rule —Subtract the quantity in Table IV from log c. The natural number corresponding to the resulting logarithm is an angle K in seconds of arc, then—

$$S = K - D \quad \text{or} \quad K + E$$

Having now found S in either case the difference in height in feet (h) between **A** and **B** is obtained from the formula—

$$h = c \tan S$$

EXAMPLE OF 2ND CASE —

Given $\log c = 4.8907$

and $D = 0^\circ\ 14'\ 25''$,

to find S in lat 20° with coefficient of refraction .07—

$\log c = 4.8907$

Number in Table IV under .07 for lat 20 } $= 2.3716$

$\log K = 2.5191$

$K = 330'' = 0^\circ\ 5'\ 30''$

$D = 0\ 14\ 35$

Hence $S = K - D = 0\ 9\ 5$

See Form II, p 31

Rope, 3 inch
Saws
Shovels

These should be supplemented by the tools in use in the country

CAMP EQUIPMENT

Baths, canvas
Beds, camp
Bedding and valises
Boxes for small stores
Buckets
Canteens and messing kit
Candle lamps
Chairs, camp
Curtains, mosquito
Hurricane lamps
Indiarubber sheets
Lamps, Lords
Mess boxes and cooking utensils
Stoves, camp and cooking (for cold climates)
Tables, camp
Tents, Willesden canvas, double roof, ridge
Washing kit

APPENDIX VII

The [illegible] sketching in dense forest [illegible] extracted from the Manual of Field Sketching. The method [illegible] for a full [illegible] exploration expeditions, and may [illegible] be used [illegible] work for filling in minor tracks between points more [illegible] fully fixed.

SKETCHING IN DENSE FOREST*

In many parts of Africa especially it is impossible on account of dense bush, [illegible] to survey any features other than the line of the road or track. As the paths will be very crooked, bearings have to be taken at short intervals, and such surveys [illegible] especially when the sketcher is marching with a column or caravan it is inconvenient and would waste a great deal of time to plot the bearings and distances on the road. It is preferable therefore to enter them in a note book and to plot them on [illegible] map. The bearings are better taken with a prismatic compass if available, but [illegible] with a [illegible] pocket compass. Distances are best arrived at by noting the times at which the bearings are taken or objects passed and estimating the rate of marching during the interval. A convenient form of note book is formed by ruling four lines about half an inch apart down the centre of each page (see fig. 70). Supposing the day's traverse is being commenced from Yandina village, start by obtaining a back bearing to the last village. This is entered as B B (back bearing) to village 208°, and a forward bearing to the next village in front entered as F B village (forward bearing) Yolu 71°. In the thickest bush country a native has generally a very good idea of the relative positions of the villages round his own, and the observed bearings from village to village are very useful as checks on the direction of the traverse.

If a distant view is obtainable it is advisable to take back readings to any marked *physical feature as far away as possible and near which the track has passed, also to any* points in advance near which it appears probable it may pass. These long bearings of points say 30 or 40 miles apart, are more useful than those from village to village in checking and correcting the direction of the traverse.

In the example (fig. 70) bearings were obtained to two hills about 30 miles ahead. The bearing of the track immediately ahead is then taken and entered in the centre column, and the time in the first or left hand column.

It is often impossible to see the general direction of the track, which probably disappears in the bush a few yards ahead, in this case it is necessary to have a native to show the direction, but constant watching is necessary, as many natives are very slow in understanding what is required, and seem unable to strike a mean between the direction of the path just a few yards in front and its position two or three miles ahead. To get a general direction of about half a mile of road, so as to take a bearing every ten minutes, is a very convenient mean, and will give fair results. On arrival at the point where the direction changes and a new bearing has to be taken the estimated rate of marching is entered in the third column.

If it be impossible from want of guides or other cause, to get satisfactorily the forward direction of the track, the best way of proceeding is to take the bearing upon which one happens to be marching at fixed intervals, say every five minutes of time, which may be

* The method here described is also best for long continuous sketches from horse or camel in 2 minutes. If the bearings are long it is better to dismount from the horse when taking them (not necessarily from the camel). The plotting is done on arrival in camp.

Rope 3-inch
Saws
Shovels

These should be supplemented by the tools in use in the country

CAMP EQUIPMENT

Baths canvas
Beds camp
Bedding and valises
Boxes for small stores
Buckets
Canteens and messing kit
Candle lamps
Chairs camp
Curtains mosquito
Hurricane lamps
Indiarubber sheets
Lamps Lord's
Mess boxes and cooking utensils
Stoves camp and cooking (for cold climates)
Tables camp
Tents Willesden canvas double roof ridge
Washing kit

note it and make allowance for it in the plotting In the example, 6 14 is the time of arrival at the spot and 6 34 that of starting off again It is sufficient to bracket the two times together to show what is intended

The distances are plotted as straight lines it is therefore necessary to allow in the "rate of marching" for the windings of the path The maximum rate entered is 2¾ miles an

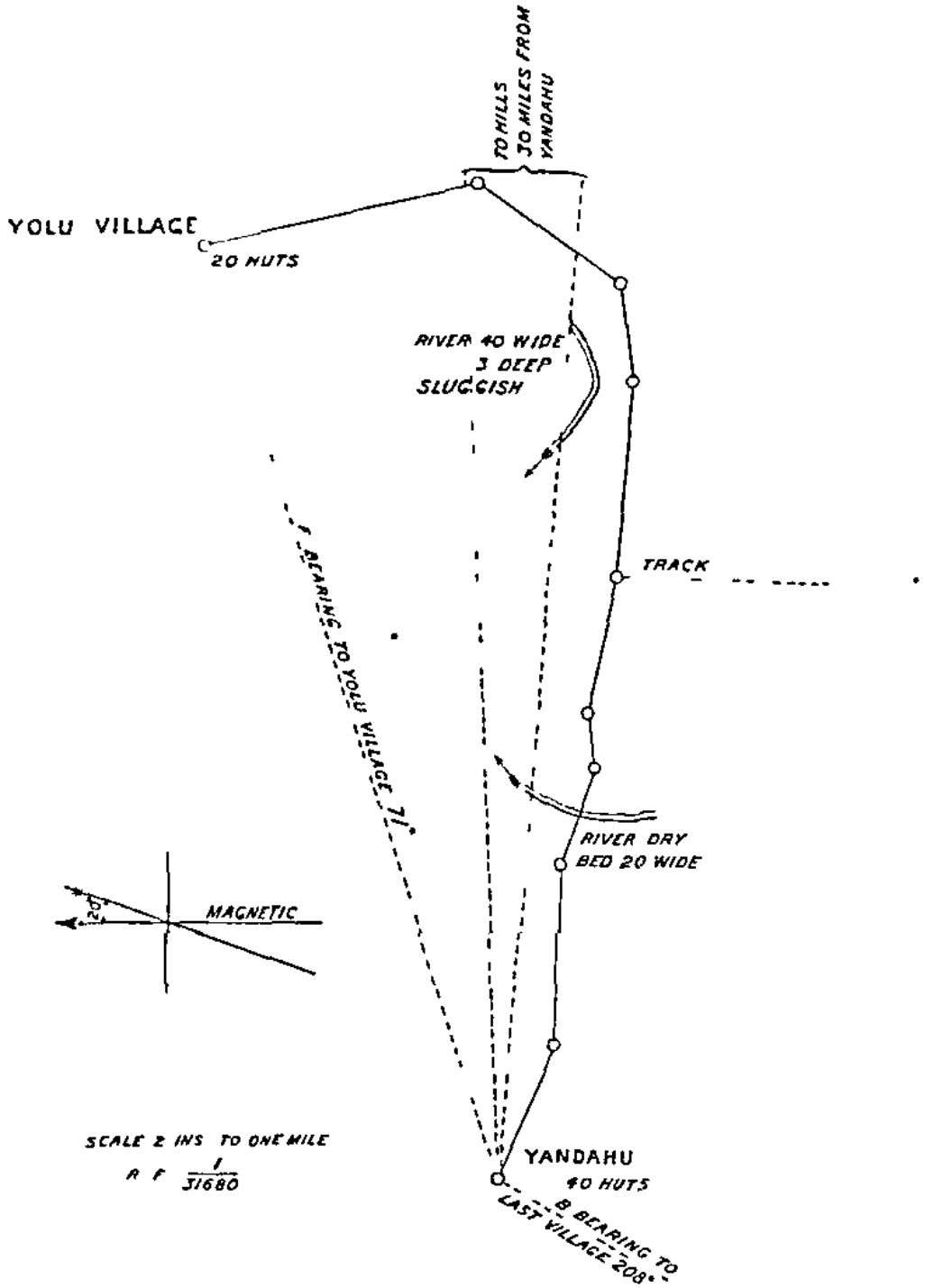


Fig 71.—Plotting of the Compass Traverse (Shown on fig 70)

hour, and this is as much as most caravans of porters will accomplish on an African bush track If the track goes up and down hill, or is very stony or otherwise bad, it is necessary to reduce the rate entered accordingly

After a little practice the error in length of traverses of this nature done with ordinary care should not exceed about eight miles in a hundred, and this is caused generally by a persistent over or under estimation of the rate of marching In direction the result is, as a rule very good it is wonderful how the number of small errors in bearings neutralise one another

The track included in fig 70 is plotted on fig 71

For plotting it is convenient to make one or two scales showing the distances to be plotted in minutes of marching at the different rates

Try to start and end up traverses of this nature on points of which the positions are known

When marching with a column or caravan it is a good thing to work, if possible, for a mile or so beyond the camping ground at the end of the march so as to be able in the morning to start off ahead and clear of the caravan

It is advisable to carry the watch by some means which enables the time to be readily noted A leather case, of the pattern used in South Africa, on the belt, or a band on the wrist are both convenient methods

It is a good thing to practise at first in a country of which there exists an accurate survey as this gives a means of checking the work and shows the topographer how much reliance he can place upon it

Excellent traverses have been executed in a similar way during canoe voyages down rivers in Africa and elsewhere

APPENDIX VIII

PHOTOGRAPHIC SURVEYING

A map of a tract of country may be constructed from photographs of it, and, under exceptional circumstances, such a process may be a useful and economical one. But suitable conditions are rare, and the resulting map is necessarily less accurate than one made by the methods which have been described in this book.

Photographic surveying is practically equivalent to constructing a map by intersection, involving the use of interpolation, traversing, and local measurement. As a survey system it has two fundamental defects: the ground is not walked over, and the map is not made in the field, but plotted in an office.

The conditions favourable to the use of phototopographic methods are —

(i.) Inaccessibility of the tract of country to be surveyed, which may be, for instance, the upper portion of a high snow range.

(ii.) Well-marked features. The method would, it is obvious, be useless on the rolling veldt, on plains, or in forests.

(iii.) A very short field season, such as may occur in subarctic regions.

(iv.) The want of skilled topographers.

The most successful instance of the use of photo-topography is to be found in the Canadian surveys of the Rocky Mountains.

Many treatises have been published on the subject, of those in English, the reader is referred to

Photographic Surveying, by I. Deville, Surveyor-General of Dominion Lands, Ottawa: Government Printing Bureau, 1895.

'Photographic Methods and Instruments,' by J. A. Flemer, in the United States Coast and Geodetic Survey Report for 1897.

'Photographic Surveying,' by J. Bridges Lee, in the Royal Geographical Society's 'Hints to Travellers,' Eighth Edition, 1901.

The use of phototopography is so purely necessary that it is not considered desirable to increase the bulk of this book by the inclusion of a detailed description.

APPENDIX IX

USEFUL TRIGONOMETRICAL FORMULÆ

(i) Plane Triangles—

Given three sides, a, b, c,

$$\sin\frac{A}{2} = \sqrt{\frac{(s-b)(s-c)}{bc}},$$

$$\cos\frac{A}{2} = \sqrt{\frac{s(s-a)}{bc}},$$

where

$$s = \tfrac{1}{2}(a+b+c)$$

Given two sides and included angle a, b, C,

$$\tan\frac{A-B}{2} = \frac{a-b}{a+b}\cot\frac{C}{2}$$

Given angles and a side, A, B, C, a,

$$\frac{a}{\sin A} = \frac{b}{\sin B} = \frac{c}{\sin C}$$

Given two sides and angle opposite one of them, a, b, A,

$$\sin B = \frac{b}{a}\sin A$$

(ii) Spherical Triangles—

Given three sides, a, b, c,

$$\sin\frac{A}{2} = \sqrt{\frac{\sin(s-b)\sin(s-c)}{\sin b \sin c}},$$

$$\tan\frac{A}{2} = \sqrt{\frac{\sin(s-b)\sin(s-c)}{\sin s \sin(s-a)}},$$

where

$$s = \tfrac{1}{2}(a+b+c)$$

Given two sides and included angle, a, b, C,

$$\tan\frac{A+B}{2} = \frac{\cos\frac{1}{2}(a-b)}{\cos\frac{1}{2}(a+b)}\cot\frac{C}{2},$$

$$\tan\frac{A-B}{2} = \frac{\sin\frac{1}{2}(a-b)}{\sin\frac{1}{2}(a+b)}\cot\frac{C}{2}$$

Given two sides and angle opposite one of them, a, b, A,

let

$$\tan\theta = \tan b\cos A,$$

$$\cos\theta' = \frac{\cos\theta\cos a}{\cos b},$$

then

$$c = \theta \pm \theta' \text{ (two solutions)}$$

Given three angles A B C

$$\cos \theta = \frac{\sin (A + \theta)}{\sin B \sin C \sin \theta},$$

where

$$\tan \theta = \frac{\cos B \cos C}{\sin A}.$$

Given two angles and the intercepted side A B

$$\theta = \frac{\cos A \sin (B - \theta)}{\sin \theta},$$

where

$$\cot \theta = \cos c \tan A$$

or

$$\tan \frac{a + b}{2} = \frac{\cos \frac{A - B}{2}}{\cos \frac{A + B}{2}} \tan \frac{c}{2}$$

$$\tan \frac{a - b}{2} = \frac{\sin \frac{A - B}{2}}{\sin \frac{A + B}{2}} \tan \frac{c}{2}$$

Given two angles and side opposite one of them, A, B a,

APPENDIX V

LENGTH OF THE METRE

In a book published by the Ordnance Survey entitled "Comparison of Standards of Length," by Captain A R Clarke, R E, F R S, 1866, will be found an elaborate account of the methods employed to determine the values of the principal national units of length in terms of each other The most important relation is the following —

THE METRE = 1 093623 yard
= 39 37043 inches

THE YARD = 0 914392 metre

REEVES'S TANGENT MICROMETER.

A micrometer which can be readily fitted to any theodolite by means of which angles can be read with much greater accuracy than by a Vernier, has been recently designed by Mr E. A. Reeves of the Royal Geographical Society.

The Tangent micrometer will be valuable when circumstances prevent the use of micrometer microscopes (and sometimes the extra bulk and large size of the boxes is a difficulty). A theodolite fitted with tangent micrometers is cheaper than one fitted with micrometer-microscopes.

By means of the addition of a micrometer drum combined with an indicator, a carefully constructed tangent screw serves also as a [illegible] consider-

to the

[illegible] *of this*

micrometer

(Wt w 1545 5300 7 | 05—H & S 7249) $\frac{P\ 05}{744}$

APPENDIX X

LENGTH OF THE METRE

In a book published by the Ordnance Survey, entitled, "Comparison of Standards of Length, by Captain A R Clarke, R E, F R S, 1866, will be found an elaborate account of the methods employed to determine the values of the principal national units of length in terms of each other The most important relation is the following —

THE METRE = 1 093623 yard
= 39 37043 inches

THE YARD = 0 914392 metre

REEVES'S TANGENT-MICROMETER.

A micrometer which can be readily fitted to any theodolite by means of which angles can be read with much greater accuracy than by a Vernier, has been recently designed by Mr E. A. Reeves of the Royal Geographical Society.

The Tangent-micrometer will be valuable when circumstances prevent the use of micrometer-microscopes (and sometimes the extra bulk and large size of the boxes is a difficulty). A theodolite fitted with tangent-micrometers is cheaper than one fitted with micrometer-microscopes.

By means of the addition of a micrometer drum combined with an indicator, a carefully constructed tangent screw serves also as a

[illegible] under-

[illegible] to the

[illegible] of this

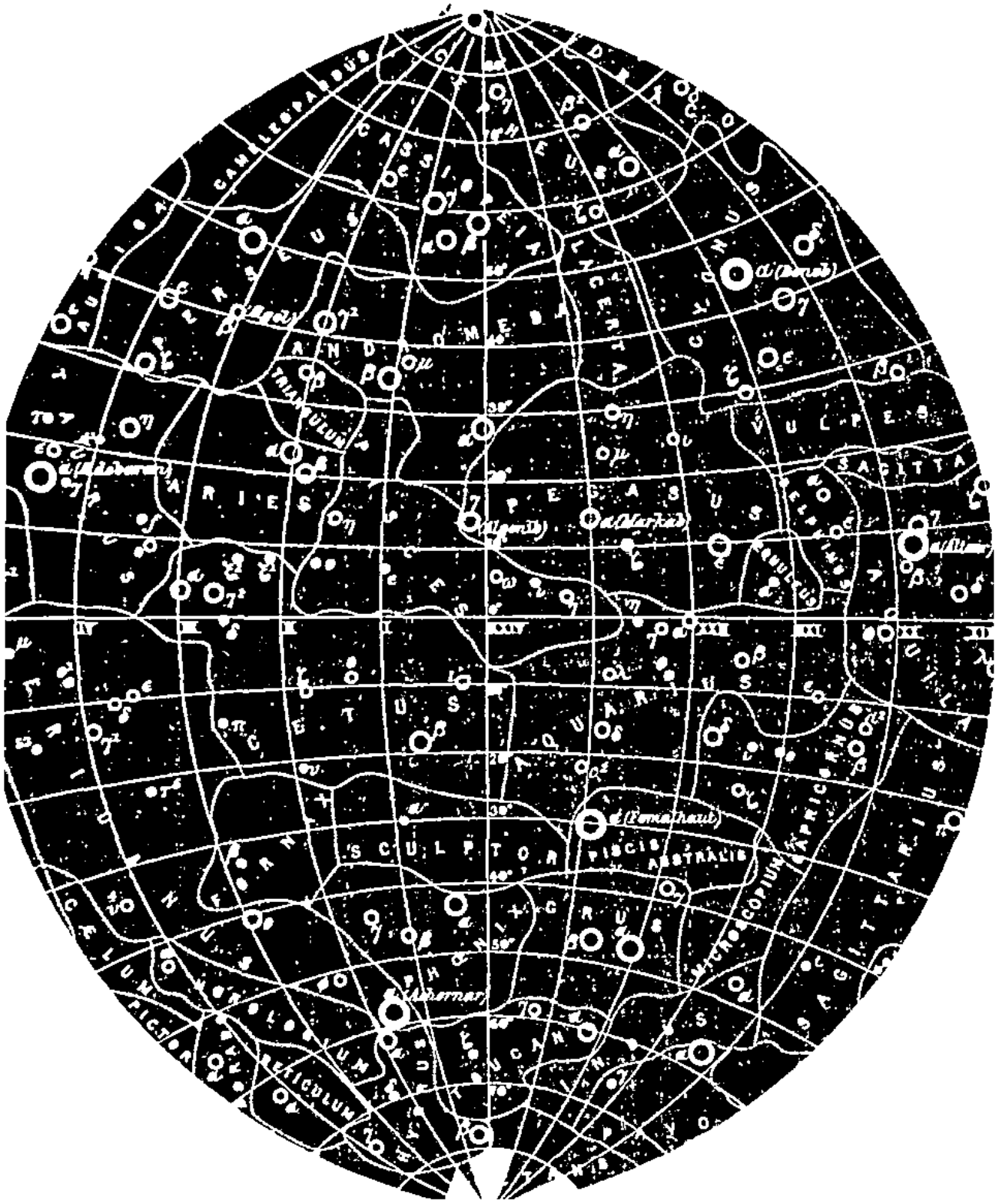
micrometer.

(Wt w 1515 5300 7 | 05—H & S 7219) P. 06/744

STAR CHART

SHOWING ALL N.A. STARS (1904)

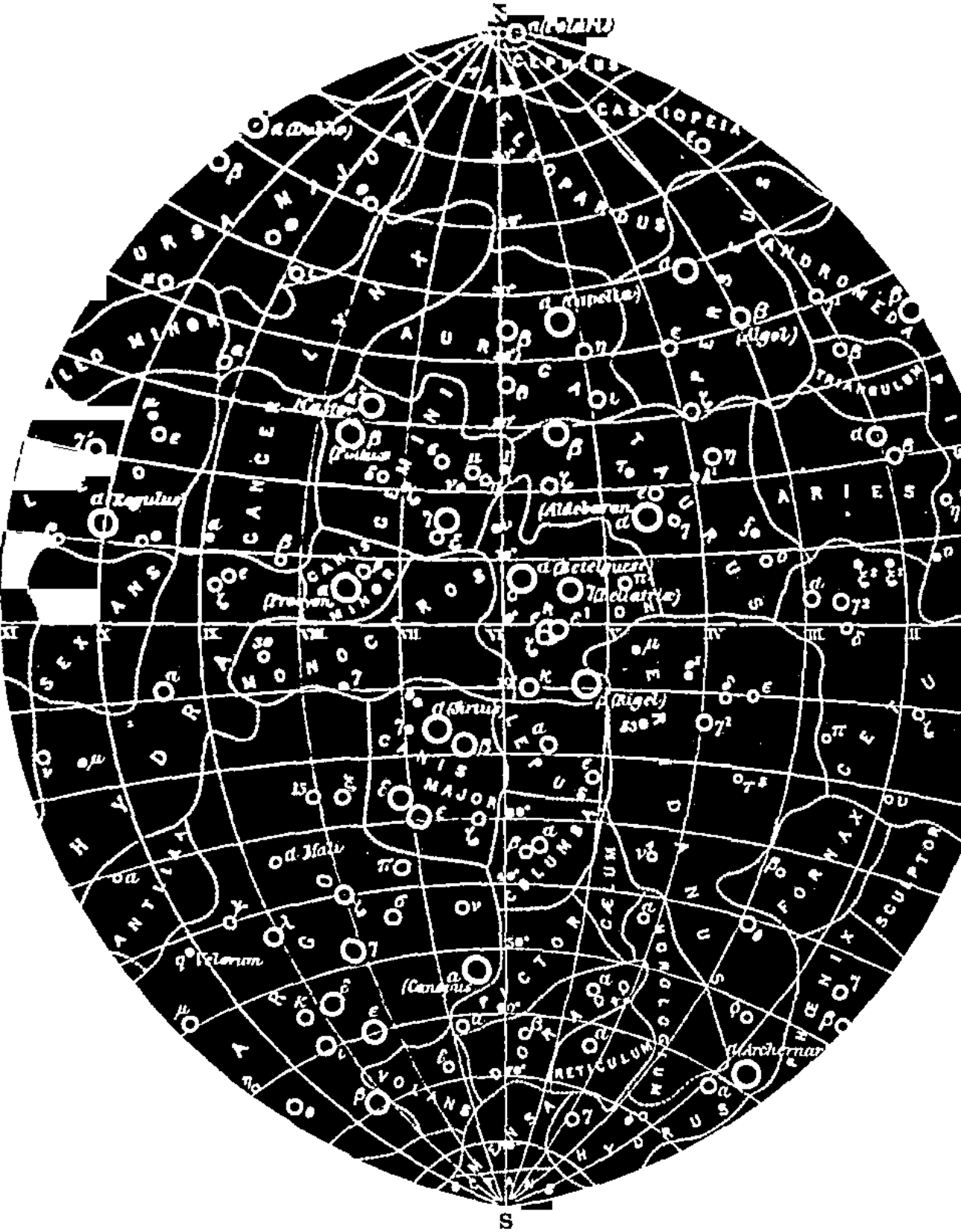
up to 4·5 mag. in four plates



STAR CHART

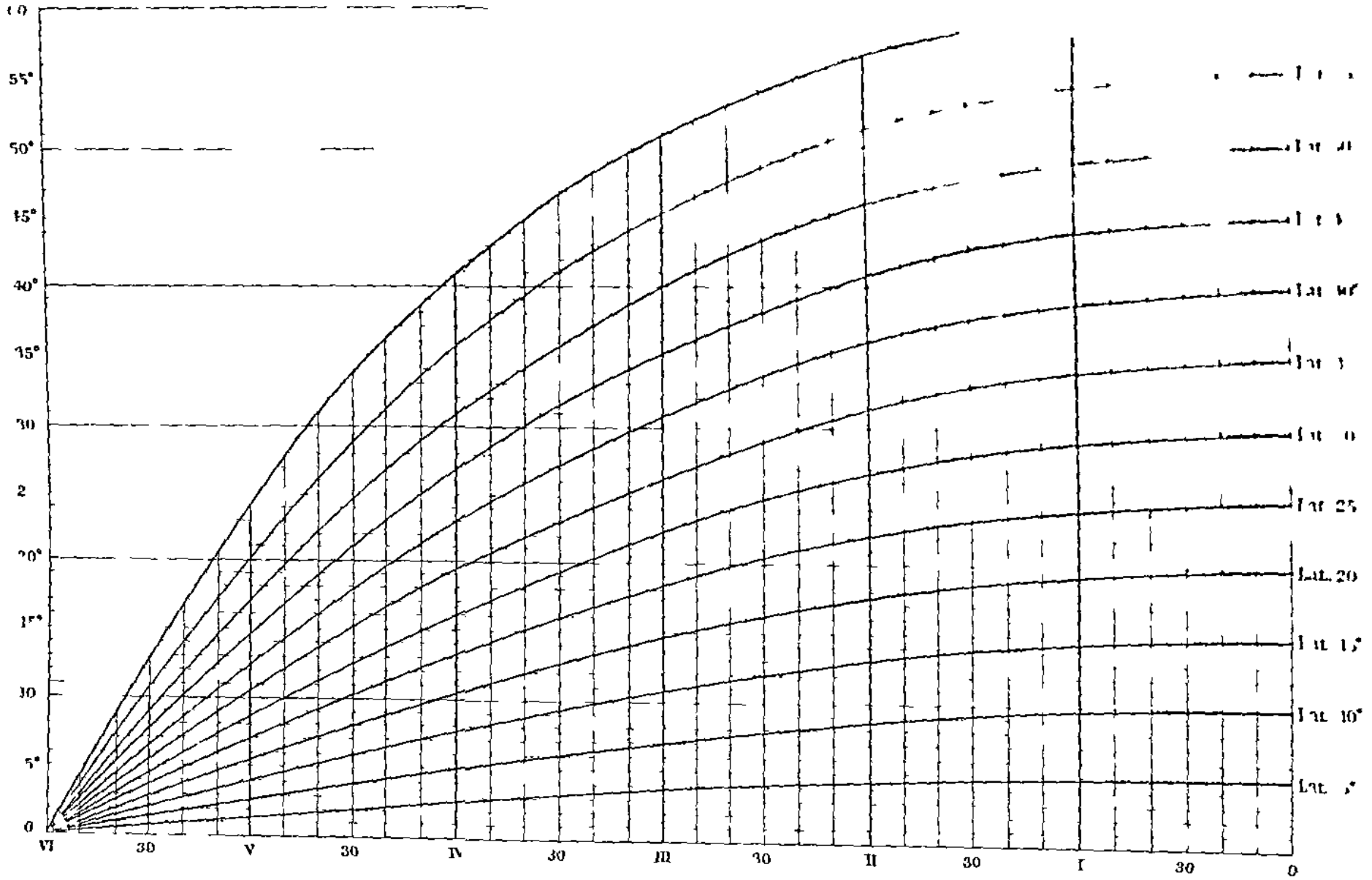
SHOWING ALL N A STARS (1904)

up to 4·5 mag in four plates



MAGNITUDES

2·5 4 4 3·5 3 5 5 6 3-2·5 2·5 2 2·1 5 1·5


60
55°
50°
45°
40°
35°
30
2
20°
15°
10
5°
0
VI
30
V
30
IV
30
III
30
II
30
I
30
0
HOUR ANGLE (in Time)

INDEX.

A

Acc racy of van u metl od of l tern n ng l tts 8C
Accurac of various n tl od of l tern n ng lo t le 203
A t re Serv e rve s on 63
A lam Mr C W n en ure ent w tl teel tape 8
A ljus t ent of errors n l n tr verses 9
Adj tn en of lev l 8
A ljus t e t of l e tr ver app rox ate 50
for run 14
of tl eod l e 15
Afgl n B l r Co o l
A r s pro j t o 3 l
All L le or s l t vane
Al rnat e form la for l t t le lo at le an l re erse az n tl 2 0
Alt tu l ol served orrect ons to l a l ied to 110
Alt u le of star 128
Alber s proj t on 9 103
A ro d l aro eter letern at on of l e gl ts l v 8
A parent lay 131
places of star 139
A pend x I —Explanat on of Table I an l Topo gra j l cal Form 2 96
II —Computat on of d ances an l az mutl s 208
III —*Alternat re formulæ for determ n ng* lat tu le long t le an l rever e az m tl 2 0
IV —Con p on of l e g t explan n of l le IV 71
V —Ll e of eel tape 7
VI —L t of tru n tool an l p equ j ent 273
VII —Ske l n len e fore t 270
VIII —Ll otogra j l surve n 2 9
IX —Useful tr ono e r al formulæ 280
X —Leng l of tl e netre 282
A j e L ne 124
Arc or zero 21
A tronom cal computat ons 169
o-ord nate 128
stat ons long trav r e 43
tr angle 130 143
Ax of earth l efin t on 12
Az tl lef on of l 9
leter n t n of 147
tat o n long traverses 44
for trigono etr c l comp tat on 26

B

B ro eter le l ts 86
B rtl olon e s l lf l p 12
Ba e o
B e o p t n 6
le l t o
l ne f re 8
r r j l t
of j r o 8
j n l l le error of o
s te f r f
stan lar l for o
ter n nal po nt
of ve f o 8
B lets gn l 10
B rose p j er 117
Ben l n ark 74 84
Bo l ng po nt tl ermometer leter nat on of le g l t by 87
tables 2 6
Bonne s proj t on 97 102
Bounda y Com n s ons 40 43 71 73 184 190
Box hrono er 141

C

C l ral j l l
C j eq j t 74
C l s rve s pl oto ur e ng n 9
C proj t n 98 111
Cu r 8
C le t al spl er 1 3
l h on f 12
C n of tr ngl s 11
Cl a nage error 41
Cl eck levell n 84
Cl ronon eter omparison of 146
Cl ro on e er error 144
wa l 141

Clarke Colonel 43, 105 282
Clarke's figure of the earth 209
projection 97, 105
Clearings for long traverses 43
Clinometer, Indian pattern 61
Coefficient of refraction 29
expansion of steel 6
Collignon's projection 97 104.
Collimation of levels, adjustments for, 76, 78
theodolite adjustments for, 16
Colour lithography 115
Comparison of chronometers 146
„ watches 146
Compass traverses 34 276
trough, 57
Compression of earth 209
Computations astronomical 169
Computation of co ordinates of traverse 35
Computations lengths of sides 23, 24
Computation trigonometrical heights, 28 31, 223 271
for rapid triangulation, 68
of rectangular co-ordinates, 25
, trigonometrical latitudes and longitudes 26 267 270
Conical projections, 96 97, 107 138
Constellations, 125
Contour, definition of a 89
, interval 91
intervals in British and Foreign topographical maps, 121
Contouring 61 89
, degrees of accuracy in, 89
methods of 89
with aneroid barometer 91
Indian clinometer and plane table, 90
„ „ level or theodolite, 89
„ „ water level, 90
Conventional projections, 97
Conversion of mean and apparent time, 133
„ , sidereal time, 134, 135
Cooke's Level 75
Cotton Mr F P steel tape measurements by, 8
Co-ordinates rectangular, 25
Culmination (moon), accuracy of, 203
„ of stars, definition of 128
Curvature of the earth 80
, and refraction amount and formula for 81
Cylindrical projections 96, 98, 110

D

Darwin Major, pamphlet, 110
Datum level, 20, 74
Declination, definition of, 129
Determination of time 143
Diaphragm of theodolite, 16, 17
Distances and azimuths, 268
Drawing on stone 115

E

Ecliptic, definition of, 127
Elastic extension, 6
Elgin local attraction at, 43
Elongation of star, 137
Error, angular of traverse, 37
definition of, 204
law of propagation, 206
Errors, adjustment of in long traverses, 207
, of compass traverses, 278
„ frequency of, 204
„ in a network of long traverses, adjustment of, 207
„ in long traverses, 16
„ probable, 205
„ residual, 205.
Equal altitudes for time, 145
Equal-area projection, 96, 101
Equation of time, 139
„ , definition of, 131.
„ „ variation in, 132
Equator, definition of, 127
Equinoxes, 127

F.

Face, 21
Farquharson, Col Sir J , 119
Field book form for traverses, 36
„ projections, 95
Focus, theodolite adjustment, 15
„ level adjustment, 75
Forest, compass sketching in, 275
Form lines, 91
Framework of a map, 2, 4

G

Gauss's method of collimating 17, 79
Geodetic survey, 1
„ triangulation definition of, 3
Germain, on projections, 98
Geographical surveys, 3
Gill, Sir David, 208
Glareanus, treatise of, 100
Globular projections, 98, 110
Gnomonic projection, 97, 101
Gold Coast Boundary, 43-45
Grant, Colonel, diagram for occultations, 180
Graticule, definition of, 92
Graticules, tables for constructing, 227, 232
Guillaume, Mr , Nickel Steel alloys, 8

H.

Height above sea correction for, to base measurement, 7.

Hen lt l lan n eter Tal les \ VI 224
t l n j nt tl ern ter Tal l \ II
\ III \
tra n ctrnsl \ 31 — l
le rees f ac rs a in etl sl f
leter n n
H l ketel n 89 11
H ll Maj r 201
H t ls C l nel 2 3
H rr l f n t n of 19
H rr tal a gles etl sl f sarv g \
eq ral t f
parallax f e 14 l
H ra le lef f 19
H ps ter l ern a n fle glt t s 5

I

I len fleat of tra tat n 64 68
In lian el n e er t l
Ink l l rajl 111
I rum e tal a l j j t l t f
I terpolat tra m l 8 3 33 t
I ers ted j n 11 \
I ar 8
taj 44
I jre n u lar f l 11 l z rjl
an l l tlo ajl 11

J

Ja e s jr ject n 97 10

K

Kejler s laws 1 4

L

Layer system 12
Lavs l tlogrjl e 11
Lavvange s project on 97 101
La Hire s 97 10
Lau bert s 97 100 101
Lat tude b Pole St r 139 1o
neridian alt tu le 1o
circum er d alt tu le 1o
d term nat on of 1 1
defin t on of 1
l near value of quarter degrees of 3
secon l of ar lo g
er dian 234
long tu le an l reverse az tl alter t ve
for ul e 270
I at tudes longitudes and reverse az n utl s 7
1able I

I at t l rel t of T l \ VIII for occ ltat o
I gtl f e ca n l alo g er t T lle XI
34
f o l alo g l n llel lul le XII
1
f gl t wl u levell g 8
of q rter legr Tal le \ 23
Le el r j ltern of o
C ok rever tl l er jton an l alj t e t
of o
D jj alj t e t of 8
\ p t r alj t e t of 8
Lev ll g 4
l c k 84
l fin t on a l jr n jle of 4
rd r or eug ne r g 4
tru ent 4
t l l book for tor 84
jvolet or pre e 4
tare le rnj t on of 80
jn ved re 81
w l tle tle c lol te 8
tle o lol e 18
l l rea l n_ korw rd L k l l t r
sl ate 8
le of tle o lol te val of 1
L l er an Bo ndar Co on 4
L tl ogrjl 113
L tl o_rajl e equj e t n tle fell 11
traw ng an l jr nt n_ r t of 113
jran n_ 114
tran fer 113
work n tl fell j r o l re j rel
tor 113
Lo l att t on 43
Logar t n t bles S ortre l 14
Long tu le fn t o of 1 7
exa p e of r j l rry b tor r l 71
b alt tu le ot n oo 03
clron eter 186
eclip es of Jup er s l 3
l ne r alue ot o s o l ot ar l
jara lel 46
ear val of q rt r te_r of _L_
l lun r l an e 03
oon l n _ t r 91
o cult t o 187
jl otogr jl 201
telegrapl 18
tr angul t on 184
relat ve a e ra of l ff
leterm n ng 203
Lon tra er e 4
a trono al s
az mu l t
o juta s f 4
errors n 41
redu t t
traver e co ju a

M

Magnitudes of stars 126
Map projections not necessarily geometrical 92
general discussion 95
list of 96
Maps British and Foreign Government topographical (see also topographical maps) 118
Mapping *versus* sketching 118
Marcheing rate of in forest 277
Marks and landmark stones 10
Means as level 30
true definition of 131
Mercator's projection 97 100
Meridian definition of 127
Metre in terms of yard and inch 282
Micrometer microscope theodolites 13 141
taking runs of 14
Mollweide's projection 97 104
Moon 125
altitudes longitude by 203
culminations longitude by 201
distance from earth 123
occultations longitude by 187
photographs for longitude 201
Moon's altitude in occultation 200
parallax correction for Table XVII 264
vertex angle from in occultation 208
Mounting a plane table 57

N

Nautical almanac 138
Nigeria Boundary Commission 190
Note book for compass sketching 270
Nyasa Boundary Commission 184

O

Observations for time 143
Occultation of star by the moon 187
example of prediction of 196
illumination of moon's limb 198
Offset lithographic 116
Ordnance survey 5 8 118
signal 10
Orthographic projection 97 104
Orthomorphic 96 97 100

P

Panama Boundary Commission 73
Paper Burnt 117
lithographic 115
transfer 113
Parallax adjustment for 15 75
effects of in occultation 187
from Table XVI 261
correction for Table XVII 264
of stars 126
sun's diurnal 140
Perspective projections 96
Photographs of moon for longitude, 201
Photographic surveying 279
Pillars isolated 15
Planets 123 124
Plane table description of 57
identification of points by 66
interpolation with 58
intersection with 58
mounting a 57
resection on from two points with 60
rules for interpolation with 59
surveying with the 57
traversing with 60
Plane tabling 57 66
Plotting a graticule 93
Polar distance 129
Pole star 126
and brush 10
Polyconical projections 97 109 110
Prediction of occultation 196
Prime vertical definition of, 127
sun or star on 138 144
Printing lithographic 114
sun 116 117
zincographic 116
Prints from Bemrose and other papers 117
Probable error 205
of arithmetic mean formula for, 205
Projection conical for South Africa 109
Projections list of 96 97 98
of some important maps 99
the choice of 98
Proper motion of stars 126

R

Rapid triangulation 63 65 71
computations for, 68
Rate of marcheing in forest, 277
Reduction to meridian for latitude observations
Table XVI 262
Referring object 20
Refraction astronomical 140 209
terrestrial amount and effects of 81
coefficient of 29 223
Register lithographic 116
Reproduction of maps in the field 112
Residuals 20
Reverse azimuths 26 267 270
Right ascension definition of 130
angled spherical triangles 137
Roller lithographic 116
Roy General 118
Rules (parameter) 14
Russel projections, 107

Sag of steel tapes, 272
Satellite stations, 22
Scale of large topographical maps, list of, 110
topographical maps, 1
for, 122
Selection of traverse stations, 40
Sea level reduction, 46
Setting up of graphical drawing, 82, 83
Shadow of stars, 141
Shutter for camera, 140
Sidereal day, 131
Slide rule for logarithms, 57
for traverses, 45
Small scale maps, latitudes and reverse azimuths, Table II, 222
Small scale triangulation, 10
for traverses, 45
Smith's projection, 97, 102.
Sketch book, 91
Sketches suitable for compiling to form maps, 118
Sketching in dense forest, 275
Solar system, 123
Stations, 127
South Africa, maps of, 119
Spherical excess, 23, 258
trigonometry, application to Field Astronomy, 136
Stations, selection of, 10
Stars, apparent places of, 139
distance of, 123
elongation of, 137
magnitude of, 126
names of, 126
, observation to, 142
on prime vertical, 138
selection of for azimuth, 148
, , latitude, 153
, , time, 144.
Steel, expansion of, 6
, tapes, sag of, 272
Stereographic projection, 97, 105
Stone, lithographic printing in colours, 115
, , preparation of, 113, 115
, , transfer to, 114
Sultense method, 51, 52
, station, 42
, traverse, 41, 53
Surveying, definition of, 1
Survey Departments of British and Foreign Governments, 118
, of India, the, 119
Sun, distance from earth, 123
, observations to, 142
, printing and apparatus for same, 116, 117
Sun's diurnal parallax, 140, 261
Swing, 20

Table, 209
Table I.—For computing latitude, longitude and reverse azimuths, 209, 270
II.—For applying signs to computations obtained by Table I, 222
III.—Computation of heights from vertical angles, 223, 271
IV.—Computation of heights, to find subtended angle, 223, 271
V and VI.—For determining relative heights by barometer, 224
VII and VIII.—For determining heights with boiling point thermometer, 226
IX.—For facilitating drawing graticules of maps, 227
, X.—Length of quarter degree of latitude and longitude, 232
XI.—Linear value of one second of arc along meridians, 234
, XII.—Linear value of one second of arc along parallels, 236
XIII.—Spherical excess, 258
XIV.—Astronomical refraction, 259
, XV.—Parallax of the sun, 261
, XVI.—Reduction to meridian (for latitude), 262
, XVII.—Correction of moon's equatorial parallax, 264
, XVIII.—Reduction of latitude (for occultations), 265
Tacheometry, 51, 55
Tapes, steel, 5, 272
Theodolite, 11
, adjustments of, 15
, , , collimation, 16
, , horizontality of wire, 17
, levelling, 18
, focus and parallax, 15
, , transit axis, 18
, verticality of wire, 17
, examination of, 14
, micrometer, 12
, vernier, 12
observations, 68
setting up a, 15
, traverses, 34.
use of in field astronomy, 141
Theodolites, portable, 63
, prices of, 141
, weights of, 141
Theory of errors, brief notes on, 204
, , , examples of use, 206
Time, determination of, 143
, mean and sidereal conversion of, 134, 135
Togo Gold Coast Boundary Commission, 44–47
Topography, definition of, 1
Topographical surveying, definition of, 1
, map, 1

M

Ma les of t rs l
M j projection t rl ɡo tr l t
ɡ rl l
l t f f
M j Br t s l l k r ɡ (lov r t t po
ɡra l l (se al o t pɡra l l n ps) 118
M pj ɡ *reversu* sket l g 118
Mar f n w r te of fore t 7
Marks an l rk s on 10
Me e lev l 30
t t o of 181
Mer tor projecto f 18
Mer l f f l
Metre ter f rd l l s
M ro er ro pe t l l l t 13 141
tak ɡ r s of 14
Mollwe le s projecto 97 1 4
M l
alt t l ng l l
l n o long l l 81
l tance fro earth 1 1
o l l ɡ l l 18
plot ɡra l f r l t l
Mo n s lt t le lt
p n llax orre f r l t l XVII
erter an ɡles fr o lf t
Mo t g a la tabl 5

N

Na t l nal n 138
N ger Bo n lary Co m s o 190
Note book for mpa k t l
N a a B u dary Co n s on 184

O

Ob erva on for t 143
O ltat o of tar b th oo 18
exa ple of pr t to of 13
ll m t o of oo s l t 198
Off et l th o ɡra l e 116
Ordnan e sur ey o 8 118
s gnal 10
Ort o ɡra l projecton 97 104
Ortho orpl 96 97 105

P

Pan rs Boun lary Co o 3
l per *Be rose* 117
l th o ɡra l e 11o
tr fer 113
l arallax ljustment for 15 o
effe ts of n o cultation 187
of un Table XV 81
oo s cor e to f r Tabl XVII 64
of star 1 6
sun s d urnal 140
l erpe t r projet 9
l l t ɡra l f r s f r l ɡ t le 91
l l t ɡra l sur y 79
l llar s l tel lo
Pl ts l 1 l 4
llan t l l rpt of o
tl t f t n of ps ts l 60
interpol t w th s
inter ct on w th o8
unt n ɡ a o7
n e t n fr two ps t w th 60
r l s f r l t rj l t n w th
s rv w th th
tr r g w th 6
l l t th n o7 60
l l t r grat l 91
l lar l a e 19
l l star l
a ll r l 10
l l al *projet* 97 189 11
l n l t of oc ltat 186
l n e vert al l f t n f l
s r or star 138 144
l s t ɡ l th gra l 114
s 11 11
z no ɡra l e 116
l n ts fr B n n e a l otl er p per 11
Instrl l erro 8
f ar th t e f r l for 6
l nj t l for Sout Afr 100
l nj to l t of 16 9 98
f s e p rt t ra 99
tl e lo f 8
l nj r t f stars l

R

R j l tr ng l t on 63 6o l
co j tat o s for 8
Rat of rd ng for t
Ref to to er l for l t t l ob r to
T ble XVI 6
R ferr g ol ject 90
Refn t on a tronom cal 140 9
terre tr al a ount l eff ts of 81
co eff e t of 9 9 3
Regi ter l tl o rn l 116
Reprod ct o of n a s tle f 11 11
Res lual 0
R r e az mutl s 96 967 a 0
R ɡl t asce on lefin t of 130
angle l spl e e l tr ɡles 137
Roller l tl o ɡ pl e 116
Roy General 118
R ns (ro e er) 14
Ru scl proje to by 107

Steel expan of t
tape sag of 2 2
Stereograpl c proje t on 97 10
Stone l tl ograpl c pr nt ng olo rs 11
preparat n of 113 11
tra fer to 114
Sul te use etl o l ol o2
tat on 4
traver s 41 o3
S rv ng defi t of 1
Survey Depart ts of Br t a d Fo g Go rn ents 118
of In lia Tl e 119
Sun d tan e fro eartl 1 3
ob rvat ons to 14
pr t ng nd app ra us f r s e 116 117
Sun s l urnal parallax 140 41
Sw g 0

T

T ll 00
T ll I—F r p t g l t t le lo t le and r v rs z tl 00 0
II —For l l s gns to co p ta ns obta l b l ble I
III —C p t t o of le gl ts fro ve t al ngl 3 1
IV —Co p t t of le gl ts to fin l b t n l l a gle 3 71
V and VI —For l ter n ngr v l lts l b ro t r 4
VII VIII —For l ter n g l e gl s l bo l ng po t t er o e er
IX F r fa l t g In g gra l of l 7
X —Le gtl of rter l gree of lat u and lo g ul 3
XI I ur value of one econ l of ar alo g n er li n 34
XII —L r l e o on ond of arc alo g p ralle 46
XIII Spl er l exce 08
XIV —A tro o l refr t on 0
XV —P r lax of tl e sun 1
XVI —Rel t on to en a (for lat le)
XVII Corr t on of oon s eq tor l p ra lax 64
XVIII —Rel ct on of lat t le (for o cultat ns) 6
T l o etr ol o
T pe t e
Tl eo lol t 11
l t ent of 1o
ol u t o 16
lor zont l t of re 17
level ng 18
o u a l paral ax 1
trans t ax s 18
vert c lity of re 17
exa nat on of 14
ro ter 1
er 1
observat on 68
et ng u a 1
tr ver e 34
u e of n fi ld trono 141
Tl o l l te port ble 63
r o 141
ts of 141
Tl eor of erro brief tes on 204
exan pl s of u e 06
T e l term nat on of 143
n and dereal con er on of 134 13
Togo Gold Co t Bo n lary Comm ss on 44–47
Topograpl y lefin t on of 1
Topograpl cal surve ng lefin t on of 1
n ap 1

Topographical maps of South Africa, 119
Austria 119
, Belgium, 119
, France 119 120
, , Germany, 120
, Italy, 120
Russia 120
, Spain 120
Switzerland 120
United States, 120
, , the Survey of India 119
, Ordnance Survey 118
Transit axis level 18
Traverses between trigonometrical points 31
errors of 34
linear measurement of 36
observations for 33
procedure for carrying out, 33
Traverse definition of 34
angular error of, 37
book 36
compass in forest 275
computation 35 42, 45
of co ordinates of 35
long computation form 48
field book form for 36
different classes of 34
stations 34
subtense, 41 53
Transfer lithographic 113
Triangulation 10
topographical definition, 3
classes of 3
, probable errors of 207
rapid 63 65 71
principal definition 3
secondary, definition, 3
, tertiary, definition 3
Triangles, size of 10
, length of sides 3
Trigonometrical formulæ, 280
height tables, 223
,, interpolation 30, 60, 70, 72
, signals, 10
Troughton and Simms, Messrs, 14

U

Unmapped area 2
Uses of maps in war, 131

V

Verniers, 12
Vertical angles best time for, 28
,, ,, methods of observing 21
, interval of contours, 62

W

Wahab Colonel, 61
Water level 80
Watches comparison of 130
Watson General, 118
Werner's projection 97 102.

Y

Yard in terms of metre, 282
Year, length of 134

Z

Zero or arc, 21
Zincography, 113 116
Zenith, definition of, 127
,, distance, 128
Zenithal projections, 96, 106